Supplementary Material of "Random Matrix Theory Proves that Deep Learning Representations of GAN-data Behave as Gaussian Mixtures"

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Abstract

This supplementary material provides the proof of our main results, specifically a detailed proof for Theorem 3.3 and a proof for the Proposition 3.1.

1. Proof of Theorem 3.3

1.1. Setting of the proof

For simplicity, we will only suppose the case k = 1 and we consider the following notations that will be used subsequently.

$$ar{m{x}} = \mathbb{E}m{x}_i, \; m{C} = \mathbb{E}[m{x}_im{x}_i^\intercal], \; m{X}_0 = m{X} - ar{m{x}}m{1}_n^\intercal, \; m{C}_0 = \mathbb{E}[m{X}_0m{X}_0^\intercal/n]$$

Let

$$\boldsymbol{X}_{-i} = (\boldsymbol{x}_1, \dots, \boldsymbol{x}_{i-1}, 0, \boldsymbol{x}_i, \dots, \boldsymbol{x}_n)$$

the matrix X with a vector of zeros at its *i*th column.

Denote the resolvents

$$\boldsymbol{R} = \left(\frac{\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X}}{p} + z\boldsymbol{I}_n\right)^{-1}, \ \boldsymbol{Q} = \left(\frac{\boldsymbol{X}\boldsymbol{X}^{\mathsf{T}}}{p} + z\boldsymbol{I}_p\right)^{-1}, \ \boldsymbol{Q}_{-i} = \left(\frac{\boldsymbol{X}\boldsymbol{X}^{\mathsf{T}}}{p} - \frac{\boldsymbol{x}_i\boldsymbol{x}_i^{\mathsf{T}}}{p} + z\boldsymbol{I}_p\right)^{-1}$$
(1)

And let

$$\tilde{\boldsymbol{Q}} = \left(\frac{1}{c}\frac{\boldsymbol{C}}{1+\delta} + z\boldsymbol{I}_p\right)^{-1},\tag{2}$$

where δ is the solution to the fixed point equation

$$\delta = \frac{1}{p} \operatorname{tr} \left(\boldsymbol{C} \left(\frac{1}{c} \frac{\boldsymbol{C}}{1+\delta} + z \boldsymbol{I}_p \right)^{-1} \right).$$

1.2. Basic tools

Lemma 1.1 ((Ledoux, 2005)). Let $z \in \mathcal{E}_q(1 | \mathbb{R}^p, \| \cdot \|)$ and $M \in \mathcal{E}_q(1 | \mathbb{R}^{p \times n}, \| \cdot \|_F)$. Then, for some numerical constant C > 0

- $\mathbb{E} \|\boldsymbol{z}\| \le \|\mathbb{E}\boldsymbol{z}\| + C\sqrt{p}, \ \mathbb{E} \|\boldsymbol{z}\|_{\infty} \le \|\mathbb{E}\boldsymbol{z}\|_{\infty} + C\sqrt{\log p}.$
- $\mathbb{E} \|\boldsymbol{M}\| \le \|\mathbb{E}\boldsymbol{M}\| + C\sqrt{p+n}, \ \mathbb{E} \|\boldsymbol{M}\|_F \le \|\mathbb{E}\boldsymbol{M}\|_F + C\sqrt{pn}.$

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Lemma 1.2. Denote $Q_{\bar{x}} = (\bar{x}\bar{x}^{\intercal} + zI_p)^{-1}$, we have:

$$Q_{\bar{x}}\bar{x} = rac{\bar{x}}{\|\bar{x}\|^2 + z}$$
 and $\|\tilde{Q}\bar{x}\|, \ \bar{x}\tilde{Q}\bar{x} = \mathcal{O}(1).$

Moreover, if $\|\bar{\boldsymbol{x}}\| \geq \sqrt{p}$, $\|\tilde{\boldsymbol{Q}}\bar{\boldsymbol{x}}\| = \mathcal{O}(p^{-1/2})$.

Proof. Since $z Q_{\bar{x}} = I_p - Q_{\bar{x}} \bar{x} \bar{x}^{\intercal}$:

$$z\boldsymbol{Q}_{\bar{\boldsymbol{x}}}\bar{\boldsymbol{x}}=\bar{\boldsymbol{x}}-\|\bar{\boldsymbol{x}}\|^2\boldsymbol{Q}_{\bar{\boldsymbol{x}}}\bar{\boldsymbol{x}},$$

and we recover the first identity of the Lemma.

And since the matrix C_0 is nonnegative symmetric, we have :

$$\tilde{\boldsymbol{Q}}\bar{\boldsymbol{x}} = \left(\frac{1}{c}\frac{\boldsymbol{C}_0 + \bar{\boldsymbol{x}}\bar{\boldsymbol{x}}^{\intercal}}{1+\delta} + z\boldsymbol{I}_p\right)^{-1}\bar{\boldsymbol{x}} \le \frac{c(1+\delta)\bar{\boldsymbol{x}}}{\|\bar{\boldsymbol{x}}\|^2 + zc(1+\delta)}$$

Therefore, $\bar{x}\tilde{Q}\bar{x} = \frac{c(1+\delta)\|\bar{x}\|^2}{\|\bar{x}\|^2 + zc(1+\delta)} = \mathcal{O}(1)$ and:

$$\|\tilde{\boldsymbol{Q}}\bar{\boldsymbol{x}}\| = \frac{c(1+\delta)\|\bar{\boldsymbol{x}}\|}{\|\bar{\boldsymbol{x}}\|^2 + zc(1+\delta)} \le \begin{cases} \frac{\|\bar{\boldsymbol{x}}\|}{z} = \mathcal{O}(1) & \text{if } \|\bar{\boldsymbol{x}}\| \le 1, \\ \frac{c(1+\delta)}{\|\bar{\boldsymbol{x}}\|} = \mathcal{O}(1) & \text{if } \|\bar{\boldsymbol{x}}\| \ge 1. \end{cases}$$

Proposition 1.3. $\bar{x}^{\intercal}\mathbb{E}[Q]\bar{x} = \bar{x}^{\intercal}\tilde{Q}\bar{x} + \mathcal{O}\left(\sqrt{\frac{\log p}{p}}\right)$

Proof. Let us bound:

$$\left| \bar{\boldsymbol{x}}^{\mathsf{T}} \boldsymbol{Q} \bar{\boldsymbol{x}} - \bar{\boldsymbol{x}}^{\mathsf{T}} \tilde{\boldsymbol{Q}} \bar{\boldsymbol{x}} \right| \leq \frac{c^{-1}}{1+\delta} \left| \mathbb{E} \left[\bar{\boldsymbol{x}} \boldsymbol{Q} \boldsymbol{x}_i \boldsymbol{x}_i^{\mathsf{T}} \tilde{\boldsymbol{Q}} \bar{\boldsymbol{x}} \left(\frac{1}{p} \boldsymbol{x}_i^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{x}_i - \delta \right) \right] + \frac{1}{p} \mathbb{E} \left[\bar{\boldsymbol{x}}^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{x}_i \boldsymbol{x}_i^{\mathsf{T}} \boldsymbol{Q} \boldsymbol{C} \tilde{\boldsymbol{Q}} \bar{\boldsymbol{x}} \right]$$

Now let us consider a supplementary random vector \boldsymbol{x}_{n+1} following the same low as the \boldsymbol{x}_i 's and independent of \boldsymbol{X} . We divide the set $\mathbb{I} = [n+1]$ into two sets $\mathbb{I}_{\frac{1}{2}}$ and $\mathbb{I}_{\frac{2}{2}}$ of same cardinality $(\lfloor \frac{n+1}{2} \rfloor \leq \#\mathbb{I}_{\frac{1}{2}}, \#\mathbb{I}_{\frac{2}{2}} \leq \lceil \frac{n+1}{2} \rceil)$, we note $\boldsymbol{X}_{\frac{1}{2}} = (\boldsymbol{x}_i \mid i \in \mathbb{I}_{\frac{1}{2}}), \boldsymbol{X}_{\frac{2}{2}} = (\boldsymbol{x}_i \mid i \in \mathbb{I}_{\frac{2}{2}})$ and we introduce the diagonal matrices $\boldsymbol{\Delta} = \operatorname{diag}\left(\frac{1}{p}\boldsymbol{x}_i^{\mathsf{T}}\boldsymbol{Q}_{-i}\boldsymbol{x}_i - \delta \mid i \in \mathbb{I}_{\frac{1}{2}}\right),$ $\boldsymbol{D} = \operatorname{diag}\left(1 + \frac{1}{p+1}\boldsymbol{x}_i^{\mathsf{T}}\boldsymbol{Q}\boldsymbol{x}_i \mid i \in \mathbb{I}_{\frac{2}{2}}\right)$. We have the bound:

$$\begin{aligned} \left| \mathbb{E} \left[\bar{\boldsymbol{x}} \boldsymbol{Q} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\mathsf{T}} \tilde{\boldsymbol{Q}} \bar{\boldsymbol{x}} \left(\frac{1}{p} \boldsymbol{x}_{i}^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} - \delta \right) \right] \right| \\ &= \left| \mathbb{E} \left[\left(1 + \frac{1}{p} \boldsymbol{x}_{n+1}^{\mathsf{T}} \boldsymbol{Q} \boldsymbol{x}_{n+1} \right) \boldsymbol{x}_{n+1} \boldsymbol{Q}_{+(n+1)} \boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\mathsf{T}} \tilde{\boldsymbol{Q}} \bar{\boldsymbol{x}} \left(\frac{1}{p} \boldsymbol{x}_{i}^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{x}_{i} - \delta \right) \right] \right| \\ &= \frac{1}{p^{2}} \left| \mathbb{E} \left[\mathbf{1}^{\mathsf{T}} \boldsymbol{D} \boldsymbol{X}_{\frac{2}{2}}^{\mathsf{T}} \boldsymbol{Q}_{+(n+1)} \boldsymbol{X}_{\frac{1}{2}} \Delta \boldsymbol{X}_{\frac{1}{2}}^{\mathsf{T}} \tilde{\boldsymbol{Q}} \bar{\boldsymbol{x}} \right] \right| \\ &\leq \sqrt{\left| \mathbb{E} \left[\frac{1}{p^{3}} \mathbf{1}^{\mathsf{T}} \boldsymbol{D} \boldsymbol{X}_{\frac{2}{2}}^{\mathsf{T}} \boldsymbol{Q}_{+(n+1)} \boldsymbol{X}_{\frac{1}{2}} \Delta^{2} \boldsymbol{X}_{\frac{1}{2}}^{\mathsf{T}} \boldsymbol{Q}_{+(n+1)} \boldsymbol{X}_{\frac{2}{2}} \boldsymbol{D} \mathbf{1} \right] \mathbb{E} \left[\frac{1}{p} \bar{\boldsymbol{x}}^{\mathsf{T}} \tilde{\boldsymbol{Q}} \boldsymbol{X}_{\frac{1}{2}} \boldsymbol{X}_{\frac{1}{2}}^{\mathsf{T}} \tilde{\boldsymbol{Q}} \bar{\boldsymbol{x}} \right] \right| \\ &\leq \sqrt{\left| \mathbb{E} \left[\left\| \frac{1}{p} \boldsymbol{X}_{\frac{2}{2}}^{\mathsf{T}} \boldsymbol{Q}_{+(n+1)} \boldsymbol{X}_{\frac{1}{2}} \right\|^{2} \left\| \boldsymbol{D} \right\|^{2} \left\| \boldsymbol{\Delta} \right\|^{2} \right] \mathbb{E} \left[\bar{\boldsymbol{x}} \tilde{\boldsymbol{Q}} \boldsymbol{C} \tilde{\boldsymbol{Q}} \bar{\boldsymbol{x}} \right] \right| \\ \leq \mathcal{O} \left(\sqrt{\frac{\log p}{p}} \right), \end{aligned}$$

thanks to Lemma 1.1 and Lemma 1.2 (the spectral norm of Δ and D is just an infinity norm if we see them as random vectors of \mathbb{R}^n). We can bound $\frac{1}{p} \left| \mathbb{E} \left[\bar{x}^{\mathsf{T}} Q_{-i} x_i x_i^{\mathsf{T}} Q C \tilde{Q} \bar{x} \right] \right|$ the same way to obtain the result of the proposition. \Box

Proposition 1.4. $\|\mathbb{E}[\boldsymbol{x}_i^{\mathsf{T}}\boldsymbol{Q}_{-i}\boldsymbol{X}_{-i}] - \frac{\bar{\boldsymbol{x}}^{\mathsf{T}}\bar{\boldsymbol{Q}}\bar{\boldsymbol{x}}\mathbf{1}^{\mathsf{T}}}{1+\delta}\| = \mathcal{O}(\sqrt{\log p})$

Proof. Considering $u \in \mathbb{R}^n$ such that ||u|| = 1:

$$\begin{split} \left| \mathbb{E}[\boldsymbol{x}_{i}^{\mathsf{T}}\boldsymbol{Q}_{-i}\boldsymbol{X}_{-i}\boldsymbol{u}] - \frac{\bar{\boldsymbol{x}}^{\mathsf{T}}\tilde{\boldsymbol{Q}}\bar{\boldsymbol{x}}\mathbf{1}^{\mathsf{T}}\boldsymbol{u}}{1+\delta} \right| \\ &= \left| \sum_{\substack{j=1\\j\neq i}}^{n} \boldsymbol{u}_{j}\mathbb{E}\left[\frac{\boldsymbol{x}_{i}^{\mathsf{T}}\boldsymbol{Q}_{-i}\boldsymbol{x}_{j}}{1+\frac{1}{p}\boldsymbol{x}_{j}^{\mathsf{T}}\boldsymbol{Q}_{-j}\boldsymbol{x}_{j}} - \frac{\boldsymbol{x}_{i}^{\mathsf{T}}\tilde{\boldsymbol{Q}}\boldsymbol{x}_{j}}{1+\delta} \right] \right| \\ &\leq \sqrt{n} \left| \mathbb{E}\left[\frac{\boldsymbol{x}_{i}^{\mathsf{T}}\boldsymbol{Q}_{-i}\boldsymbol{x}\boldsymbol{x}_{j}}{1+\frac{1}{p}\boldsymbol{x}_{j}^{\mathsf{T}}\boldsymbol{Q}_{-j}\boldsymbol{x}_{j}} - \frac{\boldsymbol{x}_{i}^{\mathsf{T}}\boldsymbol{Q}_{-i}\boldsymbol{x}\boldsymbol{x}_{j}}{1+\delta} \right] \right| + \left| \frac{1}{1+\delta}\mathbb{E}\left[\boldsymbol{x}_{i}^{\mathsf{T}}\boldsymbol{Q}_{-i}\boldsymbol{x}_{j} - \boldsymbol{x}_{i}^{\mathsf{T}}\tilde{\boldsymbol{Q}}\boldsymbol{x}_{j} \right] \right| \quad (\text{where } i\neq j) \\ &\leq \sqrt{n} \left| \mathbb{E}\left[\bar{\boldsymbol{x}}^{\mathsf{T}}\boldsymbol{Q}\boldsymbol{x}_{j}\left(\frac{1}{p}\boldsymbol{x}_{j}^{\mathsf{T}}\boldsymbol{Q}_{-j}\boldsymbol{x}_{j} - \delta \right) \right] \right| + \sqrt{n} \left| \mathbb{E}\left[\bar{\boldsymbol{x}}^{\mathsf{T}}\boldsymbol{Q}_{-i}\boldsymbol{x} - \bar{\boldsymbol{x}}^{\mathsf{T}}\tilde{\boldsymbol{Q}}\bar{\boldsymbol{x}}_{j} \right] \right|, \end{split}$$

where the first term is treated the same way as we did in the proof of Proposition 1.3 and the second term is bounded thanks to Proposition 1.3 \Box

1.3. Main body of the proof

Proof of Theorem 3.3. Recall the definition of the resolvents R and Q in Equation (1). The first step of the proof is to show the concentration of R. This comes from the fact that the application $\Phi : X \mapsto (X^{\mathsf{T}}X + zI_n)^{-1}$ is $2z^{-3/2}$ -Lipschitz *w.r.t.* the Frobenius norm. Indeed, by the matrix identity $A - B = A(B^{-1} - A^{-1})B$, we have

$$\Phi(\boldsymbol{X}) - \Phi(\boldsymbol{X} + \boldsymbol{H}) = \Phi(\boldsymbol{X})(\boldsymbol{H}^{\mathsf{T}}\boldsymbol{X} + (\boldsymbol{X} + \boldsymbol{H})^{\mathsf{T}}\boldsymbol{H})\Phi(\boldsymbol{X} + \boldsymbol{H})$$

And by the bounds $\|AB\|_F \leq \|A\| \cdot \|B\|_F$, $\|\Phi(X)X^{\intercal}\| \leq z^{-1/2}$ and $\|\Phi(X)\| \leq z^{-1}$, we have

$$\|\Phi(X + H) - \Phi(X)\|_F \le \frac{2}{z^{3/2}} \|H\|_F.$$

Therefore, given $X \in \mathcal{E}_q(1 | \mathbb{R}^{p \times n}, \| \cdot \|_F)$ and since the application $X \mapsto R = \Phi(X/\sqrt{p})$ is $2z^{-3/2}p^{-1/2}$ -Lipschitz, we have by Proposition **??** that $R \in \mathcal{E}_q(p^{-1/2} | \mathbb{R}^{n \times n}, \| \cdot \|_F)$.

The second step consists in estimating $\mathbb{E}\mathbf{R}(z)$ through a deterministic matrix $\tilde{\mathbf{R}}$. Indeed, by the identity $(\mathbf{M}^{\mathsf{T}}\mathbf{M} + z\mathbf{I})^{-1}\mathbf{M}^{\mathsf{T}} = \mathbf{M}^{\mathsf{T}}(\mathbf{M}\mathbf{M}^{\mathsf{T}} + z\mathbf{I})^{-1}$, the resolvent \mathbf{R} can be expressed in function of \mathbf{Q} as follows

$$\boldsymbol{R} = \frac{1}{z} \left(I_n - \frac{\boldsymbol{X}^{\mathsf{T}} \boldsymbol{Q} \boldsymbol{X}}{p} \right), \tag{3}$$

thus a deterministic equivalent for R can therefore be obtained through a deterministic equivalent of the matrix $X^{T}QX$. However, as demonstrated in (Louart & Couillet, 2019), the matrix Q has as a deterministic equivalent the matrix \tilde{Q} defined in equation 2. In the following, we aim at deriving a deterministic equivalent for $\frac{1}{p}X^{T}QX$ in function of \tilde{Q} . Let u and vbe two unitary vectors in \mathbb{R}^{n} , and let us estimate

$$\Delta \equiv \mathbb{E}\left[\boldsymbol{u}^{\mathsf{T}}\left(\frac{\boldsymbol{X}^{\mathsf{T}}\boldsymbol{Q}\boldsymbol{X}}{p} - \frac{\boldsymbol{X}^{\mathsf{T}}\tilde{\boldsymbol{Q}}\boldsymbol{X}}{p}\right)\boldsymbol{v}\right] = \frac{1}{p}\mathbb{E}\left[\frac{\boldsymbol{u}^{\mathsf{T}}\boldsymbol{X}^{\mathsf{T}}\boldsymbol{Q}\boldsymbol{C}\tilde{\boldsymbol{Q}}\boldsymbol{X}\boldsymbol{v}}{1+\delta} - \frac{1}{p}\boldsymbol{u}^{\mathsf{T}}\boldsymbol{X}^{\mathsf{T}}\boldsymbol{Q}\boldsymbol{X}\boldsymbol{X}^{\mathsf{T}}\tilde{\boldsymbol{Q}}\boldsymbol{X}\boldsymbol{v}\right]$$

With the following matrix identities (to explore the independence of the columns of X):

$$Q = Q_{-i} - rac{1}{p} Q_{-i} x_i x_i^{\mathsf{T}} Q$$
, $Q x_i = rac{Q_{-i} x_i}{1 + rac{1}{p} x_i^{\mathsf{T}} Q_{-i} x_i}$, $A - B = A(B^{-1} - A^{-1})B$

and the decomposition $\boldsymbol{Q}\boldsymbol{X}\boldsymbol{X}^\intercal = \sum_{i=1}^n \boldsymbol{Q}\boldsymbol{x}_i\boldsymbol{x}_i^\intercal$, we obtain:

$$\begin{split} \Delta &= \frac{1}{p^2} \mathbb{E} \left[\sum_{i=1}^n \frac{\mathbf{u}^{\mathsf{T}} \mathbf{X}^{\mathsf{T}} \mathbf{Q}_{-i} C \tilde{\mathbf{Q}} \mathbf{X} \mathbf{v}}{1+\delta} - \frac{\mathbf{u}^{\mathsf{T}} \mathbf{X}^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i \mathbf{x}_i^{\mathsf{T}} \tilde{\mathbf{Q}} \mathbf{X} \mathbf{v}}{1+\frac{1}{p} \mathbf{x}_i^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i} - \frac{1}{p} \frac{\mathbf{u}^{\mathsf{T}} \mathbf{X}^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i \mathbf{x}_i^{\mathsf{T}} \mathbf{Q} C \tilde{\mathbf{Q}} \mathbf{X} \mathbf{v}}{1+\delta} \right] \\ &= \frac{1}{p^2} \sum_{i=1}^n \mathbb{E} \left[\frac{\mathbf{u}^{\mathsf{T}} \mathbf{X}_{-i}^{\mathsf{T}} \mathbf{Q}_{-i} C \tilde{\mathbf{Q}} \mathbf{X}_{-i} \mathbf{v}}{1+\delta} - \frac{\mathbf{u}^{\mathsf{T}} \mathbf{X}_{-i}^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i \mathbf{x}_i^{\mathsf{T}} \tilde{\mathbf{Q}} \mathbf{X}_{-i} \mathbf{v}}{1+\frac{1}{p} \mathbf{x}_i^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i} \right. \\ &+ \frac{\mathbf{u}_i \mathbf{x}_i^{\mathsf{T}} \mathbf{Q}_{-i} C \tilde{\mathbf{Q}} \mathbf{X}_{-i} \mathbf{v}}{1+\delta} + \frac{\mathbf{v}_i \mathbf{u}^{\mathsf{T}} \mathbf{X}_{-i}^{\mathsf{T}} \mathbf{Q}_{-i} C \tilde{\mathbf{Q}} \mathbf{x}_i}{1+\delta} \\ &+ \frac{\mathbf{u}_i \mathbf{x}_i^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i \mathbf{x}_i^{\mathsf{T}} \tilde{\mathbf{Q}} \mathbf{X}_{-i} \mathbf{v}}{1+\delta} + \frac{\mathbf{v}_i \mathbf{u}^{\mathsf{T}} \mathbf{X}_{-i}^{\mathsf{T}} \mathbf{Q}_{-i} C \tilde{\mathbf{Q}} \mathbf{x}_i}{1+\delta} + \mathbf{u}_i \mathbf{v}_i \frac{\mathbf{x}_i^{\mathsf{T}} \mathbf{Q}_{-i} C \tilde{\mathbf{Q}} \mathbf{x}_i}{1+\delta} \\ &- \frac{\mathbf{u}_i \mathbf{x}_i^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i \mathbf{x}_i^{\mathsf{T}} \tilde{\mathbf{Q}} \mathbf{X}_{-i} \mathbf{v}}{1+\frac{1}{p} \mathbf{x}_i^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i} - \frac{\mathbf{v}_i \mathbf{u}^{\mathsf{T}} \mathbf{X}_{-i}^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i \mathbf{x}_i^{\mathsf{T}} \tilde{\mathbf{Q}} \mathbf{x}_i}{1+\frac{1}{p} \mathbf{x}_i^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i} - \mathbf{u}_i \mathbf{v}_i \frac{\mathbf{x}_i^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i \mathbf{x}_i^{\mathsf{T}} \tilde{\mathbf{Q}} \mathbf{x}_i}{1+\frac{1}{p} \mathbf{x}_i^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i} \end{bmatrix} \\ &- \frac{1}{p} \frac{\mathbf{u}^{\mathsf{T}} \mathbf{X}^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i \mathbf{x}_i^{\mathsf{T}} \mathbf{Q} C \tilde{\mathbf{Q}} \mathbf{X} \mathbf{v}}}{1+\delta} \end{bmatrix}$$

We can show with Holder's inequality and the concentration bounds (mainly the fact that $\frac{1}{p} \boldsymbol{x}_i^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{x}_i$ concentrates around δ) developed in (Louart & Couillet, 2019), that most of the above quantities vanish asymptotically. As a toy example, we consider the following term:

$$\begin{split} \left| \frac{1}{p^2} \sum_{i=1}^n \mathbb{E} \left[\frac{\mathbf{u}^{\mathsf{T}} \mathbf{X}_{-i}^{\mathsf{T}} \mathbf{Q}_{-i} C \tilde{\mathbf{Q}} \mathbf{X}_{-i} v}{1 + \delta} - \frac{\mathbf{u}^{\mathsf{T}} \mathbf{X}_{-i}^{\mathsf{T}} \mathbf{Q}_{-i} x_i x_i^{\mathsf{T}} \tilde{\mathbf{Q}} \mathbf{X}_{-i} v}{1 + \frac{1}{p} x_i^{\mathsf{T}} \mathbf{Q}_{-i} x_i} \right] \right| \\ &= \left| \frac{1}{p^2} \sum_{i=1}^n \mathbb{E} \left[\mathbf{u}^{\mathsf{T}} \mathbf{X}_{-i}^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i \mathbf{x}_i^{\mathsf{T}} \tilde{\mathbf{Q}} \mathbf{X}_{-i} v \frac{\delta - \frac{1}{p} \mathbf{x}_i^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i}{(1 + \delta)(1 + \frac{1}{p} \mathbf{x}_i^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i)} \right] \right| \\ &\leq \left| \frac{1}{p^2} \sum_{i=1}^n \mathbb{E} \left[(\mathbf{u}^{\mathsf{T}} \mathbf{X}_{-i}^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i) (\mathbf{x}_i^{\mathsf{T}} \tilde{\mathbf{Q}} \mathbf{X}_{-i} v) \left(\delta - \frac{1}{p} \mathbf{x}_i^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i) \right) \right] \right| \\ &\leq \left| \frac{1}{p^2} \sum_{i=1}^n \mathbb{E} \left[\left(\mathbf{u}^{\mathsf{T}} \mathbf{X}_{-i}^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i \right)^3 \right] \mathbb{E} \left[\left(\frac{1}{\sqrt{p}} \mathbf{x}_i^{\mathsf{T}} \tilde{\mathbf{Q}} \mathbf{X}_{-i} v \right)^3 \right] \mathbb{E} \left[\left(\delta - \frac{1}{p} \mathbf{x}_i^{\mathsf{T}} \mathbf{Q}_{-i} \mathbf{x}_i \right)^3 \right] \right)^{\frac{1}{3}} \right| \\ &= \mathcal{O} \left(\frac{1}{\sqrt{p}} \right) \end{split}$$

Similarly, we can show that:

$$\left| \frac{1}{p^2} \sum_{i=1}^n \mathbb{E} \left[\frac{\boldsymbol{u}_i \boldsymbol{x}_i^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{C} \tilde{\boldsymbol{Q}} \boldsymbol{X}_{-i} \boldsymbol{v}}{1+\delta} + \frac{\boldsymbol{v}_i \boldsymbol{u}^{\mathsf{T}} \boldsymbol{X}_{-i}^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{C} \tilde{\boldsymbol{Q}} \boldsymbol{x}_i}{1+\delta} \right. \\ \left. + \boldsymbol{u}_i \boldsymbol{v}_i \frac{\boldsymbol{x}_i^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{C} \tilde{\boldsymbol{Q}} \boldsymbol{x}_i}{1+\delta} - \frac{1}{p} \frac{\boldsymbol{u}^{\mathsf{T}} \boldsymbol{X}^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{x}_i \boldsymbol{x}_i^{\mathsf{T}} \boldsymbol{Q} \boldsymbol{C} \tilde{\boldsymbol{Q}} \boldsymbol{X} \boldsymbol{v}}{1+\delta} \right] \right| = \mathcal{O} \left(\frac{1}{\sqrt{p}} \right)$$

Finally, the remaining terms in Δ can be estimated as follows:

$$\begin{split} \Delta &= \frac{1}{p^2} \sum_{i=1}^n \mathbb{E} \left[-\frac{\boldsymbol{u}_i \boldsymbol{x}_i^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{x}_i \boldsymbol{x}_i^{\mathsf{T}} \tilde{\boldsymbol{Q}} \boldsymbol{X}_{-i} \boldsymbol{v}}{1 + \frac{1}{p} \boldsymbol{x}_i^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{x}_i} \right. \\ &- \frac{\boldsymbol{v}_i \boldsymbol{u}^{\mathsf{T}} \boldsymbol{X}_{-i}^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{x}_i \boldsymbol{x}_i^{\mathsf{T}} \tilde{\boldsymbol{Q}} \boldsymbol{x}_i}{1 + \frac{1}{p} \boldsymbol{x}_i^{\mathsf{T}} \boldsymbol{Q} \boldsymbol{x}_i} - \boldsymbol{u}_i \boldsymbol{v}_i \frac{\boldsymbol{x}_i^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{x}_i \boldsymbol{x}_i^{\mathsf{T}} \tilde{\boldsymbol{Q}} \boldsymbol{x}_i}{1 + \frac{1}{p} \boldsymbol{x}_i^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{x}_i} \right] + \mathcal{O} \left(\frac{1}{\sqrt{p}} \right) \\ &= -\frac{2}{p} \frac{\delta \boldsymbol{u}^{\mathsf{T}} \mathbf{1} \bar{\boldsymbol{x}}^{\mathsf{T}} \tilde{\boldsymbol{Q}} \bar{\boldsymbol{x}} \mathbf{1}^{\mathsf{T}} \boldsymbol{v}}{1 + \delta} - \frac{\delta^2 \boldsymbol{u}^{\mathsf{T}} \boldsymbol{v}}{1 + \delta} + \mathcal{O} \left(\sqrt{\frac{\log p}{p}} \right) \end{split}$$

Where the last equality is obtained through the following estimation:

$$\frac{1}{p^2} \sum_{i=1}^n \mathbb{E}\left[\frac{\boldsymbol{v}_i \boldsymbol{u}^{\mathsf{T}} \boldsymbol{X}_{-i}^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{x}_i \boldsymbol{x}_i^{\mathsf{T}} \tilde{\boldsymbol{Q}} \boldsymbol{x}_i}{1 + \frac{1}{p} \boldsymbol{x}_i^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{x}_i}\right] = \frac{1}{p} \sum_{i=1}^n \mathbb{E}\left[\frac{\boldsymbol{v}_i \boldsymbol{u}^{\mathsf{T}} \boldsymbol{X}_{-i}^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{x}_i \left(\frac{1}{p} \boldsymbol{x}_i^{\mathsf{T}} \tilde{\boldsymbol{Q}} \boldsymbol{x}_i(1+\delta) - \delta \left(1 + \frac{1}{p} \boldsymbol{x}_i^{\mathsf{T}} \tilde{\boldsymbol{Q}} \boldsymbol{x}_i\right)\right)}{\left(1 + \frac{1}{p} \boldsymbol{x}_i^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{x}_i\right) (1+\delta)} + \frac{1}{p} \sum_{i=1}^n \frac{\boldsymbol{v}_i \delta \mathbb{E}[\boldsymbol{u}^{\mathsf{T}} \boldsymbol{X}_{-i}^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{x}_i]}{(1+\delta)}$$

With the following bound:

$$\begin{aligned} \left| \frac{1}{p} \boldsymbol{x}_{i}^{\mathsf{T}} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i}(1+\delta) - \delta \left(1 + \frac{1}{p} \boldsymbol{x}_{i}^{\mathsf{T}} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i} \right) \right| \\ &= \left| \frac{1}{p} \boldsymbol{x}_{i}^{\mathsf{T}} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i}(1+\delta) - \delta(1+\delta) + \delta(1+\delta) - \delta \left(1 + \frac{1}{p} \boldsymbol{x}_{i}^{\mathsf{T}} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i} \right) \right| \\ &\leq \left| \frac{1}{p} \boldsymbol{x}_{i}^{\mathsf{T}} \tilde{\boldsymbol{Q}} \boldsymbol{x}_{i} - \delta \right| (1+2\delta), \end{aligned}$$

we have again with Holder's inequality and Proposition 1.4:

$$\frac{1}{p^2} \sum_{i=1}^n \mathbb{E}\left[\frac{\boldsymbol{v}_i \boldsymbol{u}^{\mathsf{T}} \boldsymbol{X}_{-i}^{\mathsf{T}} \boldsymbol{Q}_{-i} \boldsymbol{x}_i \boldsymbol{x}_i^{\mathsf{T}} \tilde{\boldsymbol{Q}} \boldsymbol{x}_i}{1 + \frac{1}{p} \boldsymbol{x}_i^{\mathsf{T}} \boldsymbol{Q} \boldsymbol{x}_i}\right] = \frac{1}{p} \sum_{i=1}^n \frac{\boldsymbol{v}_i \delta \boldsymbol{u}^{\mathsf{T}} \mathbf{1} \bar{\boldsymbol{x}}^{\mathsf{T}} \tilde{\boldsymbol{Q}} \bar{\boldsymbol{x}}}{1 + \delta} + \mathcal{O}\left(\sqrt{\frac{\log p}{p}}\right)$$

Now that we estimated Δ , it remains to estimate $\mathbb{E}[\frac{1}{p}X^{\mathsf{T}}\tilde{Q}X]$. Indeed, given two unit norm vectors $u, v \in \mathbb{R}^n$ we have:

$$\mathbb{E}\left[\frac{1}{p}\boldsymbol{u}^{\mathsf{T}}\boldsymbol{X}^{\mathsf{T}}\tilde{\boldsymbol{Q}}\boldsymbol{X}\boldsymbol{v}\right] = \frac{1}{p}\sum_{i,j=1}^{n}\boldsymbol{u}_{i}\boldsymbol{v}_{j}\mathbb{E}[\boldsymbol{x}_{i}^{\mathsf{T}}\tilde{\boldsymbol{Q}}\boldsymbol{x}_{j}] = \frac{1}{p}\sum_{i=1}^{n}\sum_{j\neq i}^{n}\boldsymbol{u}_{i}\boldsymbol{v}_{j}\bar{\boldsymbol{x}}^{\mathsf{T}}\tilde{\boldsymbol{Q}}\bar{\boldsymbol{x}} + \sum_{i=1}^{n}\boldsymbol{u}_{i}\boldsymbol{v}_{i}\delta$$
$$= \frac{1}{p}\bar{\boldsymbol{x}}^{\mathsf{T}}\tilde{\boldsymbol{Q}}\bar{\boldsymbol{x}}\boldsymbol{u}^{\mathsf{T}}\boldsymbol{1}\boldsymbol{1}^{\mathsf{T}}\boldsymbol{v} + (\delta - \frac{1}{p}\bar{\boldsymbol{x}}^{\mathsf{T}}\tilde{\boldsymbol{Q}}\bar{\boldsymbol{x}})\boldsymbol{u}^{\mathsf{T}}\boldsymbol{v} = \frac{1}{p}\bar{\boldsymbol{x}}^{\mathsf{T}}\tilde{\boldsymbol{Q}}\bar{\boldsymbol{x}}\boldsymbol{u}^{\mathsf{T}}\boldsymbol{M}_{1}\boldsymbol{v}^{\mathsf{T}} + \delta\boldsymbol{u}^{\mathsf{T}}\boldsymbol{v} + \mathcal{O}\left(\frac{1}{p}\right)$$

since we have $\bar{x}^{\mathsf{T}}\tilde{Q}\bar{x} = \mathcal{O}(1)$ by Lemma 1.2; we introduced the matrix $M_1 = \mathbf{11}^{\mathsf{T}}$. Therefore we have the following estimation:

$$\frac{1}{p}\mathbb{E}\left[\boldsymbol{X}^{\mathsf{T}}\boldsymbol{Q}\boldsymbol{X}\right] = \frac{\delta}{1+\delta}\boldsymbol{I}_{n} + \frac{1}{p}\left(\frac{1-\delta}{1+\delta}\right)\bar{\boldsymbol{x}}^{\mathsf{T}}\tilde{\boldsymbol{Q}}\bar{\boldsymbol{x}}\boldsymbol{M}_{1} + \mathcal{O}_{\parallel\cdot\parallel}\left(\sqrt{\frac{\log p}{p}}\right)$$

where $\mathbf{A} = \mathbf{B} + \mathcal{O}_{\|\cdot\|}(\alpha(p))$ means that $\|\mathbf{A} - \mathbf{B}\| = \mathcal{O}(\alpha(p))$. Finally, since \mathbf{R} concentrates around its mean, we can then conclude:

$$\boldsymbol{R} = \frac{1}{z} \left(\boldsymbol{I}_n - \frac{1}{p} \boldsymbol{X}^{\mathsf{T}} \boldsymbol{Q} \boldsymbol{X} \right) = \frac{1}{z} \frac{1}{1+\delta} \boldsymbol{I}_n + \frac{\delta - 1}{pz(\delta+1)} \bar{\boldsymbol{x}}^{\mathsf{T}} \tilde{\boldsymbol{Q}} \bar{\boldsymbol{x}} \boldsymbol{M}_1 + \mathcal{O}_{\|\cdot\|} \left(\sqrt{\frac{\log p}{p}} \right).$$

2. Proof of Proposition 3.1

Proof. Since the Lipschitz constant of a composition of Lipschitz functions is bounded by the product of their Lipschitz constants, we consider the case N = 1 and a linear activation function. In this case, the Lipschitz constant corresponds to the largest singular value of the weight matrix. We consider the following notations for the proof

$$\bar{\boldsymbol{W}}_t = \boldsymbol{W}_t - \eta \boldsymbol{E}_t \text{ with } [\boldsymbol{E}_t]_{i,j} \sim \mathcal{N}(0,1)$$
$$\boldsymbol{W}_{t+1} = \bar{\boldsymbol{W}}_t - \max(0, \bar{\sigma}_{1,t} - \sigma_*) \, \bar{\boldsymbol{u}}_{1,t} \bar{\boldsymbol{v}}_{1,t}^{\mathsf{T}}$$

where $\bar{\sigma}_{1,t} = \sigma_1(\bar{W}_t)$, $\bar{u}_{1,t} = u_1(\bar{W}_t)$ and $\bar{v}_{1,t} = v_1(\bar{W}_t)$. The effect of spectral normalization is observed in the case where $\sigma_* > \bar{\sigma}_{1,t}$, otherwise the Lipschitz constant is bounded by σ_* . We therefore have

$$\|\bar{\boldsymbol{W}}_t\|_F^2 \le \|\boldsymbol{W}_t\|_F^2 + \eta^2 d_1 d_0 \tag{4}$$

$$\|\boldsymbol{W}_{t+1}\|_F^2 = \|\bar{\boldsymbol{W}}_t\|_F^2 + \sigma_*^2 - \bar{\sigma}_{1,t}^2$$
(5)

• If $\|\boldsymbol{W}_{t+1}\|_F \geq \|\boldsymbol{W}_t\|_F$, we have by equation 4 and equation 5

$$\|\bar{\boldsymbol{W}}_t\|_F^2 \le \|\bar{\boldsymbol{W}}_t\|_F^2 + \sigma_*^2 - \bar{\sigma}_{1,t}^2 + \eta^2 d_1 d_0 \ \Rightarrow \ \|\bar{\boldsymbol{W}}_t\| = \bar{\sigma}_{1,t} \le \sqrt{\sigma_*^2 + \eta^2 d_1 d_0} = \delta$$

And since $\|\boldsymbol{W}_{t+1}\| \leq \|\bar{\boldsymbol{W}}_t\|$, we have $\|\boldsymbol{W}_{t+1}\| \leq \delta$.

• Otherwise, if there exits τ such that $\|\boldsymbol{W}_{\tau+1}\|_F < \|\boldsymbol{W}_{\tau}\|_F$, then for all $\varepsilon > 0$ there exists an iteration $\tau' \ge \tau$ such that $\|\boldsymbol{W}_{\tau'}\| \le \delta + \varepsilon$. Indeed, otherwise we denote $\varepsilon_t = \|\boldsymbol{W}_t\|^2 - \delta^2$ and $\varepsilon_t > 0$ for all $t \ge \tau$. And if for all $t \ge \tau$, $\|\boldsymbol{W}_{t+1}\|_F \le \|\boldsymbol{W}_t\|_F$, we have by equation 4 and equation 5

$$\|\boldsymbol{W}_t\|_F^2 - \|\boldsymbol{W}_{t+1}\|_F^2 \ge \|\bar{\boldsymbol{W}}_t\|^2 - \delta^2 \ge \|\boldsymbol{W}_{t+1}\|^2 - \delta^2 = \varepsilon_{t+1}$$

Integrating the above expression from τ to $T-1 \ge \tau$, we end up with

$$\|\boldsymbol{W}_{\tau}\|_{F}^{2} - \|\boldsymbol{W}_{T}\|_{F}^{2} \geq \sum_{t=\tau}^{T-1} \varepsilon_{t} \Rightarrow 0 \leq \|\boldsymbol{W}_{T}\|_{F}^{2} \leq \|\boldsymbol{W}_{\tau}\|_{F}^{2} - \sum_{t=\tau}^{T-1} \varepsilon_{t},$$

therefore, when $T \to \infty$, ε_t has to tend to 0 otherwise the right hand-side of the last inequality will tend to $-\infty$ which is absurd.

References

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