

Appendix

1 Uncertainties

1.1 u^σ uncertainties

Here we present the u^σ values obtained from training the MuJoCo environments with parallel module composition. The results can be seen in Figure 1.

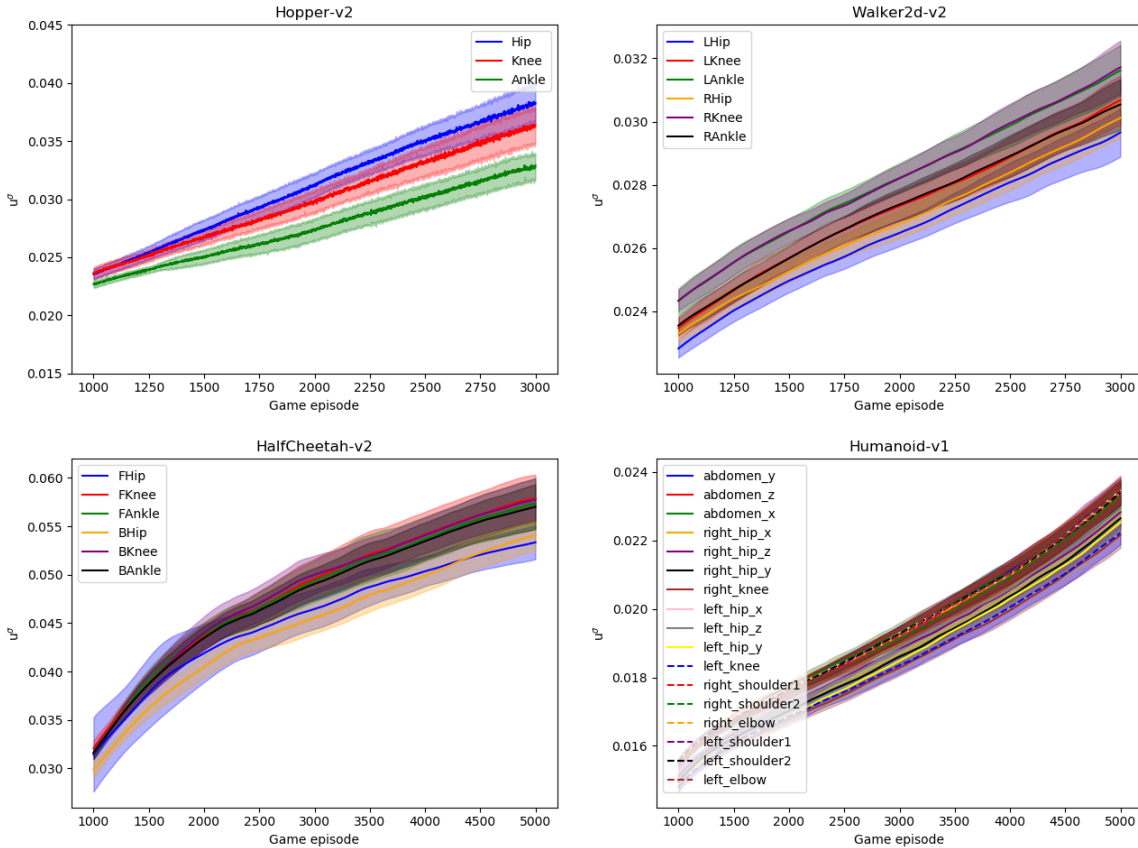


Figure 1: u^σ uncertainties for MuJoCo environments

1.2 u^q uncertainties

Here we present the u^q values obtained from training the MuJoCo environments with parallel module composition. The results can be seen in Figure 2.

2 Inferred structures

In Table 1 we present the compositional structures inferred from u^σ and u^q values. In Table 2 we present the configuration used to estimate the effect of the module composition.

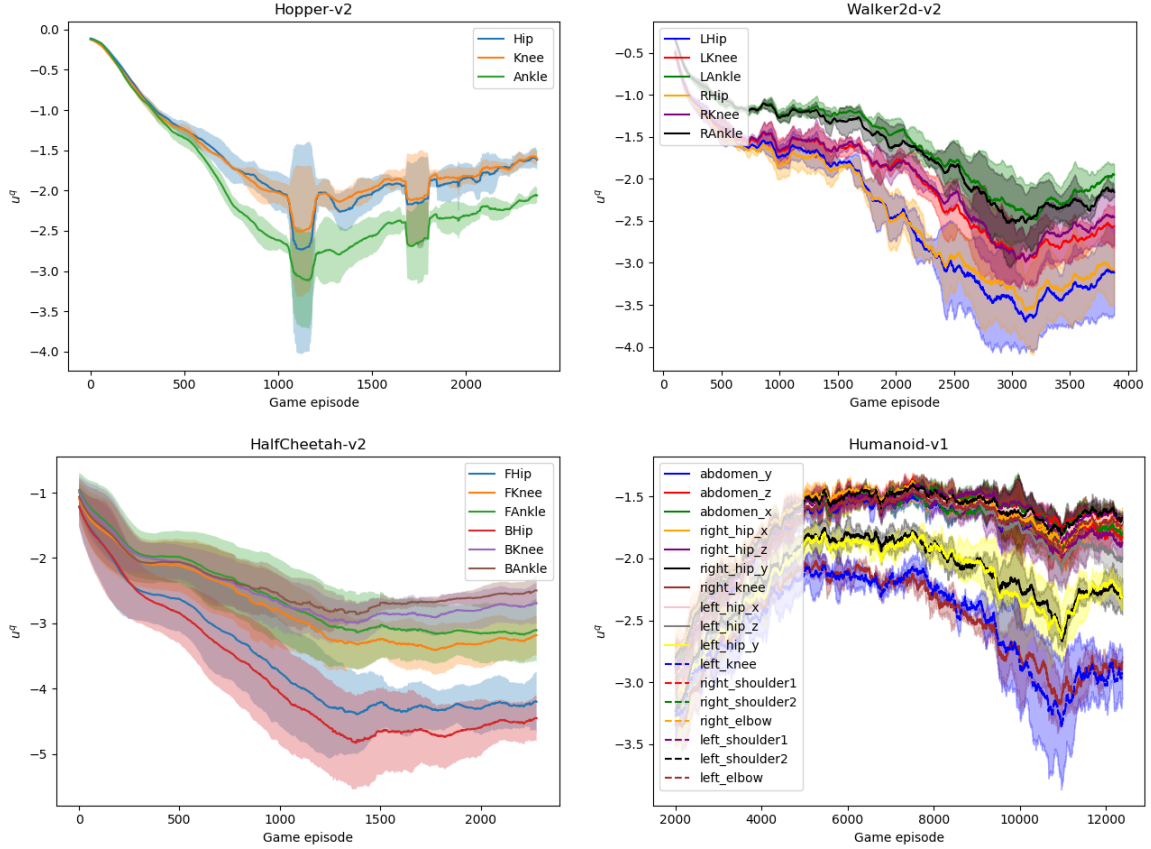


Figure 2: u^σ uncertainties for MuJoCo environments

	u^σ	u^q
Hopper	$\{\{\text{Ankle}\}, \{\text{Knee}, \text{Hip}\}\}$	$\{\{\text{Ankle}\}, \{\text{Knee}, \text{Hip}\}\}$
Walker2d	$\{\{\text{LHip}\}, \{\text{RHip}\}, \{\text{LKnee}, \text{RAnkle}\}, \{\text{LAnkle}, \text{RKnee}\}\}$	$\{\{\text{LHip}, \text{RHip}\}, \{\text{LKnee}, \text{RKnee}\}, \{\text{LAnkle}, \text{RAnkle}\}\}$
Cheetah	$\{\{\text{FHip}, \text{BHip}\}, \{\text{FKnee}, \text{BKnee}, \text{FAnkle}, \text{BAnkle}\}\}$	$\{\{\text{FHip}, \text{BHip}\}, \{\text{FKnee}, \text{BKnee}, \text{FAnkle}, \text{BAnkle}\}\}$
Humanoid	$\{\{\text{RKnee}, \text{LKnee}\}, \{\text{RHip}_y, \text{LHip}_y\}, \{\text{RHip}_z, \text{LHip}_z\}, \{\text{Abdomen}_x, \text{Abdomen}_y, \text{Abdomen}_z, \text{RHip}_x, \text{RShoulder1}, \text{RShoulder2}, \text{LHip}_x, \text{LShoulder1}, \text{LShoulder2}, \text{RElbow}, \text{LElbow}\}\}$	$\{\{\text{RKnee}, \text{LKnee}\}, \{\text{RHip}_y, \text{LHip}_y\}, \{\text{Abdomen}_x, \text{Abdomen}_y, \text{Abdomen}_z, \text{RHip}_x, \text{RHip}_z, \text{RShoulder2}, \text{LHip}_z, \text{RShoulder1}, \text{LHip}_x, \text{LShoulder1}, \text{LShoulder2}, \text{RElbow}, \text{LElbow}\}\}$

Table 1: Module composition structures (c) obtained as a result of clustering uncertainty estimations based on u^σ and u^q values.

	Real	Inversed u^σ	Inversed u^q
Hopper	$\{\{\text{Hip}\},\{\text{Knee}\},\{\text{Ankle}\}\}$	$\{\{\text{Knee,Hip}\},\{\text{Ankle}\}\}$	$\{\{\text{Knee,Hip}\},\{\text{Ankle}\}\}$
Walker2d	$\{\{\text{LHip,RHip}\},\{\text{LKnee,RKnee}\},\{\text{LAnkle,LAnkle}\}\}$	$\{\{\text{LAnkle,RKnee}\},\{\text{LKnee,RAnkle}\},\{\text{RHip}\},\{\text{LHip}\}\}$	$\{\{\text{LAnkle,RAnkle}\},\{\text{LKnee,RKnee}\},\{\text{LHip,RHip}\}\}$
Cheetah	$\{\{\text{FHip,BHip}\},\{\text{FKnee,BKnee}\},\{\text{FAnkle, BAnkle}\}\}$	$\{\{\text{FKnee,BKnee, FAnkle, BAnkle}\},\{\text{FHip,BHip}\}\}$	$\{\{\text{FKnee,BKnee, FAnkle, BAnkle}\},\{\text{FHip,BHip}\}\}$
Humanoid	$\{\{\text{RKnee,LKnee}\},\{\text{RHip}_x,\text{LHip}_x,\text{RHip}_y,\text{LHip}_y,\text{RHip}_z,\text{LHip}_z\},\{\text{Abdomen}_x,\text{Abdomen}_y,\text{Abdomen}_z\},\{\text{RShoulder1,RShoulder2,LShoulder1,LShoulder2}\},\{\text{RElbow,LElbow}\}\}$	$\{\{\text{Abdomen}_x,\text{Abdomen}_y,\text{Abdomen}_z,\text{RHip}_x,\text{RShoulder1,RShoulder2,LHip}_x,\text{LShoulder1,LShoulder2,RElbow,LElbow}\},\{\text{RHip}_z,\text{LHip}_z\},\{\text{RHip}_y,\text{LHip}_y\},\{\text{RKnee,LKnee}\}\}$	$\{\{\text{Abdomen}_x,\text{Abdomen}_y,\text{Abdomen}_z,\text{RHip}_x,\text{RHip}_z,\text{RShoulder2,LHip}_z,\text{RShoulder1,LHip}_x,\text{LShoulder1,LShoulder2,RElbow,LElbow}\},\{\text{RHip}_y,\text{LHip}_y\},\{\{\text{RKnee,LKnee}\}\}\}$

Table 2: Module composition structures (c) used to estimate the effect of the compositional structure.