## A Appendix

We now provide additional details for our results in Section 2 of the paper.
Lemma 1. Let $A, B$ be full column rank matrices of size $n \times d$, with $\log (n)=d^{o(1)}$. Let $S$ be an SRHT with ${ }^{1} m=\tilde{O}\left((d+\log (1 / \delta)) / \epsilon^{2}\right)$ rows. For any matrix $B$ of size $n \times d$ we have

$$
\|X\|_{2}=\left\|(S A)^{\dagger} S B\right\|_{2} \lesssim\left\|A^{\dagger} B\right\|_{2}+\epsilon\left\|\Sigma^{-1}\right\|_{2}\left(\sqrt{(1+d / k)\left(\|B\|_{2}^{2}+\|B\|_{F}^{2} / k\right)}\right)
$$

with probability $1-1 / \operatorname{poly}(d)$.
Proof. From Equation 5 in the body and the triangle inequality, we have

$$
\begin{align*}
(S A)^{\dagger} S B & =V \Sigma^{-1}\left(\sum_{k=0}^{\infty} T^{K}\right) U^{\mathrm{T}} S^{\mathrm{T}} S B  \tag{1}\\
\left\|(S A)^{\dagger} S B\right\|_{2} & \leq\left\|A^{\dagger} B\right\|_{2}+\left\|(S A)^{\dagger} S B-A^{\dagger} B\right\|_{2}  \tag{2}\\
& \leq\left\|A^{\dagger} B\right\|_{2}+\left\|V \Sigma^{-1}\left(\sum_{k=0}^{\infty} T^{k}\right) U^{\mathrm{T}} S^{\mathrm{T}} S B-V \Sigma^{-1} U^{\mathrm{T}} B\right\|_{2}  \tag{3}\\
& \leq\left\|A^{\dagger} B\right\|_{2}+\left\|\Sigma^{-1}\right\|_{2} \sum_{k=0}^{\infty} \epsilon^{k}\left\|U^{\mathrm{T}} S^{\mathrm{T}} S B-U^{\mathrm{T}} B\right\|_{2}  \tag{4}\\
& \leq\left\|A^{\dagger} B\right\|_{2}+\left\|\Sigma^{-1}\right\|_{2} \frac{\epsilon}{1-\epsilon} \sqrt{(1+d / k)\left(\|B\|_{2}^{2}+\|B\|_{F}^{2} / k\right)} \tag{5}
\end{align*}
$$

where we used equation 8 in the body in the last step.

## A. 1 AD

Let us manually derive the AD for the least squares regression problem.

$$
\begin{aligned}
\operatorname{LLS}(A, b) & =\operatorname{LS}\left(A^{\mathrm{T}} A, A^{\mathrm{T}} b\right) \\
& =\mathrm{LS}(M, m) \\
(M, m) & \equiv\left(A^{\mathrm{T}} A, A^{\mathrm{T}} b\right) \\
B & =A^{\mathrm{T}} \\
\left(B_{1}, B_{2}\right) & =(B, B) \\
C & =B_{1} A \\
d & =B_{2} b \\
\bar{A}_{M} & =A \bar{M}+A \bar{M}^{\mathrm{T}} \\
\bar{A}_{m} & =b \bar{m}^{\mathrm{T}} \\
\bar{A} & =\bar{A}_{M}+\bar{A}_{m} \\
& =A \bar{M}+A \bar{M}^{\mathrm{T}}+b \bar{m}^{\mathrm{T}} \\
\bar{b} & =A \bar{m} \\
(\bar{M}, \bar{m}) & =\mathcal{J}^{\mathrm{T}}(\mathrm{LS})(M, m)(\bar{y}) \\
& =\left(-\bar{m} y^{\mathrm{T}}, \mathrm{LS}\left(M^{\mathrm{T}}, \bar{y}\right)\right. \\
& =\left(-\mathrm{LS}\left(A^{\mathrm{T}} A, \bar{y}\right) y^{\mathrm{T}}, \mathrm{LS}\left(A^{\mathrm{T}} A, \bar{y}\right)\right)
\end{aligned}
$$

This gives us the final reverse mode AD :

$$
\begin{align*}
\bar{A} & \left.=-A\left(A^{\mathrm{T}} A\right)^{-1} \bar{y} y^{\mathrm{T}}\right)-A y \bar{y}^{\mathrm{T}}\left(A^{\mathrm{T}} A\right)^{-1}+b y^{\mathrm{T}}\left(A^{\mathrm{T}} A\right)^{-1}  \tag{6}\\
\bar{b} & =A\left(A^{\mathrm{T}} A\right)^{-1} \bar{y} \tag{7}
\end{align*}
$$

[^0]
## A. 2 Approximation bounds

Let us derive some additional bounds which were missing in the main paper:

$$
\begin{align*}
\left\|A y \bar{y}^{\mathrm{T}} M^{-1}-A y_{D} \bar{y}^{T} M_{S}^{-1}\right\|_{F} & \leq\left\|A y \bar{y}^{\mathrm{T}} M^{-1}-A y_{D} \bar{y}^{T} M^{-1}\right\|_{F}+\left\|A y_{D} \bar{y}^{\mathrm{T}}\left(M-M_{S}^{-1}\right)\right\|_{F}  \tag{8}\\
& \leq\left\|U\left(I-\left(U^{\mathrm{T}} S^{\mathrm{T}} S U\right)^{-1}\right) U^{\mathrm{T}} b\right\|_{F}+\epsilon\left\|A y_{D}\right\|\|\bar{y}\|\left\|\Sigma^{-1}\right\|_{2}\left\|\Sigma^{-1}\right\|_{F}  \tag{9}\\
& \lesssim \epsilon\left(\|b\|_{2}+\|b\|_{2}\|\bar{y}\|_{2}\left\|\Sigma^{-1}\right\|_{2}\left\|\Sigma^{-1}\right\|_{F}\right) \tag{10}
\end{align*}
$$

Table 1: Cheat sheet to derive AD.

| Original | Forward Transform | Reverse Transform |
| :---: | :---: | :---: |
| $z=a+b$ | $\dot{z}=\dot{a}+\dot{b}$ | $(\bar{a}, \bar{b})=(\bar{z}, \bar{z})$ |
| $z=a b$ | $\dot{z}=\dot{a} b+a \dot{b}$ | $(\bar{a}, \bar{b})=(\bar{z} b, a \bar{z})$ |
| $\left(z_{1}, z_{2}\right)=(a, a)$ | $\left(\dot{z}_{1}, \dot{z}_{2}\right)=(\dot{a}, \dot{a})$ | $\bar{a}=\bar{z}_{1}+\bar{z}_{2}$ |
| $Y=A X B$ | $\dot{Y}=A \dot{Y} B$ | $\bar{X}=A^{\mathrm{T}} \bar{Y} B^{\mathrm{T}}$ |
| $y=\mathrm{LS}(M, m)$ | $\begin{aligned} \dot{y} & =\mathcal{J} \operatorname{LS}(M, m)(y, \dot{M}, \dot{m}) \\ & =\operatorname{LS}(M, \dot{m}-\dot{M} y) \end{aligned}$ | $\begin{aligned} (\bar{M}, \bar{m}) & =\mathcal{J}^{\mathrm{T}} \operatorname{LS}(M, m)(y, \bar{y}) \\ & =\left(-\bar{m} y^{\mathrm{T}}, \operatorname{LS}\left(M^{\mathrm{T}}, \bar{y}\right)\right) \end{aligned}$ |

Table 2: Forward mode AD Transformations.

| Type | Primal | Forward Transform |
| :---: | :---: | :---: |
| Regular | $y=\operatorname{LLS}(A, b)$ | $\begin{aligned} \dot{y} & =\mathcal{J} \operatorname{LLS}(A, b)(y, \dot{A}, \dot{b}) \\ & =\mathrm{LS}\left(A^{\mathrm{T}} A, \dot{A}^{\mathrm{T}} b+A^{\mathrm{T}} \dot{b}-\left(\dot{A}^{\mathrm{T}} A+A^{\mathrm{T}} \dot{A}\right) y\right) \end{aligned}$ |
| "Diff + Sketch" | $y_{D}=\operatorname{LLS}(A, b, S)$ | $\begin{aligned} \dot{y}_{D} & =\mathcal{J} \operatorname{LLS}(A, b)\left(y_{D}, \dot{A}, \dot{b}, S\right) \\ & =\mathrm{LS}\left(A^{\mathrm{T}} S^{\mathrm{T}} S A, \dot{A}^{\mathrm{T}} b+A^{\mathrm{T}} \dot{b}-\left(\dot{A}^{\mathrm{T}} A+A^{\mathrm{T}} \dot{A}\right) y_{D}\right) \end{aligned}$ |
| "Sketch + Diff" | $y_{S}=\operatorname{LLS}(A, b, S)$ | $\begin{aligned} \dot{y}_{S} & =\mathcal{J} \operatorname{LLS}(A, b)\left(y_{S}, \dot{A}, \dot{b}, S\right) \\ & =\operatorname{LS}\left(A^{\mathrm{T}} S^{\mathrm{T}} S A, \dot{A}^{\mathrm{T}} S^{\mathrm{T}} S b+A^{\mathrm{T}} S^{\mathrm{T}} S \dot{b}\right. \\ & \left.-\left(\dot{A}^{\mathrm{T}} S^{\mathrm{T}} S A+A^{\mathrm{T}} S^{\mathrm{T}} S \dot{A}\right) y_{S}\right) \end{aligned}$ |

Table 3: Reverse mode AD Transformations.

| Type | Primal | Reverse Transform |
| :---: | :---: | :---: |
| Regular | $y=\operatorname{LLS}(A, b)$ | $\begin{aligned} (\bar{A}, \bar{b}) & =\mathcal{J}^{\mathrm{T}} \operatorname{LLS}(A, b)(y, \bar{y}) \\ & =\left(-A^{\dagger \mathrm{T}} \bar{y} y^{\mathrm{T}}-A y \bar{y}^{\mathrm{T}} M^{-1}+b \bar{y}^{\mathrm{T}} M^{-1}, A^{\dagger T} \bar{y}\right) \end{aligned}$ |
| "Diff + Sketch" | $y_{D}=\operatorname{LLS}(A, b, S)$ | $\begin{aligned} (\bar{A}, \bar{b}) & =\mathcal{J}^{\mathrm{T}} \operatorname{LLS}(A, b)(y, \bar{y}) \\ & =\left(-A M_{S}^{-1} \bar{y} y_{D}^{\mathrm{T}}-A y_{D} \bar{y}^{\mathrm{T}} M_{S}^{-1}+b \bar{y}^{\mathrm{T}} M_{S}^{-1}, A^{\dagger T} \bar{y}\right) \end{aligned}$ |
| "Sketch + Diff" | $y_{S}=\operatorname{LLS}_{S}(A, b, S)$ | $\begin{aligned} \left(\bar{A}_{S}, \bar{b}_{S}\right) & =\mathcal{J}^{\mathrm{T}} \operatorname{LLS}_{S}(A, b, S)\left(y_{S}, \bar{y}\right) \\ & =\left(-S^{\mathrm{T}} A_{S}^{\dagger T} \bar{y} y_{S}^{\mathrm{T}}-S^{\mathrm{T}} S A y_{S} \bar{y}^{\mathrm{T}} M_{S}^{-1}+S^{\mathrm{T}} S b \bar{y}^{\mathrm{T}} M_{S}^{-1}, S^{\mathrm{T}} A_{S}^{\dagger T} \bar{y}\right) \end{aligned}$ |

## A. 3 "Sketch and Differentiate"

Lemma 2. The reverse mode approximation error for the term $\bar{b}$ when we approximate it by sketching matrix $S$ can be bounded with probability $1-\delta$ as follows: $\left\|\bar{b}-\bar{b}_{S}\right\|_{2} \leq\left\|\Sigma^{-1}\right\|_{2}\|\bar{y}\|_{2}(\epsilon+(1+$ $\left.\epsilon)\left\|I-S^{\mathrm{T}} S\right\|_{2}\right)$.

Proof. Let us use Lemma 1 and sub-multiplicativity to obtain the following:

$$
\begin{align*}
\left\|\bar{b}-\bar{b}_{S}\right\|_{2} & =\left\|A M^{-\mathrm{T}} \bar{y}-S^{\mathrm{T}} S A M_{S}{ }^{-\mathrm{T}} \bar{y}_{S}\right\|_{2} \\
& =\left\|A M^{-1} \bar{y}-A M_{S}^{-1} \bar{y}+A M_{S}^{-1} \bar{y}-S^{\mathrm{T}} S A M_{S}^{-1} \bar{y}\right\|_{2} \\
& \leq\left\|A M^{-1}-A M_{S}^{-1}\right\|_{2}\|\bar{y}\|_{2}+\left\|I-S^{\mathrm{T}} S\right\|_{2}\left\|A M_{S}^{-1}\right\|_{2}\|\bar{y}\|_{2} \\
& \leq \epsilon\left\|\Sigma^{-1}\right\|_{2}\|\bar{y}\|_{2}+\left\|I-S^{\mathrm{T}} S\right\|_{2}\left\|A M_{S}^{-1}\right\|_{2}\|\bar{y}\|_{2} \\
& \leq\left\|\Sigma^{-1}\right\|_{2}\|\bar{y}\|_{2}\left(\epsilon+(1+\epsilon)\left\|I-S^{\mathrm{T}} S\right\|_{2}\right) \tag{11}
\end{align*}
$$

where we used a lemma from the main paper. So, the error can be large ( $\left\|I-S^{\mathrm{T}} S\right\|_{2}$ ).
Lemma 3. The reverse mode approximation error for the term $\bar{A}$ when we approximate it using the sketching matrix $S$ can be bounded with probability $1-\delta$.

Proof.

$$
\begin{align*}
& \left\|\bar{A}-\bar{A}_{S}\right\|_{F}=\left\|-2 A M^{-\mathrm{T}} \bar{y} y^{\mathrm{T}}+b \bar{y}^{\mathrm{T}} M^{-1}-\left(-2 S^{\mathrm{T}} S A M_{S}{ }^{-\mathrm{T}} \bar{y}_{S} y_{S}{ }^{\mathrm{T}}+S^{\mathrm{T}} S b \bar{y}_{S}{ }^{\mathrm{T}} M_{S}^{-1}\right)\right\|_{F} \\
& \left.\quad \leq\left\|2 A M^{-1} \bar{y} y^{\mathrm{T}}-2 S^{\mathrm{T}} S A M_{S}^{-1} \bar{y} y_{S}^{\mathrm{T}}\right\|_{F}+\| b \bar{y}^{\mathrm{T}} M^{-1}-S^{\mathrm{T}} S b \bar{y}^{\mathrm{T}} M_{S}^{-1}\right) \|_{F} \\
& \left\|A M^{-1} \bar{y} y^{\mathrm{T}}-S^{\mathrm{T}} S A M_{S}^{-1} \bar{y} y_{S}^{\mathrm{T}}\right\|_{F} \leq\left\|A M^{-1} \bar{y} y^{\mathrm{T}}-A M_{S}^{-1} \bar{y} y^{\mathrm{T}}\right\|_{F}+\left\|A M_{S}^{-1} \bar{y} y^{\mathrm{T}}-S^{\mathrm{T}} S A M_{S}^{-1} \bar{y} y_{S}{ }^{\mathrm{T}}\right\|_{F} \\
& \leq \epsilon\left\|\Sigma^{-1}\right\|_{F}\|\bar{y}\|\|y\|+\left\|A M_{S}^{-1} \bar{y} y^{\mathrm{T}}-S^{\mathrm{T}} S A M_{S}^{-1} \bar{y} y_{S}{ }^{\mathrm{T}}\right\|_{F} \tag{13}
\end{align*}
$$

## A. 4 'Differentiate and Sketch"

Lemma 4. The reverse mode approximation error for the term $\bar{b}$ when we sketch only the computationally expensive terms by $S$, with probability at least $1-\delta$, satisfies: $\left\|\bar{b}-\bar{b}_{S}\right\|_{2} \lesssim \epsilon\left\|\Sigma^{-1}\right\|_{2}\|\bar{y}\|_{2}$.

Proof. Let us use the sketching properties and sub-multiplicativity to obtain the following:

$$
\begin{align*}
\left\|\bar{b}-\bar{b}_{S}\right\|_{2} & =\left\|A M^{-\mathrm{T}} \bar{y}-A M_{S}{ }^{-\mathrm{T}} \bar{y}_{S}\right\|_{2} \\
& \approx\left\|U\left(I-U^{\mathrm{T}} S^{\mathrm{T}} S U\right) \Sigma^{-1} V^{\mathrm{T}} \bar{y}\right\|_{2} \quad \bar{y} \approx \bar{y}_{S} \\
& \lesssim \epsilon\|U\|_{2}\left\|\Sigma^{-1}\right\|_{2}\|\bar{y}\|_{2} \\
& \lesssim \epsilon\left\|\Sigma^{-1}\right\|_{2}\|\bar{y}\|_{2} \tag{14}
\end{align*}
$$

Lemma 5. The reverse mode approximation error for the term $\bar{A}$ when we sketch only the computationally expensive terms by $S$, with probability $1-1 / \operatorname{poly}(d)$, satisfies: $\left\|\bar{A}-\bar{A}_{S}\right\|_{2} \lesssim$ $\epsilon\|\bar{y}\|_{2}\left(\left\|\Sigma^{-1}\right\|_{2}\|y\|_{2}+\frac{1}{1-\epsilon}\left\|\Sigma^{-1}\right\|_{2}\|A y-b\|_{2}\left\|A^{\dagger}\right\|_{2}\right)$.

Proof. The approximation error can be split into 3 terms such that $\left\|\bar{A}-\bar{A}_{S}\right\| \leq Q_{1}+Q_{2}+Q_{3}$ where:

$$
\begin{aligned}
Q_{1} & =\left\|b \bar{y}^{\mathrm{T}} M^{-1}-b \bar{y}_{S}{ }^{\mathrm{T}} M_{S^{\prime}}^{-1}\right\|_{F} \\
& \leq \epsilon\left\|b \bar{y}^{\mathrm{T}}\right\|_{F}\left\|\Sigma^{-1}\right\|_{2}\left\|\Sigma^{-1}\right\|_{F}
\end{aligned}
$$

Let us bound $Q_{2}$ as follows:

$$
\begin{align*}
Q_{2}=\left\|A M^{-1} \bar{y} y^{\mathrm{T}}-A M_{S^{\prime}}^{-1} \bar{y} y_{S}{ }^{\mathrm{T}}\right\|_{F} & =\left\|A\left(M^{-1}-M_{S^{\prime}}^{-1}\right) \bar{y} y^{\mathrm{T}}+A M_{S^{\prime}}^{-1} \bar{y} y^{\mathrm{T}}-A M_{S^{\prime}}^{-1} \bar{y} y_{S}{ }^{\mathrm{T}}\right\|_{F} \\
& \leq\left\|A\left(M^{-1}-M_{S^{\prime}}^{-1}\right) \bar{y} y^{\mathrm{T}}\right\|_{F}+\left\|A M_{S^{\prime}}^{-1} \bar{y}\left(y-y_{S}\right)^{\mathrm{T}}\right\|_{F} \\
& \leq \epsilon\left\|\Sigma^{-1}\right\|_{2}\left\|\bar{y} y^{\mathrm{T}}\right\|_{F}+\left\|A M_{S^{\prime}}^{-1}\right\|_{2}\left\|\bar{y}\left(y-y_{S}\right)^{\mathrm{T}}\right\|_{F} \\
& \leq \epsilon\left\|\Sigma^{-1}\right\|_{2}\|\bar{y}\|_{2}\|y\|_{2}+\left\|A M_{S^{\prime}}^{-1}\right\|_{2}\|\bar{y}\|_{2}\left\|\left(y-y_{S}\right)\right\|_{2} \\
& \leq \epsilon\|\bar{y}\|_{2}\left(\left\|\Sigma^{-1}\right\|_{2}\|y\|_{2}+\left\|A M_{S^{\prime}}^{-1}\right\|_{2}\|A y-b\|_{2}\left\|A^{\dagger}\right\|_{2}\right) \\
& \leq \epsilon\|\bar{y}\|_{2}\left(\left\|\Sigma^{-1}\right\|_{2}\|y\|_{2}+(1+\epsilon)\left\|\Sigma^{-1}\right\|_{2}\|A y-b\|_{2}\left\|A^{\dagger}\right\|_{2}\right) \tag{15}
\end{align*}
$$

where we used the following result Price et al. (2017):

$$
\begin{equation*}
\left\|y-y_{S}\right\|_{2} \leq \epsilon\|A y-b\|_{2}\left\|A^{\dagger}\right\|_{2} \tag{16}
\end{equation*}
$$

and the last term $Q_{3}$ can be bounded as:

$$
\begin{align*}
Q_{3}=\left\|A y \bar{y}^{\mathrm{T}} M^{-1}-A y_{S} \bar{y}^{\mathrm{T}} M_{S}^{-1}\right\| & =\left\|A y \bar{y}^{\mathrm{T}}\left(M^{-1}-M_{S}^{-1}\right)+A y \bar{y}^{\mathrm{T}} M_{S}^{-1}-A y_{S} \bar{y}^{\mathrm{T}} M_{S}^{-1}\right\|  \tag{17}\\
& \leq \epsilon\left\|A y \bar{y}^{\mathrm{T}}\right\|+\left\|A\left(y-y_{S}\right) \bar{y}^{\mathrm{T}} M_{S}^{-1}\right\| \\
& \leq \epsilon\left\|A y \bar{y}^{\mathrm{T}}\right\|+\epsilon\|A\|\|A y-b\|\left\|\bar{y}^{\mathrm{T}} M_{S}^{-1}\right\| \tag{18}
\end{align*}
$$

Note that all three terms $Q_{1}, Q_{2}, Q_{3}$ are $O(\epsilon)$.

## B Experiments

We plot the performance of the two proposed approaches for obtaining forward and reverse mode AD in the case of linear regression. We generate a linear regression problem by choosing the entries of matrix $A$ and vector $b$ from i.i.d. $N(0,1)$ (Normal distribution with mean 0 and variance 1 ). The differences from the two approaches, "sketch+differentiate" and "differentiate+sketch" are shown in Figure 1.


Figure 1: Numerical observation that differentiation and sketching do not commute, and that differentiation-then-sketch is more accurate. We show the forward mode along with its approximation corresponding to the three sketching matrices of Gaussian, Count-sketch and Subsampled Randomized Hadamard Transform (SRHT), on a randomly generated least squares problem of size $100000 \times 100$, along with a random perturbation. Reverse mode is shown for a subsample of 100 randomly chosen values for the variable $b$, where we used sign as the cost function.

## References

Eric Price, Zhao Song, and David P. Woodruff. Fast regression with an $l_{\infty}$ guarantee. In $44 t h$ International Colloquium on Automata, Languages, and Programming, ICALP 2017, July 10-14, 2017, Warsaw, Poland, pages 59:1-59:14, 2017. doi: 10.4230/LIPIcs.ICALP.2017.59.


[^0]:    ${ }^{1}$ For a function $f$, we use the notation $\tilde{O}(f)$ to denote $f \cdot \operatorname{polylog}(f)$.

