# Supplementary Material of "Random Matrix Theory Proves that Deep Learning Representations of GAN-data Behave as Gaussian Mixtures" 

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#### Abstract

This supplementary material provides the proof of our main results, specifically a detailed proof for Theorem 3.3 and a proof for the Proposition 3.1.


## 1. Proof of Theorem 3.3

### 1.1. Setting of the proof

For simplicity, we will only suppose the case $k=1$ and we consider the following notations that will be used subsequently.

$$
\overline{\boldsymbol{x}}=\mathbb{E} \boldsymbol{x}_{i}, \boldsymbol{C}=\mathbb{E}\left[\boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top}\right], \quad \boldsymbol{X}_{0}=\boldsymbol{X}-\overline{\boldsymbol{x}} \mathbf{1}_{n}^{\top}, \boldsymbol{C}_{0}=\mathbb{E}\left[\boldsymbol{X}_{0} \boldsymbol{X}_{0}^{\boldsymbol{\top}} / n\right] .
$$

Let

$$
\boldsymbol{X}_{-i}=\left(\boldsymbol{x}_{1}, \ldots, \boldsymbol{x}_{i-1}, 0, \boldsymbol{x}_{i}, \ldots, \boldsymbol{x}_{n}\right)
$$

the matrix $X$ with a vector of zeros at its $i$ th column.
Denote the resolvents

$$
\begin{equation*}
\boldsymbol{R}=\left(\frac{\boldsymbol{X}^{\top} \boldsymbol{X}}{p}+z \boldsymbol{I}_{n}\right)^{-1}, \boldsymbol{Q}=\left(\frac{\boldsymbol{X} \boldsymbol{X}^{\boldsymbol{\top}}}{p}+z \boldsymbol{I}_{p}\right)^{-1}, \boldsymbol{Q}_{-i}=\left(\frac{\boldsymbol{X} \boldsymbol{X}^{\top}}{p}-\frac{\boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top}}{p}+z \boldsymbol{I}_{p}\right)^{-1} \tag{1}
\end{equation*}
$$

And let

$$
\begin{equation*}
\tilde{\boldsymbol{Q}}=\left(\frac{1}{c} \frac{\boldsymbol{C}}{1+\delta}+z \boldsymbol{I}_{p}\right)^{-1} \tag{2}
\end{equation*}
$$

where $\delta$ is the solution to the fixed point equation

$$
\delta=\frac{1}{p} \operatorname{tr}\left(\boldsymbol{C}\left(\frac{1}{c} \frac{\boldsymbol{C}}{1+\delta}+z \boldsymbol{I}_{p}\right)^{-1}\right)
$$

### 1.2. Basic tools

Lemma 1.1 ((Ledoux, 2005)). Let $\boldsymbol{z} \in \mathcal{E}_{q}\left(1 \mid \mathbb{R}^{p},\|\cdot\|\right)$ and $\boldsymbol{M} \in \mathcal{E}_{q}\left(1 \mid \mathbb{R}^{p \times n},\|\cdot\|_{F}\right)$. Then, for some numerical constant $C>0$

- $\mathbb{E}\|\boldsymbol{z}\| \leq\|\mathbb{E} \boldsymbol{z}\|+C \sqrt{p}, \mathbb{E}\|\boldsymbol{z}\|_{\infty} \leq\|\mathbb{E} \boldsymbol{z}\|_{\infty}+C \sqrt{\log p}$.
- $\mathbb{E}\|\boldsymbol{M}\| \leq\|\mathbb{E} \boldsymbol{M}\|+C \sqrt{p+n}, \mathbb{E}\|\boldsymbol{M}\|_{F} \leq\|\mathbb{E} \boldsymbol{M}\|_{F}+C \sqrt{p n}$.
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Lemma 1.2. Denote $\boldsymbol{Q}_{\overline{\boldsymbol{x}}}=\left(\overline{\boldsymbol{x}} \overline{\boldsymbol{x}}^{\boldsymbol{\top}}+z \boldsymbol{I}_{p}\right)^{-1}$, we have:

$$
\boldsymbol{Q}_{\bar{x}} \overline{\boldsymbol{x}}=\frac{\overline{\boldsymbol{x}}}{\|\overline{\boldsymbol{x}}\|^{2}+z} \text { and }\|\tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}\|, \overline{\boldsymbol{x}} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}=\mathcal{O}(1)
$$

Moreover, if $\|\overline{\boldsymbol{x}}\| \geq \sqrt{p},\|\tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}\|=\mathcal{O}\left(p^{-1 / 2}\right)$.
Proof. Since $z \boldsymbol{Q}_{\overline{\boldsymbol{x}}}=\boldsymbol{I}_{p}-\boldsymbol{Q}_{\overline{\boldsymbol{x}}} \overline{\boldsymbol{x}} \overline{\boldsymbol{x}}^{\top}$ :

$$
z \boldsymbol{Q}_{\bar{x}} \overline{\boldsymbol{x}}=\overline{\boldsymbol{x}}-\|\overline{\boldsymbol{x}}\|^{2} \boldsymbol{Q}_{\bar{x}} \overline{\boldsymbol{x}}
$$

and we recover the first identity of the Lemma.
And since the matrix $C_{0}$ is nonnegative symmetric, we have :

$$
\tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}=\left(\frac{1}{c} \frac{\boldsymbol{C}_{0}+\overline{\boldsymbol{x}} \overline{\boldsymbol{x}}^{\boldsymbol{\top}}}{1+\delta}+z \boldsymbol{I}_{p}\right)^{-1} \overline{\boldsymbol{x}} \leq \frac{c(1+\delta) \overline{\boldsymbol{x}}}{\|\overline{\boldsymbol{x}}\|^{2}+z c(1+\delta)} .
$$

Therefore, $\overline{\boldsymbol{x}} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}=\frac{c(1+\delta)\|\overline{\boldsymbol{x}}\|^{2}}{\|\overline{\boldsymbol{x}}\|^{2}+z c(1+\delta)}=\mathcal{O}(1)$ and:

$$
\|\tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}\|=\frac{c(1+\delta)\|\overline{\boldsymbol{x}}\|}{\|\overline{\boldsymbol{x}}\|^{2}+z c(1+\delta)} \leq\left\{\begin{array}{l}
\frac{\|\overline{\boldsymbol{x}}\|}{z}=\mathcal{O}(1) \text { if }\|\overline{\boldsymbol{x}}\| \leq 1 \\
\frac{c(1+\delta)}{\|\overline{\boldsymbol{x}}\|}=\mathcal{O}(1) \text { if }\|\overline{\boldsymbol{x}}\| \geq 1
\end{array}\right.
$$

Proposition 1.3. $\overline{\boldsymbol{x}}^{\top} \mathbb{E}[\boldsymbol{Q}] \overline{\boldsymbol{x}}=\overline{\boldsymbol{x}}^{\top} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}+\mathcal{O}\left(\sqrt{\frac{\log p}{p}}\right)$
Proof. Let us bound:

$$
\left|\overline{\boldsymbol{x}}^{\top} \boldsymbol{Q} \overline{\boldsymbol{x}}-\overline{\boldsymbol{x}}^{\top} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}\right| \leq \frac{c^{-1}}{1+\delta}\left|\mathbb{E}\left[\overline{\boldsymbol{x}} \boldsymbol{Q} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}\left(\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}-\delta\right)\right]+\frac{1}{p} \mathbb{E}\left[\overline{\boldsymbol{x}}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q} \boldsymbol{C} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}\right]\right|
$$

Now let us consider a supplementary random vector $\boldsymbol{x}_{n+1}$ following the same low as the $\boldsymbol{x}_{i}$ 's and independent of $\boldsymbol{X}$. We divide the set $\mathbb{I}=[n+1]$ into two sets $\mathbb{I}_{\frac{1}{2}}$ and $\mathbb{I}_{\frac{2}{2}}$ of same cardinality $\left(\left\lfloor\frac{n+1}{2}\right\rfloor \leq \# \mathbb{I}_{\frac{1}{2}}, \# \mathbb{I}_{\frac{2}{2}} \leq\left\lceil\frac{n+1}{2}\right\rceil\right)$, we note $\boldsymbol{X}_{\frac{1}{2}}=\left(\boldsymbol{x}_{i} \left\lvert\, i \in \mathbb{I}_{\frac{1}{2}}\right.\right), \boldsymbol{X}_{\frac{2}{2}}=\left(\boldsymbol{x}_{i} \left\lvert\, i \in \mathbb{I}_{\frac{2}{2}}\right.\right)$ and we introduce the diagonal matrices $\boldsymbol{\Delta}=\operatorname{diag}\left(\left.\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}-\delta \right\rvert\, i \in \mathbb{I}_{\frac{1}{2}}\right)$, $\boldsymbol{D}=\operatorname{diag}\left(\left.1+\frac{1}{p+1} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q} \boldsymbol{x}_{i} \right\rvert\, i \in \mathbb{I}_{\frac{2}{2}}\right)$. We have the bound:

$$
\begin{aligned}
& \left|\mathbb{E}\left[\overline{\boldsymbol{x}} \boldsymbol{Q} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}\left(\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}-\delta\right)\right]\right| \\
& \quad=\left|\mathbb{E}\left[\left(1+\frac{1}{p} \boldsymbol{x}_{n+1}^{\top} \boldsymbol{Q} \boldsymbol{x}_{n+1}\right) \boldsymbol{x}_{n+1} \boldsymbol{Q}_{+(n+1)} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}\left(\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}-\delta\right)\right]\right| \\
& \quad=\frac{1}{p^{2}}\left|\mathbb{E}\left[\mathbf{1}^{\top} \boldsymbol{D} \boldsymbol{X}_{\frac{2}{2}}^{\top} \boldsymbol{Q}_{+(n+1)} \boldsymbol{X}_{\frac{1}{2}} \boldsymbol{\Delta} \boldsymbol{X}_{\frac{1}{2}}^{\top} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}\right]\right| \\
& \quad \leq \sqrt{\left|\mathbb{E}\left[\frac{1}{p^{3}} \mathbf{1}^{\top} \boldsymbol{D} \boldsymbol{X}_{\frac{2}{2}}^{\top} \boldsymbol{Q}_{+(n+1)} \boldsymbol{X}_{\frac{1}{2}} \boldsymbol{\Delta}^{2} \boldsymbol{X}_{\frac{1}{2}}^{\top} \boldsymbol{Q}_{+(n+1)} \boldsymbol{X}_{\frac{2}{2}} \boldsymbol{D} \mathbf{1}\right] \mathbb{E}\left[\frac{1}{p} \overline{\boldsymbol{x}}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{X}_{\frac{1}{2}} \boldsymbol{X}_{\frac{1}{2}}^{\top} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}\right]\right|} \\
& \quad \leq \sqrt{\left|\mathbb{E}\left[\left\|\frac{1}{p} \boldsymbol{X}_{\frac{2}{2}}^{\top} \boldsymbol{Q}_{+(n+1)} \boldsymbol{X}_{\frac{1}{2}}\right\|^{2}\|\boldsymbol{D}\|^{2}\|\boldsymbol{\Delta}\|^{2}\right] \mathbb{E}[\overline{\boldsymbol{x}} \tilde{\boldsymbol{Q}} \boldsymbol{C} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}]\right|} \leq \mathcal{O}\left(\sqrt{\frac{\log p}{p}}\right)
\end{aligned}
$$

thanks to Lemma 1.1 and Lemma 1.2 (the spectral norm of $\Delta$ and $D$ is just an infinity norm if we see them as random vectors of $\mathbb{R}^{n}$ ). We can bound $\frac{1}{p}\left|\mathbb{E}\left[\overline{\boldsymbol{x}}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q} C \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}\right]\right|$ the same way to obtain the result of the proposition.

Proposition 1.4. $\left\|\mathbb{E}\left[\boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{X}_{-i}\right]-\frac{\overline{\boldsymbol{x}}^{\top} \tilde{\boldsymbol{Q}} \overline{\bar{x}} 1^{\top}}{1+\delta}\right\|=\mathcal{O}(\sqrt{\log p})$

Proof. Considering $\boldsymbol{u} \in \mathbb{R}^{n}$ such that $\|\boldsymbol{u}\|=1$ :

$$
\begin{aligned}
& \left|\mathbb{E}\left[\boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{X}_{-i} \boldsymbol{u}\right]-\frac{\overline{\boldsymbol{x}}^{\top} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}} \mathbf{1}^{\top} \boldsymbol{u}}{1+\delta}\right| \\
& \quad=\left|\sum_{\substack{j=1 \\
j \neq i}}^{n} \boldsymbol{u}_{j} \mathbb{E}\left[\frac{\boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{j}}{1+\frac{1}{p} \boldsymbol{x}_{j}^{\top} \boldsymbol{Q}_{-j}^{-j} \boldsymbol{x}_{j}}-\frac{\boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{j}}{1+\delta}\right]\right| \\
& \quad \leq \sqrt{n}\left|\mathbb{E}\left[\frac{\boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{j}}{1+\frac{1}{p} \boldsymbol{x}_{j}^{\top} \boldsymbol{Q}_{-j} \boldsymbol{x}_{j}}-\frac{\boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{j}}{1+\delta}\right]\right|+\left|\frac{1}{1+\delta} \mathbb{E}\left[\boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{j}-\boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{j}\right]\right| \quad(\text { where } i \neq j) \\
& \quad \leq \sqrt{n}\left|\mathbb{E}\left[\overline{\boldsymbol{x}}^{\top} \boldsymbol{Q} \boldsymbol{x}_{j}\left(\frac{1}{p} \boldsymbol{x}_{j}^{\top} \boldsymbol{Q}_{-j} \boldsymbol{x}_{j}-\delta\right)\right]\right|+\sqrt{n}\left|\mathbb{E}\left[\overline{\boldsymbol{x}}^{\top} \boldsymbol{Q}_{-i} \overline{\boldsymbol{x}_{-i}}-\overline{\boldsymbol{x}}^{\top} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}\right]\right|
\end{aligned}
$$

where the first term is treated the same way as we did in the proof of Proposition 1.3 and the second term is bounded thanks to Proposition 1.3

### 1.3. Main body of the proof

Proof of Theorem 3.3. Recall the definition of the resolvents $\boldsymbol{R}$ and $\boldsymbol{Q}$ in Equation (1). The first step of the proof is to show the concentration of $\boldsymbol{R}$. This comes from the fact that the application $\Phi: \boldsymbol{X} \mapsto\left(\boldsymbol{X}^{\top} \boldsymbol{X}+z \boldsymbol{I}_{n}\right)^{-1}$ is $2 z^{-3 / 2}$-Lipschitz w.r.t. the Frobenius norm. Indeed, by the matrix identity $\boldsymbol{A}-\boldsymbol{B}=\boldsymbol{A}\left(\boldsymbol{B}^{-1}-\boldsymbol{A}^{-1}\right) \boldsymbol{B}$, we have

$$
\Phi(\boldsymbol{X})-\Phi(\boldsymbol{X}+\boldsymbol{H})=\Phi(\boldsymbol{X})\left(\boldsymbol{H}^{\top} \boldsymbol{X}+(\boldsymbol{X}+\boldsymbol{H})^{\top} \boldsymbol{H}\right) \Phi(\boldsymbol{X}+\boldsymbol{H})
$$

And by the bounds $\|\boldsymbol{A} \boldsymbol{B}\|_{F} \leq\|\boldsymbol{A}\| \cdot\|\boldsymbol{B}\|_{F},\left\|\Phi(\boldsymbol{X}) \boldsymbol{X}^{\boldsymbol{\top}}\right\| \leq z^{-1 / 2}$ and $\|\Phi(\boldsymbol{X})\| \leq z^{-1}$, we have

$$
\|\Phi(\boldsymbol{X}+\boldsymbol{H})-\Phi(\boldsymbol{X})\|_{F} \leq \frac{2}{z^{3 / 2}}\|\boldsymbol{H}\|_{F}
$$

Therefore, given $\boldsymbol{X} \in \mathcal{E}_{q}\left(1 \mid \mathbb{R}^{p \times n},\|\cdot\|_{F}\right)$ and since the application $\boldsymbol{X} \mapsto \boldsymbol{R}=\Phi(\boldsymbol{X} / \sqrt{p})$ is $2 z^{-3 / 2} p^{-1 / 2}$-Lipschitz, we have by Proposition ?? that $\boldsymbol{R} \in \mathcal{E}_{q}\left(p^{-1 / 2} \mid \mathbb{R}^{n \times n},\|\cdot\|_{F}\right)$.
The second step consists in estimating $\mathbb{E} \boldsymbol{R}(z)$ through a deterministic matrix $\tilde{\boldsymbol{R}}$. Indeed, by the identity $\left(\boldsymbol{M}^{\top} \boldsymbol{M}+\right.$ $z \boldsymbol{I})^{-1} \boldsymbol{M}^{\boldsymbol{\top}}=\boldsymbol{M}^{\boldsymbol{\top}}\left(\boldsymbol{M} \boldsymbol{M}^{\boldsymbol{\top}}+z \boldsymbol{I}\right)^{-1}$, the resolvent $\boldsymbol{R}$ can be expressed in function of $\boldsymbol{Q}$ as follows

$$
\begin{equation*}
\boldsymbol{R}=\frac{1}{z}\left(I_{n}-\frac{\boldsymbol{X}^{\top} \boldsymbol{Q} \boldsymbol{X}}{p}\right) \tag{3}
\end{equation*}
$$

thus a deterministic equivalent for $\boldsymbol{R}$ can therefore be obtained through a deterministic equivalent of the matrix $\boldsymbol{X}^{\top} \boldsymbol{Q} \boldsymbol{X}$. However, as demonstrated in (Louart \& Couillet, 2019), the matrix $\boldsymbol{Q}$ has as a deterministic equivalent the matrix $\tilde{\boldsymbol{Q}}$ defined in equation 2. In the following, we aim at deriving a deterministic equivalent for $\frac{1}{p} \boldsymbol{X}^{\top} \boldsymbol{Q} \boldsymbol{X}$ in function of $\tilde{\boldsymbol{Q}}$. Let $\boldsymbol{u}$ and $\boldsymbol{v}$ be two unitary vectors in $\mathbb{R}^{n}$, and let us estimate

$$
\Delta \equiv \mathbb{E}\left[\boldsymbol{u}^{\top}\left(\frac{\boldsymbol{X}^{\top} \boldsymbol{Q} \boldsymbol{X}}{p}-\frac{\boldsymbol{X}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{X}}{p}\right) \boldsymbol{v}\right]=\frac{1}{p} \mathbb{E}\left[\frac{\boldsymbol{u}^{\top} \boldsymbol{X}^{\top} \boldsymbol{Q} \boldsymbol{C} \tilde{\boldsymbol{Q}} \boldsymbol{X} \boldsymbol{v}}{1+\delta}-\frac{1}{p} \boldsymbol{u}^{\top} \boldsymbol{X}^{\top} \boldsymbol{Q} \boldsymbol{X} \boldsymbol{X}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{X} \boldsymbol{v}\right]
$$

With the following matrix identities (to explore the independence of the columns of $\boldsymbol{X}$ ):

$$
\boldsymbol{Q}=\boldsymbol{Q}_{-i}-\frac{1}{p} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}, \quad \boldsymbol{Q} \boldsymbol{x}_{i}=\frac{\boldsymbol{Q}_{-i} \boldsymbol{x}_{i}}{1+\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}}, \quad \boldsymbol{A}-\boldsymbol{B}=\boldsymbol{A}\left(\boldsymbol{B}^{-1}-\boldsymbol{A}^{-1}\right) \boldsymbol{B}
$$

and the decomposition $\boldsymbol{Q} \boldsymbol{X} \boldsymbol{X}^{\boldsymbol{\top}}=\sum_{i=1}^{n} \boldsymbol{Q} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top}$, we obtain:

$$
\begin{aligned}
& \Delta=\frac{1}{p^{2}} \mathbb{E}\left[\sum_{i=1}^{n} \frac{\boldsymbol{u}^{\top} \boldsymbol{X}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{C} \tilde{\boldsymbol{Q}} \boldsymbol{X} \boldsymbol{v}}{1+\delta}-\frac{\boldsymbol{u}^{\top} \boldsymbol{X}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{X} \boldsymbol{v}}{1+\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}}-\frac{1}{p} \frac{\boldsymbol{u}^{\top} \boldsymbol{X}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q} \boldsymbol{C} \tilde{\boldsymbol{Q}} \boldsymbol{X} \boldsymbol{v}}{1+\delta}\right] \\
& =\frac{1}{p^{2}} \sum_{i=1}^{n} \mathbb{E}\left[\frac{\boldsymbol{u}^{\top} \boldsymbol{X}_{-i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{C} \tilde{\boldsymbol{Q}} \boldsymbol{X}_{-i} \boldsymbol{v}}{1+\delta}-\frac{\boldsymbol{u}^{\top} \boldsymbol{X}_{-i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{X}_{-i} \boldsymbol{v}}{1+\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}}\right. \\
& +\frac{\boldsymbol{u}_{i} x_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{C} \tilde{\boldsymbol{Q}} \boldsymbol{X}_{-i} \boldsymbol{v}}{1+\delta}+\frac{\boldsymbol{v}_{i} \boldsymbol{u}^{\top} \boldsymbol{X}_{-i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{C} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i}}{1+\delta}+\boldsymbol{u}_{i} \boldsymbol{v}_{i} \frac{\boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{C} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i}}{1+\delta} \\
& -\frac{\boldsymbol{u}_{i} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{X}_{-i} \boldsymbol{v}}{1+\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}}-\frac{\boldsymbol{v}_{i} \boldsymbol{u}^{\top} \boldsymbol{X}_{-i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i}}{1+\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}}-\boldsymbol{u}_{i} \boldsymbol{v}_{i} \frac{\boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i}}{1+\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}} \\
& \left.-\frac{1}{p} \frac{\boldsymbol{u}^{\top} \boldsymbol{X}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q C} \tilde{\boldsymbol{Q}} \boldsymbol{X} \boldsymbol{v}}{1+\delta}\right]
\end{aligned}
$$

We can show with Holder's inequality and the concentration bounds (mainly the fact that $\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}$ concentrates around $\delta$ ) developed in (Louart \& Couillet, 2019), that most of the above quantities vanish asymptotically. As a toy example, we consider the following term:

$$
\begin{array}{rl}
\left\lvert\, \frac{1}{p^{2}} \sum_{i=1}^{n}\right. & \left.\mathbb{E}\left[\frac{\boldsymbol{u}^{\top} \boldsymbol{X}_{-i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{C} \tilde{\boldsymbol{Q}} \boldsymbol{X}_{-i} \boldsymbol{v}}{1+\delta}-\frac{\boldsymbol{u}^{\top} \boldsymbol{X}_{-i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{X}_{-i} \boldsymbol{v}}{1+\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}}\right] \right\rvert\, \\
& =\left|\frac{1}{p^{2}} \sum_{i=1}^{n} \mathbb{E}\left[\boldsymbol{u}^{\top} \boldsymbol{X}_{-i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{X}_{-i} \boldsymbol{v} \frac{\delta-\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}}{(1+\delta)\left(1+\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}\right)}\right]\right| \\
& \leq\left|\frac{1}{p^{2}} \sum_{i=1}^{n} \mathbb{E}\left[\left(\boldsymbol{u}^{\top} \boldsymbol{X}_{-i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}\right)\left(\boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{X}_{-i} \boldsymbol{v}\right)\left(\delta-\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}\right)\right]\right| \\
& \leq\left|\frac{1}{p} \sum_{i=1}^{n}\left(\mathbb{E}\left[\left(\frac{1}{\sqrt{p}} \boldsymbol{u}^{\top} \boldsymbol{X}_{-i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}\right)^{3}\right] \mathbb{E}\left[\left(\frac{1}{\sqrt{p}} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{X}_{-i} \boldsymbol{v}\right)^{3}\right] \mathbb{E}\left[\left(\delta-\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}\right)^{3}\right]\right)^{\frac{1}{3}}\right| \\
& =\mathcal{O}\left(\frac{1}{\sqrt{p}}\right)
\end{array}
$$

Similarly, we can show that:

$$
\begin{aligned}
& \left\lvert\, \frac{1}{p^{2}} \sum_{i=1}^{n} \mathbb{E}[ \right. \frac{\boldsymbol{u}_{i} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{C} \tilde{\boldsymbol{Q}} \boldsymbol{X}_{-i} \boldsymbol{v}}{1+\delta}+\frac{\boldsymbol{v}_{i} \boldsymbol{u}^{\top} \boldsymbol{X}_{-i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{C} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i}}{1+\delta} \\
&\left.\quad+\boldsymbol{u}_{i} \boldsymbol{v}_{i} \frac{\boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{C} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i}}{1+\delta}-\frac{1}{p} \frac{\boldsymbol{u}^{\top} \boldsymbol{X}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q} \boldsymbol{C} \tilde{\boldsymbol{Q}} \boldsymbol{X} \boldsymbol{v}}{1+\delta}\right] \left\lvert\,=\mathcal{O}\left(\frac{1}{\sqrt{p}}\right)\right.
\end{aligned}
$$

Finally, the remaining terms in $\Delta$ can be estimated as follows:

$$
\begin{aligned}
\Delta=\frac{1}{p^{2}} \sum_{i=1}^{n} \mathbb{E}[ & -\frac{\boldsymbol{u}_{i} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{X}_{-i} \boldsymbol{v}}{1+\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}} \\
& \left.\quad-\frac{\boldsymbol{v}_{i} \boldsymbol{u}^{\top} \boldsymbol{X}_{-i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i}}{1+\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q} \boldsymbol{x}_{i}}-\boldsymbol{u}_{i} \boldsymbol{v}_{i} \frac{\boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i}}{1+\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}}\right]+\mathcal{O}\left(\frac{1}{\sqrt{p}}\right) \\
=- & \frac{2}{p} \frac{\delta \boldsymbol{u}^{\top} \mathbf{1} \overline{\boldsymbol{x}}^{\top} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}} \mathbf{1}^{\top} \boldsymbol{v}}{1+\delta}-\frac{\delta^{2} \boldsymbol{u}^{\top} \boldsymbol{v}}{1+\delta}+\mathcal{O}\left(\sqrt{\frac{\log p}{p}}\right)
\end{aligned}
$$

Where the last equality is obtained through the following estimation:

$$
\begin{aligned}
& \frac{1}{p^{2}} \sum_{i=1}^{n} \mathbb{E}\left[\frac{\boldsymbol{v}_{i} \boldsymbol{u}^{\top} \boldsymbol{X}_{-i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i}}{1+\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}}\right]=\frac{1}{p} \sum_{i=1}^{n} \mathbb{E}\left[\frac{\boldsymbol{v}_{i} \boldsymbol{u}^{\top} \boldsymbol{X}_{-i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}\left(\frac{1}{p} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i}(1+\delta)-\delta\left(1+\frac{1}{p} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i}\right)\right)}{\left(1+\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}\right)(1+\delta)}\right] \\
&+\frac{1}{p} \sum_{i=1}^{n} \frac{\boldsymbol{v}_{i} \delta \mathbb{E}\left[\boldsymbol{u}^{\top} \boldsymbol{X}_{-i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i}\right]}{(1+\delta)}
\end{aligned}
$$

With the following bound:

$$
\begin{aligned}
& \left|\frac{1}{p} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i}(1+\delta)-\delta\left(1+\frac{1}{p} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i}\right)\right| \\
& \quad=\left|\frac{1}{p} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i}(1+\delta)-\delta(1+\delta)+\delta(1+\delta)-\delta\left(1+\frac{1}{p} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i}\right)\right| \\
& \quad \leq\left|\frac{1}{p} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i}-\delta\right|(1+2 \delta)
\end{aligned}
$$

we have again with Holder's inequality and Proposition 1.4:

$$
\frac{1}{p^{2}} \sum_{i=1}^{n} \mathbb{E}\left[\frac{\boldsymbol{v}_{i} \boldsymbol{u}^{\top} \boldsymbol{X}_{-i}^{\top} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i}}{1+\frac{1}{p} \boldsymbol{x}_{i}^{\top} \boldsymbol{Q} \boldsymbol{x}_{i}}\right]=\frac{1}{p} \sum_{i=1}^{n} \frac{\boldsymbol{v}_{i} \delta \boldsymbol{u}^{\top} \mathbf{1} \overline{\boldsymbol{x}}^{\top} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}}{1+\delta}+\mathcal{O}\left(\sqrt{\frac{\log p}{p}}\right)
$$

Now that we estimated $\Delta$, it remains to estimate $\mathbb{E}\left[\frac{1}{p} \boldsymbol{X}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{X}\right]$. Indeed, given two unit norm vectors $u, v \in \mathbb{R}^{n}$ we have:

$$
\begin{aligned}
\mathbb{E}\left[\frac{1}{p} \boldsymbol{u}^{\top} \boldsymbol{X}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{X} \boldsymbol{v}\right] & =\frac{1}{p} \sum_{i, j=1}^{n} \boldsymbol{u}_{i} \boldsymbol{v}_{j} \mathbb{E}\left[\boldsymbol{x}_{i}^{\top} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{j}\right]=\frac{1}{p} \sum_{i=1}^{n} \sum_{\substack{j=1 \\
j \neq i}}^{n} \boldsymbol{u}_{i} \boldsymbol{v}_{j} \overline{\boldsymbol{x}}^{\top} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}+\sum_{i=1}^{n} \boldsymbol{u}_{i} \boldsymbol{v}_{i} \delta \\
& =\frac{1}{p} \overline{\boldsymbol{x}}^{\top} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}} \boldsymbol{u}^{\top} \mathbf{1 1} \mathbf{1}^{\top} \boldsymbol{v}+\left(\delta-\frac{1}{p} \overline{\boldsymbol{x}}^{\top} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}\right) \boldsymbol{u}^{\top} \boldsymbol{v}=\frac{1}{p} \overline{\boldsymbol{x}} \overline{\boldsymbol{x}}^{\top} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}} \boldsymbol{u}^{\top} \boldsymbol{M}_{1} \boldsymbol{v}^{\top}+\delta \boldsymbol{u}^{\top} \boldsymbol{v}+\mathcal{O}\left(\frac{1}{p}\right)
\end{aligned}
$$

since we have $\overline{\boldsymbol{x}}^{\top} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}}=\mathcal{O}(1)$ by Lemma 1.2; we introduced the matrix $\boldsymbol{M}_{1}=\mathbf{1 1}^{\top}$. Therefore we have the following estimation:

$$
\frac{1}{p} \mathbb{E}\left[\boldsymbol{X}^{\top} \boldsymbol{Q} \boldsymbol{X}\right]=\frac{\delta}{1+\delta} \boldsymbol{I}_{n}+\frac{1}{p}\left(\frac{1-\delta}{1+\delta}\right) \overline{\boldsymbol{x}}^{\top} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}} \boldsymbol{M}_{1}+\mathcal{O}_{\|\cdot\|}\left(\sqrt{\frac{\log p}{p}}\right)
$$

where $\boldsymbol{A}=\boldsymbol{B}+\mathcal{O}_{\|\cdot\|}(\alpha(p))$ means that $\|\boldsymbol{A}-\boldsymbol{B}\|=\mathcal{O}(\alpha(p))$. Finally, since $\boldsymbol{R}$ concentrates around its mean, we can then conclude:

$$
\boldsymbol{R}=\frac{1}{z}\left(\boldsymbol{I}_{n}-\frac{1}{p} \boldsymbol{X}^{\boldsymbol{\top}} \boldsymbol{Q} \boldsymbol{X}\right)=\frac{1}{z} \frac{1}{1+\delta} \boldsymbol{I}_{n}+\frac{\delta-1}{p z(\delta+1)} \overline{\boldsymbol{x}}^{\boldsymbol{\top}} \tilde{\boldsymbol{Q}} \overline{\boldsymbol{x}} \boldsymbol{M}_{1}+\mathcal{O}_{\|\cdot\|}\left(\sqrt{\frac{\log p}{p}}\right)
$$

## 2. Proof of Proposition 3.1

Proof. Since the Lipschitz constant of a composition of Lipschitz functions is bounded by the product of their Lipschitz constants, we consider the case $N=1$ and a linear activation function. In this case, the Lipschitz constant corresponds to the largest singular value of the weight matrix. We consider the following notations for the proof

$$
\begin{aligned}
& \overline{\boldsymbol{W}}_{t}=\boldsymbol{W}_{t}-\eta \boldsymbol{E}_{t} \text { with }\left[\boldsymbol{E}_{t}\right]_{i, j} \sim \mathcal{N}(0,1) \\
& \boldsymbol{W}_{t+1}=\overline{\boldsymbol{W}}_{t}-\max \left(0, \bar{\sigma}_{1, t}-\sigma_{*}\right) \overline{\boldsymbol{u}}_{1, t} \overline{\boldsymbol{v}}_{1, t}^{\mathrm{T}}
\end{aligned}
$$

where $\bar{\sigma}_{1, t}=\sigma_{1}\left(\overline{\boldsymbol{W}}_{t}\right), \overline{\boldsymbol{u}}_{1, t}=\boldsymbol{u}_{1}\left(\overline{\boldsymbol{W}}_{t}\right)$ and $\overline{\boldsymbol{v}}_{1, t}=\boldsymbol{v}_{1}\left(\overline{\boldsymbol{W}}_{t}\right)$. The effect of spectral normalization is observed in the case where $\sigma_{*}>\bar{\sigma}_{1, t}$, otherwise the Lipschitz constant is bounded by $\sigma_{*}$. We therefore have

$$
\begin{align*}
& \left\|\overline{\boldsymbol{W}}_{t}\right\|_{F}^{2} \leq\left\|\boldsymbol{W}_{t}\right\|_{F}^{2}+\eta^{2} d_{1} d_{0}  \tag{4}\\
& \left\|\boldsymbol{W}_{t+1}\right\|_{F}^{2}=\left\|\overline{\boldsymbol{W}}_{t}\right\|_{F}^{2}+\sigma_{*}^{2}-\bar{\sigma}_{1, t}^{2} \tag{5}
\end{align*}
$$

- If $\left\|\boldsymbol{W}_{t+1}\right\|_{F} \geq\left\|\boldsymbol{W}_{t}\right\|_{F}$, we have by equation 4 and equation 5

$$
\left\|\overline{\boldsymbol{W}}_{t}\right\|_{F}^{2} \leq\left\|\overline{\boldsymbol{W}}_{t}\right\|_{F}^{2}+\sigma_{*}^{2}-\bar{\sigma}_{1, t}^{2}+\eta^{2} d_{1} d_{0} \Rightarrow\left\|\overline{\boldsymbol{W}}_{t}\right\|=\bar{\sigma}_{1, t} \leq \sqrt{\sigma_{*}^{2}+\eta^{2} d_{1} d_{0}}=\delta
$$

And since $\left\|\boldsymbol{W}_{t+1}\right\| \leq\left\|\overline{\boldsymbol{W}}_{t}\right\|$, we have $\left\|\boldsymbol{W}_{t+1}\right\| \leq \delta$.

- Otherwise, if there exits $\tau$ such that $\left\|\boldsymbol{W}_{\tau+1}\right\|_{F}<\left\|\boldsymbol{W}_{\tau}\right\|_{F}$, then for all $\varepsilon>0$ there exists an iteration $\tau^{\prime} \geq \tau$ such that $\left\|\boldsymbol{W}_{\tau^{\prime}}\right\| \leq \delta+\varepsilon$. Indeed, otherwise we denote $\varepsilon_{t}=\left\|\boldsymbol{W}_{t}\right\|^{2}-\delta^{2}$ and $\varepsilon_{t}>0$ for all $t \geq \tau$. And if for all $t \geq \tau$, $\left\|\boldsymbol{W}_{t+1}\right\|_{F} \leq\left\|\boldsymbol{W}_{t}\right\|_{F}$, we have by equation 4 and equation 5

$$
\left\|\boldsymbol{W}_{t}\right\|_{F}^{2}-\left\|\boldsymbol{W}_{t+1}\right\|_{F}^{2} \geq\left\|\overline{\boldsymbol{W}}_{t}\right\|^{2}-\delta^{2} \geq\left\|\boldsymbol{W}_{t+1}\right\|^{2}-\delta^{2}=\varepsilon_{t+1}
$$

Integrating the above expression from $\tau$ to $T-1 \geq \tau$, we end up with

$$
\left\|\boldsymbol{W}_{\tau}\right\|_{F}^{2}-\left\|\boldsymbol{W}_{T}\right\|_{F}^{2} \geq \sum_{t=\tau}^{T-1} \varepsilon_{t} \Rightarrow 0 \leq\left\|\boldsymbol{W}_{T}\right\|_{F}^{2} \leq\left\|\boldsymbol{W}_{\tau}\right\|_{F}^{2}-\sum_{t=\tau}^{T-1} \varepsilon_{t}
$$

therefore, when $T \rightarrow \infty, \varepsilon_{t}$ has to tend to 0 otherwise the right hand-side of the last inequality will tend to $-\infty$ which is absurd.

## References

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