# Supplementary Material for Implicit Regularization of Random Feature Models 

We organize the Supplementary Material (Supp. Mat.) as follows:

- In Section A, we present the details for the numerical results presented in the main text (and in the Supp. Mat.).
- In Section B, we present additional experiments and some discussions.
- In Section C, we present the proofs of the mathematical results presented in the main text.


## A. Experimental Details

The experimental setting consists of $N$ training and $N_{\text {tst }}$ test datapoints $\left\{\left(x_{i}, y_{i}\right)\right\}_{i=1}^{N+N_{\text {tst }}} \in \mathbb{R}^{d} \times \mathbb{R}$. We sample $P$ Gaussian features $f^{(1)}, \ldots, f^{(P)}$ of $N+N_{\text {tst }}$ dimension with zero mean and covariance matrix entries thereof $C_{i, j}=K\left(x_{i}, x_{j}\right)$ where $K\left(x, x^{\prime}\right)=\exp \left(-\left\|x-x^{\prime}\right\|^{2} / \ell\right)$ is a Radial Basis Function (RBF) Kernel with lengthscale $\ell$. The extended data matrix $\bar{F}=\frac{1}{\sqrt{P}}\left[f^{(1)}, \ldots, f^{(P)}\right]$ of size $\left(N+N_{\text {tst }}\right) \times P$ is decomposed into two matrices: the (training) data matrix $F=\bar{F}_{[: N,:]}$ of size $N \times P$, and a test data matrix $F_{\text {tst }}=\bar{F}_{[N:,:]}$ of size $N_{\text {tst }} \times P$ so that $\bar{F}=\left[F ; F_{\text {tst }}\right]$. For a given ridge $\lambda$, we compute the optimal solution using the data matrix $F$, i.e. $\hat{\theta}=F^{T}\left(F F^{T}+\lambda \mathrm{I}_{N}\right)^{-1} y$ and obtain the predictions on the test datapoints $\hat{y}_{\text {tst }}=F_{\text {tst }} F^{T}\left(F F^{T}+\lambda \mathrm{I}_{N}\right)^{-1} y$.

Using the procedure above, we performed the following experiments:

## A.1. Experiments with Sinusoidal data

We consider a dataset of $N=4$ training datapoints $\left(x_{i}, \sin \left(x_{i}\right)\right) \in[0,2 \pi) \times[-1,1]$ and $N_{\text {tst }}=100$ equally spaced test data points in the interval $[0,2 \pi)$. In this experiment, the lengthscale of the RBF Kernel is $\ell=2$. We compute the average and standard deviation the $\lambda$-RF predictor using 500 samplings of $\bar{F}$ (see Figure 1 in the main text and Figure 1 in the Supp. Mat.).

## A.2. MNIST experiments

We sample $N=100$ and $N_{\text {tst }}=100$ images of digits 7 and 9 from the MNIST dataset (image size $d=24 \times 24$, edge pixels cropped, all pixels rescaled down to $[0,1]$ and recentered around the mean value) and label each of them with +1 and -1 labels, respectively. In this experiment, the lengthscale of the RBF Kernel is $\ell=d \ell_{0}$ where $\ell_{0}=0.2$. We approximate the expected $\lambda$-RF predictor on the test datapoints using the average of $\hat{y}_{\text {tst }}$ over 50 instances of $\bar{F}$ and compute the MSE (see Figures 2, 3 in the main text; in the ridgeless case $-\lambda=10^{-4}$ in our experiments- when $P$ is close to $N$, the average is over 500 instances). In Figure 4 of the main text, using $N_{\text {tst }}=100$ test points, we compare two predictors trained over $N=100$ and $N=1000$ training datapoints.

## A.3. Random Fourier Features

We sample random Fourier Features corresponding to the RBF Kernel with lengthscale $\ell=d \ell_{0}$ where $\ell_{0}=0.2$ (same as above) and consider the same dataset as in the MNIST experiment. The extended data matrix $\bar{F}$ for Fourier features is obtained as follows: we sample $d$-dimensional i.i.d. centered Gaussians $w^{(1)}, \ldots, w^{(P)}$ with standard deviation $\sqrt{2 / \ell}$, sample $b^{(1)}, \ldots, b^{(P)}$ uniformly in $[0,2 \pi)$, and define $\bar{F}_{i, j}=\sqrt{\frac{2}{P}} \cos \left(x_{i}^{T} w^{(j)}+b^{(j)}\right)$. We approximate the expected Fourier Features predictor on the test datapoints using the average of $\hat{y}_{\text {tst }}$ over 50 instances of $\bar{F}$ (see Figure 5).

## B. Additional Experiments

We present the following complementary simulations:

- In Section B.1, we present the distribution of the $\lambda$-RF predictor for the selected $P$ and $\lambda$.
- In Section B.2, we present the evolution of $\tilde{\lambda}$ and its derivative $\partial_{\lambda} \tilde{\lambda}$ for different eigenvalue spectra.
- In Section B.3, we show the evolution of the eigenvalue spectrum of $\mathbb{E}\left[A_{\lambda}\right]$.
- In Section B.4, we present numerical experiments on MNIST using random Fourier features.


## B.1. Distribution of the RF predictor



Figure 1. Distribution of the RF predictor. Red dots represent a sinusoidal dataset $y_{i}=\sin \left(x_{i}\right)$ for $N=4$ points $x_{i}$ in $[0,2 \pi)$. For $P \in\{2,4,10,100\}$ and $\lambda \in\left\{0,10^{-4}, 10^{-1}, 1\right\}$, we sample ten RF predictors (blue dashed lines) and compute empirically the average RF predictor (black lines) with $\pm 2$ standard deviations intervals (shaded regions).

## B.2. Evolution of the Effective Ridge $\tilde{\lambda}$

In Figure 2, we show how the effective ridge $\tilde{\lambda}$ and its derivative $\partial_{\lambda} \tilde{\lambda}$ evolve for the selected eigenvalue spectra with various decays (exponential or polynomial) as a function of $\gamma$ and $\lambda$. In Figure 3, we compare the evolution of $\lambda$ for various $N$.


Figure 2. Evolution of the effective ridge $\tilde{\lambda}$ and its derivative $\partial_{\lambda} \tilde{\lambda}$ for various levels of ridge $\lambda$ (or $\gamma$ ) and for $N=20$. We consider two different decays for $d_{1}, \ldots, d_{N}$ : (i) exponential decay in $i$ (i.e. $d_{i}=e^{-\frac{(i-1)}{2}}$, top plots) and (ii) polynomial decay in $i$ (i.e. $d_{i}=\frac{1}{i}$, bottom plots).


Figure 3. Evolution of effective ridge $\tilde{\lambda}$ as a function of $\gamma$ for two ridges (a) $\lambda=10^{-4}$ and (b) $\lambda=0.5$ and for various $N$. We consider an exponential decay for $d_{1}, \ldots, d_{N}$, i.e. $d_{i}=e^{-\frac{(i-1)}{2}}$.

## B.3. Eigenvalues of $A_{\lambda}$

The (random) prediction $\hat{y}$ on the training data is given by $\hat{y}=A_{\lambda} y$ where $A_{\lambda}=F\left(F^{T} F+\lambda I\right)^{-1} F^{T}$. The average $\lambda$-RF predictor is $\mathbb{E}\left[\hat{f}_{\lambda}^{(R F)}(x)\right]=K(x, X) K(X, X)^{-1} \mathbb{E}\left[A_{\lambda}\right] y$. We denote by $\tilde{d}_{1}, \ldots \tilde{d}_{N}$ the eigenvalues of $\mathbb{E}\left[A_{\lambda}\right]$. By Proposition C.7, the $\tilde{d}_{i}$ 's converge to the eigenvalues $\frac{d_{1}}{d_{1}+\tilde{\lambda}}, \ldots, \frac{d_{N}}{d_{N}+\tilde{\lambda}}$ of $K\left(K+\tilde{\lambda} I_{N}\right)^{-1}$ as $P$ goes to infinity. We illustrate the evolution of $\tilde{d}_{i}$ and their convergence to $\frac{d_{i}}{d_{i}+\tilde{\lambda}}$ for two different eigenvalue spectrums $d_{1}, \ldots d_{N}$.


Figure 4. Eigenvalues $\tilde{d}_{1}, \ldots \tilde{d}_{N}$ (red dots) vs. eigenvalues $\frac{d_{1}}{d_{1}+\tilde{\lambda}}, \ldots, \frac{d_{N}}{d_{N}+\tilde{\lambda}}$ (blue dots) for $N=10$. We consider various values of $P$ and two different decays for $d_{1}, \ldots, d_{N}$ : (i) exponential decay in $i$, i.e. $d_{i}=e^{-\frac{(i-1)}{2}}$ (right plots) and (ii) polynomial decay in $i$, i.e. $d_{i}=\frac{1}{i}$ (left plots).

## B.4. Average Fourier Features Predictor

The Fourier Features predictor $\lambda$-FF is $\hat{f}^{(F F)}(x)=\frac{1}{\sqrt{P}} \sum_{j=1}^{P} \hat{\theta}_{j} \phi^{(j)}(x)$ where $\phi^{(j)}(x)=\cos \left(x^{T} w^{(j)}+b^{(j)}\right)$ and $\hat{\theta}=F^{T}\left(F F^{T}+\lambda \mathrm{I}_{N}\right)^{-1} y$ with the data matrix $F$ as described in Section A.3.
We investigate how close the average $\lambda$-FF predictor is to the $\tilde{\lambda}$-KRR predictor and we observe the following:

1. The difference of the test errors of the two predictors decreases as $\gamma$ increases.
2. In the overparameterized regime, i.e. $P \geq N$, the test error of the $\tilde{\lambda}$-KRR predictor matches with the test error of the $\lambda$-FF predictor.
3. For $N=1000$, strong agreement between the two test errors is observed already for $\gamma>0.1$. We also observe that Gaussian features achieve lower (or equal) test error than the Fourier features for all $\gamma$ in our experiments.


Figure 5. Comparision of the test errors of the average $\lambda$-FF predictor and the $\tilde{\lambda}$-KRR predictor. In (a) and (c), the test errors of the average $\lambda$-FF predictor and of the $\tilde{\lambda}$-KRR predictor are reported for various ridge for $N=100$ and $N=1000$ MNIST data points (top and bottom rows). In (b) and (d), the average test error of the $\lambda$-FF predictor and the test error of its average are reported.

## C. Proofs

## C.1. Gaussian Random Features

Proposition C.1. Let $\hat{f}_{\lambda}^{(R F)}$ be the $\lambda-R F$ predictor and let $\hat{y}=F \hat{\theta}$ be the prediction vector on training data, i.e. $\hat{y}_{i}=$ $\hat{f}_{\lambda}^{(R F)}\left(x_{i}\right)$. The process $\hat{f}_{\lambda}^{(R F)}$ is a mixture of Gaussians: conditioned on $F$, we have that $\hat{f}_{\lambda}^{(R F)}$ is a Gaussian process. The mean and covariance of $\hat{f}_{\lambda}^{(R F)}$ conditioned on $F$ are given by

$$
\begin{align*}
& \mathbb{E}\left[\hat{f}_{\lambda}^{(R F)}(x) \mid F\right]=K(x, X) K(X, X)^{-1} \hat{y}  \tag{1}\\
& \operatorname{Cov}\left[\hat{f}_{\lambda}^{(R F)}(x), \hat{f}_{\lambda}^{(R F)}\left(x^{\prime}\right) \mid F\right]=\frac{\|\hat{\theta}\|^{2}}{P} \tilde{K}\left(x, x^{\prime}\right) \tag{2}
\end{align*}
$$

where $\tilde{K}\left(x, x^{\prime}\right)=K\left(x, x^{\prime}\right)-K(x, X) K(X, X)^{-1} K\left(X, x^{\prime}\right)$ denotes the posterior covariance kernel.
Proof. Let $F=\left(\frac{1}{\sqrt{P}} f^{(j)}\left(x_{i}\right)\right)_{i, j}$ be the $N \times P$ matrix of values of the random features on the training set. By definition, $\hat{f}_{\lambda}^{(R F)}=\frac{1}{\sqrt{P}} \sum_{p=1}^{P} \hat{\theta}_{p} f^{(p)}$. Conditioned on the matrix $F$, the optimal parameters $\left(\hat{\theta}_{p}\right)_{p}$ are not random and $\left(f^{(p)}\right)_{p}$ is still Gaussian, hence, conditioned on the matrix $F$, the process $\hat{f}_{\lambda}^{(R F)}$ is a mixture of Gaussians. Moreover, conditioned on the matrix $F$, for any $p, p^{\prime}, f^{(p)}$ and $f^{\left(p^{\prime}\right)}$ remain independent, hence

$$
\begin{aligned}
\mathbb{E}\left[\hat{f}_{\lambda}^{(R F)}(x) \mid F\right] & =\frac{1}{\sqrt{P}} \sum_{p=1}^{P} \hat{\theta}_{p} \mathbb{E}\left[f^{(p)}(x) \mid f_{N}^{(p)}\right] \\
\operatorname{Cov}\left[\hat{f}_{\lambda}^{(R F)}(x), \hat{f}_{\lambda}^{(R F)}\left(x^{\prime}\right) \mid F\right] & =\frac{1}{P} \sum_{p=1}^{P} \hat{\theta}_{p}^{2} \operatorname{Cov}\left[f^{(p)}(x), f^{(p)}\left(x^{\prime}\right) \mid f_{N}^{(p)}\right]
\end{aligned}
$$

where we have set $f_{N}^{(p)}=\left(f^{(p)}\left(x_{i}\right)\right)_{i} \in \mathbb{R}^{N}$. The value of $\mathbb{E}\left[f^{(p)}(x) \mid f_{N}^{(p)}\right]$ and $\operatorname{Cov}\left[f^{(p)}(x), f^{(p)}\left(x^{\prime}\right) \mid f_{N}^{(p)}\right]$ are obtained from classical results on Gaussian conditional distributions (Eaton, 2007):

$$
\begin{aligned}
\mathbb{E}\left[f^{(p)}(x) \mid f_{N}^{(p)}\right] & =K(x, X) K(X, X)^{-1} f_{N}^{(p)}, \\
\operatorname{Cov}\left[f^{(p)}(x), f^{(p)}\left(x^{\prime}\right) \mid f_{N}^{(p)}\right] & =\tilde{K}\left(x, x^{\prime}\right),
\end{aligned}
$$

where $\tilde{K}\left(x, x^{\prime}\right)=K\left(x, x^{\prime}\right)-K(x, X) K(X, X)^{-1} K\left(X, x^{\prime}\right)$. Thus, conditioned on $F$, the predictor $\hat{f}_{\lambda}^{(R F)}$ has expectation:

$$
\mathbb{E}\left[\hat{f}_{\lambda}^{(R F)}(x) \mid F\right]=K(x, X) K(X, X)^{-1} \frac{1}{\sqrt{P}} \sum_{p=1}^{P} \hat{\theta}_{p} f_{N}^{(p)}=K(x, X) K(X, X)^{-1} \hat{y}
$$

and covariance:

$$
\operatorname{Cov}\left[\hat{f}_{\lambda}^{(R F)}(x), \hat{f}_{\lambda}^{(R F)}\left(x^{\prime}\right) \mid F\right]=\frac{1}{P} \sum_{p=1}^{P} \hat{\theta}_{p}^{2} \tilde{K}\left(x, x^{\prime}\right)=\frac{\|\hat{\theta}\|^{2}}{P} \tilde{K}\left(x, x^{\prime}\right)
$$

## C.2. Generalized Wishart Matrix

Setup. In this section, we consider a fixed deterministic matrix $K$ of size $N \times N$ which is diagonal positive semi-definite, with eigenvalues $d_{1}, \ldots, d_{N}$. We also consider a $P \times N$ random matrix $W$ with i.i.d. standard Gaussian entries.
The key object of study is the $P \times P$ generalized Wishart random matrix $F^{T} F=\frac{1}{P} W K W^{T}$ and in particular its Stieltjes transform defined on $z \in \mathbb{C} \backslash \mathbb{R}^{+}$, where $\mathbb{R}^{+}=[0,+\infty[$ :

$$
m_{P}(z)=\frac{1}{P} \operatorname{Tr}\left[\left(F^{T} F-z \mathrm{I}_{P}\right)^{-1}\right]=\frac{1}{P} \operatorname{Tr}\left[\left(\frac{1}{P} W K W^{T}-z \mathrm{I}_{P}\right)^{-1}\right]
$$

where $K$ is a fixed positive semi-definite matrix.
Since $F^{T} F$ has positive real eigenvalues $\lambda_{1}, \ldots, \lambda_{P} \in \mathbb{R}_{+}$, and

$$
m_{P}(z)=\frac{1}{P} \sum_{p=1}^{P} \frac{1}{\lambda_{p}-z}
$$

we have that for any $z \in \mathbb{C} \backslash \mathbb{R}^{+}$,

$$
\left|m_{P}(z)\right| \leq \frac{1}{d\left(z, \mathbb{R}_{+}\right)}
$$

where $d\left(z, \mathbb{R}_{+}\right)=\inf \left\{|z-y|, y \in \mathbb{R}^{+}\right\}$is the distance of $z$ to the positive real line. More precisely, $m_{P}(z)$ lies in the convex hull $\Omega_{z}=\operatorname{Conv}\left(\left\{\frac{1}{d-z}: d \in \mathbb{R}_{+}\right\}\right)$. As a consequence, the argument $\arg \left(m_{P}(z)\right) \in(-\pi, \pi)$ lies between 0 and $\arg \left(-\frac{1}{z}\right)$, i.e. $m_{P}(z)$ lies in the cone spanned by 1 and $-\frac{1}{z}$.
Our first lemma implies that the Stieljes transform concentrates around its mean as $N$ and $P$ go to infinity with $\gamma=\frac{P}{N}$ fixed.
Lemma C.2. For any integer $m \in \mathbb{N}$ and any $z \in \mathbb{C} \backslash \mathbb{R}^{+}$, we have

$$
\mathbb{E}\left[\left|m_{P}(z)-\mathbb{E}\left[m_{P}(z)\right]\right|^{m}\right] \leq \mathbf{c} P^{-\frac{m}{2}}
$$

where $\mathbf{c}$ depends on $z, \gamma$, and $m$ only.

Proof. The proof follows Step 1 of (Bai \& Wang, 2008). Let $w_{1}, \ldots, w_{N}$ be the columns of $W$ from left to right. Let us introduce the $P \times P$ matrices $B(z)=\frac{1}{P} W K W^{T}-z \mathrm{I}_{P}$ and $B_{(i)}(z)=\frac{1}{P} W_{(i)} K_{(i)} W_{(i)}^{T}-z \mathrm{I}_{P}$ where $W_{(i)}$ is the $P \times(N-1)$ submatrix of $W$ obtained by removing its $i$-th column $w_{i}$, and $K_{(i)}$ is the $(N-1) \times(N-1)$ submatrix of $K$ obtained by removing both its $i$-th column and $i$-th row. Since the eigenvalues of $W K W^{T}$ and $W_{(i)} K_{(i)} W_{(i)}^{T}$ are all real and positive, $B(z)$ and $B_{(i)}(z)$ are invertible matrices for $z \notin \mathbb{R}^{+}$.
Noticing that

$$
B(z)=\frac{1}{P} W K W^{T}-z \mathrm{I}_{P}=\frac{1}{P} W_{(i)} K_{(i)} W_{(i)}^{T}-z \mathrm{I}_{P}+\frac{d_{i}}{P} w_{i} w_{i}^{T}
$$

is a rank one perturbation of the matrix $B_{(i)}(z)$, by the Sherman-Morrison's formula, the inverse of $B(z)$ is given by:

$$
B(z)^{-1}=\left(B_{(i)}(z)\right)^{-1}-\frac{d_{i}}{P} \frac{1}{1+\frac{d_{i}}{P} w_{i}^{T}\left(B_{(i)}(z)\right)^{-1} w_{i}}\left(B_{(i)}(z)\right)^{-1} w_{i} w_{i}^{T}\left(B_{(i)}(z)\right)^{-1}
$$

We denote $\mathbb{E}_{i}$ the conditional expectation given $w_{i+1}, \ldots, w_{N}$. We have $\mathbb{E}_{0}\left[m_{P}(z)\right]=m_{P}(z)$ and $\mathbb{E}_{N}\left[m_{P}(z)\right]=\mathbb{E}\left[m_{P}(z)\right]$. As a consequence, we get:

$$
\begin{aligned}
m_{P}(z)-\mathbb{E}\left[m_{P}(z)\right] & =\sum_{i=1}^{N}\left(\mathbb{E}_{i-1}\left[m_{P}(z)\right]-\mathbb{E}_{i}\left[m_{P}(z)\right]\right) \\
& =\frac{1}{P} \sum_{i=1}^{N}\left(\mathbb{E}_{i-1}-\mathbb{E}_{i}\right)\left[\operatorname{Tr}\left(B(z)^{-1}\right)\right] \\
& =\frac{1}{P} \sum_{i=1}^{N}\left(\mathbb{E}_{i-1}-\mathbb{E}_{i}\right)\left[\operatorname{Tr}\left(B(z)^{-1}\right)-\operatorname{Tr}\left(B_{(i)}(z)^{-1}\right)\right]
\end{aligned}
$$

The last equality comes from the fact that $\operatorname{Tr}\left(B_{(i)}(z)^{-1}\right)$ does not depend on $w_{i}$, hence

$$
\mathbb{E}_{i-1}\left[\operatorname{Tr}\left(B_{(i)}(z)^{-1}\right)\right]=\mathbb{E}_{i}\left[\operatorname{Tr}\left(B_{(i)}(z)^{-1}\right)\right]
$$

Let $g_{i}: \mathbb{C} \backslash \mathbb{R}^{+} \rightarrow \mathbb{C}$ be the holomorphic function given by $g_{i}(z):=\frac{1}{P} w_{i}^{T}\left(B_{(i)}(z)\right)^{-1} w_{i}$. Its derivative is given by $g_{i}^{\prime}(z)=\frac{1}{P} w_{i}^{T}\left(B_{(i)}(z)\right)^{-2} w_{i}$. Hence

$$
\begin{aligned}
\operatorname{Tr}\left(B(z)^{-1}\right)-\operatorname{Tr}\left(B_{(i)}(z)^{-1}\right) & =-\frac{\frac{d_{i}}{P} \operatorname{Tr}\left(\left(B_{(i)}(z)\right)^{-1} w_{i} w_{i}^{T}\left(B_{(i)}(z)\right)^{-1}\right)}{1+d_{i} g_{i}(z)} \\
& =-\frac{d_{i} g_{i}^{\prime}(z)}{1+d_{i} g_{i}(z)}
\end{aligned}
$$

where we used the cyclic property of the trace. We can now bound this difference:

$$
\begin{aligned}
\left|\operatorname{Tr}\left(B(z)^{-1}\right)-\operatorname{Tr}\left(B_{(i)}(z)^{-1}\right)\right| & =\left|\frac{d_{i} g_{i}^{\prime}(z)}{1+d_{i} g_{i}(z)}\right| \\
& \leq\left|\frac{w_{i}^{T}\left(B_{(i)}(z)\right)^{-2} w_{i}}{w_{i}^{T}\left(B_{(i)}(z)\right)^{-1} w_{i}}\right| \\
& \leq \max _{w}\left|\frac{w^{T}\left(B_{(i)}(z)\right)^{-2} w}{w^{T}\left(B_{(i)}(z)\right)^{-1} w}\right| \\
& \leq\left\|\left(B_{(i)}(z)\right)^{-1}\right\|_{o p}=\max _{j}\left|\frac{1}{\nu_{j}-z}\right| \leq \frac{1}{d\left(z, \mathbb{R}^{+}\right)},
\end{aligned}
$$

where $\nu_{j}$ are the eigenvalues of $\frac{1}{P} W_{(i)} K_{(i)} W_{(i)}^{T}$.
The sequence

$$
\left(\left(\mathbb{E}_{N-i}-\mathbb{E}_{N-i+1}\right)\left[\operatorname{Tr}\left(B(z)^{-1}\right)-\operatorname{Tr}\left(B_{(N-i+1)}(z)^{-1}\right)\right]\right)_{i=1, \ldots, N}
$$

is a martingale difference sequence. Hence, by Burkholder's inequality, there exists a positive constant $K_{m}$ such that

$$
\begin{aligned}
\mathbb{E}\left[\left|m_{P}(z)-\mathbb{E}\left[m_{P}(z)\right]\right|^{m}\right] & \leq K_{m} \frac{1}{P^{m}} \mathbb{E}\left[\left(\sum_{i=1}^{N}\left|\left[\mathbb{E}_{i-1}-\mathbb{E}_{i}\right]\left(\operatorname{Tr}\left(B(z)^{-1}\right)-\operatorname{Tr}\left(B_{(i)}(z)^{-1}\right)\right)\right|^{2}\right)^{\frac{m}{2}}\right] \\
& \leq K_{m} \frac{1}{P^{m}}\left(N\left(\frac{2}{d\left(z, \mathbb{R}_{+}\right)}\right)^{2}\right)^{\frac{m}{2}} \\
& \leq K_{m} \gamma^{-\frac{m}{2}}\left(\frac{2}{d\left(z, \mathbb{R}_{+}\right)}\right)^{m} P^{-\frac{m}{2}}
\end{aligned}
$$

hence the desired result with $\mathbf{c}=K_{m} \gamma^{-\frac{m}{2}}\left(\frac{2}{d\left(z, \mathbb{R}_{+}\right)}\right)^{m}$.

The following lemma, which is reminiscent of Lemma 4.5 in (Au et al., 2018), is a consequence of Wick's formula for Gaussian random variables and is key to prove Lemma C.4.

Lemma C.3. If $A^{(1)}, \ldots, A^{(k)}$ are $k$ square random matrices of size $P$ independent from a standard Gaussian vector $w$ of size $P$,

$$
\begin{equation*}
\mathbb{E}\left[w^{T} A^{(1)} w w^{T} A^{(2)} w \ldots w^{T} A^{(k)} w\right]=\sum_{\substack{p \in \boldsymbol{P}_{2}(2 k)}} \sum_{\substack{i_{1}, \ldots, i_{2 k} \in\{1, \ldots, P\} \\ p \leq \operatorname{Ker}\left(i_{1}, \ldots, i_{2 k}\right)}} \mathbb{E}\left[A_{i_{1} i_{2}}^{(1)} \ldots A_{i_{2 k-1} i_{2 k}}^{(k)}\right] \tag{3}
\end{equation*}
$$

where $\boldsymbol{P}_{2}(2 k)$ is the set of pair partitions of $\{1, \ldots, 2 k\}, \leq$ is the coarser (i.e. $p \leq q$ if $q$ is coarser than $p$ ), and for any $i_{1}, \ldots, i_{2 k}$ in $\{1, \ldots, P\}, \operatorname{Ker}\left(i_{1}, \ldots, i_{2 k}\right)$ is the partition of $\{1, \ldots, 2 k\}$ such that two elements $u$ and $v$ in $\{1, \ldots, 2 k\}$ are in the same block (i.e. pair) of $\operatorname{Ker}\left(i_{1}, \ldots, i_{2 k}\right)$ if and only if $i_{u}=i_{v}$.

## Furthermore,

$$
\begin{align*}
& \mathbb{E}\left[\left(w^{T} A^{(1)} w-\operatorname{Tr}\left(A^{(1)}\right)\right)\left(w^{T} A^{(2)} w-\operatorname{Tr}\left(A^{(2)}\right)\right) \ldots\left(w^{T} A^{(k)} w-\operatorname{Tr}\left(A^{(k)}\right)\right)\right] \\
&=\sum_{p \in: P_{2}(2 k): i_{1}, \ldots, i_{2 k} \in\{1, \ldots, P\}}^{p \leq \operatorname{Ker}\left(i_{1}, \ldots, i_{2 k}\right)}<
\end{align*} \sum_{\substack{  \tag{4}\\
}}\left[A_{i_{1} i_{2}}^{(1)} \ldots A_{i_{2 k-1} i_{2 k}}^{(k)}\right],
$$

where : $\boldsymbol{P}_{2}(2 k)$ : is the subset of partitions $p$ in $\boldsymbol{P}_{2}(2 k)$ for which $\{2 j-1,2 j\}$ is not a block of $p$ for any $j \in\{1, \ldots, k\}$.

Proof. Expanding the left-hand side of Equation (3), we obtain:

$$
\mathbb{E}\left[\sum_{i_{1}, \ldots, i_{2 k} \in\{1, \ldots, P\}} w_{i_{1}} A_{i_{1} i_{2}}^{(1)} w_{i_{2}} w_{i_{3}} A_{i_{3} i_{4}}^{(2)} w_{i_{4}} \ldots w_{i_{2 k-1}} A_{i_{2 k-1} i_{2 k}}^{(k)} w_{i_{2 k}}\right]
$$

Using Wick's formula, we get:

$$
\sum_{i_{1}, \ldots, i_{2 k} \in\{1, \ldots, P\}} \sum_{\substack{p \in P_{2}(2 k), p \leq \operatorname{Ker}\left(i_{1}, \ldots, i_{2 k}\right)}} \mathbb{E}\left[A_{i_{1} i_{2}}^{(1)} A_{i_{3} i_{4}}^{(2)} \ldots A_{i_{2 k-1} i_{2 k}}^{(k)}\right],
$$

hence, interchanging the order of summation, we recover the left-hand side of Equation (3):

$$
\sum_{p \in P_{2}(2 k)} \sum_{\substack{i_{1}, \ldots, i_{2 k} \in\{1, \ldots, P\} \\ p \leq \operatorname{Ker}\left(i_{1}, \ldots, i_{2 k}\right)}} \mathbb{E}\left[A_{i_{1} i_{2}}^{(1)} \ldots A_{i_{2 k-1} i_{2 k}}^{(k)}\right]
$$

We now prove Equation (4). Expanding the product, the left-hand side is equal to:

$$
\sum_{I \subset\{1, \ldots, k\}}(-1)^{k-\# I} \mathbb{E}\left[\prod_{i \in I} w^{T} A^{(i)} w \prod_{i \notin I} \operatorname{Tr}\left(A^{(i)}\right)\right]
$$

Expanding the product and the trace, and using Wick's equation, we obtain: a

$$
\sum_{I \subset\{1, \ldots, k\}}(-1)^{k-\# I} \sum_{i_{1}, \ldots, i_{2 k} \in\{1, \ldots, P\}} \sum_{\substack{p \in \boldsymbol{P}_{2}(2 k), p \leq p_{I} \\ p \leq \operatorname{Ker}\left(i_{1}, \ldots, i_{2 k}\right)}} \mathbb{E}\left[A_{i_{1} i_{2}}^{(1)} \ldots A_{i_{2 k-1} i_{2 k}}^{(k)}\right]
$$

where $p_{I}$ is the partition composed of blocks of size 2 given by $\{2 l, 2 l+1\}$ with $l \notin I$ and the rest of the indices contained in a single block. Interchanging the order of summation, we get:

$$
\sum_{i_{1}, \ldots, i_{2 k} \in\{1, \ldots, P\}} \sum_{\substack{p \in P_{2}(2 k), p \leq \operatorname{Ker}\left(i_{1}, \ldots, i_{2 k}\right)}} \mathbb{E}\left[A_{i_{1} i_{2}}^{(1)} \ldots A_{i_{2 k-1} i_{2 k}}^{(k)}\right]\left[\sum_{\substack{I \subset\{1, \ldots, k\}, p \leq p_{I}}}(-1)^{k-\# I}\right] .
$$

Since $\left[\sum_{I \subset\{1, \ldots, k\} p \leq p_{I}}(-1)^{\# I}\right]=\delta_{\left\{I \subset[k], p \leq p_{I}\right\}=\{\{1, \ldots, k\}\}}$ and $\left\{I \subset[k], p \leq p_{I}\right\}=\{\{1, \ldots, k\}\}$ if and only if $p \in \boldsymbol{P}_{2}(2 k)$, interchanging a last time the order of summation, we recover the left-hand side of Equation (4):

$$
\sum_{p \in: \boldsymbol{P}_{2}(2 k): i_{1}, \ldots, i_{2 k} \in\{1, \ldots, P\}}^{p \leq \operatorname{Ker}\left(i_{1}, \ldots, i_{2 k}\right)} \mid ~ \mathbb{E}\left[A_{i_{1} i_{2}}^{(1)} \ldots A_{i_{2 k-1} i_{2 k}}^{(k)}\right]
$$

For any $z \in \mathbb{C} \backslash \mathbb{R}^{+}$, we define the holomorphic function $g_{i}: \mathbb{C} \backslash \mathbb{R}^{+} \rightarrow \mathbb{C}$ by

$$
g_{i}(z)=\frac{1}{P} w_{i}^{T}\left(\frac{1}{P} W_{(i)} K_{(i)} W_{(i)}^{T}-z I_{P}\right)^{-1} w_{i}
$$

where $W_{(i)}$ is the $P \times(N-1)$ submatrix of $W$ obtained by removing its $i$-th column $w_{i}$, and $K_{(i)}$ is the $(N-1) \times(N-1)$ submatrix of $K$ obtained by removing both its $i$-th column and $i$-th row. In the following lemma, we bound the distance of $g_{i}(z)$ to its mean. Then we prove that $\mathbb{E}\left[g_{i}(z)\right]$ is close to the expected Stieljes transform of $K$.
Lemma C.4. The random function $g_{i}(z)$ satisfies:

$$
\begin{aligned}
\left|\mathbb{E}\left[g_{i}(z)\right]-\mathbb{E}\left[m_{P}(z)\right]\right| & \leq \frac{\mathbf{c}_{\mathbf{0}}}{P}, \\
\operatorname{Var}\left(g_{i}(z)\right) & \leq \frac{\mathbf{c}_{\mathbf{1}}}{P}, \\
\mathbb{E}\left[\left(g_{i}(z)-\mathbb{E}\left[g_{i}(z)\right]\right)^{4}\right] & \leq \frac{\mathbf{c}_{\mathbf{2}}}{P^{2}}, \\
\mathbb{E}\left[\left(g_{i}(z)-\mathbb{E}\left[g_{i}(z)\right]\right)^{8}\right] & \leq \frac{\mathbf{c}_{3}}{P^{4}},
\end{aligned}
$$

where $\mathbf{c}_{\mathbf{0}}, \mathbf{c}_{\mathbf{1}}, \mathbf{c}_{\mathbf{2}}$, and $\mathbf{c}_{\mathbf{3}}$ depend on $\gamma$ and $z$ only.
Proof. The random variable $w_{i}$ is independent from $B_{(i)}(z)=\frac{1}{P} W_{(i)} K_{(i)} W_{(i)}^{T}-z \mathrm{I}_{P}$ since the $i$-th column of $W$ does not appear in the definition of $B_{(i)}(z)$. Using Lemma C.3, since there exists a unique pair partition $p \in \boldsymbol{P}_{2}(2)$, namely $\{\{1,2\}\}$, the expectation of $g_{i}(z)$ is given by

$$
\mathbb{E}\left[g_{i}(z)\right]=\frac{1}{P} \mathbb{E}\left[\operatorname{Tr}\left[B_{(i)}(z)^{-1}\right]\right]
$$

Recall that $\mathbb{E}\left[m_{P}(z)\right]=\frac{1}{P} \mathbb{E}\left[\operatorname{Tr}\left[B(z)^{-1}\right]\right]$ and $\left|\operatorname{Tr}\left(B(z)^{-1}\right)-\operatorname{Tr}\left(B_{(i)}(z)^{-1}\right)\right| \leq \frac{1}{d\left(z, \mathbb{R}_{+}\right)}$(from the proof of Lemma C.2). Hence

$$
\left|\mathbb{E}\left[g_{i}(z)\right]-\mathbb{E}\left[m_{P}(z)\right]\right| \leq \frac{1}{P} \mathbb{E}\left[\left|\operatorname{Tr}\left(B(z)^{-1}\right)-\operatorname{Tr}\left(B_{(i)}(z)^{-1}\right)\right|\right] \leq \frac{1}{P} \frac{1}{d\left(z, \mathbb{R}_{+}\right)}
$$

which proves the first assertion with $\mathbf{c}_{\mathbf{0}}=\frac{1}{d\left(z, \mathbb{R}_{+}\right)}$.
Now, let us consider the variance of $g_{i}(z)$. Using our previous computation of $\mathbb{E}\left[g_{i}(z)\right]$, we have

$$
\operatorname{Var}\left(g_{i}(z)\right)=\mathbb{E}\left[w_{i}^{T} \frac{\left(B_{(i)}(z)\right)^{-1}}{P} w_{i} w_{i}^{T} \frac{\left(B_{(i)}(z)\right)^{-1}}{P} w_{i}\right]-\mathbb{E}\left[\frac{1}{P} \operatorname{Tr}\left[B_{(i)}(z)^{-1}\right]\right]^{2}
$$

The first term can be computed using the first assertion of Lemma C.3: there are 2 matrices involved, thus we have to sum over 3 pair partitions. A simplification arises since $\frac{\left(B_{(i)}(z)\right)^{-1}}{P}$ is symmetric: the partition $\{\{1,2\},\{3,4\}\}$ yields $\mathbb{E}\left[\left(\operatorname{Tr}\left[\frac{\left(B_{(i)}(z)\right)^{-1}}{P}\right]\right)^{2}\right]$ whereas both $\{\{1,3\},\{2,4\}\}$ and $\{\{1,4\},\{2,4\}\}$ yield $\mathbb{E}\left(\operatorname{Tr}\left[\frac{\left(B_{(i)}(z)\right)^{-2}}{P^{2}}\right]\right)$.
Thus, the variance of $g_{i}(z)$ is given by:

$$
\operatorname{Var}\left(g_{i}(z)\right)=2 \mathbb{E}\left(\operatorname{Tr}\left[\frac{\left(B_{(i)}(z)\right)^{-2}}{P^{2}}\right]\right)+\mathbb{E}\left[\left(\frac{1}{P} \operatorname{Tr}\left[\left(B_{(i)}(z)\right)^{-1}\right]\right)^{2}\right]-\mathbb{E}\left[\frac{1}{P} \operatorname{Tr}\left[\left(B_{(i)}(z)\right)^{-1}\right]\right]^{2}
$$

hence is given by a sum of two terms:

$$
\operatorname{Var}\left(g_{i}(z)\right)=\frac{2}{P} \mathbb{E}\left(\frac{1}{P} \operatorname{Tr}\left[\left(B_{(i)}(z)\right)^{-2}\right]\right)+\operatorname{Var}\left(\frac{1}{P} \operatorname{Tr}\left[\left(B_{(i)}(z)\right)^{-1}\right]\right)
$$

Using the same arguments as those explained for the bound on the Stieltjes transform, the first term is bounded by $\frac{2}{\operatorname{Pd}\left(z, \mathbb{R}_{+}\right)^{2}}$. In order to bound the second term, we apply Lemma C. 2 for $W_{(i)}$ and $K_{(i)}$ in place of $W$ and $K$. The second term is bounded by $\frac{\mathbf{c}}{P}$, hence the bound $\operatorname{Var}\left(g_{i}(z)\right) \leq \frac{\mathbf{c}_{1}}{P}$.

Finally, we prove the bound on the fourth moment of $g_{i}(z)-\mathbb{E}\left[g_{i}(z)\right]$. We denote $m_{(i)}(z)=\frac{1}{P} \operatorname{Tr}\left[\left(B_{(i)}(z)\right)^{-1}\right]$. Recall that $\mathbb{E}\left[g_{i}(z)\right]=\mathbb{E}\left[m_{(i)}(z)\right]$. Using the convexity of $t \mapsto t^{4}$, we have

$$
\begin{aligned}
\mathbb{E}\left[\left(g_{i}(z)-\mathbb{E}\left[g_{i}(z)\right]\right)^{4}\right] & =\mathbb{E}\left[\left(g_{i}(z)-m_{(i)}(z)+m_{(i)}(z)-\mathbb{E}\left[m_{(i)}(z)\right]\right)^{4}\right] \\
& \leq 8 \mathbb{E}\left[\left(g_{i}(z)-m_{(i)}(z)\right)^{4}\right]+8 \mathbb{E}\left[\left(m_{(i)}(z)-\mathbb{E}\left[m_{(i)}(z)\right]\right)^{4}\right] .
\end{aligned}
$$

We bound the second term using the concentration of the Stieljes transform (Lemma C.2): it is bounded by $\frac{8 \mathrm{Cc}}{P^{2}}$. The first term is bounded using the second assertion of Lemma C.3. Using the symmetry of $B_{(i)}(z)$, the partitions in : $\boldsymbol{P}_{2}(4)$ : yield two different terms, namely:

1. $\frac{1}{P^{2}} \mathbb{E}\left[\left(\frac{1}{P} \operatorname{Tr}\left[\left(B_{(i)}(z)\right)^{-2}\right]\right)^{2}\right]$, for example if $p=\{\{1,3\},\{2,4\},\{5,7\},\{6,8\}\}$
2. $\frac{1}{P^{3}} \mathbb{E}\left[\frac{1}{P} \operatorname{Tr}\left[\left(B_{(i)}(z)\right)^{-4}\right]\right]$, for example if $p=\{\{2,3\},\{4,5\},\{6,7\},\{8,1\}\}$.

We bound the two terms using the same arguments as those explained for the bound on the Stieljes transform at the beginning of the section. The first term is bounded by $\frac{d\left(z, \mathbb{R}^{+}\right)^{-4}}{P^{2}}$ and the second term by $\frac{d\left(z, \mathbb{R}^{+}\right)^{-4}}{P^{3}}$ hence the bound $\mathbb{E}\left[\left(g_{i}(z)-\mathbb{E}\left[g_{i}(z)\right]\right)^{4}\right] \leq \frac{\mathbf{c}_{2}}{P^{2}}$.
The bound $\mathbb{E}\left[\left(g_{i}(z)-\mathbb{E}\left[g_{i}(z)\right]\right)^{8}\right] \leq \frac{\mathrm{c}_{3}}{P^{4}}$ is obtained in a similar way, using the second assertion of Lemma C. 3 and simple bounds on the Stieljes transform.

In the next proposition we show that the Stieltjes transform $m_{P}(z)$ is close in expectation to the solution of a fixed point equation.
Proposition C.5. For any $z \in \mathbb{H}_{<0}=\{z: \operatorname{Re}(z)<0\}$,

$$
\left|\mathbb{E}\left[m_{P}(z)\right]-\tilde{m}(z)\right| \leq \frac{\mathbf{e}}{P}
$$

where $\mathbf{e}$ depends on $z, \gamma$, and $\frac{1}{N} \operatorname{Tr}(K)$ only and where $\tilde{m}(z)$ is the unique solution in the cone $\mathcal{C}_{z}:=\left\{u-\frac{1}{z} v: u, v \in \mathbb{R}_{+}\right\}$ spanned by 1 and $-\frac{1}{z}$ of the equation

$$
\gamma=\frac{1}{N} \sum_{i=1}^{N} \frac{d_{i} \tilde{m}(z)}{1+d_{i} \tilde{m}(z)}-\gamma z \tilde{m}(z) .
$$

Proof. We use the same notation as in the previous proofs, namely $B(z)=\frac{1}{P} W K W^{T}-z \mathrm{I}_{P}, B_{(i)}(z)=\frac{1}{P} W_{(i)} K_{(i)} W_{(i)}^{T}-$ $z \mathrm{I}_{P}$ and $g_{i}(z)=\frac{1}{P} w_{i}^{T}\left(B_{(i)}(z)\right)^{-1} w_{i}$. Let $\nu_{j} \geq 0, j=1, \ldots, P$ be the spectrum of the positive semi-definite matrix ${ }_{\frac{1}{P}} W_{(i)} K_{(i)} W_{(i)}^{T}$. After diagonalization, we have

$$
B_{(i)}(z)^{-1}=O^{T} \operatorname{diag}\left(\frac{1}{\nu_{1}-z}, \ldots, \frac{1}{\nu_{P}-z}\right) O,
$$

with $O$ an orthogonal matrix. Then

$$
\begin{equation*}
g_{i}(z)=\frac{1}{P} \operatorname{Tr}\left(\left(B_{(i)}(z)\right)^{-1} w_{i} w_{i}^{T}\right)=\frac{1}{P} \sum_{j=1}^{P} \frac{\left(\left(O w_{i}\right)_{j j}\right)^{2}}{\nu_{j}-z} . \tag{5}
\end{equation*}
$$

Since $z \in \mathbb{H}_{<0}$, we conclude that $\Re\left[g_{i}(z)\right] \geq 0$ for all $i=1, \ldots, P$.
In order to prove the proposition, the key remark is that, since $\operatorname{Tr}\left(\left(\frac{1}{P} W K W^{T}-z \mathrm{I}_{P}\right)(B(z))^{-1}\right)=P$, the Stieltjes transform $m_{P}(z)$ satisfies the following equation:

$$
P=\operatorname{Tr}\left(\frac{1}{P} K W^{T} B(z)^{-1} W\right)-z P m_{P}(z)
$$

From the proof of Lemma C.2, recall that $B^{-1}(z)=B_{(i)}^{-1}(z)-\frac{d_{i}}{P} \frac{1}{1+\frac{d_{i} w_{i}^{T} B_{(i)}^{-1}(z) w_{i}}{}} B_{(i)}^{-1}(z) w_{i} w_{i}^{T} B_{(i)}^{-1}(z)$, hence:

$$
\begin{align*}
\frac{1}{P} w_{i}^{T} B^{-1}(z) w_{i} & =g_{i}(z)-\frac{d_{i} g_{i}(z)^{2}}{1+d_{i} g_{i}(z)}  \tag{6}\\
& =\frac{g_{i}(z)}{1+d_{i} g_{i}(z)}
\end{align*}
$$

Expanding the trace,

$$
\operatorname{Tr}\left(\frac{1}{P} K W^{T} B(z)^{-1} W\right)=\sum_{i=1}^{N} d_{i} \frac{1}{P} w_{i}^{T} B^{-1}(z) w_{i}=\sum_{i=1}^{N} \frac{d_{i} g_{i}(z)}{1+d_{i} g_{i}(z)}
$$

Thus, the Stieljes transform $m_{P}(z)$ satisfies the following equation $P=\sum_{i=1}^{N} \frac{d_{i} g_{i}(z)}{1+d_{i} g_{i}(z)}-z P m_{P}(z)$, or equivalently

$$
\gamma=\frac{1}{N} \sum_{i=1}^{N} \frac{d_{i} g_{i}(z)}{1+d_{i} g_{i}(z)}-z \gamma m_{P}(z)
$$

Recall that $\gamma>0$ and $\operatorname{Re}(z)<0$. The Stieljes transform $m_{P}(z)$ can be written as a function of $g_{i}(z)$ for $i=1, \ldots, n$ : $m_{P}(z)=f\left(g_{1}(z), \ldots, g_{N}(z)\right)$ where

$$
f\left(g_{1}, \ldots, g_{N}\right)=\frac{1}{\gamma z N} \sum_{i=1}^{N} \frac{d_{i} g_{i}}{1+d_{i} g_{i}}-\frac{1}{z}=-\frac{1}{z}\left(1-\frac{1}{\gamma}+\frac{1}{\gamma} \frac{1}{N} \sum_{i=1}^{N} \frac{1}{1+d_{i} g_{i}}\right)
$$

From Lemma C.6, the map $f(m)=f(m, \ldots, m)$ has a unique non-degenerate fixed point $\tilde{m}(z)$ in the cone $\mathcal{C}_{z}$. We will show that $\mathbb{E}\left[m_{P}(z)\right]$ is close to $\tilde{m}(z)$ using the following two steps: we show a non-tight bound $\left|\mathbb{E}\left[m_{P}(z)\right]-\tilde{m}(z)\right| \leq \frac{\mathbf{e}^{\prime}}{\sqrt{P}}$ and use it to obtain the tighter bound $\left|\mathbb{E}\left[m_{P}(z)\right]-\tilde{m}(z)\right| \leq \frac{\mathrm{e}}{P}$.
Let us prove the $\frac{\mathbf{e}^{\prime}}{\sqrt{P}}$ bound. From Lemma C.6, the distance between $m_{P}(z)$ and the fixed point $\tilde{m}(z)$ of $f$ is bounded by the distance between $f\left(m_{P}(z), \ldots, m_{P}(z)\right)$ and $m_{P}(z)$. Using the fact that $m_{P}(z)=f\left(g_{1}(z), \ldots, g_{N}(z)\right)$, we obtain

$$
\left|\mathbb{E}\left[m_{P}(z)\right]-\tilde{m}(z)\right| \leq \mathbb{E}\left[\left|m_{P}(z)-\tilde{m}(z)\right|\right] \leq \mathbb{E}\left[\left|f\left(m_{P}(z), \ldots, m_{P}(z)\right)-f\left(g_{1}(z), \ldots, g_{N}(z)\right)\right|\right]
$$

Recall that for any $z \in \mathbb{H}_{<0}, \Re\left(g_{i}(z)\right) \geq 0$ : we need to study the function $f$ on $\mathbb{H}_{\geq 0}^{N}$ where $\mathbb{H}_{\geq 0}=\{z \in \mathbb{C} \mid \Re(z) \geq 0\}$. On $\mathbb{H}_{\geq 0}^{N}$, the function $f$ is Lipschitz:

$$
\left|\partial_{g_{i}} f\left(g_{1}, . ., g_{N}\right)\right|=\left|\frac{1}{\gamma z N} \frac{d_{i}}{\left(1+d_{i} g_{i}\right)^{2}}\right| \leq \frac{d_{i}}{\gamma|z| N}
$$

Thus,

$$
\mathbb{E}\left[\left|f\left(m_{P}(z), \ldots, m_{P}(z)\right)-f\left(g_{1}(z), \ldots, g_{N}(z)\right)\right|\right] \leq \sum_{i=1}^{N} \frac{d_{i}}{\gamma|z| N} \mathbb{E}\left[\left|m_{P}(z)-g_{i}(z)\right|\right]
$$

Since

$$
\mathbb{E}\left[\left|m_{P}(z)-g_{i}(z)\right|\right] \leq \mathbb{E}\left[\left|m_{P}(z)-\mathbb{E}\left[m_{P}(z)\right]\right|\right]+\left|\mathbb{E}\left[m_{P}(z)\right]-\mathbb{E}\left[g_{i}(z)\right]\right|+\mathbb{E}\left[\left|g_{i}(z)-\mathbb{E}\left[g_{i}(z)\right]\right|\right]
$$

using Lemmas C. 2 and C.4, we get that $\mathbb{E}\left[\left|m_{P}(z)-g_{i}(z)\right|\right] \leq \frac{\mathrm{d}}{\sqrt{P}}$, where $\mathbf{d}$ depends on $\gamma$ and $z$ only. This implies that

$$
\mathbb{E}\left[\left|f\left(m_{P}(z), \ldots, m_{P}(z)\right)-f\left(g_{1}(z), \ldots, g_{N}(z)\right)\right|\right] \leq \frac{1}{\sqrt{P}} \frac{\mathbf{d}}{N} \operatorname{Tr}(K)
$$

which allows to conclude that $\left|\mathbb{E}\left[m_{P}(z)\right]-\tilde{m}(z)\right| \leq \frac{\mathbf{e}^{\prime}}{\sqrt{P}}$ where $\mathbf{e}^{\prime}$ depends on $\gamma, z$ and $\frac{1}{N} \operatorname{Tr}(K)$ only.

We strengthen this inequality and show the $\frac{\mathrm{e}}{P}$ bound. Using again Lemma C.6, we bound the distance between $\mathbb{E}\left[m_{P}(z)\right]$ and the fixed point $\tilde{m}(z)$ by

$$
\left|\mathbb{E}\left[m_{P}(z)\right]-\tilde{m}(z)\right| \leq\left|\mathbb{E}\left[f\left(g_{1}(z), \ldots, g_{N}(z)\right)\right]-f\left(\mathbb{E}\left[m_{P}(z)\right], \ldots, \mathbb{E}\left[m_{P}(z)\right]\right)\right|
$$

and study the r.h.s. using a Taylor approximation of $f$ near $\mathbb{E}\left[m_{P}(z)\right]$. For $i=1, \ldots, N$ and $m_{0} \in \mathbb{H}_{\geq 0}$, let $\mathrm{T}_{m_{0}} h_{i}$ be the first order Taylor approximation of the map $h_{i}: m \mapsto \frac{1}{1+d_{i} m}$ at a point $m_{0}$. The error of the first order Taylor approximation is given by

$$
h_{i}(m)-\mathrm{T}_{m_{0}} h_{i}(m)=\frac{1}{1+d_{i} m}-\left(\frac{1}{1+d_{i} m_{0}}-\frac{d_{i}\left(m-m_{0}\right)}{\left(1+d_{i} m_{0}\right)^{2}}\right)=\frac{d_{i}^{2}\left(m_{0}-m\right)^{2}}{\left(1+d_{i} m\right)\left(1+d_{i} m_{0}\right)^{2}}
$$

which, for $m \in \mathbb{H}_{\geq 0}$ can be upper bounded by a quadratic term:

$$
\begin{equation*}
\left|h_{i}(m)-\mathrm{T}_{m_{0}} h_{i}(m)\right|=\left|\frac{d_{i}^{2}}{\left(1+d_{i} m\right)\left(1+d_{i} m_{0}\right)^{2}}\right|\left|m_{0}-m\right|^{2} \leq \frac{1}{\left|m_{0}\right|^{2}}\left|m_{0}-m\right|^{2} \tag{7}
\end{equation*}
$$

The first order Taylor approximation $\mathrm{T} f$ of $f$ at the $N$-tuple $\left(\mathbb{E}\left[m_{P}(z)\right], \ldots, \mathbb{E}\left[m_{P}(z)\right]\right)$ is

$$
\mathrm{T} f\left(g_{1}, . ., g_{N}\right)=-\frac{1}{z}\left(1-\frac{1}{\gamma}+\frac{1}{\gamma} \frac{1}{N} \sum_{i=1}^{N} \mathrm{~T}_{\mathbb{E}\left[m_{P}(z)\right]} h_{i}\left(g_{i}\right)\right)
$$

Using this Taylor approximation, $\mathbb{E}\left[f\left(g_{1}(z), \ldots, g_{N}(z)\right)\right]-f\left(\mathbb{E}\left[m_{P}(z)\right], \ldots, \mathbb{E}\left[m_{P}(z)\right]\right)$ is equal to:

$$
\mathbb{E}\left[\mathrm{T} f\left(g_{1}(z), . ., g_{N}(z)\right)\right]-f\left(\mathbb{E}\left[m_{P}(z)\right], \ldots, \mathbb{E}\left[m_{P}(z)\right]\right)+\mathbb{E}\left[f\left(g_{1}(z), \ldots, g_{N}(z)\right)-\mathrm{T} f\left(g_{1}(z), . ., g_{N}(z)\right)\right]
$$

Using Lemma C.4, we get

$$
\begin{aligned}
\left|\mathbb{E}\left[f\left(g_{1}(z), \ldots, g_{N}(z)\right)-\mathrm{T} f\left(g_{1}(z), . ., g_{N}(z)\right)\right]\right| & \leq \frac{1}{|z| \gamma} \frac{1}{N} \sum_{i=1}^{N} \frac{1}{\left|\mathbb{E}\left[m_{P}(z)\right]\right|^{2}} \mathbb{E}\left[\left|g_{i}(z)-\mathbb{E}\left[m_{P}(z)\right]\right|^{2}\right] \\
& \leq \frac{1}{P} \frac{\alpha}{\left|\mathbb{E}\left[m_{P}(z)\right]\right|^{2}}
\end{aligned}
$$

and

$$
\begin{aligned}
\left|\mathbb{E}\left[\mathrm{T} f\left(g_{1}(z), . ., g_{N}(z)\right)\right]-f\left(\mathbb{E}\left[m_{P}(z)\right], \ldots, \mathbb{E}\left[m_{P}(z)\right]\right)\right| & \leq \frac{1}{|z| \gamma} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i}\left|\mathbb{E}\left[g_{i}\right]-\mathbb{E}\left[m_{P}(z)\right]\right|}{\left|1+d_{i} \mathbb{E}\left[m_{P}(z)\right]\right|^{2}} \\
& \leq \frac{\beta\left(\frac{1}{N} \operatorname{Tr} K\right)}{P}
\end{aligned}
$$

where $\alpha$ and $\beta$ depends on $z$ and $\gamma$ only. From the bounds $\left|\mathbb{E}\left[m_{P}(z)\right]-\tilde{m}(z)\right| \leq \frac{\mathbf{e}^{\prime}}{\sqrt{P}}$ and $|\tilde{m}(z)| \geq\left(|z|+\frac{1}{N \gamma} \operatorname{Tr}(K)\right)^{-1}$ (Lemma C.6), the bound $\frac{1}{P} \frac{\alpha}{\left|\mathbb{E}\left[m_{P}(z)\right]\right|^{2}}$ yields a $\frac{\tilde{\alpha}}{P}$ bound. This implies that $\left|\mathbb{E}\left[m_{P}(z)\right]-f\left(\mathbb{E}\left[m_{P}(z)\right], \ldots, \mathbb{E}\left[m_{P}(z)\right]\right)\right| \leq \frac{\mathrm{e}}{P}$, hence the desired inequality $\left|\mathbb{E}\left[m_{P}(z)\right]-\tilde{m}(z)\right| \leq \frac{\mathbf{e}}{P}$.

For the proof of Proposition C.5, we have used the fact that the map $f_{z}$ introduced therein has a unique non-degenerate fixed point in the cone $\mathcal{C}_{z}:=\left\{u-\frac{1}{z} v: u, v \in \mathbb{R}_{+}\right\}$. We now proceed with proving this statement.
Lemma C.6. Let $d_{1}, \ldots, d_{n} \geq 0$ and let $\gamma \geq 0$. For any fixed $z \in \mathbb{H}_{<0}$, let $f_{z}: \mathbb{H}_{\geq 0} \rightarrow \mathbb{C}$ be the function $t \mapsto f_{z}(t)=$ $-\frac{1}{z}\left(1-\frac{1}{\gamma} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i} t}{1+d_{i} t}\right)$. Let $\mathcal{C}_{z}:=\left\{u-\frac{1}{z} v: u, v \in \mathbb{R}_{+}\right\}$be the convex region spanned by the half-lines $\mathbb{R}_{+}$and $-\frac{1}{z} \mathbb{R}_{+}$. Then for every $z \in \mathbb{H}_{<0}$ there exists a unique fixed point $\tilde{t}(z) \in \mathcal{C}_{z}$ such that $\tilde{t}(z)=f_{z}(\tilde{t}(z))$. The map $\tilde{t}: z \mapsto \tilde{t}(z)$ is holomorphic in $\mathbb{H}_{<0}$ and

$$
|\tilde{t}(z)| \geq\left(|z|+\frac{\sum_{i} d_{i}}{\gamma N}\right)^{-1}
$$

Furthermore for every $z \in \mathbb{H}_{<0}$ and any $t \in \mathbb{H}_{\geq 0}$, one has

$$
|t-\tilde{t}(z)| \leq\left|t-f_{z}(t)\right|
$$

Proof. By means of Schwarz reflection principle, we can assume that $\Im(z) \geq 0$. Let $z \in \mathbb{H}_{<0}$ and let $\Pi_{z}:=\left\{-\frac{w}{z}\right.$ : $\Im(w) \leq 0\}$ and let $\mathcal{C}_{z}$ be the wedged region $\mathcal{C}_{z}:=\Pi_{z} \cap\{w \in \mathbb{C}: \Im(w) \geq 0\}$. To show the existence of a fixed point in $\mathcal{C}_{z}$ we show that 0 is in the image of the function $\psi: t \mapsto f_{z}(t)-t$. Note that since $d_{i} \geq 0$, the eventual poles of $f_{z}$ are all strictly negative real numbers, hence $\psi: \mathcal{C}_{z} \rightarrow \mathbb{C}$ is an holomorphic function.
To prove that $0 \in \psi\left(\mathcal{C}_{z}\right)$ we proceed with a geometrical reasoning: the image $\psi\left(\mathcal{C}_{z}\right)$ is (one of) the region of the plane confined by $\psi\left(\partial \mathcal{C}_{z}\right)$, so we only need to "draw" $\psi\left(\partial \mathcal{C}_{z}\right)$ and show that 0 belongs to the "good" connected component confined by it.
The boundary of $C_{z}$ is made up of two half-lines $\mathbb{R}_{+}$and $-\frac{1}{z} \mathbb{R}_{+}$. Under the map $f_{z}, 0$ is mapped to $-\frac{1}{z}$ and $\infty$ is mapped to $-\frac{1-\frac{1}{\gamma}}{z}$, the two half-lines are hence mapped to paths from $-\frac{1}{z}$ to $-\frac{1-\frac{1}{\gamma}}{z}$. Now under $\psi$ the half-lines will be mapped to paths going $-\frac{1}{z}$ to $\infty$ because by our assumption $-\frac{1}{z}$ lies in the upper right quadrant, we will show that the image of $\mathbb{R}_{+}$ under $\phi$ goes 'above' the origin while the image of $-\frac{1}{z} \mathbb{R}_{+}$goes 'under' the origin:

- $\mathbb{R}_{+}$is mapped under $f_{z}$ to the segment $-\frac{1}{z}\left[1,1-\frac{1}{\gamma}\right]$, as a result, its map under $\psi$ lies in the Minkowski sum $-\frac{1}{z}\left[1,1-\frac{1}{\gamma}\right]+\left(-\mathbb{R}_{+}\right)$which is contained in $\overline{\mathbb{C} \backslash \Pi_{z}}$.
- For any $t \in-\frac{1}{z} \mathbb{R}_{+}$we have for all $d_{i}$

$$
\Im\left(\frac{d_{i} t}{1+d_{i} t}\right)=\Im\left(1-\frac{1}{1+d_{i} t}\right)=\Im\left(\frac{1}{1+d_{i} t}\right) \leq 0
$$

since $\Im(t) \geq 0$. As a result the image of $-\frac{1}{z} \mathbb{R}_{+}$under $f_{z}$ lies in $\Pi_{z}$ and its image under $\psi$ lies in the Minkovski sum $\Pi_{z}+\left(-\frac{1}{z} \mathbb{R}_{+}\right)=\Pi_{z}$.

Thus we can conclude that $0 \in \psi\left(\mathcal{C}_{z}\right)$, which shows that there exists at least a fixed point $\tilde{m}$ in $\mathcal{C}_{z}$.
We observe that, for every $t \in \mathcal{C}_{z}$, the derivative of $f$ has negative real part:

$$
\begin{aligned}
\operatorname{Re}\left(f_{z}^{\prime}(t)\right) & =\frac{1}{\gamma} \frac{1}{N} \sum_{i=1}^{N} \operatorname{Re}\left(\frac{d_{i}}{z\left(1+d_{i} t\right)^{2}}\right) \\
& =\frac{1}{\gamma} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i}\left[\Re(z)+2 d_{i} \Re(z) \Re(t)-2 d_{i} \Im(z) \Im(t)+d_{i}^{2} \Re\left(z t^{2}\right)\right]}{|z|^{2}\left|1+d_{i} t\right|^{4}} \leq 0
\end{aligned}
$$

where we concluded the last inequality by using that $\Re(z) \leq 0, \Re(t) \geq 0, \Im(z) \Im(t) \geq 0$ and $\Re\left(z t^{2}\right) \leq 0$. Thus, since for no point $t \in \mathcal{C}_{z}$ has $f_{z}^{\prime}(t)=1$, any fixed point of $f_{z}$ is a simple fixed point.
We now proceed to show the uniqueness of the fixed point in the region $\mathcal{C}_{z}$. Suppose there are two fixed points $t_{1}$ and $t_{2}$, then

$$
\begin{aligned}
t_{1}-t_{2} & =f_{z}\left(t_{1}\right)-f_{z}\left(t_{2}\right) \\
& =\left(t_{1}-t_{2}\right) \frac{1}{z} \frac{1}{\gamma N} \sum_{i=1}^{N} \frac{d_{i}}{\left(1+d_{i} t_{1}\right)\left(1+d_{i} t_{2}\right)}
\end{aligned}
$$

Again, since $\Re(z) \leq 0, \Re\left(t_{1}\right), \Re\left(t_{2}\right) \geq 0, \Im(z) \Im\left(t_{1}\right), \Im(z) \Im\left(t_{2}\right), \geq 0$ and $\Re\left(z t_{1} t_{2}\right) \leq 0$, the factor $\frac{1}{z} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i}}{\left(1+d_{i} t_{1}\right)\left(1+d_{i} t_{2}\right)}$ has negative real part, and thus the identity is possible only if $t_{1}=t_{2}$. Let's then $\tilde{t}(z)$ be the only fixed point in $\mathcal{C}_{z}$.
We proceed now to show that $\left|t-f_{z}(t)\right| \geq|t-\tilde{t}(z)|$, i.e. if $t$ and its image are close, then $t$ is not too far from being a fixed point, and so it is close to $\tilde{t}(z)$.

For any $t \in \mathcal{C}_{z}$, we have

$$
\begin{aligned}
\left|t-f_{z}(t)\right| & =\left|t-\tilde{t}(z)+f_{z}(\tilde{t}(z))-\tilde{f}_{z}(t)\right| \\
& =\left|(t-\tilde{t}(z))-(t-\tilde{t}(z))\left(\frac{1}{z} \frac{1}{\gamma N} \sum_{i=1}^{N} \frac{d_{i}}{\left(1+d_{i} t\right)\left(1+d_{i} \tilde{t}(z)\right)}\right)\right| \\
& =|t-\tilde{t}(z)|\left|1-\frac{1}{z} \frac{1}{\gamma N} \sum_{i=1}^{N} \frac{d_{i}}{\left(1+d_{i} t\right)\left(1+d_{i} \tilde{t}(z)\right)}\right| \\
& \geq|t-\tilde{t}(z)|
\end{aligned}
$$

where we have used again that $\frac{1}{z} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i}}{\left(1+d_{i} t\right)\left(1+d_{i} \tilde{t}(z)\right)}$ has negative real part.
We provide a lower bound on the norm of the fixed point:

$$
|\tilde{t}(z)|=\frac{1}{|z|}\left|1-\frac{1}{\gamma} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i} \tilde{t}(z)}{1+d_{i} \tilde{t}(z)}\right| \geq \frac{1}{|z|}\left(1-\frac{1}{\gamma} \frac{1}{N} \sum_{i=1}^{N}\left|\frac{d_{i} \tilde{t}(z)}{1+d_{i} \tilde{t}(z)}\right|\right) \geq \frac{1}{|z|}\left(1-\frac{|\tilde{t}(z)|}{\gamma N} \sum_{i=1}^{N} d_{i}\right)
$$

hence

$$
|\tilde{t}(z)| \geq\left(|z|+\frac{\sum_{i} d_{i}}{\gamma N}\right)^{-1}
$$

Finally, note that $z$ can be expressed from the fixed point $\tilde{m}$, hence defining an inverse for the map $\tilde{t}$ :

$$
\tilde{t}^{-1}(\tilde{m})=z=-\frac{1}{\tilde{m}}\left(1-\frac{1}{\gamma} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i} \tilde{m}}{1+d_{i} \tilde{m}}\right)
$$

because the inverse is holomorphic, so is $\tilde{t}$.

## C.3. Ridge

Using Proposition C.1, in order to have a better description of the distribution of the predictor $\hat{f}_{\lambda, \gamma}^{(R F)}$, it remains to study the distributions of both the final labels $\hat{y}$ on the training set and the parameter norm $\|\hat{\theta}\|^{2}$. In Section C.3.1, we first study the expectation of the final labels $\hat{y}$ : this allows us to study the loss of the average predictor $\mathbb{E}\left[\hat{f}_{\lambda, \gamma}^{(R F)}\right]$. Then in Section C.3.3, a study of the variance of the predictor allows us to study the average loss of the RF predictor.

## C.3.1. EXPECTATION OF THE PREDICTOR

The optimal parameters $\hat{\theta}$ which minimize the regularized MSE loss is given by $\hat{\theta}=F^{T}\left(F F^{T}+\lambda \mathrm{I}_{N}\right)^{-1} y$, or equivalently by $\hat{\theta}=\left(F^{T} F+\lambda\right)^{-1} F^{T} y$. Thus, the final labels take the form $\hat{y}=A(-\lambda) y$ where $A(z)$ is the random matrix defined as

$$
\begin{aligned}
A(z) & :=F\left(F^{T} F-z \mathrm{I}_{P}\right)^{-1} F^{T} \\
& =\frac{1}{P} K^{\frac{1}{2}} W^{T}\left(\frac{1}{P} W K W^{T}-z \mathrm{I}_{P}\right)^{-1} W K^{\frac{1}{2}}
\end{aligned}
$$

Note that the matrix $A_{\lambda}$ defined in the proof sketch of Theorem 4.1 in the main text is given by $A_{\lambda}=A(-\lambda)$.
Proposition C.7. For any $\gamma>0$, any $z \in \mathbb{H}_{<0}$, and any symmetric positive definite matrix $K$,

$$
\begin{equation*}
\left\|\mathbb{E}[A(z)]-K\left(K+\tilde{\lambda}(-z) I_{N}\right)^{-1}\right\|_{o p} \leq \frac{c}{P} \tag{8}
\end{equation*}
$$

where $\tilde{\lambda}(z):=\frac{1}{\tilde{m}(-z)}$ and $c>0$ depends on $z, \gamma$ and $\frac{1}{N} \operatorname{Tr}(K)$ only.

Proof. Since the distribution of $W$ is invariant under orthogonal transformations, by applying a change of basis, in order to prove Inequality (8), we may assume that $K$ is diagonal with diagonal entries $d_{1}, \ldots, d_{N}$. Denoting $w_{1}, \ldots, w_{N}$ the columns of $W$, for any $i, j=1, \ldots, N$,

$$
(A(z))_{i j}=\frac{1}{P} \sqrt{d_{i} d_{j}} w_{i}^{T}\left(\frac{1}{P} W K W^{T}-z I_{P}\right)^{-1} w_{j}
$$

where $W K W^{T}=\sum_{i=1}^{N} d_{i} w_{i} w_{i}^{T}$. Replacing $w_{i}$ by $-w_{i}$ does not change the law $W$ hence does not change the law of $(A(z))_{i j}$. Since $W K W^{T}$ is invariant under this change of sign, we get that for $i \neq j, \mathbb{E}\left[(A(z))_{i j}\right]=-\mathbb{E}\left[(A(z))_{i j}\right]$, hence the off-diagonal terms of $\mathbb{E}[A(z)]$ vanish.

Consider a diagonal term $(A(z))_{i i}$. From Equation (6), we get

$$
\begin{equation*}
(A(z))_{i i}=\frac{d_{i}}{P} w_{i}^{T} B^{-1}(z) w_{i}=\frac{d_{i} g_{i}(z)}{1+d_{i} g_{i}(z)} \tag{9}
\end{equation*}
$$

By Lemma C.4, $g_{i}$ lies close to $m_{P}(z)$ which itself is approximatively equal to $\tilde{m}(z)$ by Proposition C.5. Therefore, we expect $\mathbb{E}\left[(A(z))_{i i}\right]=\mathbb{E}\left[\frac{d_{i} g_{i}}{1+d_{i} g_{i}}\right]$ to be at short distance from $\frac{d_{i} \tilde{m}(z)}{1+d_{i} \tilde{m}(z)}$.
In order to make rigorous this heuristic and to prove that $\mathbb{E}\left[(A(z))_{i i}\right]$ is within $\mathcal{O}\left(\frac{1}{P}\right)$ distance to $\frac{d_{i} \tilde{m}(z)}{1+d_{i} \tilde{m}(z)}$, we consider the first order Taylor approximation $\mathrm{T}_{\tilde{m}(z)} h_{i}$ of the map $h_{i}: g \mapsto \frac{1}{1+d_{i} g}$ (as in the proof Proposition C. 5 but this time centered at $\tilde{m}(z))$. Using the fact that $\frac{d_{i} t}{1+d_{i} t}=1-\frac{1}{1+d_{i} t}=1-h_{i}(t)$, and inserting the Taylor approximation, $\mathbb{E}\left[(A(z))_{i i}\right]-\frac{d_{i} \tilde{m}(z)}{1+d_{i} \tilde{m}(z)}$ is equal to:

$$
h_{i}(\tilde{m}(z))-h_{i}\left(g_{i}(z)\right)=\frac{1}{1+d_{i} \tilde{m}(z)}-\mathbb{E}\left[\mathrm{T}_{\tilde{m}(z)} h\left(g_{i}(z)\right)\right]+\mathbb{E}\left[\mathrm{T}_{\tilde{m}(z)} h\left(g_{i}(z)\right)-h\left(g_{i}(z)\right)\right]
$$

Thus,

$$
\left|\mathbb{E}\left[(A(z))_{i i}\right]-\frac{d_{i} \tilde{m}(z)}{1+d_{i} \tilde{m}(z)}\right| \leq\left|\frac{1}{1+d_{i} \tilde{m}(z)}-\mathbb{E}\left[\mathrm{T}_{\tilde{m}(z)} h\left(g_{i}(z)\right)\right]\right|+\left|\mathbb{E}\left[\mathrm{T}_{\tilde{m}(z)} h\left(g_{i}(z)\right)-h\left(g_{i}(z)\right)\right]\right|
$$

Using Lemma C. 4 and Proposition C.5, the first term $\left|\frac{1}{1+d_{i} \tilde{m}(z)}-\mathbb{E}\left[\mathrm{T}_{\tilde{m}(z)} h\left(g_{i}(z)\right)\right]\right|=\frac{d_{i}\left|\mathbb{E}\left[g_{i}(z)\right]-\tilde{m}(z)\right|}{\left|1+d_{i} \tilde{m}(z)\right|^{2}}$ can be bounded by $\frac{\delta}{P} \frac{d_{i}}{\left|1+d_{i} \tilde{m}(z)\right|^{2}}$ where $\delta$ depends on $z, \gamma$ and $\frac{1}{N} \operatorname{Tr}(K)$ only. Since $\operatorname{Re}[\tilde{m}(z)] \geq 0$ thus $\left|1+d_{i} \tilde{m}(z)\right| \geq \max \left(1,\left|d_{i} \tilde{m}(z)\right|\right)$, and $|\tilde{m}(z)| \geq \frac{1}{|z|+\frac{1}{\gamma} \frac{1}{N} \operatorname{Tr} K}$ (Lemma C.6), the denominator can be lower bounded:

$$
\left|1+d_{i} \tilde{m}(z)\right|^{2} \geq\left|d_{i} \tilde{m}(z)\right| \geq \frac{d_{i}}{|z|+\frac{1}{\gamma} \frac{1}{N} \operatorname{Tr} K}
$$

yielding the upper bound:

$$
\left|\frac{1}{1+d_{i} \tilde{m}(z)}-\mathbb{E}\left[\mathrm{T}_{\tilde{m}(z)} h\left(g_{i}(z)\right)\right]\right| \leq \frac{1}{P} \delta\left[|z|+\frac{1}{\gamma} \frac{1}{N} \operatorname{Tr} K\right]
$$

For the second term, using the same arguments as for the proof of Proposition C.5, we have:

$$
\left|\mathbb{E}\left[\mathrm{T}_{\tilde{m}(z)} h\left(g_{i}(z)\right)-h\left(g_{i}(z)\right)\right]\right| \leq \frac{\mathbb{E}\left[\left|\tilde{m}(z)-g_{i}(z)\right|^{2}\right]}{|\tilde{m}(z)|^{2}}
$$

Recall that $|\tilde{m}(z)| \geq \frac{1}{|z|+\frac{1}{\gamma} \frac{1}{N} \operatorname{Tr} K}$ and that, by Lemma C. 4 and Proposition C.2, $\mathbb{E}\left[\left|\tilde{m}(z)-g_{i}(z)\right|^{2}\right] \leq \frac{\tilde{\delta}}{P}$ where $\tilde{\delta}$ depends on $z, \gamma$ and $\frac{1}{N} \operatorname{Tr}(K)$ only. This implies that

$$
\left|\mathbb{E}\left[\mathrm{T}_{\tilde{m}(z)} h\left(g_{i}(z)\right)-h\left(g_{i}(z)\right)\right]\right| \leq \frac{\tilde{\delta}}{P}\left[|z|+\frac{1}{\gamma} \frac{1}{N} \operatorname{Tr} K\right]^{2}
$$

As a consequence, there exists a constant $c$ which depends on $z, \gamma$ and $\frac{1}{N} \operatorname{Tr}(K)$ only such that:

$$
\left|\mathbb{E}\left[(A(z))_{i i}\right]-\frac{d_{i} \tilde{m}(z)}{1+d_{i} \tilde{m}(z)}\right| \leq \frac{c}{P}
$$

Using the effective ridge $\tilde{\lambda}(z):=\frac{1}{\tilde{m}(-z)}$, the term $\frac{d_{i} \tilde{m}(z)}{1+d_{i} \tilde{m}(z)}=\frac{d_{i}}{d_{i}+\tilde{\lambda}(-z)}$ is equal to $\left(K\left(K+\tilde{\lambda} I_{N}\right)^{-1}\right)_{i i}$ since, in the basis considered, $K\left(K+\tilde{\lambda} I_{N}\right)^{-1}$ is a diagonal matrix. Hence, we obtain:

$$
\left\|\mathbb{E}[A(z)]-K\left(K+\tilde{\lambda} I_{N}\right)^{-1}\right\|_{o p} \leq \frac{c}{P}
$$

which allows us to conclude.
Using the above proposition, we can bound the distance between the expected $\lambda$-RF predictor and the $\tilde{\lambda}$-RF predictor.
Theorem C.8. For $N, P>0$ and $\lambda>0$, we have

$$
\begin{equation*}
\left|\mathbb{E}\left[\hat{f}_{\lambda, \gamma}^{(R F)}(x)\right]-\hat{f}_{\tilde{\lambda}}^{(K)}(x)\right| \leq \frac{c \sqrt{K(x, x)}\|y\|_{K^{-1}}}{P} \tag{10}
\end{equation*}
$$

where the effective ridge $\tilde{\lambda}(\lambda, \gamma)>\lambda$ is the unique positive number satisfying

$$
\begin{equation*}
\tilde{\lambda}=\lambda+\frac{\tilde{\lambda}}{\gamma} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i}}{\tilde{\lambda}+d_{i}} \tag{11}
\end{equation*}
$$

and where $c>0$ depends on $\lambda, \gamma$, and $\frac{1}{N} \operatorname{Tr} K(X, X)$ only.
Proof. Recall that $\tilde{m}(-\lambda)$ is the unique non negative real such that $\gamma=\frac{1}{N} \sum_{i=1}^{N} \frac{d_{i} \tilde{m}(-\lambda)}{1+d_{i} \tilde{m}(-\lambda)}+\gamma \lambda \tilde{m}(-\lambda)$. Dividing this equality by $\gamma \tilde{m}(-\lambda)$ yields Equation (11). From now on, let $\tilde{\lambda}=\tilde{\lambda}(\lambda, \gamma)$.
We now bound the l.h.s. of Equation (10). By Proposition C.1, since $\hat{y}=A(-\lambda) y$, the average $\lambda$-RF predictor is $\mathbb{E}\left[f_{\lambda, \gamma}^{(R F)}(x)\right]=K(x, X) K^{-1} \mathbb{E}[A(-\lambda)] y$. The $\tilde{\lambda}-K R R$ predictor is $f_{\tilde{\lambda}}^{(K)}(x)=K(x, X)\left(K+\tilde{\lambda} I_{N}\right)^{-1} y$. Thus:

$$
\left|\mathbb{E}\left[f_{\lambda, \gamma}^{(R F)}(x)\right]-f_{\tilde{\lambda}}^{(K)}(x)\right|=\left|K(x, X) K^{-1}\left[\mathbb{E}[A(-\lambda)]-K\left(K+\tilde{\lambda} I_{N}\right)^{-1}\right] y\right|
$$

The r.h.s. can be expressed as the absolute value of the scalar product $\left|\langle w, v\rangle_{K^{-1}}\right|=\left|v^{T} K^{-1} w\right|$ where $v=K(x, X)$ and $w=\left[\mathbb{E}[A(-\lambda)]-K\left(K+\tilde{\lambda} I_{N}\right)^{-1}\right] y$. By Cauchy-Schwarz inequality, $\left|\langle v, w\rangle_{K^{-1}}\right| \leq\|v\|_{K^{-1}}\|w\|_{K^{-1}}$.
For a general vector $v$, the $K^{-1}$-norm $\|v\|_{K^{-1}}$ is equal to the norm mininum Hilbert norm (for the RKHS associated to the kernel $K$ ) interpolating function:

$$
\|v\|_{K^{-1}}=\min _{f \in \mathcal{H}, f\left(x_{i}\right)=v_{i}}\|f\|_{\mathcal{H}}
$$

Indeed the minimal interpolating function is the kernel regression given by $f^{(K)}(\cdot)=K(\cdot, X) K(X, X)^{-1} v$ which has norm (writing $\beta=K^{-1} v$ ):

$$
\left\|f^{(K)}\right\|_{\mathcal{H}}=\left\|\sum_{i=1}^{N} \beta_{i} K\left(\cdot, x_{i}\right)\right\|_{\mathcal{H}}=\sqrt{\sum_{i, j=1}^{N} \beta_{i} \beta_{j} K\left(x_{i}, x_{j}\right)}=\sqrt{v^{T} K^{-1} K K^{-1} v}=\|v\|_{K^{-1}}
$$

We can now bound the two norms $\|v\|_{K^{-1}}$ and $\|w\|_{K^{-1}}$. For $v=K(x, X)$, we have

$$
\begin{equation*}
\|v\|_{K^{-1}}=\min _{f \in \mathcal{H}, f\left(x_{i}\right)=v_{i}}\|f\|_{\mathcal{H}} \leq\|K(x, \cdot)\|_{\mathcal{H}}=K(x, x)^{\frac{1}{2}} \tag{12}
\end{equation*}
$$

since $K(x, \cdot)$ is an interpolating function for $v$.

It remains to bound $\|w\|_{K^{-1}}$. Recall that $K=U D U^{T}$ with $D$ diagonal, and that, from the previous proposition, $\mathbb{E}[A(-\lambda)]=U D_{A} U^{T}$ where $D_{A}=\operatorname{diag}\left(\frac{d_{1} g_{1}(-\lambda)}{1+d_{1} g_{1}(-\lambda)}, \ldots, \frac{d_{N} g_{N}(-\lambda)}{1+d_{N} g_{N}(-\lambda)}\right)$. The norm $\|w\|_{K^{-1}}$ is equal to

$$
\sqrt{\tilde{y}^{T}\left[D_{A}-D\left(D+\tilde{\lambda}(\lambda) I_{N}\right)^{-1}\right]^{T} D^{-1}\left[D_{A}-D\left(D+\tilde{\lambda}(\lambda) I_{N}\right)^{-1}\right] \tilde{y}}
$$

where $\tilde{y}=U^{T} y$. Expanding the product, $\|w\|_{K^{-1}}=\sqrt{\sum_{i=1}^{N} \frac{\tilde{y}_{i}^{2}}{d_{i}}\left(\left(D_{A}\right)_{i i}-\frac{d_{i}}{\tilde{\lambda}(\lambda)+d_{i}}\right)^{2}}$, hence by Proposition C.7, $\|w\|_{K^{-1}} \leq \frac{c}{P} \sqrt{\sum_{i=1}^{N} \frac{\tilde{y}^{2}}{d_{i}}}$. The result follows from noticing that $\sum_{i=1}^{N} \frac{\tilde{y}^{2}}{d_{i}}=\tilde{y}^{T} D^{-1} \tilde{y}=\|y\|_{K^{-1}}^{2}$ :

$$
\left|\mathbb{E}\left[f_{\lambda, \gamma}^{(R F)}(x)\right]-f_{\tilde{\lambda}}^{(K)}(x)\right| \leq\|v\|_{K^{-1}}\|w\|_{K^{-1}} \leq \frac{c K(x, x)^{\frac{1}{2}}\|y\|_{K^{-1}}}{P}
$$

which allows us to conclude.
Corollary C.9. If $\mathbb{E}_{\mathcal{D}}[K(x, x)]<\infty$, we have that the difference of errors $\delta_{E}=\left|L\left(\mathbb{E}\left[\hat{f}_{\lambda, \gamma}^{(R F)}\right]\right)-L\left(\hat{f}_{\tilde{\lambda}}^{(K)}\right)\right|$ is bounded from above by

$$
\delta_{E} \leq \frac{C\|y\|_{K^{-1}}}{P}\left(2 \sqrt{L\left(\hat{f}_{\tilde{\lambda}}^{(K)}\right)}+\frac{C\|y\|_{K^{-1}}}{P}\right)
$$

where $C$ is given by $c \sqrt{\mathbb{E}_{\mathcal{D}}[K(x, x)]}$, with $c$ the constant appearing in (10) above.
Proof. For any function $f: \mathbb{R}^{d} \rightarrow \mathbb{R}$, we denote by $\|f\|=\left(\mathbb{E}_{\mathcal{D}}\left[f(x)^{2}\right]\right)^{\frac{1}{2}}$ its $L^{2}(\mathcal{D})$-norm. Integrating $\left|\mathbb{E}\left[f_{\lambda, \gamma}^{(R F)}(x)\right]-f_{\tilde{\lambda}}^{(K)}(x)\right|^{2} \leq \frac{c^{2} K(x, x)\|y\|_{K^{-1}}^{2}}{P^{2}}$ over $x \sim \mathcal{D}$, we get the following bound:

$$
\left\|\mathbb{E}\left[f_{\lambda, \gamma}^{(R F)}\right]-f_{\tilde{\lambda}}^{(K)}\right\| \leq \frac{c\left[\mathbb{E}_{\mathcal{D}}[K(x, x)]\right]^{\frac{1}{2}}\|y\|_{K^{-1}}}{P}
$$

Hence, if $f^{*}$ is the true function, by the triangular inequality,

$$
\left|\left\|\mathbb{E}\left[f_{\lambda, \gamma}^{(R F)}\right]-f^{*}\right\|-\left\|f_{\tilde{\lambda}}^{(K)}-f^{*}\right\|\right| \leq \frac{c\left[\mathbb{E}_{\mathcal{D}}[K(x, x)]\right]^{\frac{1}{2}}\|y\|_{K^{-1}}}{P}
$$

Notice that $L\left(\mathbb{E}\left[\hat{f}_{\gamma, \lambda}^{(R F)}\right]\right)=\left\|\mathbb{E}\left[f_{\lambda, \gamma}^{(R F)}\right]-f^{*}\right\|^{2}$ and $L\left(\hat{f}_{\tilde{\lambda}}^{(K)}\right)=\left\|f_{\tilde{\lambda}}^{(K)}-f^{*}\right\|^{2}$. Since $\left|a^{2}-b^{2}\right| \leq|a-b|(|a-b|+2|b|)$, we obtain

$$
\left|L\left(\mathbb{E}\left[\hat{f}_{\gamma, \lambda}^{(R F)}\right]\right)-L\left(\hat{f}_{\tilde{\lambda}}^{(K)}\right)\right| \leq \frac{c\left[\mathbb{E}_{\mathcal{D}}[K(x, x)]\right]^{\frac{1}{2}}\|y\|_{K^{-1}}}{P}\left(2 \sqrt{L\left(\hat{f}_{\tilde{\lambda}}^{(K)}\right)}+\frac{c\left[\mathbb{E}_{\mathcal{D}}[K(x, x)]\right]^{\frac{1}{2}}\|y\|_{K^{-1}}}{P}\right)
$$

which allows us to conclude.

## C.3.2. Properties of the effective ridge

Thanks to the implicit definition of the effective ridge $\tilde{\lambda}$, we obtain the following:
Proposition C.10. The effective ridge $\tilde{\lambda}$ satisfies the following properties:

1. for any $\gamma>0$, we have $\lambda<\tilde{\lambda}(\lambda, \gamma) \leq \lambda+\frac{1}{\gamma} T$;
2. the function $\gamma \mapsto \tilde{\lambda}(\lambda, \gamma)$ is decreasing;
3. for $\gamma>1$, we have $\tilde{\lambda} \leq \frac{\gamma}{\gamma-1} \lambda$;
4. for $\gamma<1$, we have $\tilde{\lambda} \geq \frac{1-\sqrt{\gamma}}{\sqrt{\gamma}} \min _{i} d_{i}$.

Proof. (1) The upper bound in the first statement follows directly from Lemma C. 6 where it was shown that $\tilde{m}(-\lambda) \geq$ $\frac{1}{\lambda+\frac{1}{\gamma} \frac{1}{N} \operatorname{Tr} K}$ and from the fact that $\tilde{\lambda}(\lambda, \gamma)=\frac{1}{\tilde{m}(-\lambda)}$. For the lower bound, remark that Equation (11) can be written as:

$$
\tilde{\lambda}(\lambda, \gamma)=\lambda+\frac{1}{\gamma} \frac{1}{N} \operatorname{Tr}\left[\tilde{\lambda}(\lambda, \gamma) K\left(\tilde{\lambda}(\lambda, \gamma) I_{N}+K\right)^{-1}\right]
$$

Since $\tilde{\lambda}(\lambda, \gamma) \geq 0$ and $K$ is a positive symmetric matrix, $\operatorname{Tr}\left[K\left[\tilde{\lambda}(\lambda, \gamma) I_{N}+K\right]^{-1}\right] \geq 0$ : this yields $\tilde{\lambda}(\lambda, \gamma) \geq \lambda$.
(2) We show that $\gamma \mapsto \tilde{\lambda}(\lambda, \gamma)$ is decreasing by computing the derivative of the effective ridge with respect to $\gamma$. Differentiating both sides of Equation (11), $\partial_{\gamma} \tilde{\lambda}=\partial_{\gamma}\left[\lambda+\frac{\tilde{\lambda}}{\gamma} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i}}{\tilde{\lambda}+d_{i}}\right]$. The r.h.s. is equal to:

$$
\frac{\partial_{\gamma} \tilde{\lambda}}{\gamma} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i}}{\tilde{\lambda}+d_{i}}-\frac{\tilde{\lambda}}{\gamma^{2}} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i}}{\tilde{\lambda}+d_{i}}-\frac{\tilde{\lambda}}{\gamma} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i} \partial_{\gamma} \tilde{\lambda}}{\left(\tilde{\lambda}+d_{i}\right)^{2}}
$$

Using Equation (11), $\frac{1}{\gamma} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i}}{\tilde{\lambda}+d_{i}}=\frac{\tilde{\lambda}-\lambda}{\tilde{\lambda}}$ and thus:

$$
\partial_{\gamma} \tilde{\lambda}\left[\frac{\lambda}{\tilde{\lambda}}+\frac{\tilde{\lambda}}{\gamma} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i}}{\left(\tilde{\lambda}+d_{i}\right)^{2}}\right]=-\frac{\tilde{\lambda}-\lambda}{\gamma}
$$

Since $\tilde{\lambda} \geq \lambda \geq 0$, the derivative of the effective ridge with respect to $\gamma$ is negative: the function $\gamma \mapsto \tilde{\lambda}(\lambda, \gamma)$ is decreasing.
(3) Using the bound $\frac{d_{i}}{\tilde{\lambda}+d_{i}} \leq 1$ in Equation (11), we obtain $\tilde{\lambda} \leq \lambda+\frac{\tilde{\lambda}}{\gamma}$ which, when $\gamma \geq 1$, implies that $\tilde{\lambda} \leq \lambda \frac{\gamma}{\gamma-1}$.
(4) Recall that $\lambda>0$ and that the effective ridge $\tilde{\lambda}$ is the unique fixpoint of the map $f(t)=\lambda+\frac{t}{\gamma} \frac{1}{N} \sum_{i} \frac{d_{i}}{t+d_{i}}$ in $\mathbb{R}_{+}$. The map is concave and, at $t=0$, we have $f(t)=\lambda>0=t$ : this implies that $f^{\prime}(\tilde{\lambda})<1$ otherwise by concavity, for any $t \leq \tilde{\lambda}$ one would have $f(t) \leq t$. The derivative of $f$ is $f^{\prime}(t)=\frac{1}{\gamma} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i}^{2}}{\left(t+d_{i}\right)^{2}}$, thus $\frac{1}{\gamma} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i}^{2}}{\left(\tilde{\lambda}+d_{i}\right)^{2}}<1$. Using the fact that $d_{0}$ is the smallest eigenvalue of $K(X, X)$, i.e. $d_{i} \geq d_{0}$, we get $1>\frac{1}{\gamma} \frac{d_{0}^{2}}{\left(\tilde{\lambda}+d_{0}\right)^{2}}$ hence $\tilde{\lambda} \geq d_{0} \frac{1-\sqrt{\gamma}}{\sqrt{\gamma}}$.

Similarily, we gather a number of properties of the derivative $\partial_{\lambda} \tilde{\lambda}(\lambda, \gamma)$.
Proposition C.11. For $\gamma>1$, as $\lambda \rightarrow 0$, the derivative $\partial_{\lambda} \tilde{\lambda}$ converges to $\frac{\gamma}{\gamma-1}$. As $\lambda \gamma \rightarrow \infty$, we have $\partial_{\lambda} \tilde{\lambda}(\lambda, \gamma) \rightarrow 1$.
Proof. Differentiating both sides of Equation (11),

$$
\partial_{\lambda} \tilde{\lambda}=1+\partial_{\lambda} \tilde{\lambda} \frac{1}{\gamma} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i}}{\tilde{\lambda}+d_{i}}-\tilde{\lambda} \partial_{\lambda} \tilde{\lambda} \frac{1}{\gamma} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i}}{\left(\tilde{\lambda}+d_{i}\right)^{2}}
$$

Hence the derivative $\partial_{\lambda} \tilde{\lambda}$ satisfies the following equality

$$
\begin{equation*}
\partial_{\lambda} \tilde{\lambda}\left(1-\frac{1}{\gamma} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i}}{\tilde{\lambda}+d_{i}}+\tilde{\lambda} \frac{1}{\gamma} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i}}{\left(\tilde{\lambda}+d_{i}\right)^{2}}\right)=1 \tag{13}
\end{equation*}
$$

(1) Assuming $\gamma>1$, from the point 3. of Proposition C.10, we already know that $\tilde{\lambda}(\lambda, \gamma) \leq \lambda \frac{\gamma}{\gamma-1}$ hence $\tilde{\lambda}(0, \gamma)=0$. Actually, using similar arguments as in the proof of point 3., this holds also for $\gamma=1$. Using the fact that $\tilde{\lambda}(0, \gamma)=0$, we get $\partial_{\lambda} \tilde{\lambda}(0, \gamma)=1+\frac{\partial_{\lambda} \tilde{\lambda}(0, \gamma)}{\gamma}$, hence $\partial_{\lambda} \tilde{\lambda}(0, \gamma)=\frac{\gamma}{\gamma-1}$.
(2) From the first point of Proposition C.10, $\tilde{\lambda} \sim \lambda$ as $\lambda \gamma \rightarrow \infty$. Since Equation (13) can be expressed as:

$$
\partial_{\lambda} \tilde{\lambda}\left(1-\frac{1}{\gamma \lambda} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i}}{\frac{\tilde{\lambda}}{\lambda}+d_{i}}+\frac{1}{\gamma \lambda} \frac{\tilde{\lambda}}{\lambda} \frac{1}{N} \sum_{i=1}^{N} \frac{d_{i}}{\left(\frac{\tilde{\lambda}}{\lambda}+d_{i}\right)^{2}}\right)=1
$$

we obtain that $\partial_{\lambda} \tilde{\lambda} \rightarrow 1$ as $\lambda \rightarrow \infty$.

## C.3.3. VARIANCE OF THE PREDICTOR

By the bias-variance decomposition, in order to bound the difference between $\mathbb{E}\left[L\left(\hat{f}_{\gamma, \lambda}^{(R F)}\right)\right]$ and $L\left(\hat{f}_{\tilde{\lambda}}^{(K)}\right.$, we have to bound $\mathbb{E}_{\mathcal{D}}[\operatorname{Var}(f(x))]$. The law of total variance yields $\operatorname{Var}(\hat{f}(x))=\operatorname{Var}(\mathbb{E}[\hat{f}(x) \mid F])+\mathbb{E}[\operatorname{Var}[\hat{f}(x) \mid F]]$. By Proposition C.1, we have $\mathbb{E}[\hat{f}(x) \mid F]=K(x, X) K(X, X)^{-1} \hat{y}$ and $\operatorname{Var}[\hat{f}(x) \mid F]=\frac{1}{P}\|\hat{\theta}\|^{2} \tilde{K}(x, x)$. Hence, it remains to study $\operatorname{Var}\left(K(x, X) K(X, X)^{-1} \hat{y}\right)$ and $\mathbb{E}\left[\|\hat{\theta}\|^{2}\right]$. Recall that we denote $T=\frac{1}{N} \operatorname{Tr} K(X, X)$.
This section is dedicated to the proof of the variance bound of Theorem 5.1 of the paper:
Theorem 5.1 There are constants $c_{1}, c_{2}>0$ depending on $\lambda, \gamma, T$ only such that

$$
\begin{aligned}
& \operatorname{Var}\left(K(x, X) K(X, X)^{-1} \hat{y}\right) \leq \frac{c_{1} K(x, x)\|y\|_{K^{-1}}^{2}}{P} \\
& \left|\mathbb{E} \|\left[\hat{\theta} \|^{2}\right]-\partial_{\lambda} \tilde{\lambda} y^{T} M_{\tilde{\lambda}} y\right| \leq \frac{c_{2}\|y\|_{K^{-1}}^{2}}{P}
\end{aligned}
$$

where $\partial_{\lambda} \tilde{\lambda}$ is the derivative of $\tilde{\lambda}$ with respect to $\lambda$ and for $M_{\tilde{\lambda}}=K(X, X)\left(K(X, X)+\tilde{\lambda} I_{N}\right)^{-2}$. As a result

$$
\operatorname{Var}\left(\hat{f}_{\lambda}^{(R F)}(x)\right) \leq \frac{c_{3} K(x, x)\|y\|_{K^{-1}}^{2}}{P}
$$

where $c_{3}>0$ depends on $\lambda, \gamma, T$.

- Bound on $\operatorname{Var}\left(K(x, X) K(X, X)^{-1} \hat{y}\right)$. We first study the covariance of the entries of the matrix

$$
A_{\lambda}=\frac{1}{P} K^{\frac{1}{2}} W^{T}\left(\frac{1}{P} W K W^{T}+\lambda \mathrm{I}_{P}\right)^{-1} W K^{\frac{1}{2}}
$$

where $K=\operatorname{diag}\left(d_{1}, \ldots, d_{N}\right)$ is a positive definite diagonal matrix and $W$ is a $P \times N$ matrix with i.i.d. Gaussian entries. In the next proposition we show a $\frac{c_{1}}{P}$ bound for the covariance of the entries of $A_{\lambda}$, then we exploit this result in order to prove the bound on the variance of $K(x, X) K(X, X)^{-1} \hat{y}$.

Proposition C.12. There exists a constant $c_{1}^{\prime}>0$ depending on $\lambda, \gamma$, and $\frac{1}{N} \operatorname{Tr}(K)$ only, such that the following bounds hold:

$$
\begin{aligned}
\left|\operatorname{Cov}\left(\left(A_{\lambda}\right)_{i i},\left(A_{\lambda}\right)_{j j}\right)\right| & \leq \frac{c_{1}^{\prime}}{P} \\
\operatorname{Var}\left(\left(A_{\lambda}\right)_{i j}\right) & \leq \min \left\{\frac{d_{i}}{d_{j}}, \frac{d_{j}}{d_{i}}\right\} \frac{c_{1}^{\prime}}{P}
\end{aligned}
$$

For all other cases (i.e. if $i, j, k$ and $l$ take more than two different values), $\operatorname{Cov}\left(\left(A_{\lambda}\right)_{i j},\left(A_{\lambda}\right)_{k l}\right)=0$.

Proof. We want to study the covariances $\operatorname{Cov}\left(\left(A_{\lambda}\right)_{i j},\left(A_{\lambda}\right)_{k l}\right)$ for any $i, j, k, l$. Using the same symmetry argument as in the proof of Proposition C.7, $\mathbb{E}\left[\left(A_{\lambda}\right)_{i j}\left(A_{\lambda}\right)_{k l}\right]=0$ whenever each value in $\{i, j, k, l\}$ does not appear an even number of times in $(i, j, k, l)$. Using the fact that $A_{\lambda}$ is symmetric, it remains to study $\operatorname{Cov}\left(\left(A_{\lambda}\right)_{i i},\left(A_{\lambda}\right)_{j j}\right), \operatorname{Var}\left(\left(A_{\lambda}\right)_{i i}\right)$ and $\operatorname{Var}\left[\left(A_{\lambda}\right)_{i j}\right]$ for all $i \neq j$. By the Cauchy-Schwarz inequality, any bound on $\operatorname{Var}\left(\left(A_{\lambda}\right)_{i i}\right)$ will imply a similar bound on $\operatorname{Cov}\left(\left(A_{\lambda}\right)_{i i},\left(A_{\lambda}\right)_{j j}\right)$. Besides, as we have seen in the proof of Proposition C.7, $\mathbb{E}\left[\left(A_{\lambda}\right)_{i j}\right]=0$ for any $i \neq j$. Thus, we only have to study $\operatorname{Var}\left(\left(A_{\lambda}\right)_{i i}\right)$ and $\mathbb{E}\left[\left(A_{\lambda}\right)_{i j}^{2}\right]$.

- Bound on $\operatorname{Var}\left(\left(A_{\lambda}\right)_{i i}\right)$ : From Equation (9),

$$
\operatorname{Var}\left(\left(A_{\lambda}\right)_{i i}\right)=\operatorname{Var}\left(\frac{d_{i} g_{i}}{1+d_{i} g_{i}}\right)=\operatorname{Var}\left(1-\frac{1}{1+d_{i} g_{i}}\right)=\operatorname{Var}\left(\frac{1}{1+d_{i} g_{i}}\right) \leq \mathbb{E}\left[\left(\frac{1}{1+d_{i} g_{i}}-\frac{1}{1+d_{i} \tilde{m}}\right)^{2}\right]
$$

where $g_{i}:=g_{i}(-\lambda)$. Again, we use the first order Taylor approximation $\mathrm{T} h$ of $h: x \rightarrow \frac{1}{1+d_{i} x}$ centered at $\tilde{m}:=\tilde{m}(-\lambda)$, as
well as the bound (7), to obtain

$$
\begin{aligned}
\mathbb{E}\left[\left(\frac{1}{1+d_{i} g_{i}}-\frac{1}{1+d_{i} \tilde{m}}\right)^{2}\right] & =\mathbb{E}\left[\left(-\frac{d_{i}}{\left(1+d_{i} \tilde{m}\right)^{2}}\left(g_{i}-\tilde{m}\right)+h\left(g_{i}\right)-\mathrm{T} h\left(g_{i}\right)\right)^{2}\right] \\
& \leq \frac{2 d_{i}^{2}}{\left(1+d_{i} \tilde{m}\right)^{4}} \mathbb{E}\left[\left(g_{i}-\tilde{m}\right)^{2}\right]+2 \mathbb{E}\left[\left(h\left(g_{i}\right)-\mathrm{T} h\left(g_{i}\right)\right)^{2}\right] \\
& \leq \frac{2}{6 \tilde{m}^{2}} \mathbb{E}\left[\left(g_{i}-\tilde{m}\right)^{2}\right]+\frac{2}{\tilde{m}^{4}} \mathbb{E}\left[\left(g_{i}-\tilde{m}\right)^{4}\right]
\end{aligned}
$$

Using Lemma C.4, we get $\operatorname{Var}\left(\left(A_{\lambda}\right)_{i i}\right) \leq \frac{c_{1}^{\prime}}{P}$, where $c_{1}^{\prime}>0$ depends on $\lambda, \gamma$, and $\frac{1}{N} \operatorname{Tr}(K)$ only.

- Bound on $\mathbb{E}\left(\left(A_{\lambda}\right)_{i j}\right)$ for $i \neq j$ : Following the same arguments as for Equation (9), $\left(A_{\lambda}\right)_{i j}$ is equal to

$$
\left(A_{\lambda}\right)_{i j}=\frac{\sqrt{d_{i} d_{j}}}{P}\left[w_{i}^{T} B_{(i)}^{-1} w_{j}-\frac{d_{i} g_{i}}{1+d_{i} g_{i}} w_{i}^{T} B_{(i)}^{-1} w_{j}\right]=\frac{\sqrt{d_{i} d_{j}}}{1+d_{i} g_{i}} \frac{1}{P} w_{i}^{T} B_{(i)}^{-1} w_{j}
$$

where we set $B_{(i)}:=B_{i}(-\lambda)$. Since $w_{i}$ and $B_{(i)}$ are independent, $\mathbb{E}\left[\left(w_{i}^{T} B_{(i)}^{-1} w_{j}\right)^{2}\right]=\mathbb{E}\left[w_{j}^{T} B_{(i)}^{-2} w_{j}\right]$, and thus, by the Cauchy-Schwarz inequality, we have

$$
\begin{equation*}
\mathbb{E}\left[\left(A_{\lambda}\right)_{i j}^{2}\right] \leq \frac{1}{P^{2}} \sqrt{\mathbb{E}\left[\frac{d_{i}^{2} d_{j}^{2}}{\left(1+d_{i} g_{i}\right)^{4}}\right]} \sqrt{\mathbb{E}\left[\left(w_{j}^{T} B_{(i)}^{-2} w_{j}\right)^{2}\right]} \tag{14}
\end{equation*}
$$

Recall that $\tilde{m}:=\tilde{m}(-\lambda)$. Using the fact that $\frac{1}{1+d_{i} g_{i}}=\frac{1}{1+d_{i} \tilde{m}}+\frac{1}{1+d_{i} g_{i}}-\frac{1}{1+d_{i} \tilde{m}}$ and inserting the first Taylor approximation Th of $h: x \rightarrow \frac{1}{1+d_{i} x}$ centered at $\tilde{m}$, we get:

$$
\mathbb{E}\left[\left(\frac{1}{1+d_{i} g_{i}}\right)^{4}\right]=\mathbb{E}\left[\left(\frac{1}{1+d_{i} \tilde{m}}-\frac{d_{i}}{\left(1+d_{i} \tilde{m}\right)^{2}}\left(g_{i}-\tilde{m}\right)+h\left(g_{i}\right)-\mathrm{Th}\left(g_{i}\right)\right)^{4}\right]
$$

Using a convexity argument, the bound (7), and the lower bound on $\tilde{m}$ given by Lemma C.6, there exists three constants $\tilde{c}_{1}$, $\tilde{c}_{2}, \tilde{c}_{3}$, which depend on $\lambda, \gamma$ and $\frac{1}{N} \operatorname{Tr}(K)$ only, such that $\mathbb{E}\left[\left(\frac{1}{1+d_{i} g_{i}}\right)^{4}\right]$ is bounded by

$$
\frac{\tilde{c}_{1}}{\left(1+d_{i} \tilde{m}\right)^{4}}+\frac{\tilde{c}_{2} d_{i}^{4}}{\left(1+d_{i} \tilde{m}\right)^{8}} \mathbb{E}\left[\left(g_{i}-\tilde{m}\right)^{4}\right]+\tilde{c}_{3} \mathbb{E}\left[\left(g_{i}-\tilde{m}\right)^{8}\right]
$$

Thanks to Lemma C. 4 and Proposition C.5, this last expression can be bounded by an expression of the form $\frac{\tilde{e}_{1}}{d_{i}^{4}}+\frac{\tilde{e}_{2}}{P^{2} d_{i}^{4}}+\frac{\tilde{e}_{3}}{P^{4}}$. Note that $\frac{\tilde{e}_{2}}{P^{2} d_{i}^{4}} \leq \frac{\tilde{e}_{2}}{d_{i}^{4}}$ and $\frac{\tilde{e}_{3}}{P^{4}} \leq \frac{\tilde{e}_{3}}{\gamma^{4}} \frac{\left(\frac{1}{N} \operatorname{Tr}(K)\right)^{4}}{d_{i}^{4}}$. Hence, we obtain the bound:

$$
\mathbb{E}\left[\left(\frac{1}{1+d_{i} g_{i}}\right)^{4}\right] \leq \frac{\tilde{c}}{d_{i}^{4}}
$$

where $\tilde{c}=\tilde{e}_{1}+\tilde{e}_{2}+\frac{\left.\tilde{e}_{3}\left(\frac{1}{N} \operatorname{Tr}(K)\right)^{4}\right)}{\gamma^{4}}$ depends on $\lambda, \gamma$ and and $\frac{1}{N} \operatorname{Tr}(K)$ only.
Let us now consider the second term in the r.h.s. of (14). Using the fact that $\left\|B_{(i)}\right\|_{o p} \geq \frac{1}{\lambda}$, we get

$$
\sqrt{\mathbb{E}\left[\left(w_{j}^{T} B_{(i)}^{-2} w_{j}\right)^{2}\right]} \leq \sqrt{\frac{1}{\lambda^{4}} \mathbb{E}\left[\left(w_{j}^{T} w_{j}\right)^{2}\right]}=\sqrt{\frac{1}{\lambda^{4}} N(N+2)} \leq \frac{N+1}{\lambda^{2}}
$$

where we have used the fact that the second moment of a $\chi^{2}(N)$ distribution is $N(N+2)$. Together, we obtain

$$
\begin{aligned}
\mathbb{E}\left[(A)_{i j}^{2}\right] & \leq \frac{1}{P^{2}} \sqrt{\mathbb{E}\left[\frac{d_{i}^{2} d_{j}^{2}}{\left(1+d_{i} g_{i}\right)^{4}}\right]} \sqrt{\mathbb{E}\left[\left(w_{j}^{T} B_{(i)}^{-2} w_{j}\right)^{2}\right]} \\
& \leq \frac{\tilde{c} d_{i} d_{j}}{d_{i}^{2}} \frac{N+1}{P^{2} \lambda^{2}} \\
& \leq \frac{\tilde{c} d_{j}}{P d_{i} \lambda^{2} \gamma} \frac{N+1}{N} \leq \frac{c_{1}^{\prime}}{P} \frac{d_{i}}{d_{j}}
\end{aligned}
$$

for $c_{1}^{\prime}=2 \frac{\tilde{c}}{\lambda^{2} \gamma}$. Since the matrix $A_{\lambda}$ is symmetric, we finally conclude that

$$
\mathbb{E}\left[\left(A_{\lambda}\right)_{i j}^{2}\right] \leq \frac{c_{1}^{\prime}}{P} \min \left\{\frac{d_{i}}{d_{j}}, \frac{d_{j}}{d_{i}}\right\}
$$

Note that $c_{1}^{\prime}$ is a constant related to the bounds constructed in Lemma C. 2 and Proposition C. 5 and as such it depends on $\frac{1}{N} \operatorname{Tr}(K), \gamma$ and $\lambda$ only.
Proposition C.13. There exists a constant $c_{1}>0$ (depending on $\lambda, \gamma, T$ only) such that the variance of the estimator is bounded by

$$
\operatorname{Var}\left(K(x, X) K(X, X)^{-1} \hat{y}\right) \leq \frac{c_{1}\|y\|_{K^{-1}}^{2} K(x, x)}{P}
$$

Proof. As in the proof of Theorem C.8, with the right change of basis, we may assume the Gram matrix $K(X, X)$ to be diagonal.
We first express the covariances of $\hat{y}=A(-\lambda) y$. Using Proposition Proposition C.12, for $i \neq j$ we have

$$
\operatorname{Cov}\left(\hat{y}_{i}, \hat{y}_{j}\right)=\sum_{k, l=1}^{N} \operatorname{Cov}\left(\left(A_{\lambda}\right)_{i k},\left(A_{\lambda}\right)_{l j}\right) y_{k} y_{l}=\operatorname{Cov}\left(\left(A_{\lambda}\right)_{i i},\left(A_{\lambda}\right)_{j j}\right) y_{i} y_{j}+\mathbb{E}\left[\left(A_{\lambda}\right)_{i j}^{2}\right] y_{j} y_{i}
$$

whereas for $i=j$ we have

$$
\operatorname{Cov}\left(\hat{y}_{i}, \hat{y}_{i}\right)=\sum_{k=1}^{N} \operatorname{Cov}\left(\left(A_{\lambda}\right)_{i k},\left(A_{\lambda}\right)_{k i}\right) y_{k}^{2}=\operatorname{Var}\left(\left(A_{\lambda}\right)_{i i}\right) y_{i}^{2}+\sum_{k \neq i} \mathbb{E}\left[\left(A_{\lambda}\right)_{i k}^{2}\right] y_{k}^{2}
$$

We decompose $K^{-\frac{1}{2}} \operatorname{Cov}(\hat{y}, \hat{y}) K^{-\frac{1}{2}}$ into two terms: let $C$ be the matrix of entries

$$
C_{i j}=\frac{\operatorname{Cov}\left(\left(A_{\lambda}\right)_{i i},\left(A_{\lambda}\right)_{j j}\right)+\delta_{i \neq j} \mathbb{E}\left[\left(A_{\lambda}\right)_{i j}^{2}\right]}{\sqrt{d_{i} d_{j}}} y_{i} y_{j}
$$

and let $D$ the diagonal matrix with entries

$$
D_{i i}=\frac{\sum_{k \neq i} \mathbb{E}\left[\left(A_{\lambda}\right)_{i k}^{2}\right] y_{k}^{2}}{d_{i}}
$$

We have the decomposition $K^{-\frac{1}{2}} \operatorname{Cov}(\hat{y}, \hat{y}) K^{-\frac{1}{2}}=C+D$.
Proposition C. 12 asserts that $\operatorname{Cov}\left(\left(A_{\lambda}\right)_{i i},\left(A_{\lambda}\right)_{j j} \leq \frac{c_{1}^{\prime}}{P}\right.$ and $\mathbb{E}\left[\left(A_{\lambda}\right)_{i j}^{2}\right] \leq \frac{c_{1}^{\prime}}{P}$, and thus the operator norm of $C$ is bounded by

$$
\begin{aligned}
\|C\|_{o p} & \leq\|C\|_{F} \\
& =\sqrt{\sum_{i, j} \frac{\left(\operatorname{Cov}\left(\left(A_{\lambda}\right)_{i i},\left(A_{\lambda}\right)_{j j}\right)+\delta_{i \neq j} \mathbb{E}\left[\left(A_{\lambda}\right)_{i j}^{2}\right]\right)^{2}}{d_{i} d_{j}} y_{i}^{2} y_{j}^{2}} \\
& \leq \frac{2 c_{1}^{\prime}}{P} \sqrt{\sum_{i j} \frac{1}{d_{i} d_{j}} y_{i}^{2} y_{j}^{2}}=\frac{2 c_{1}^{\prime}\|y\|_{K^{-1}}^{2}}{P}
\end{aligned}
$$

For the matrix $D$, we use the bound $\mathbb{E}\left[\left(A_{\lambda}\right)_{i k}^{2}\right] \leq \frac{c_{1}^{\prime}}{P} \frac{d_{i}}{d_{k}}$ to obtain

$$
D_{i i}=\frac{\sum_{k \neq i} \mathbb{E}\left[\left(A_{\lambda}\right)_{i k}^{2}\right] y_{k}^{2}}{d_{i}} \leq \frac{c_{1}^{\prime}}{P} \sum_{k \neq i} \frac{y_{k}^{2}}{d_{k}} \leq \frac{c_{1}^{\prime}\|y\|_{K^{-1}}^{2}}{P}
$$

which implies that $\|D\|_{o p} \leq \frac{c_{1}^{\prime}\|y\|_{K^{-1}}^{2}}{P}$. As a result

$$
\begin{aligned}
\operatorname{Var}\left(K(x, X) K^{-1} \hat{y}\right) & =K(x, X) K^{-1} \operatorname{Cov}(\hat{y}, \hat{y}) K^{-1} K(X, x) \\
& \leq K(x, X) K^{-\frac{1}{2}}\|C+D\|_{o p} K^{-\frac{1}{2}} K(X, x) \\
& \leq \frac{3 c_{1}^{\prime}\|y\|_{K^{-1}}^{2}}{P}\|K(x, X)\|_{K^{-1}}^{2} \\
& \leq \frac{3 c_{1}^{\prime} K(x, x)\|y\|_{K^{-1}}^{2}}{P}
\end{aligned}
$$

where we used Inequality (12). This yields the result with $c_{1}=3 c_{1}^{\prime}$.

- Bound on $\mathbb{E}_{\pi}\left[\|\hat{\theta}\|^{2}\right]$. To understand the variance of the $\lambda$-RF estimator $\hat{f}_{\lambda}^{(R F)}$, we need to describe the distribution of the squared norm of the parameters:

Proposition C.14. For $\gamma, \lambda>0$ there exists a constant $c_{2}>0$ depending on $\lambda, \gamma, T$ only such that

$$
\begin{equation*}
\left|\mathbb{E}\left[\|\hat{\theta}\|^{2}\right]-\partial_{\lambda} \tilde{\lambda} y^{T} K(X, X)\left(K(X, X)+\tilde{\lambda} I_{N}\right)^{-2} y\right| \leq \frac{c_{2}\|y\|_{K^{-1}}^{2}}{P} \tag{15}
\end{equation*}
$$

Proof. As in the proof of Theorem C.8, with the right change of basis, we may assume the Gram matrix $K(X, X)$ to be diagonal. Recall that $\hat{\theta}=\frac{1}{\sqrt{P}}\left(\frac{1}{P} W K(X, X) W^{T}+\lambda I_{N}\right)^{-1} W K(X, X)^{\frac{1}{2}} y$, thus we have:

$$
\begin{equation*}
\|\hat{\theta}\|^{2}=\frac{1}{P} y^{T} K(X, X)^{\frac{1}{2}} W^{T}\left(\frac{1}{P} W K(X, X) W^{T}+\lambda I_{P}\right)^{-2} W K(X, X)^{\frac{1}{2}} y=y^{T} A^{\prime}(-\lambda) y \tag{16}
\end{equation*}
$$

where $A^{\prime}(-\lambda)$ is the derivative of

$$
A(z)=\frac{1}{P} K(X, X)^{\frac{1}{2}} W^{T}\left(\frac{1}{P} W K(X, X) W^{T}-z \mathrm{I}_{P}\right)^{-1} W K(X, X)^{\frac{1}{2}}
$$

with respect to $z$ evaluated at $-\lambda$. Let

$$
\tilde{A}(z)=K(X, X)\left(K(X, X)+\tilde{\lambda}(-z) \mathrm{I}_{N}\right)^{-1}
$$

Remark that the derivative of $\tilde{A}(z)$ is given by $\tilde{A}^{\prime}(z)=\tilde{\lambda}^{\prime}(-z) K(X, X)\left(K(X, X)+\tilde{\lambda}(-z) I_{N}\right)^{-2}$. Thus, from Equation (16), the l.h.s. of (15) is equal to:

$$
\begin{equation*}
\left|y^{T}\left(\mathbb{E}\left[A^{\prime}(-\lambda)\right]-\tilde{A}^{\prime}(-\lambda)\right) y\right| \tag{17}
\end{equation*}
$$

Using a classical complex analysis argument, we will show that $\mathbb{E}\left[A^{\prime}(-\lambda)\right]$ is close to $\tilde{A}^{\prime}(-\lambda)$ by proving a bound of the difference between $\mathbb{E}[A(z)]$ and $\tilde{A}(z)$ for any $z \in \mathbb{H}_{<0}$.
Note that the proof of Proposition C. 7 provides a bound on the diagonal entries of $\mathbb{E}[A(z)]$, namely that for any $z \in \mathbb{H}_{<0}$,

$$
\left|\mathbb{E}\left[(A(z))_{i i}\right]-(\tilde{A}(z))_{i i}\right| \leq \frac{c}{P}
$$

where $\hat{c}$ depends on $z, \gamma$ and $T$ only. Actually, in order to prove (15), we will derive the following slightly different bound: for any $z \in \mathbb{H}_{<0}$,

$$
\begin{equation*}
\left|\mathbb{E}\left[(A(z))_{i i}\right]-(\tilde{A}(z))_{i i}\right| \leq \frac{\hat{c}}{d_{i} P} \tag{18}
\end{equation*}
$$

where $\hat{c}$ depends on $z, \gamma$ and $T$ only. Let $g_{i}:=g_{i}(z)$ and $\tilde{m}:=\tilde{m}(z)$. Recall that for $h_{i}: x \mapsto \frac{d_{i} x}{1+d_{i} x}$, one has $(A(z))_{i i}=h_{i}\left(g_{i}\right),(\tilde{A}(z))_{i i}=h_{i}(\tilde{m})$ and

$$
\begin{aligned}
\mathrm{T}_{\tilde{m}} h_{i}\left(g_{i}\right) & =\frac{d_{i} \tilde{m}}{1+d_{i} \tilde{m}}-\frac{d_{i}\left(g_{i}-\tilde{m}\right)}{\left(1+d_{i} \tilde{m}\right)^{2}} \\
h_{i}\left(g_{i}\right)-\mathrm{T}_{\tilde{m}} h_{i}\left(g_{i}\right) & =\frac{d_{i}^{2}\left(g_{i}-\tilde{m}\right)^{2}}{\left(1+d_{i} g_{i}\right)\left(1+d_{i} \tilde{m}\right)^{2}}
\end{aligned}
$$

where $\mathrm{T}_{\tilde{m}} h_{i}$ is the first order Taylor approximation of $h_{i}$ centered at $\tilde{m}$. Using this first order Taylor approximation, we can bound the difference $\left|\mathbb{E}\left[h_{i}\left(g_{i}\right)\right]-h_{i}(\tilde{m})\right|$ :

$$
\begin{aligned}
\left|\mathbb{E}\left[h_{i}\left(g_{i}\right)\right]-h_{i}(\tilde{m})\right| & \leq \frac{d_{i}\left|\mathbb{E}\left[g_{i}\right]-\tilde{m}\right|}{\left(1+d_{i} \tilde{m}\right)^{2}}+\frac{d_{i}^{2}}{\left(1+d_{i} \tilde{m}\right)^{2}} \mathbb{E}\left[\frac{\left|g_{i}-\tilde{m}\right|^{2}}{1+d_{i} g_{i}}\right] \\
& \leq \frac{\mathbf{a}}{d_{i} P}+\mathbf{a} \sqrt{\mathbb{E}\left[\frac{1}{\left(1+d_{i} g_{i}\right)^{2}}\right] \mathbb{E}\left[\left|g_{i}-\tilde{m}\right|^{4}\right]}
\end{aligned}
$$

where a depends on $z, \gamma$ and $T$. We need to bound $\mathbb{E}\left[\frac{1}{\left(1+d_{i} g_{i}\right)^{2}}\right]$. Recall that in the proof of Proposition C.12, we bounded $\mathbb{E}\left[\frac{1}{\left(1+d_{i} g_{i}\right)^{4}}\right]$. Using similar arguments, one shows that

$$
\mathbb{E}\left[\frac{1}{\left(1+d_{i} g_{i}\right)^{2}}\right] \leq \frac{\hat{e}^{2}}{d_{i}^{2}}
$$

where $\hat{e}$ depends on $z, \gamma$ and $\frac{1}{N} \operatorname{Tr}(K(X, X))$ only. The term $\mathbb{E}\left[\left|g_{i}-\tilde{m}\right|^{4}\right]$ is bounded using Lemmas C.4, C. 2 and Proposition C.5. This allows us to conclude that:

$$
\left|\mathbb{E}\left[h_{i}\left(g_{i}\right)\right]-h_{i}(\tilde{m})\right| \leq \frac{\hat{c}}{d_{i} P}
$$

where $\hat{c}$ depends on $z, \gamma$ and $\frac{1}{N} \operatorname{Tr}(K(X, X))$ only, hence we obtain the Inequality (18).
We can now prove Inequality 15 . We bound the difference of the derivatives of the diagonal terms of $A(z)$ and $\tilde{A}(z)$ by means of Cauchy formula. Consider a simple closed path $\phi:[0,1] \rightarrow \mathbb{H}_{<0}$ which surrounds $z$. Since

$$
\mathbb{E}\left[\left(A^{\prime}(z)\right)_{i i}\right]-\left(\tilde{A}^{\prime}(z)\right)_{i i}=\frac{1}{2 \pi i} \oint_{\phi} \frac{\mathbb{E}\left[(A(z))_{i i}\right]-(\tilde{A}(z))_{i i}}{(w-z)^{2}} d w
$$

using the bound (18), we have:

$$
\left|\mathbb{E}\left[\left(A^{\prime}(z)\right)_{i i}\right]-\left(\tilde{A}^{\prime}(z)\right)_{i i}\right| \leq \frac{\hat{c}}{d_{i} P} \frac{1}{2 \pi} \oint_{\phi} \frac{1}{|w-z|^{2}} d w \leq \frac{c_{2}}{d_{i} P}
$$

where $c_{2}$ depends on $z, \gamma$, and $T$ only. This allows one to bound the operator norm of $K(X, X)\left(\mathbb{E}\left[A^{\prime}(z)\right]-\tilde{A}^{\prime}(z)\right)$ :

$$
\left\|K(X, X)\left(\mathbb{E}\left[A^{\prime}(z)\right]-\tilde{A}^{\prime}(z)\right)\right\|_{o p} \leq \frac{c_{2}}{P}
$$

Using this bound and (17), we have

$$
\left|\mathbb{E}\left[\|\hat{\theta}\|^{2}\right]-\partial_{\lambda} \tilde{\lambda} y^{T} K(X, X)\left(K(X, X)+\tilde{\lambda} I_{N}\right)^{-2} y\right|=\left|y^{T}\left(\mathbb{E}\left[A^{\prime}(-\lambda)\right]-\tilde{A}^{\prime}(-\lambda)\right) y\right| \leq \frac{c_{2}\|y\|_{K^{-1}}^{2}}{P}
$$

which allows us to conclude.

- Bound on $\operatorname{Var}\left(\hat{f}_{\lambda}^{(R F)}(x)\right)$. We have shown all the bounds needed in order to prove the following proposition.

Proposition C.15. For any $x \in \mathbb{R}^{d}$, we have

$$
\operatorname{Var}\left(\hat{f}_{\lambda}^{(R F)}(x)\right) \leq \frac{c_{3} K(x, x)\|y\|_{K^{-1}}^{2}}{P}
$$

where $c_{3}>0$ depends on $\lambda, \gamma, T$.
Proof. Recall that for any $x \in \mathbb{R}^{d}$,

$$
\begin{aligned}
\operatorname{Var}\left(\hat{f}_{\lambda}^{(R F)}(x)\right) & =\operatorname{Var}\left(\mathbb{E}\left[\hat{f}_{\lambda}^{(R F)}(x) \mid F\right]\right)+\mathbb{E}\left[\operatorname{Var}\left[\hat{f}_{\lambda}^{(R F)}(x) \mid F\right]\right] \\
& =\operatorname{Var}\left(K(x, X) K(X, X)^{-1} \hat{y}\right)+\frac{1}{P} \mathbb{E}\left[\|\hat{\theta}\|^{2}\right]\left[K(x, x)-K(x, X) K(X, X)^{-1} K(X, x)\right]
\end{aligned}
$$

From Proposition C.13,

$$
\operatorname{Var}\left(K(x, X) K(X, X)^{-1} \hat{y}\right) \leq \frac{c_{1} K(x, x)\|y\|_{K^{-1}}^{2}}{P}
$$

and from Proposition C.14, we have:

$$
\mathbb{E}\left[\|\hat{\theta}\|^{2}\right] \leq \partial_{\lambda} \tilde{\lambda} y^{T} K\left(K+\tilde{\lambda} I_{N}\right)^{-2} y+\frac{c_{2}\|y\|_{K^{-1}}^{2}}{P} \leq \partial_{\lambda} \tilde{\lambda}\|y\|_{K^{-1}}^{2}+\frac{c_{2}\|y\|_{K^{-1}}^{2}}{P} \leq \alpha\|y\|_{K^{-1}}^{2}
$$

where $\alpha=\partial_{\lambda} \tilde{\lambda}+c_{2}$. Using the fact that $\tilde{K}(x, x) \leq K(x, x)$, we get

$$
\begin{aligned}
\mathbb{E}[\operatorname{Var}[\hat{f}(x) \mid F]] & =\frac{1}{P} \mathbb{E}\left[\|\hat{\theta}\|^{2}\right]\left[K(x, x)-K(x, X) K(X, X)^{-1} K(X, x)\right] \\
& \leq \frac{\alpha\|y\|_{K^{-1}}^{2} K(x, x)}{P}
\end{aligned}
$$

This yields

$$
\operatorname{Var}\left(\hat{f}_{\lambda}^{(R F)}(x)\right) \leq \frac{c_{3}\|y\|_{K^{-1}}^{2} K(x, x)}{P}
$$

where $c_{3}=\alpha+c_{1}$.

## C.3.4. Average loss of $\lambda$-RF predictor and loss of $\tilde{\lambda}$-KRR:

Putting the pieces together, we obtain the following bound on the difference $\Delta_{E}=\left|\mathbb{E}\left[L\left(\hat{f}_{\lambda, \gamma}^{(R F)}\right)\right]-L\left(\hat{f}_{\tilde{\lambda}}^{(K)}\right)\right|$ between the expected RF loss and the KRR loss:
Corollary C.16. If $\mathbb{E}_{\mathcal{D}}[K(x, x)]<\infty$, we have

$$
\Delta_{E} \leq \frac{C_{1}\|y\|_{K^{-1}}}{P}\left(2 \sqrt{L\left(\hat{f}_{\tilde{\lambda}}^{(K)}\right)}+C_{2}\|y\|_{K^{-1}}\right)
$$

where $C_{1}$ and $C_{2}$ depend on $\lambda, \gamma, T$ and $\mathbb{E}_{\mathcal{D}}[K(x, x)]$ only.
Proof. Using the bias/variance decomposition, Corollary C.9, and the bound on the variance of the predictor, we obtain

$$
\begin{aligned}
\left|\mathbb{E}\left[L\left(\hat{f}_{\gamma, \lambda}^{(R F)}\right)\right]-L\left(\hat{f}_{\tilde{\lambda}}^{(K)}\right)\right| & \leq\left|L\left(\mathbb{E}\left[\hat{f}_{\gamma, \lambda}^{(R F)}\right]\right)-L\left(\hat{f}_{\tilde{\lambda}}^{(K)}\right)\right|+\mathbb{E}_{\mathcal{D}}[\operatorname{Var}(\hat{f}(x))] \\
& \leq \frac{C\|y\|_{K^{-1}}}{P}\left(2 \sqrt{L\left(\hat{f}_{\tilde{\lambda}}^{(K)}\right)}+\frac{C\|y\|_{K^{-1}}}{P}\right)+\frac{c_{3}\|y\|_{K^{-1}}^{2} \mathbb{E}_{\mathcal{D}}[K(x, x)]}{P} \\
& \leq \frac{C_{1}\|y\|_{K^{-1}}}{P}\left(2 \sqrt{L\left(\hat{f}_{\tilde{\lambda}}^{(K)}\right)}+C_{2}\|y\|_{K^{-1}}\right)
\end{aligned}
$$

where $C_{1}$ and $C_{2}$ depends on $\lambda, \gamma, T$ and $\mathbb{E}_{\mathcal{D}}[K(x, x)]$ only.

## C.3.5. Double descent curve

Recall that for any $\tilde{\lambda}$, we denote $M_{\tilde{\lambda}}=K(X, X)\left(K(X, X)+\tilde{\lambda} I_{N}\right)^{-2}$. A direct consequence of Proposition C. 14 is the following lower bound on the variance of the predictor.
Corollary C.17. There exists $c_{4}>0$ depending on $\lambda, \gamma, T$ only such that $\operatorname{Var}\left(\hat{f}_{\lambda}^{(R F)}(x)\right)$ is bounded from below by

$$
\partial_{\lambda} \tilde{\lambda} \frac{y^{T} M_{\tilde{\lambda}} y}{P} \tilde{K}(x, x)-\frac{c_{4} K(x, x)\|y\|_{K^{-1}}^{2}}{P^{2}}
$$

Proof. By the law of total cumulance,

$$
\operatorname{Var}\left(\hat{f}_{\lambda}^{(R F)}(x)\right) \geq \mathbb{E}\left[\operatorname{Var}\left[\hat{f}_{\lambda}^{(R F)}(x) \mid F\right]\right] \geq \frac{1}{P} \mathbb{E}\left[\|\hat{\theta}\|^{2}\right] \tilde{K}(x, x)
$$

From Proposition C. 14, $\mathbb{E}\left[\|\hat{\theta}\|^{2}\right] \geq \partial_{\lambda} \tilde{\lambda} y^{T} M_{\tilde{\lambda}} y-\frac{c_{2}\|y\|_{K^{-1}}^{2}}{P}$, hence

$$
\operatorname{Var}\left(\hat{f}_{\lambda}^{(R F)}(x)\right) \geq \partial_{\lambda} \tilde{\lambda} \frac{y^{T} M_{\tilde{\lambda}} y}{P} \tilde{K}(x, x)-\frac{c_{4} \tilde{K}(x, x)\|y\|_{K^{-1}}^{2}}{P^{2}}
$$

The result follows from the fact that $\tilde{K}(x, x) \leq K(x, x)$.

## References

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