

A. Missing Proofs from Section 3

Before proving Lemma 4, we first need the following Lemma that bounds the probability of a single arm being misordered when deciding which arms to remove in a round:

Lemma 3. *Assume that the best arm was not eliminated prior to round m . Let $[x]_+ = \max(x, 0)$. Then for any arm $x_i \in S_m$,*

$$\mathbb{P}[\langle \hat{\theta}_m, x_i \rangle > \langle \hat{\theta}_m, x_1 \rangle] \leq \exp\left(-\frac{[\Delta_i - (2 + 2\sqrt{2h_{|S_m|/4}})\gamma_{\max}]_+^2 T}{16 \log_2(n) h_{|S_m|/4} \sigma^2}\right)$$

Proof. For simplicity, we will drop all subscripts m in this proof, so that we say $\hat{\theta}$ instead of $\hat{\theta}_m$ and \mathcal{Z} instead of \mathcal{Z}_m etc. By slight abuse of notation, let $y \in \mathbb{R}^N$ be the vector of true rewards for the sampled arms \mathcal{Z} , let $\gamma \in \mathbb{R}^N$ be the misspecification vector, and let $X \in \mathbb{R}^{N \times d}$ be the design matrix whose rows are the elements of \mathcal{Z} . That is, we have $y = X\theta + \gamma$. Let $s = \hat{y} - y$, all of whose components are independent 1-subgaussian random variables

Fix some index i . Notice that if i does not satisfy $\Delta_i > (2 + 2\sqrt{2h_{S_m}})|\gamma_{\max}|$, then the statement is trivially true. Therefore, we may safely assume $\Delta_i > (2 + 2\sqrt{2h_{S_m}})|\gamma_{\max}|$

Let $\theta' = \operatorname{argmin}_{X\theta = X\theta'} \|\theta'\|_2$. Notice that $y = X\theta + \gamma = X\theta' + \gamma$ implies that using θ' does not introduce more misspecification. (In fact, $\theta = \theta'$ if X has rank d .) Further, by Lemma 10, we have that $x_i - x_j$ is in the span of \mathcal{Z} for all x_i and x_j in S_m , so that $\langle \theta', x_i - x_j \rangle = \langle \theta, x_i - x_j \rangle$ for all i and j .

Then, after the player obtains the vector of rewards \hat{y} by playing each arm in \mathcal{Z} , the estimate $\hat{\theta}$ is given by:

$$\begin{aligned} \hat{\theta} &= \operatorname{argmin}_{\theta \in \operatorname{span}(\mathcal{Z})} \sum_{x_i \in \hat{\mathcal{Z}}} (\langle \theta, x_i \rangle - \hat{y}_i)^2 \\ &= \operatorname{argmin}\{\|\hat{\theta}\|_2 \text{ s.t. } X^T X \hat{\theta} = X^T \hat{y}\} \end{aligned}$$

Now, since for any v there exists u such that $X^T X u = X^T v$, we have:

$$\begin{aligned} \hat{\theta} &= (X^T X)^\dagger X^T \hat{y} = (X^T X)^\dagger X^T (X\theta + s + \gamma) \\ &= \theta' + (X^T X)^\dagger X^T (s + \gamma) \end{aligned}$$

This implies:

$$\begin{aligned} \langle \hat{\theta}, x_i \rangle &> \langle \hat{\theta}, x_1 \rangle \\ \langle \hat{\theta}, x_i - x_1 \rangle - y_i + y_1 &\geq \Delta_i \\ \langle \hat{\theta} - \theta', x_i - x_1 \rangle &> \Delta_i - \gamma_1 + \gamma_i \\ &\geq \Delta_i - 2\gamma_{\max} \end{aligned}$$

Substituting in our expression for $\hat{\theta}$, we have that the probability that the empirical average of the best arm is smaller than the empirical average of arm i is at most

$$\mathbb{P}[(x_i - x_1)^T (X^T X)^\dagger X^T (s + \gamma) > \Delta_i - 2\gamma_{\max}]$$

Next, we will need some guarantee about the quality of the set \mathcal{Z} . By Theorem 5, `GetArms` returns \mathcal{Z} that satisfies $|\mathcal{Z}| = N$ and

$$\sup_{x_i - x_j \in S_m} (x_j - x_i)^T \left(\sum_{z \in \mathcal{Z}} z z^T \right)^\dagger (x_j - x_i) \leq 8 \frac{h_{|S_m|/4}}{N} \quad (3)$$

Using this fact, we apply Cauchy-Schwarz to obtain:

$$\begin{aligned}
 |(x_i - x_1)^T (X^T X)^\dagger X^T \gamma| &\leq \|X(X^T X)^\dagger(x_i - x_1)\|_2 \|\gamma\|_2 \\
 &\leq \sqrt{N} \|\gamma\|_\infty \sqrt{\sup_{x_i, x_j \in S_m} (x_j - x_i)^T (X^T X)^\dagger (x_j - x_i)} \\
 &= \sqrt{N} \|\gamma\|_\infty \sqrt{\sup_{x_i, x_j \in S_m} (x_j - x_i)^T \left(\sum_{z \in \hat{Z}} z z^T \right)^\dagger (x_j - x_i)} \\
 &\leq \sqrt{N} \sqrt{\frac{8h_{|S_m|/4}}{N}} \|\gamma\|_\infty \leq \sqrt{8h_{|S_m|/4}} \gamma_{\max}
 \end{aligned}$$

Thus,

$$\begin{aligned}
 &\mathbb{P}[(x_i - x_1)^T (X^T X)^\dagger X^T (s + \gamma) > \Delta_i - 2\gamma_{\max}] \leq \\
 &\mathbb{P}\left[(x_i - x_1)^T (X^T X)^\dagger X^T s > \Delta_i - \left(2 + \sqrt{8h_{|S_m|/4}}\right) \gamma_{\max}\right]
 \end{aligned}$$

Then, since s is a mean zero, σ -subgaussian vector, for any $v \in \mathbb{R}^N$, $\langle v, s \rangle$ is a mean 0, $\|v\|_2 \sigma$ -subgaussian random variable. Applying the Hoeffding bound, for any $\epsilon > 0$,

$$\mathbb{P}[\langle v, s \rangle > \epsilon] \leq \exp\left(-\frac{\epsilon^2}{2\|v\|_2^2 \sigma^2}\right)$$

We will substitute $X(X^T X)^\dagger(x_i - x_1)$ for v in the above formulation of Hoeffding's bound. To start, we compute the norm:

$$\begin{aligned}
 \|X(X^T X)^\dagger(x_i - x_1)\|_2^2 &= (x_i - x_1)^T (X^T X)^\dagger (x_i - x_1) \\
 &\leq \sup_{x_i, x_j \in Z} (x_j - x_i)^T \left(\sum_{z \in \hat{Z}} z z^T \right)^\dagger (x_j - x_i) \leq 8 \frac{h_{|S_m|/4}}{N}
 \end{aligned}$$

Then substituting $N = \frac{T}{\log_2 n}$, and combining the above, we get that

$$\begin{aligned}
 &\mathbb{P}[(x_i - x_1)^T (X^T X)^\dagger X^T (s + \gamma) \geq \Delta_i - 2\gamma_{\max}] \leq \\
 &\exp\left(-\frac{(\Delta_i - (2 + 2\sqrt{2h_{|S_m|/4}})\gamma_{\max})^2 T}{16 \log_2(n) h_{|S_m|/4} \sigma^2}\right)
 \end{aligned}$$

□

Next, following (Karnin et al., 2013), we provide the missing proof of Lemma 4:

Lemma 4. *Assume that the best arm was not eliminated prior to round m , and let $[x]_+ = \max(0, x)$. Then the probability that the best arm is eliminated on round m is at most*

$$3 \exp\left(-\frac{\left[\Delta_{\frac{1}{4}|S_m|} - (2 + 2\sqrt{2h_{\frac{1}{4}|S_m|}})\gamma_{\max}\right]_+^2 T}{16 \log_2(n) h_{|S_m|/4} \sigma^2}\right)$$

Proof. If the best arm is thrown out at round m , there are at least $\frac{1}{2}|S_m|$ arms in S_m whose \hat{y} estimates are higher than that of the best arm. Let $S'_m \subset S_m$ be the set of arms that excludes the $\frac{1}{4}|S_m|$ arms with the largest true means in S_m . If the best arm is thrown out, then at least $\frac{1}{3}$ of arms in S'_m must have higher \hat{y} estimates than that of the best arm. Let N_m be the

number of such arms. Define $D = \max\{(\Delta_{\frac{1}{4}|S_m|} - (2 + 2\sqrt{2h_{|S_m|/4}})\gamma_{\max})^2, 0\}$. Then using Lemma 3, the expected number of such arms is at most

$$\begin{aligned}\mathbb{E}[N_m] &= \sum_{x_i \in S'_m} \mathbb{P}[\langle \hat{\theta}, x_i \rangle \geq \langle \hat{\theta}, x_1 \rangle] \\ &\leq |S'_m| \exp\left(-\frac{DT}{16 \log_2(n) h_{|S_m|/4} \sigma^2}\right)\end{aligned}$$

Then, by Markov inequality, the probability of the best arm being thrown out at round m is at most

$$\mathbb{P}\left[N_m > \frac{1}{3}|S'_m|\right] \leq \frac{\mathbb{E}[N_m]}{\frac{1}{3}|S'_m|} \leq 3 \exp\left(-\frac{DT}{16 \log_2(n) h_{|S_m|/4} \sigma^2}\right)$$

□

B. Missing Proofs from Section 4

Before proving Theorem 5, we need the following Lemmas, which characterize the quality of the candidate set of arms returned by the method of (Allen-Zhu et al., 2017).

First, we have the following easy technical Lemma:

Lemma 10. *If for some sets S and \mathcal{Z}*

$$\sup_{x_i - x_j \in S} (x_j - x_i)^T \left(\sum_{z \in \mathcal{Z}} z z^T \right)^\dagger (x_j - x_i) < \infty$$

then $S \subset \text{span}(\mathcal{Z})$.

Proof. Fix any $x = x_i - x_j \neq 0, x_i, x_j \in S$. Then, since

$$x^T \left(\sum_{z \in \mathcal{Z}} z z^T \right)^\dagger x < \infty$$

there exists y s.t.

$$\left(\sum_{z \in \mathcal{Z}} z z^T \right) y = \sum_{z \in \mathcal{Z}} z (z^T y) = x$$

which implies that $x \in \text{span}(\mathcal{Z})$. □

Lemma 11. *Given the set $S \subset \mathcal{A} \subset \mathbb{R}^d$ the objective f_S above, and a number $N \geq d$ the output $\hat{\mathcal{Z}}$ of OptDesign satisfies $\hat{\mathcal{Z}} \subset \mathcal{A}, |\hat{\mathcal{Z}}| \leq N$ and $\sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{z \in \hat{\mathcal{Z}}} z z^T \right)^\dagger (x_j - x_i) \leq \frac{14}{N} \inf_v \inf_{\|\pi\|_1 \leq N} \sup_{x_i \in S} (x_i - v)^T \left(\sum_{a \in \mathcal{A}} \pi(a) a a^T \right)^\dagger (x_i - v) \leq 14 \frac{d}{N}$. That is, $\sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{z \in \hat{\mathcal{Z}}} z z^T \right)^\dagger (x_j - x_i) \leq \tilde{d}$ and also $\tilde{d} \leq d$.*

Proof. Let

$$\mathcal{Z} = \underset{\substack{\mathcal{Z}' \subset \mathcal{A} \\ |\mathcal{Z}'| \leq N}}{\text{argmin}} \left\{ \sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{z \in \mathcal{Z}'} z z^T \right)^\dagger (x_j - x_i) \right\} \quad (4)$$

Note that we consider \mathcal{Z} to be a set *with multiplicity* - it is permitted for an element to appear multiple times in \mathcal{Z} . Computing \mathcal{Z} exactly is NP-hard, but (Allen-Zhu et al., 2017) provides a way to approximate the solution. Note that equation 4 can be restated as follows:

$$c^* = \underset{c \in \{0, 1, 2, \dots, N\}^{|\mathcal{A}|}}{\text{argmin}} \left\{ \sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{a \in \mathcal{A}} c(a) a a^T \right)^\dagger (x_j - x_i) \right\} \quad (5)$$

where c is treated as a vector in $|\mathcal{A}|$ indexed by $a \in \mathcal{A}$ and \mathcal{Z} is related to c^* as

$$\mathcal{Z} = \{a \in \mathcal{A} \text{ repeated } c^*(a) \text{ times}\}$$

Then, define the continuous relaxation of the objective in 5 as:

$$\pi^* = \operatorname{argmin}_{\substack{\|\pi\|_1 \leq N \\ \pi \in [0, N]^{|\mathcal{A}|}}} \left\{ \sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{a \in \mathcal{A}} \pi(a) a a^T \right)^\dagger (x_j - x_i) \right\} \quad (6)$$

Section 3 from (Allen-Zhu et al., 2017) guarantees that a polynomial-time continuous optimization procedure can find a fractional solution π such that

$$\sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{a \in \mathcal{A}} \pi(a) a a^T \right)^\dagger (x_j - x_i) \leq 7/6 \sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{a \in \mathcal{A}} \pi^*(a) a a^T \right)^\dagger (x_j - x_i)$$

At the same time, Theorem 2.1 from (Allen-Zhu et al., 2017) (see Appendix C) provides a polynomial-time algorithm that rounds any fractional solution π to an integer solution c such that

$$\sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{a \in \mathcal{A}} c(a) a a^T \right)^\dagger (x_j - x_i) \leq 3 \sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{a \in \mathcal{A}} \pi(a) a a^T \right)^\dagger (x_j - x_i)$$

Combining the two equations, we get that there exists a polynomial-time algorithm that finds an integer solution c (or, equivalently, set \mathcal{Z}) such that

$$\sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{a \in \mathcal{A}} c(a) a a^T \right)^\dagger (x_j - x_i) \leq 7/2 \sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{a \in \mathcal{A}} \pi^*(a) a a^T \right)^\dagger (x_j - x_i)$$

Now, notice that for any solution π , we have:

$$\begin{aligned} & \sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{a \in \mathcal{A}} \pi(a) a a^T \right)^\dagger (x_j - x_i) \\ &= \inf_v \sup_{x_i, x_j \in S} (x_j - v + v x_i)^T \left(\sum_{a \in \mathcal{A}} \pi(a) a a^T \right)^\dagger (x_j - v + v x_i) \\ &\leq \inf_v \sup_{x_i, x_j \in S} (x_i - v)^T \left(\sum_{a \in \mathcal{A}} \pi(a) a a^T \right)^\dagger (x_i - v) + (x_j - v)^T \left(\sum_{a \in \mathcal{A}} \pi(a) a a^T \right)^\dagger (x_j - v) + 2(x_j - v)^T \left(\sum_{a \in \mathcal{A}} \pi^*(a) a a^T \right)^\dagger (x_i - v) \end{aligned}$$

Now, observe that $a^T M b = \langle \sqrt{M} a, \sqrt{M} b \rangle \leq \frac{a^T M a}{2} + \frac{b^T M b}{2}$ for any positive-semidefinite matrix M by Young inequality. Therefore:

$$\begin{aligned} \sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{a \in \mathcal{A}} \pi^*(a) a a^T \right)^\dagger (x_j - x_i) &\leq 4 \inf_v \inf_{\substack{\|\pi\|_1 \leq N \\ \pi \in [0, N]^{|\mathcal{A}|}}} \sup_{x \in S} (x - v)^T \left(\sum_{a \in \mathcal{A}} \pi(a) a a^T \right)^\dagger (x - v) \\ &\leq \frac{4}{N} \inf_v \inf_{\substack{\|\pi\|_1 \leq 1 \\ \pi \in [0, N]^{|\mathcal{A}|}}} \sup_{x \in S} (x - v)^T \left(\sum_{a \in \mathcal{A}} \pi(a) a a^T \right)^\dagger (x - v) \\ &\leq 4 \frac{d}{N} \end{aligned}$$

where the last line follows from setting $v = 0$ and applying the Kiefer-Wolfowitz theorem (Kiefer & Wolfowitz, 1960).

Thus, combining everything, we get that

$$\begin{aligned} & \sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{a \in \mathcal{A}} c(a) a a^T \right)^\dagger (x_j - x_i) \leq \\ & 7/2 \sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{a \in \mathcal{A}} \pi^*(a) a a^T \right)^\dagger (x_j - x_i) \leq \\ & \frac{14}{N} \inf_v \inf_{\substack{\|\pi\|_1 \leq 1 \\ \pi \in [0, N]^{|\mathcal{A}|}}} \sup_{x \in S} (x - v)^T \left(\sum_{a \in \mathcal{A}} \pi(a) a a^T \right)^\dagger (x - v) \leq \\ & 14 \frac{d}{N} \end{aligned}$$

□

Lemma 11 depends only on the budget N and the number of dimensions d . Notice that the bound does not depend on distribution of the arms.

Lemma 12. *Given the objective f_S , the set \mathcal{A} , and a number $N \geq |S|$, the output \mathcal{Z} of `GetArms` satisfies $|\mathcal{Z}| \leq N$ and $\sup_{x_i, x_j \in S} (x_j - x_i)^T (\sum_{z \in \mathcal{Z}} z z^T)^\dagger (x_j - x_i) \leq 2 \frac{|S|}{N}$.*

Proof. By Lemma 14, for any $x_i, x_j \in S$,

$$(x_j - x_i)^T \left(\sum_{x \in S} x x^T \right)^\dagger (x_j - x_i) \leq 2$$

So, letting $\tilde{\mathcal{Z}} \leftarrow \{s \in S \text{ repeated } \frac{N}{|S|} \text{ times}\}$

$$\begin{aligned} & \sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{z \in \tilde{\mathcal{Z}}} z z^T \right)^\dagger (x_j - x_i) \\ & \leq \frac{|S|}{N} \sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{x \in S} x x^T \right)^\dagger (x_j - x_i) \\ & \leq 2 \frac{|S|}{N} \end{aligned}$$

□

While the above Lemma requires the number of pulls to be greater than the candidate set S , the next Lemma shows that it is possible to bound the performance of `OptDesign` even if $N < |S|$.

Lemma 13. *Given the objective f_S , the set \mathcal{A} , and a number N , the output \mathcal{Z} of `GetArms` satisfies $|\mathcal{Z}| \leq N$ and $\sup_{x_i, x_j \in S} (x_j - x_i)^T (\sum_{z \in \mathcal{Z}} z z^T)^\dagger (x_j - x_i) \leq 6 \frac{|S|}{N}$.*

Proof. Given any fractional solution to f_S π , using Theorem 2.1 from (Allen-Zhu et al., 2017), `OptDesign` outputs an integer solution \mathcal{Z} such that

$$\begin{aligned} & \sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{z \in \mathcal{Z}} z z^T \right)^\dagger (x_j - x_i) \leq \\ & 3 \sup_{x_i, x_j \in \mathcal{Z}} (x_j - x_i)^T \left(\sum_{z \in \mathcal{Z}} \pi_z z z^T \right)^\dagger (x_j - x_i) \leq \\ & 3 \sup_{z_i, z_j \in \mathcal{Z}} (x_j - x_i)^T \left(\sum_{z \in S} \frac{N}{|S|} z z^T \right)^\dagger (x_j - x_i) \leq \\ & 3 \frac{|S|}{N} \sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{z \in S} z z^T \right)^\dagger (x_j - x_i) \leq 6 \frac{|S|}{N} \end{aligned}$$

where the last step uses Lemma 14 below. □

Now we prove Lemma 14:

Lemma 14. *Let x_1, \dots, x_n be arbitrary vectors in \mathbb{R}^d . Let X be a matrix s.t. i th row of X corresponds to x_i for all i . Then for any j, k ,*

$$(x_j - x_k)^T (X^T X)^\dagger (x_j - x_k) \leq 2$$

Proof. For any j , $x_j = X^T e_j$ where e_j is the j th identity vector. Then for any j, k ,

$$\begin{aligned} & (x_j - x_k)^T (X^T X)^\dagger (x_j - x_k) = \\ & (e_j - e_k)^T X (X^T X)^\dagger X^T (e_j - e_k) \end{aligned}$$

Let $e = e_j - e_k$, and let $u = (X^T X)^\dagger X^T e$. Then,

$$\begin{aligned} X^T X u &= X^T e \implies X^T (X u - e) = 0 \implies \\ X u - e &\in \ker(X^T) \implies X u - e \perp \text{Im}(X) \end{aligned}$$

Then there exists a w such that $e = X u + Q w$, where Q is a matrix with columns orthogonal to columns of X . Then,

$$e^T X (X^T X)^\dagger X^T e = u^T X^T X (X^T X)^\dagger X^T X u$$

By definition of u , $u \perp \ker(X^T X)$, and thus

$$\begin{aligned} (x_j - x_k)^T (X^T X)^\dagger (x_j - x_k) &= \\ u^T X^T X (X^T X)^\dagger X^T X u &= \\ u^T X^T X u = \|X u\|_2^2 &\leq \|e\|_2^2 = 2 \end{aligned}$$

because $\|e\|_2^2 = \|X u\|_2^2 + \|Q w\|_2^2$ □

Given the above, we are ready to proof Theorem 5.

Proof of Theorem 5. Combining Lemmas 11, 12, and 13, we get that on inputs S , N and \mathcal{A} , `GetArms` produces a set \mathcal{Z} such that if $\frac{T}{\lceil \log_2 n \rceil} = N \geq |S|$, `GetArms` returns a set \mathcal{Z} that satisfies:

$$\sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{z \in \mathcal{Z}} z z^T \right)^\dagger (x_j - x_i) \leq \min \left\{ \frac{8|S|/4}{N}, \frac{14\tilde{d}}{N} \right\} = 8 \frac{h_{|S|/4}}{N}$$

Similarly, if $N < |S|$, `GetArms` returns a set \mathcal{Z} that satisfies:

$$\sup_{x_i, x_j \in S} (x_j - x_i)^T \left(\sum_{z \in \mathcal{Z}} z z^T \right)^\dagger (x_j - x_i) \leq \min \left\{ 14 \frac{\tilde{d}}{N}, 24 \frac{|S|/4}{N} \right\} = 8 \frac{h_{|S|/4}}{N}$$

□

C. Properties of the Objective f_S

In this section we verify that the assumptions required to use the approach of (Allen-Zhu et al., 2017) in `GetArms` hold.

C.1. Equivalence of objectives

Lemma 15. Assume we are given a set of n vectors $\mathcal{Z} \subset \mathbb{R}^d$ that span a k -dimensional subspace. Let $Z \in \mathbb{R}^{n \times d}$ be a matrix such that each row represents a vector in \mathcal{Z} . Let $Q \in \mathbb{R}^{k \times d}$ be a matrix with orthogonal rows such that $\text{span}(Q^T) = \text{span}(Z^T)$. Define $M = (Q Q^T)^{-1/2} Q$. Then, for any symmetric, positive semi-definite matrix $A \in \mathbb{R}^{d \times d}$ such that $A^\dagger z < \infty$ for all $z \in \mathcal{Z}$, it holds that $M A M^T$ is invertible and for all $z \in \mathcal{Z}$

$$(M z)^T (M A M^T)^{-1} M z = z^T A^\dagger z$$

Proof.

$$M A M^T = (Q Q^T)^{-1/2} Q A Q^T (Q Q^T)^{-1/2}$$

Since A is a symmetric PSD matrix, it has a symmetric PSD root $A^{1/2}$. Since $(Q Q^T)^{-1/2}$ is invertible, $A^{1/2} Q^T (Q Q^T)^{-1/2}$ has rank less than k iff there exists $v \neq 0$,

$$A^{1/2} Q^T v = A^{1/2} \left(\sum_{i=1}^k v_i q_i \right) = 0$$

where q_i correspond to rows of Q . By assumption, for each $z_i \in \mathcal{Z}$, there exists y_i s.t. $Ay_i = A^{1/2}A^{1/2}y_i = z_i$. Thus, $z_i \in \text{Im}(A^{1/2})$ for all i . Since $\text{span}(Z^T) = \text{span}(Q^T)$, it must be that $\sum_{i=1}^k v_i q_i \in \text{Im}(A^{1/2})$. Since the kernel of $A^{1/2}$ is orthogonal to the image of $A^{1/2}$, we get that $A^{1/2}(\sum_{i=1}^k v_i q_i) = 0$ iff $\sum_{i=1}^k v_i q_i = 0$, which is impossible, since q_i form an orthogonal set.

Thus, $B = A^{1/2}Q^T(QQ^T)^{-1/2}$ has rank k , and thus $MAM^T = B^T B \in \mathbb{R}^{k \times k}$ is invertible.

Moreover, note that if \mathcal{Z} is not in the image of A , then MAM^T is not invertible.

For the second part of the Lemma, fix some $z \in \mathcal{Z}$. By assumption, there exists $y \in \mathbb{R}^d$ s.t. $A^\dagger z = y$, which implies that $Ay = z$ and y is orthogonal to $\ker(A)$. Since A is a symmetric PSD matrix, this means that $y \in \text{Im}(A)$. Let $Q_1 \in \mathbb{R}^{k_1 \times d}$ be an orthogonal row matrix s.t. the rows of Q and Q_1 together span $\text{Im}(A)$ and rows of Q and Q_1 are orthogonal to each other. Notice that that implies that $A = [Q^T | Q_1^T] \Lambda [Q^T | Q_1^T]^T$ where Λ is diagonal. Then, $y = Q^T w + Q_1^T w_1$ for some w, w_1 . Then substituting the definition of M and using the fact that $Ay = z$,

$$\begin{aligned} (Mz)^T (MAM^T)^{-1} Mz &= z^T Q^T (QAQ^T)^{-1} QAy = \\ &= z^T Q^T (QAQ^T)^{-1} QA(Q^T w + Q_1^T w_1) = \\ &= z^T Q^T w + z^T Q^T (QAQ^T)^{-1} QAQ_1^T w_1 \end{aligned}$$

Then,

$$\begin{aligned} QAQ_1^T &= Q[Q^T | Q_1^T] \Lambda [Q^T | Q_1^T]^T Q_1^T = \\ &= [I_{k \times k} | \mathbf{0}_{k \times k_1}] \Lambda [\mathbf{0}_{k_1 \times k}^T | I_{k_1 \times k_1}]^T = \mathbf{0} \end{aligned}$$

Thus, the equation above becomes

$$(Mz)^T (MAM^T)^{-1} Mz = z^T Q^T w$$

Since columns in Q_1 are orthogonal to columns of z ,

$$\begin{aligned} z^T A^\dagger z &= z^T y = z^T Q^T w = \\ &= (Mz)^T (MAM^T)^{-1} Mz \end{aligned}$$

□

Using the above, given a set of arms $\mathcal{A} \subset \mathbb{R}^d$ and a set $\mathcal{Z} \subset \mathbb{R}^d$, define M as in Lemma 15. Then for any subset $\mathcal{A}' \subset \mathcal{A}$,

$$\begin{aligned} \sup_{z \in \mathcal{Z}} (Mz)^T \left(\sum_{x \in \mathcal{A}'} Mx(Mx)^T \right)^{-1} Mz &= \\ \sup_{z \in \mathcal{Z}} z^T \left(\sum_{x \in \mathcal{A}'} xx^T \right)^\dagger z & \end{aligned}$$

where we use

$$(Mz)^T \left(\sum_{x \in \mathcal{A}'} Mx(Mx)^T \right)^{-1} Mz = \infty$$

if $\sum_{x \in \mathcal{A}'} Mx(Mx)^T$ is not invertible. Notice that if $\mathcal{Z} = \{z_i - z_j | z_i, z_j \in \mathcal{S}\}$ for some set of arms \mathcal{S} , and $\mathcal{S} \subset \text{span}(\mathcal{A})$, then \mathcal{Z} is in the image of $\sum_{x \in \mathcal{A}} xx^T$.

Thus, if we are give a number N , sets \mathcal{Z}, \mathcal{A} , then

$$\begin{aligned} \operatorname{argmin}_{\substack{\mathcal{X} \subset \mathcal{A} \\ |\mathcal{A}| \leq N}} f_{\mathcal{Z}}(\mathcal{X}) &= \\ \operatorname{argmin}_{\substack{\mathcal{X} \subset \mathcal{A} \\ |\mathcal{A}| \leq N}} \sup_{z \in \mathcal{Z}} z^T \left(\sum_{x \in \mathcal{X}} xx^T \right)^\dagger z &= \\ \operatorname{argmin}_{\substack{\mathcal{X} \subset \mathcal{A} \\ |\mathcal{A}| \leq N}} \sup_{z \in \mathcal{Z}} (Mz)^T \left(\sum_{x \in \mathcal{X}} Mx(Mx)^T \right)^{-1} Mz & \end{aligned}$$

The algorithm `GetArms` ensures that $\mathcal{Z} \subset \mathcal{A}$, and $N \geq \dim(\text{span}(\mathcal{Z}))$ whenever it attempts to find a solution to

$$\underset{\substack{\mathcal{X} \subset \mathcal{A} \\ |\mathcal{A}| \leq N}}{\text{argmin}} f_{\mathcal{Z}}(\mathcal{X})$$

Thus, every time the minimization algorithm for the above objective is called, there exists a subset \mathcal{X} that makes $f_{\mathcal{Z}}$ finite. Moreover, $\sum_{x \in \mathcal{X}} Mx(Mx)^T$ is invertible.

Using this, we can now replace the minimization objective with

$$\underset{\substack{\tilde{\mathcal{X}} \subset \tilde{\mathcal{A}} \\ |\tilde{\mathcal{A}}| \leq N}}{\text{argmin}} \sup_{z \in \tilde{\mathcal{Z}}} z^T \left(\sum_{x \in \tilde{\mathcal{X}}} xx^T \right)^{-1} z$$

where $\tilde{\mathcal{A}} = M\mathcal{A}$ and $\tilde{\mathcal{Z}} = M\mathcal{Z}$. Notice that then, the solution to the objective $\tilde{\mathcal{X}}$ forms an invertible matrix $\sum_{x \in \tilde{\mathcal{X}}} xx^T$. Thus, to find an approximate solution, we can use the procedure in (Allen-Zhu et al., 2017) that finds an approximate solution over the space of positive-definite matrices. Moreover, if $\mathcal{Z} \subset \mathbb{R}^d$ span \mathbb{R}^d , then $M = I$ and the two objective are exactly the same.

C.2. Solution over the set of positive-definite matrices

By the discussion in the previous section, we can assume that the objective optimized in `GetArms` has the following form:

Given a set of arms $\mathcal{A} \subset \mathbb{R}^k$ that span \mathbb{R}^k , a subset $Z \in \mathcal{A}$ and number of pulls per round N ,

$$f(M) = \sup_{\substack{z = z_i - z_j \\ z_i, z_j \in \mathcal{A}}} z^T M^{-1} z$$

Below, we will show that f satisfies the conditions required by the approximation algorithm (Allen-Zhu et al., 2017) hold.

f satisfies the following assumptions (see (Allen-Zhu et al., 2017)):

- (A1) Monotonicity: for any $A, B \in \mathbb{S}_d^+$ with $A \preceq B$, $f(A) \geq f(B)$
- (A2) Reciprocal sub-linearity: for any $A \in \mathbb{S}_d^+$ and $t \in (0, 1)$, $f(tA) \leq t^{-1}f(A)$
- (A3) Polynomial-time approximability of continuous relaxation: for any fixed $\delta \in (0, 1)$, the continuous relaxation of 4 defined as

$$\min_{s \in C} F(s) = \min_{s \in C} f\left(\sum_{i=1}^{Nn} s_i x_i x_i^T\right) \text{ where}$$

$$C = \left\{s \in [0, N]^{Nn} : \sum_{i=1}^{Nn} s_i \leq N\right\}$$

can be solved with $(1 + \delta)$ -relative error by a polynomial-time algorithm.

Assumptions (A1) and (A2) trivially hold. As for assumption (A3), notice that

Theorem 16. f is a convex function in s over a convex set C .

Proof. Given any $s_1, s_2 \in C$ and $t \in [0, 1]$,

$$\left(t \sum_{i=1}^{Nn} s_{1,i} x_i x_i^T + (1-t) \sum_{i=1}^{Nn} s_{2,i} x_i x_i^T \right)^{-1} \preceq$$

$$t \left(\sum_{i=1}^{Nn} s_{1,i} x_i x_i^T \right)^{-1} + (1-t) \left(\sum_{i=1}^{Nn} s_{2,i} x_i x_i^T \right)^{-1}$$

Let

$$z = \operatorname{argmax}_{\substack{z = z_i - z_j \\ z_i, z_j \in Z}} z^T \left(t \sum_{i=1}^{Nn} s_{1,i} x_i x_i^T + (1-t) \sum_{i=1}^{Nn} s_{2,i} x_i x_i^T \right) z$$

Then, using (A1),

$$\begin{aligned} F(ts_1 + (1-t)s_2) &= \\ z^T \left(t \sum_{i=1}^n s_{1,i} x_i x_i^T + (1-t) \sum_{i=1}^n s_{2,i} x_i x_i^T \right) z &\leq \\ tz^T \left(\sum_{i=1}^n s_{1,i} x_i x_i^T \right)^{-1} z + (1-t) z^T \left(\sum_{i=1}^n s_{2,i} x_i x_i^T \right)^{-1} z &\leq \\ tF(s_1) + (1-t)F(s_2) \end{aligned}$$

□

Thus, since $F(s)$ is convex, there are a number of convex solvers that minimize F over C in polynomial time. For completeness, we also show that entropic mirror descent method from (Allen-Zhu et al., 2017) can be used to optimize F : Assumptions B1 and B3 are trivially satisfied, while for B2, F_λ is Lipschitz because it is convex.

Then, notice that equation (4) can be restated as follows: let $\{x_1, x_2, \dots, x_{N \times n}\}$ be a set of arms such that each of the n arms in \mathcal{A} is replicated exactly N times. Then, minimizing (4) is equivalent to

$$\begin{aligned} \operatorname{argmin}_{s \in S} F(s) &= \operatorname{argmin}_{s \in S} f\left(\sum_{i=1}^{Nn} s_i x_i x_i^T\right) \text{ where} \\ S &= \{s \in \{0, 1, \dots, N\}^{Nn} : \sum_{i=1}^{Nn} s_i \leq N\} \end{aligned}$$

Thus, using Theorem 2.1 from (Allen-Zhu et al., 2017) (stated below, using our notation) and assuming $T \geq 45d \log_2 n$, we get that

Theorem 17. *Suppose $\varepsilon \in (0, 1/3]$, $Nn \geq N \geq 5d/\varepsilon^2$, $b \in \{1, 2, \dots, N\}$, and $f : S_d^+ \rightarrow \mathbb{R}$ satisfies assumptions (A1) and (A2). Let $\pi \in C$ by any fractional solution so that $F(\pi) < \infty$. Then, in time complexity $\tilde{O}(Nnd^2)$ we can round π to an integral solution*

$$\hat{s} \in S \text{ satisfying } F(\hat{s}) \leq (1 + 6\varepsilon)F(\pi)$$

where $C = \{c \in [0, N]^{Nn} : \sum_{i=1}^{Nn} c_i \leq N\}$.

For completion, we also note that our algorithm is almost optimal, which follows from Theorem 1.4 from (Allen-Zhu et al., 2017):

Theorem 18. *Suppose $\varepsilon \in (0, 1/3]$, $Nn \geq N \geq 5d/\varepsilon^2$, $f : S_d^+ \rightarrow \mathbb{R}$ satisfies assumptions (A1)-(A3), and $\min_{s \in S} F(s) < +\infty$. Then, there exist a polynomial-time algorithm that outputs $\hat{s} \in S$ satisfying*

$$F(\hat{s}) \leq (1 + 8\varepsilon) \min_{s \in S} F(s)$$

Thus, under assumption that $T > 45d \log_2 n$, using $N = \frac{T}{\log_2 n} \geq 45d$, we get that there exists an $\varepsilon \in (0, 1/3]$ s.t. $N\varepsilon^2 \geq 5d$ and so the hypotheses of Theorem 18 are satisfied. In particular, we have the following result:

Theorem 19. *If $T > 45d \log_2(n)$, then in `GetArms`, the output $\hat{\mathcal{X}}$ provided by the algorithm of (Allen-Zhu et al., 2017) satisfies:*

$$f_S(\hat{\mathcal{X}}) \leq \frac{11}{3} \inf_{|\mathcal{X}|=N} f_S(\mathcal{X})$$

D. Proof of Theorem 6

Theorem 6. *Given a d -dimensional linear bandit pure-exploration algorithm, any $p \in (0, 1/2)$, and any $n \geq d$, there exists an problem instance on which the probability of identifying the best arm is at most $1 - \exp\left(\frac{-(15+o(1))T}{p(1-p)\bar{H}_2}\right)$, where the $o(1)$ depends on n, T and p and goes to zero as $T \rightarrow \infty$.*

Proof. Suppose otherwise. Then given any d -armed multi-armed bandit problem with true rewards y_1, \dots, y_d contained in $[p, 1-p]$, we construct an $d+1$ -dimensional linear bandit problem as follows: choose an arbitrary orthonormal set $z_1, \dots, z_d \subset \mathbb{R}^{d+1}$. Set $\theta = \sum_{i=1}^d y_i z_i$. For $i > d$, set $x_i = z_i$ where now r_i is an arbitrary value in $[0, p]$, and z_i is an arbitrary vector such that $\langle z - i, z_j \rangle = 0$ for all $i \leq d$. When our algorithm queries arm x_i for $i \leq d$, we provide an observed Bernoulli reward with mean $\langle x_i, \theta \rangle = y_i$, and for $i > d$, we provide $\langle x_i, \theta \rangle < p$. Then finding the best arm in this setting is equivalent to finding the best arm in the original multi-armed bandit problem. The value H_2 in the multi-armed bandit instance is $\max_{i \leq d} i \Delta_i^{-2} \geq \frac{1}{3} \bar{H}_2$, and so the Theorem follows from (Audibert & Bubeck, 2010a) Theorem 4. \square

E. Proof of Theorem 7

Theorem 7. *Given a linear bandit pure-exploration algorithm, there exists a problem instance on which the probability of identifying the best arm is at most $1 - \exp(-T \cdot (1/\sqrt{H_{LB}} + 2 \sin \frac{\pi}{n}))^2$.*

We will use the following construction. Consider a problem instance with set A of n arms x_1, x_2, \dots, x_n that are equispaced on the unit circle $S^1 \subset \mathbb{R}^2$ (the construction can be extended to higher dimensions). The angle between every consecutive pair of arms is therefore $\frac{2\pi}{n}$. Let θ have unit norm and be aligned along x_1 . Consider the set of parameter vectors M that are exactly aligned along one of the arms, i.e. $M := \{x_1, x_2, \dots, x_n\}$. By rotational invariance, for any parameter vector $\lambda \in M$, the problem instances will have exactly the same value of H_{LB} . Now, we can use the same construction as in the proof of Theorem 1 from (Degenne et al., 2020), but with the added assumption that the strategy ψ has knowledge of the H_{LB} value for the two problem instances, to show the following:

Lemma 20. *For any linear-bandit fixed budget algorithm running for time T and achieving error probability δ , for all $\theta \in M$, we have*

$$\frac{T}{\log_2(1/\delta)} \geq \frac{1}{\max_{w \in D_d} \min_{\lambda \in M, \lambda \in -\theta} \|\theta - \lambda\|_{V_w}^2},$$

where $-\theta$ refers to the set $\{\lambda : \max_{a \in A} \lambda^T a > \max_{a \in A} \theta^T a\}$

Proof. Suppose there exists a linear bandit fixed-budget algorithm for which the above bound is not true. We will use such an algorithm. along with the value of H_{LB} from the construction to create a fixed-confidence strategy ψ to distinguish between two problem instances with parameter vector $\theta, \lambda \in M$, as described in the proof of Theorem 1 of (Degenne et al., 2020), from which the lemma follows. \square

We can further show the following lemma, that relates $\min_{\lambda \in M, \lambda \in -\theta} \|\theta - \lambda\|^2$

Lemma 21. *For a fixed w and θ , we have*

$$\min_{\lambda \in M, \lambda \in -\theta} \|\theta - \lambda\|_{V_w} < \min_{\lambda \in S^1, \lambda \in -\theta} \|\theta - \lambda\|_{V_w} + 2 \sin \frac{\pi}{n}$$

Proof. Let λ^* be the minimizer of $\min_{\lambda \in S^1, \lambda \in -\theta} \|\theta - \lambda\|_{V_w}$. By definition of M , there exists a $\lambda' \in M$ such that $\|\lambda' - \lambda^*\|_{V_w} \leq \|\lambda' - \lambda^*\|_2 \|V_w\|_2 = 2 \sin \frac{\pi}{n} \|V_w\|_2 \leq 2 \sin \frac{\pi}{n}$. The last inequality is true since $\|V_w\|_2 = \|\sum_{i=1}^d w_i x_i x_i^T\|_2 \leq \sum_{i=1}^d w_i \|x_i x_i^T\| = 1$, since the w_i lie on a simplex and x_i lie on the unit circle. \square

Using the above two lemmas, we have

$$\begin{aligned}
 \frac{T}{\log_2(1/\delta)} &\geq \frac{1}{\max_{w \in D_d} \min_{\lambda \in M, \lambda \in -\theta} \|\theta - \lambda\|_{V_w}^2} \\
 &= \frac{1}{\max_{w \in D_d} (\min_{\lambda \in M, \lambda \in -\theta} \|\theta - \lambda\|_{V_w})^2} \\
 &\geq \frac{1}{\max_{w \in D_d} (\min_{\lambda \in S^1, \lambda \in -\theta} \|\theta - \lambda\|_{V_w} + 2 \sin \frac{\pi}{n})^2} \\
 &\geq \frac{1}{\left(\frac{1}{\sqrt{H_{LB}}} + 2 \sin \frac{\pi}{n}\right)^2}
 \end{aligned}$$

where the last inequality follows from Lemma 8 of (Degenne et al., 2020). The theorem follows.

F. Proofs for Section 6

Lemma 8. *The probability that $y_{1,m+1} < y_{1,m} - \epsilon$ is at most:*

$$3 \exp\left(-\frac{\max\{(\epsilon - (2 + \sqrt{2h_{|S_m|/4})\gamma_{\max})^2, 0\}T}{\log_2(n)h_{|S_m|/4}}\right)$$

Proof. Define $\Delta_{i,m} \leq \Delta_i$ to be the gap between the i th best arm and the best arm remaining in S_m . Then notice that the result of Lemma 3 still holds if we replace x_1 with the best arm remaining in S_m and Δ_i with $\Delta_{i,m}$

Let S_m^ϵ be the set of arms in S_m with y value less than $y_{1,m} - \epsilon$. Notice that in order for $y_{1,m+1}$ to be less than $y_{1,m} - \epsilon$, we must have $|S_m|/2$ elements of $|S_m^\epsilon|$ to have \hat{y} values larger than those of the best arm left in S_m . Let $S_m^{\epsilon'}$ be the set of arms that excludes the $\frac{1}{4}|S_m|$ arms with highest true mean from S_m^ϵ . Then if $y_{1,m+1} < y_{1,m}$, we must have $\frac{1}{3}$ of the arms in $S_m^{\epsilon'}$ have higher \hat{y} estimates than the best arm in S_m . Let N_m be the number of such arms. Define $D = \max\{(\epsilon - (2 + \sqrt{h_{|S_m|/4})\gamma_{\max})^2, 0\}$.

Then, since all arms in S_m^ϵ have $\Delta_{i,m} \geq \epsilon$, we have by Lemma 3 that

$$\mathbb{E}[N_m] \leq |S_m^{\epsilon'}| \exp\left(-\frac{DT}{\log_2(n)h_{|S_m|/4}}\right)$$

So using Markov inequality in exactly the same way as in the proof of Lemma 3, the conclusion follows. \square