Effective Structured Prompting by Meta-Learning and Representative Verbalizer

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Abstract

Prompt tuning for pre-trained masked language models (MLM) has shown promising performance in natural language processing tasks with few labeled examples. It tunes a prompt for the downstream task, and a verbalizer is used to bridge the predicted token and label prediction. Due to the limited training data, prompt initialization is crucial for prompt tuning. Recently, MetaPrompting (Hou et al., 2022) uses metalearning to learn a shared initialization for all taskspecific prompts. However, a single initialization is insufficient to obtain good prompts for all tasks and samples when the tasks are complex. Moreover, MetaPrompting requires tuning the whole MLM, causing a heavy burden on computation and memory as the MLM is usually large. To address these issues, we use a prompt pool to extract more task knowledge and construct instancedependent prompts via attention. We further propose a novel soft verbalizer (RepVerb) which constructs label embedding from feature embeddings directly. Combining meta-learning the prompt pool and RepVerb, we propose MetaPrompter for effective structured prompting. MetaPrompter is parameter-efficient as only the pool is required to be tuned. Experimental results demonstrate that MetaPrompter performs better than the recent state-of-the-arts and RepVerb outperforms existing soft verbalizers.

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1. Introduction

In recent years, large pre-trained language models have achieved great success in solving a variety of downstream tasks (Howard & Ruder, 2018; Devlin et al., 2019; Yang et al., 2019; Conneau & Lample, 2019; Song et al., 2020; Guo et al., 2020; Raffel et al., 2020; Brown et al., 2020; Lester et al., 2021; Cui et al., 2022). Though fine-tuning the whole model (Howard & Ruder, 2018; Devlin et al., 2019) is effective and widely-used, optimizing and storing all the task-specific parameters can be compute- and memoryexpensive when the model is large (e.g., GPT-3 (Brown et al., 2020) contains 100+ billion parameters). To alleviate this issue, many approaches have been proposed. Examples include adapter tuning (Houlsby et al., 2019; Lin et al., 2020; Hu et al., 2022a) and prompt learning (Radford et al., 2019; Shin et al., 2020; Brown et al., 2020; Lester et al., 2021; Liu et al., 2021; Li & Liang, 2021; Liu et al., 2022b; Prasad et al., 2022; Liu et al., 2022a). However, prompt learning is more preferable due to its effectiveness and also that it can be easily plugged into a pre-trained MLM without invasive modification (Li & Liang, 2021; Hambardzumyan et al., 2021; He et al., 2022; Sun et al., 2022).

Prompt learning formulates the downstream task as a cloze-style MLM problem. It is useful for few-shot tasks due to its effectiveness, parameter-efficiency, and plug-and-play nature (Radford et al., 2019; Brown et al., 2020; Liu et al., 2022a). Specifically, prompt learning wraps an input text with a discrete prompt (e.g., "Topic is [MASK]") and feeds it to the MLM to predict a token at the [MASK] position. A verbalizer (Lester et al., 2021; Ding et al., 2022; Hu et al., 2022b) then maps the predicted token to the label. However, designing an effective prompt requires a good understanding of the downstream tasks.

Recently, *prompt tuning* (Lester et al., 2021; Liu et al., 2021; Zhang et al., 2022) proposes to wrap the input embedding with a *continuous* prompt. To reduce the number of parameters to be learned, the MLM is kept frozen. The continuous prompt can be further combined with discrete tokens to form a *template* (Liu et al., 2021; Schick & Schütze, 2021; Ding et al., 2022).

Prompt tuning can be sensitive to initialization (Lester et al.,

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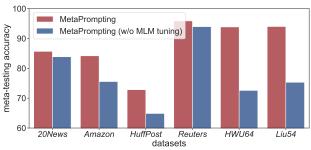


Figure 1. 5-way 5-shot classification meta-testing accuracy of MetaPrompting with or without MLM tuning on six data sets.

2021). Recently, a number of approaches have been proposed to alleviate this problem (Lester et al., 2021; Li et al., 2022; Vu et al., 2022). In particular, MetaPrompting (Hou et al., 2022) is the state-of-the-art that uses metalearning (Bengio et al., 1991; Thrun & Pratt, 1998; Finn et al., 2017) to learn a meta-initialization for all task-specific prompts. However, MetaPrompting suffers from three problems. (i) When the tasks are complex, it is challenging to obtain good prompts for all tasks and samples from a single meta-initialized prompt. (ii) MetaPrompting uses a hand-crafted verbalizer. However, selecting good label tokens for the hand-crafted verbalizer is labor-intensive and not scalable for a large label set. (iii) MetaPrompting requires expensive tuning the whole MLM. Figure 1 shows a large gap in meta-testing accuracies with and without MLM tuning (experimental details are in Section 4).

In this paper, we use a pool of multiple prompts (Li et al., 2022; Wang et al., 2022a;b) to extract task knowledge from meta-training tasks, and then construct instance-dependent prompts as weighted combinations of all the prompts in the pool via attention (Vaswani et al., 2017). The attention's query vector is the instance's feature embedding. The prompt pool is the shared meta-knowledge and learned by the MAML algorithm (Finn et al., 2017). Specifically, given a task with a support set and a query set, the base learner takes the meta-parameter and the support set to build a task-specific prompt pool, then the meta-learner optimizes the meta-parameter on the query set. Meta-learning a prompt pool is more flexible than meta-learning only a single prompt initialization (as in MetaPrompting), and allows better adaptation of complex tasks. Moreover, as only the prompt pool is tuned, it is much more parameter-efficient than MetaPrompting (with $1000 \times$ fewer parameters).

We also propose a novel soft verbalizer called *representative verbalizer* (RepVerb), which constructs label embeddings by averaging feature embeddings of the corresponding training samples. Unlike manually-designed verbalizers, RepVerb does not incur human effort for label token selection. Moreover, as RepVerb does not require learning any additional parameters, empirical results in Section 4.2 demonstrate that RepVerb is more effective than the soft verbalizers in WARP (Hambardzumyan et al., 2021), DART (Zhang et al.,

2022), ProtoVerb (Cui et al., 2022). Besides, the feature embedding learned by RepVerb is more discriminative.

The whole procedure, which combines meta-learning the structured prompts and RepVerb, is called **MetaPrompter** in the sequel. Experiments are performed on six widely used classification data sets. Results demonstrate that RepVerb outperforms existing soft verbalizers, and is also beneficial to other prompt-based methods such as MetaPrompting. Moreover, MetaPrompter achieves better performance than the recent state-of-the-arts.

Our contributions are summarized as follows: (i) We propose a parameter-efficient algorithm MetaPrompter for effective structured prompting. (ii) We propose a simple and effective soft verbalizer (RepVerb). (iii) Experimental results demonstrate the effectiveness and parameter-efficiency of MetaPrompter.

2. Preliminaries and Related Work

2.1. Prompt Learning

Recently, it is common to use a pre-trained MLM $\mathcal{M}(\cdot; \phi)$, with parameter ϕ , for various downstream tasks such as language understanding (Dong et al., 2019; Yang et al., 2019; Song et al., 2020), machine translation (Conneau & Lample, 2019; Guo et al., 2020), and text classification (Brown et al., 2020; Lester et al., 2021; Liu et al., 2022b). Given a raw sentence represented as a sequence of n tokens (x_1, \ldots, x_n) , the MLM takes $\mathbf{x} = ([CLS], x_1, \dots, x_n, [SEP])$ as input (where [CLS] is the start token and [SEP] is the separator), and encodes it into a sequence of hidden representations ($\mathbf{h}_{\lceil \text{CLS} \rceil}, \mathbf{h}_1, \dots, \mathbf{h}_n, \mathbf{h}_{\lceil \text{SEP} \rceil}$). In standard finetuning (Howard & Ruder, 2018; Devlin et al., 2019), an extra classifier (e.g., a fully connected layer with softmax normalization) is added on top of $\mathbf{h}_{\texttt{[CLS]}}$ to predict the label distribution. This classifier, together with ϕ , are tuned to maximize the probability of correct labels. As language models are large (e.g., 175 billion parameters in GPT-3 (Brown et al., 2020)), fine-tuning all parameters can cause a heavy burden on computation and memory.

On the other hand, prompt learning (Brown et al., 2020; Shin et al., 2020; Ding et al., 2022) freezes the pretrained model and formulates the downstream task as a cloze-style MLM problem. For example, in topic classification, "Topic is [MASK]" can be used as the prompt, where [MASK] is a special token for prediction. The *discrete* tokens "Topic is" are also called anchor tokens. An input text \mathbf{x} is wrapped with the prompt and mapped to an input embedding sequence $(\mathcal{E}(\mathbf{x}), \mathcal{E}(\texttt{Topic}), \mathcal{E}(\texttt{is}), \mathcal{E}(\texttt{[MASK]}))$, where $\mathcal{E}(\cdot)$ denotes the input embedding. Designing a suitable prompt requires domain expertise and a good understanding of the downstream tasks (Brown et al., 2020; Sanh et al.,

2022). Thus, manually-designed prompts are likely to be sub-optimal.

Unlike discrete prompts, prompt tuning (Lester et al., 2021; Liu et al., 2021) uses a *continuous* prompt $\theta \in \mathbb{R}^{L_p \times d_i}$ (of length L_p) to directly wrap the input embedding sequence as $(\mathcal{E}(\mathbf{x}), \theta, \mathcal{E}([MASK]))$. This can be further combined with anchor tokens to form a *template* (Liu et al., 2021; Schick & Schütze, 2021; Ding et al., 2022):

$$\tilde{\mathbf{x}} \equiv \mathbb{T}(\mathbf{x}; \boldsymbol{\theta}) = (\mathcal{E}(\mathbf{x}), \boldsymbol{\theta}, \mathcal{E}(\texttt{Topic}), \mathcal{E}(\texttt{is}), \mathcal{E}(\texttt{[MASK]})).$$

The MLM then outputs the hidden embedding $\mathbf{h}_{\text{[MASK]}}(\tilde{\mathbf{x}}) \in \mathbb{R}^{d_o}$ of [MASK], and infers the token to be filled at the [MASK] position.

A verbalizer (Lester et al., 2021; Ding et al., 2022; Hu et al., 2022b) bridges the prediction at the [MASK] position and labels in prompt learning. Specifically, it is a hard mapping from each label y to a set of label-relevant tokens \mathcal{V}_y . For example, for y = SPORTS, we can have $\mathcal{V}_y = \{\text{sports}, \text{football}, \text{basketball}\}$. Prompt tuning then optimizes (ϕ, θ) by maximizing the label probability:

$$\hat{\mathbb{P}}(y|\mathbf{x}; \boldsymbol{\phi}, \boldsymbol{\theta}) = \frac{1}{|\mathcal{V}_y|} \sum_{\mathbf{w} \in \mathcal{V}_y} \mathbb{P}_{\mathcal{M}}(\text{[MASK]} = \mathbf{w} | \mathbb{T}(\mathbf{x}; \boldsymbol{\theta})), (1)$$

where $\mathbb{P}_{\mathcal{M}}([MASK]|\mathbb{T}(\mathbf{x};\boldsymbol{\theta}))$ is the probability distribution over vocabulary as predicted by the MLM at the [MASK] position.

The verbalizer is crucial to the performance of prompt learning (Lester et al., 2021; Ding et al., 2022). However, selecting label-relevant tokens requires intensive human labor. To address this problem, search-based methods (Schick et al., 2020; Shin et al., 2020; Gao et al., 2021) try to find label tokens automatically from the training data. However, searching in a discrete space is computationally intensive (Schick et al., 2020; Shin et al., 2020; Gao et al., 2021), especially with a large number of labels or vocabulary. Some recent works (Hambardzumyan et al., 2021; Zhang et al., 2022; Cui et al., 2022) propose soft verbalizers, which map each label to a continuous embedding and predict the label distribution based on the similarities between feature embedding and label embeddings. WARP (Hambardzumyan et al., 2021) and DART (Zhang et al., 2022) obtain this label embedding by supervised learning, while ProtoVerb (Cui et al., 2022) uses contrastive learning (Chen et al., 2020; Tian et al., 2020). However, learning the embedding $\mathbf{v}_y \in \mathbb{R}^{d_o}$ for each label y can be challenging in the few-shot learning setting (Gao et al., 2019; Bao et al., 2020; Han et al., 2021; Chen et al., 2022; Hou et al., 2022), as the number of samples per class is typically much smaller than d_o (e.g., $d_o = 768$ for BERT (Devlin et al., 2019)).

2.2. Meta-Learning for Prompt Learning

In meta-learning (Bengio et al., 1991; Thrun & Pratt, 1998), a collection \mathcal{T} of tasks are used to learn a shared meta-parameter. Each task $\tau \in \mathcal{T}$ has a support set \mathcal{S}_{τ} and a query set \mathcal{Q}_{τ} . Let \mathcal{Y}_{τ} be the label set of τ . Typical meta-learning algorithms can be metric-based (Vinyals et al., 2016; Snell et al., 2017; Bertinetto et al., 2018; Lee et al., 2019), memory-based (Santoro et al., 2016; Munkhdalai & Yu, 2017), or optimization-based (Finn et al., 2017; Rajeswaran et al., 2019; Raghu et al., 2020; Ye et al., 2021; Jiang et al., 2021; 2022; Flennerhag et al., 2022). In general, the optimization-based approach is preferred due to its simplicity and effectiveness. A representative algorithm is model-agnostic meta-learning (MAML) (Finn et al., 2017).

As prompt tuning is sensitive to prompt initialization in few-shot tasks (Lester et al., 2021), meta-learning can be used to search for a good initialization. MetaPrompting (Hou et al., 2022) uses MAML to learn a meta-initialization for the task-specific prompts. At iteration t, the base learner takes a task τ and meta-parameter $(\phi_{t-1}, \theta_{t-1})$, and builds a task-specific model $(\phi_{t,J}, \theta_{t,J})$ by performing J gradient updates on the support set with step size α and initialization $(\phi_{t,0}, \theta_{t,0}) \equiv (\phi_{t-1}, \theta_{t-1})$:

$$(\phi_{t,j}, \boldsymbol{\theta}_{t,j}) = (\phi_{t,j-1}, \boldsymbol{\theta}_{\mathbf{x},j-1}) + \alpha \nabla_{(\boldsymbol{\phi}_{t,j-1}, \boldsymbol{\theta}_{\mathbf{x},j-1})} \sum_{(\mathbf{x}, y) \in \mathcal{S}_{\tau}} \log \hat{\mathbb{P}}(y | \mathbf{x}; \boldsymbol{\phi}_{t,j-1}, \boldsymbol{\theta}_{\mathbf{x},j-1}).$$

The meta-learner then updates the meta-initialization by maximizing the log-likelihood objective on the query set with step size η :

$$(\phi_t, \boldsymbol{\theta}_t) = (\phi_{t-1}, \boldsymbol{\theta}_{t-1}) + \eta \nabla_{(\phi_{t-1}, \boldsymbol{\theta}_{t-1})} \sum_{(\mathbf{x}, y) \in \mathcal{Q}_{\tau}} \log \hat{\mathbb{P}}(y | \mathbf{x}; \phi_{t, J}, \boldsymbol{\theta}_{t, J}).$$

Though MetaPrompting achieves state-of-the-art performance in the few-shot classification experiments (Hou et al., 2022), it suffers from the three problems discussed in Section 1. (i) When the tasks are complex, it is challenging to use a single meta-initialized prompt for adaptation to the various tasks. (ii) MetaPrompting uses a hand-crafted verbalizer, which is labor-intensive and not scalable as discussed in Section 2.1. (iii) MetaPrompting needs to tune the MLM parameters, and thus is not parameter-efficient.

3. Proposed Method

In Section 3.1, we first propose a novel and effective soft verbalizer (representative verbalizer) without inducing additional parameters. Moreover, while MetaPrompting uses a single prompt initialization to build task-specific prompts, we propose in Section 3.2 the extraction of task knowledge

 $^{^{1}\}phi$ can be fixed for parameter-efficiency in prompt learning.

Algorithm 1 Representative Verbalizer (RepVerb).

- 1: **procedure** ComputeLabelEmbedding(S_{τ}):
- 2: compute $\mathbf{h}_{[MASK]}(\tilde{\mathbf{x}})$ for $(\mathbf{x}, \cdot) \in \mathcal{S}_{\tau}$;
- 3: compute \mathbf{v}_y by (2) for $y \in \mathcal{Y}_\tau$;
- 4: end procedure

1: **procedure** Predict($\mathbf{x}; \mathbf{v}_y : y \in \mathcal{Y}_{\tau}$)

2: compute $\mathbf{h}_{[MASK]}(\tilde{\mathbf{x}})$ for \mathbf{x} ;

3: compute $\mathbb{P}(y|\mathbf{x}; \boldsymbol{\phi}, \boldsymbol{\theta})$ by (3);

4: end procedure

into a pool of multiple prompts, and constructs instancedependent prompts by attention (Vaswani et al., 2017).

3.1. Representative Verbalizer (RepVerb)

Instead of explicitly learning an embedding \mathbf{v}_y for each label y (Hambardzumyan et al., 2021; Cui et al., 2022; Zhang et al., 2022), we propose the *Representative Verbalizer* (RepVerb), which constructs \mathbf{v}_y from feature embeddings of the corresponding training samples (Algorithm 1). It does not require learning additional parameters, and is thus more effective on limited data as in few-shot learning.

Specifically, let $S_{\tau,y}$ be the subset of samples in S_{τ} with label y. For an input \mathbf{x} , we wrap it with the template and feed $\tilde{\mathbf{x}} \equiv \mathbb{T}(\mathbf{x}; \boldsymbol{\theta})$ to the pre-trained MLM, and then obtain [MASK] 's embedding $\mathbf{h}_{\text{[MASK]}}(\tilde{\mathbf{x}})$ as its feature embedding. Similar to ProtoNet (Snell et al., 2017), we propose to construct \mathbf{v}_y for each y by averaging the corresponding samples' feature embeddings, as:

$$\mathbf{v}_{y} = \frac{1}{|\mathcal{S}_{\tau,y}|} \sum_{(\mathbf{x},y) \in \mathcal{S}_{\tau,y}} \mathbf{h}_{[\text{MASK}]}(\tilde{\mathbf{x}}). \tag{2}$$

To predict the label of a given \mathbf{x} , we measure the cosine similarity² between $\mathbf{h}_{[MASK]}(\tilde{\mathbf{x}})$ and each \mathbf{v}_y $(y \in \mathcal{Y}_\tau)$:

$$\tilde{\mathbb{P}}(y|\mathbf{x};\boldsymbol{\phi},\boldsymbol{\theta}) = \frac{\exp(\rho\cos(\mathbf{v}_y, \mathbf{h}_{[MASK]}(\tilde{\mathbf{x}})))}{\sum_{y' \in \mathcal{Y}} \exp(\rho\cos(\mathbf{v}_{y'}, \mathbf{h}_{[MASK]}(\tilde{\mathbf{x}})))}, \quad (3)$$

where $\rho>0$ is the temperature. When $\rho\to\infty, \tilde{\mathbb{P}}(y|\mathbf{x};\boldsymbol{\phi},\boldsymbol{\theta})$ becomes one-hot; whereas when $\rho\to0, \,\tilde{\mathbb{P}}(y|\mathbf{x};\boldsymbol{\phi},\boldsymbol{\theta})$ becomes uniform. In the experiments, we set $\rho=10$ as in Oreshkin et al. (2018).

3.2. Meta Structured-Prompting

In the following, we propose the use of MAML and attention mechanism (Vaswani et al., 2017) to meta-learn a prompt pool. While MetaPrompting uses task-specific prompts (Hou et al., 2022), we propose the construction of instance-specific prompts, which allows more flexibility.

3.2.1. META-LEARN A PROMPT POOL

While MetaPrompting uses only a single initialization for the prompt, we propose to leverage a pool of prompts to extract more task knowledge, which is particularly effective when the tasks are complex and very different prompts may be needed. A prompt pool has K learnable prompts $\{(\mathbf{k}_i, \boldsymbol{\theta}_i): i=1,\ldots,K\}$, with key $\mathbf{k}_i \in \mathbb{R}^{d_o}$ and value $\boldsymbol{\theta}_i \in \mathbb{R}^{L_p \times d_i}$ (Li et al., 2022; Wang et al., 2022a;b). Note that the size of the prompt pool is negligible compared with that of the MLM. For example, in our experiments, the MLM has 109.52×10^6 parameters, while the prompt pool has only 55,296.

The prompt pool can be considered as shared metaknowledge. Given an input \mathbf{x} , the attention weights between \mathbf{x} and the K prompts are computed as $\mathbf{a} = \operatorname{softmax}(\frac{\mathbf{K}\mathbf{q}_{\mathbf{x}}}{\sqrt{d_o}})$, where $\operatorname{softmax}(\cdot)$ is the softmax function, $\mathbf{K} = [\mathbf{k}_1^\top; \dots; \mathbf{k}_K^\top]$, and $\mathbf{q}_{\mathbf{x}} \in \mathbb{R}^{d_o}$ is the embedding of the <code>[MASK]</code> output by a pre-trained and frozen MLM with the wrapped input (e.g., $(\mathbf{x}. \texttt{Topicis}[MASK])$) (Wang et al., 2022a;b). Such a mapping from \mathbf{x} to $\mathbf{q}_{\mathbf{x}}$ is called the query function $q(\cdot)$. An instance-dependent prompt is then generated by weighted averaging over all the values $(\boldsymbol{\theta}_i$'s):

$$\boldsymbol{\theta}_{\mathbf{x}}(\mathbf{K}, \boldsymbol{\Theta}) = \sum_{i=1}^{K} a_i \boldsymbol{\theta}_i, \tag{4}$$

where $\Theta = [\theta_1; \dots; \theta_K]$. While Wang et al. (2022a;b) only select the top-N most similar prompts from the pool, in (4) all the prompts are used and updated simultaneously.

The proposed procedure for meta-learning the prompt pool $(\mathbf{K}, \boldsymbol{\Theta})$, which will be called MetaPrompter, is shown in Algorithm 2. The MAML algorithm (Finn et al., 2017) is used here, but other meta-learning algorithms (e.g., Reptile (Nichol et al., 2018), BMG (Flennerhag et al., 2022)) can also be used. At iteration t, the base learner takes $(\mathbf{K}_{t-1}, \boldsymbol{\Theta}_{t-1})$ and a task τ to optimize for a task-specific prompt pool by gradient descent (steps 4-15). $(\mathbf{K}_{t-1}, \boldsymbol{\Theta}_{t-1})$ is used as the initialization (step 4). For each inner iteration j, $(\mathbf{K}_{t,j-1}, \boldsymbol{\Theta}_{t,j-1})$ constructs the instance-dependent prompts $\boldsymbol{\theta}_{\mathbf{x},j}(\mathbf{K}_{t,j-1}, \boldsymbol{\Theta}_{t,j-1})$ in (4) (steps 7 and 8). Next, $\boldsymbol{\theta}_{\mathbf{x},j}$ is used to predict the label probability with a combination of the hand-crafted verbalizer (step 9) and soft verbalizer (steps 11 and 12):

$$\mathbb{P}(y|\mathbf{x};\boldsymbol{\theta}_{\mathbf{x},j}) = (1-\lambda)\hat{\mathbb{P}}(y|\mathbf{x};\boldsymbol{\theta}_{\mathbf{x},j}) + \lambda \tilde{\mathbb{P}}(y|\mathbf{x};\boldsymbol{\theta}_{\mathbf{x},j}), \quad (5)$$

where $\lambda \in [0,1]$ (in the experiments, we set $\lambda = 0.5$). Let $\mathcal{L}(\mathcal{S}_{\tau}; \mathbf{K}_{t,j-1}, \mathbf{\Theta}_{t,j-1}) = -\sum_{(\mathbf{x},y)\in\mathcal{S}_{\tau}} \log \mathbb{P}(y|\mathbf{x}; \boldsymbol{\theta}_{\mathbf{x},j})$ be the loss on \mathcal{S}_{τ} (step 13). The base learner builds a

²Dissimilarity measures, such as the Euclidean distance, can also be used.

Algorithm 2 MetaPrompter.

```
Require: prompt length L_p; size of prompt pool K; \lambda = 0.5; step sizes \alpha, \eta; meta-parameters (\mathbf{K}, \boldsymbol{\Theta}); query function q(\cdot);
  1: for t = 1, ..., T do
                  sample a task \tau = (S_{\tau}, Q_{\tau}) \in \mathcal{T};
  2:
  3:
                   base learner:
  4:
                   (\mathbf{K}_{t,0},\mathbf{\Theta}_{t,0}) \equiv (\mathbf{K}_{t-1},\mathbf{\Theta}_{t-1});
                  for j = 1, \dots, J do
   5:
                           for (\mathbf{x}, y) \in \mathcal{S}_{\tau} do
   6:
   7:
                                    compute \mathbf{q}_{\mathbf{x}} by q(\cdot);
                                    \boldsymbol{\theta}_{\mathbf{x},j}(\mathbf{K}_{t,j-1},\boldsymbol{\Theta}_{t,j-1}) = \operatorname{softmax}(\mathbf{K}_{t,j-1}\mathbf{q}_{\mathbf{x}})^{\top}\boldsymbol{\Theta}_{t,j-1};
  8:
  9:
                                    feed \tilde{\mathbf{x}} \equiv \mathbb{T}(\mathbf{x}; \boldsymbol{\theta}_{\mathbf{x},j}) into \mathcal{M}, obtain \mathbf{h}_{[MASK]}(\tilde{\mathbf{x}}), and \hat{\mathbb{P}}(y|\mathbf{x}; \boldsymbol{\theta}_{\mathbf{x},j}) by (1);
10:
11:
                           call ComputeLabelEmbedding(S_{\tau}) of Algorithm 1 to obtain \{\mathbf{v}_y : y \in \mathcal{Y}_{\tau}\};
                           for (\mathbf{x}, y) \in \mathcal{S}_{\tau}, call Predict (\mathbf{x}, \mathbf{v}_{\eta}; y \in \mathcal{Y}_{\tau}) of Algorithm 1 to obtain \mathbb{P}(y|\mathbf{x}; \boldsymbol{\theta}_{\mathbf{x}, j}), and compute \mathbb{P}(y|\mathbf{x}; \boldsymbol{\theta}_{\mathbf{x}, j}) by (5);
12:
                           \mathcal{L}(\mathcal{S}_{\tau}; \mathbf{K}_{t,j-1}, \mathbf{\Theta}_{t,j-1}) = -\sum_{(\mathbf{x},y) \in \mathcal{S}_{\tau}} \log \mathbb{P}(y|\mathbf{x}; \boldsymbol{\theta}_{\mathbf{x},j});
13:
                           (\mathbf{K}_{t,j},\mathbf{\Theta}_{t,j}) = (\mathbf{K}_{t,j-1},\mathbf{\Theta}_{t,j-1}) - \alpha \nabla_{(\mathbf{K}_{t,j-1},\mathbf{\Theta}_{t,j-1})} \mathcal{L}(\mathcal{S}_{\tau};\mathbf{K}_{t,j-1},\mathbf{\Theta}_{t,j-1});
14:
15:
                  end for
16:
                  meta-learner:
17:
                  for (\mathbf{x}, y) \in \mathcal{Q}_{\tau} do
18:
                           compute \mathbf{q}_{\mathbf{x}} by q(\cdot);
                           \boldsymbol{\theta}_{\mathbf{x},J}(\mathbf{K}_{t,J},\boldsymbol{\Theta}_{t,J}) = \operatorname{softmax}(\mathbf{K}_{t,J}\mathbf{q}_{\mathbf{x}})^{\top}\boldsymbol{\Theta}_{t,J};
19:
                           call Predict(\mathbf{x}; \mathbf{v}_y : y \in \mathcal{Y}_{\tau}) of Algorithm 1 to obtain \tilde{\mathbb{P}}(y|\mathbf{x}; \boldsymbol{\theta}_{\mathbf{x},J});
20:
                           compute \mathbb{P}(y|\mathbf{x}; \boldsymbol{\theta}_{\mathbf{x},J}) and \mathbb{P}(y|\mathbf{x}; \boldsymbol{\theta}_{\mathbf{x},J}) by (1) and (5), respectively;
21:
22:
                  \mathcal{L}(\mathcal{Q}_{\tau}; \mathbf{K}_{t,J}, \mathbf{\Theta}_{t,J}) = -\sum_{(\mathbf{x},y) \in \mathcal{Q}_{\tau}} \log \mathbb{P}(y|\mathbf{x}; \boldsymbol{\theta}_{\mathbf{x},J});
23:
                   (\mathbf{K}_t, \mathbf{\Theta}_t) = (\mathbf{K}_{t-1}, \mathbf{\Theta}_{t-1}) - \eta \nabla_{(\mathbf{K}_{t-1}, \mathbf{\Theta}_{t-1})} \mathcal{L}(\mathcal{Q}_\tau; \mathbf{K}_{t,J}, \mathbf{\Theta}_{t,J});
24:
25: end for
26: return (\mathbf{K}_T, \mathbf{\Theta}_T).
```

task-specific prompt pool $(\mathbf{K}_{t,J}, \mathbf{\Theta}_{t,J})$ by taking J gradient updates $(j = 1, \dots, J)$ at step 14:

$$(\mathbf{K}_{t,j}, \mathbf{\Theta}_{t,j}) = (\mathbf{K}_{t,j-1}, \mathbf{\Theta}_{t,j-1}) - \alpha \nabla_{\mathbf{K}_{t,j-1},\mathbf{\Theta}_{t,j-1}} \mathcal{L}(\mathcal{S}_{\tau}; \mathbf{K}_{t,j-1}, \mathbf{\Theta}_{t,j-1}).$$

The meta-learner takes $(\mathbf{K}_{t,J}, \boldsymbol{\Theta}_{t,J})$ and \mathcal{Q}_{τ} to update the meta-parameters (steps 17-24). For $(\mathbf{x},y) \in \mathcal{Q}_{\tau}$, we use $(\mathbf{K}_{t,J}, \boldsymbol{\Theta}_{t,J})$ to generate its prompt $\boldsymbol{\theta}_{\mathbf{x},J}(\mathbf{K}_{t,J}, \boldsymbol{\Theta}_{t,J})$ (steps 18 and 19), which is used for make prediction $\mathbb{P}(y|\mathbf{x};\boldsymbol{\theta}_{\mathbf{x},J})$ (steps 20 and 21). Let $\mathcal{L}(\mathcal{Q}_{\tau};\mathbf{K}_{t,J},\boldsymbol{\Theta}_{t,J}) = -\sum_{(\mathbf{x},y)\in\mathcal{Q}_{\tau}}\log\mathbb{P}(y|\mathbf{x};\boldsymbol{\theta}_{\mathbf{x},J})$ be the negative log-likelihood loss on \mathcal{Q}_{τ} (step 23). The meta-learner updates the meta-parameters by performing one gradient descent step on $\mathcal{L}(\mathcal{Q}_{\tau};\mathbf{K}_{t,J},\boldsymbol{\Theta}_{t,J})$ at step 24:

$$(\mathbf{K}_t, \mathbf{\Theta}_t) = (\mathbf{K}_{t-1}, \mathbf{\Theta}_{t-1}) - \eta \nabla_{(\mathbf{K}_{t-1}, \mathbf{\Theta}_{t-1})} \mathcal{L}(\mathcal{Q}_\tau; \mathbf{K}_{t,J}, \mathbf{\Theta}_{t,J}).$$

The meta-gradient $\nabla_{(\mathbf{K}_{t-1},\Theta_{t-1})}\mathcal{L}(\mathcal{Q}_{\tau};\mathbf{K}_{t,J},\Theta_{t,J}) = \nabla_{(\mathbf{K}_{t,J},\Theta_{t,J})}\mathcal{L}(\mathcal{Q}_{\tau};\mathbf{K}_{t,J},\Theta_{t,J})\nabla_{(\mathbf{K}_{t-1},\Theta_{t-1})}(\mathbf{K}_{t,J},\Theta_{t,J})$ requires back-propagating through the entire inner optimization path, which is computationally infeasible for large models and J is large. To reduce the computational cost, we discard the second-order derivative and use the first-order approximation $\nabla_{(\mathbf{K}_{t-1},\Theta_{t-1})}\mathcal{L}(\mathcal{Q}_{\tau};\mathbf{K}_{t,J},\Theta_{t,J}) \approx$

 $\nabla_{(\mathbf{K}_{t,J},\mathbf{\Theta}_{t,J})} \mathcal{L}(\mathcal{Q}_{\tau}; \mathbf{K}_{t,J},\mathbf{\Theta}_{t,J})$ (step 24) as in (Finn et al., 2017; Hou et al., 2022).

3.2.2. META-TESTING

Given an unseen task $\tau' = (\mathcal{S}_{\tau'}, \mathcal{Q}_{\tau'})$, the base learner takes $\mathcal{S}_{\tau'}$ and $(\mathbf{K}_T, \mathbf{\Theta}_T)$ to build a task-specific prompt pool $(\mathbf{K}_{T,J}, \mathbf{\Theta}_{T,J})$ as in steps 4-15. This pool is then used to construct instance-dependent prompts $\boldsymbol{\theta}_{\mathbf{x},J}$ for each $(\mathbf{x},\cdot) \in \mathcal{Q}_{\tau'}$. The MLM receives the wrapped input $\tilde{\mathbf{x}} \equiv \mathbb{T}(\mathbf{x}; \boldsymbol{\theta}_{\mathbf{x},J})$ and predicts the label probability by (5).

3.2.3. METAPROMPTER IS PARAMETER-EFFICIENT

As MetaPrompter only tunes $(\mathbf{K}, \boldsymbol{\Theta})$, the total number of meta-parameters is $K(d_o + L_p d_i)$ (where d_i and d_o are the dimensions of the input and feature embeddings, respectively). This is much smaller than that of MetaPrompting (which is equal to $d_{\boldsymbol{\phi}} + L_p d_i$, where $d_{\boldsymbol{\phi}}$ is the size of $\boldsymbol{\phi}$), as it requires tuning the whole MLM. For example, in the experiments, we use BERT (with $d_o = d_i = 768$, $d_{\boldsymbol{\phi}} = 109 \times 10^6$) and $K = L_p = 8$ in MetaPrompter.

4. Experiments

4.1. Setup

Following Chen et al. (2022), we perform few-shot classification on six popularly used data sets: (i) 20News (Lang, 1995), which contains informal discourses from news discussion forums of 20 topics; (ii) Amazon (He & McAuley, 2016), which consists of customer reviews from 24 products. The task is to classify reviews into product categories; (iii) HuffPost (Misra, 2022), which contains news headlines of 41 topics published in the HuffPost between 2012 and 2018. These headlines are shorter and less grammatical than formal sentences, thus are more challenging for classification; (iv) Reuters (Lewis, 1997), which is a collection of Reuters newswire articles of 31 topics from 1996 to 1997; (v) HWU64 (Liu et al., 2019), which is an intent classification data set containing user utterances of 64 intents; (vi) Liu54 (Liu et al., 2019), which is an imbalanced intent classification data set of 54 classes collected on Amazon Mechanical Turk. We use the meta-training/metavalidation/meta-testing splits provided in Chen et al. (2022). A summary of the data sets is in Table 1.

Following (Bao et al., 2020; Han et al., 2021; Chen et al., 2022; Hou et al., 2022), we perform experiments in the 5-way 1-shot and 5-way 5-shot settings with 15 query samples per class. The pre-trained BERT (*bert-base-uncased*) from HuggingFace (Wolf et al., 2020) is used as the pre-trained MLM as in (Chen et al., 2022; Hou et al., 2022). Experiments are run on a DGX station with 8 V100 32GB GPUs. The experiment is repeated three times with different random seeds.

Table 1. Statistics of the data sets.

	#classes (meta-train/valid/test)	#samples	#tokens per sample (mean \pm std)
20News	8/5/7	18,820	340 ± 151
Amazon	10/5/9	24,000	140 ± 32
HuffPost	20/5/16	36,900	11 ± 4
Reuters	15/5/11	620	168 ± 136
HWU64	23/16/25	11,036	7 ± 3
Liu54	18/18/18	25,478	8 ± 4

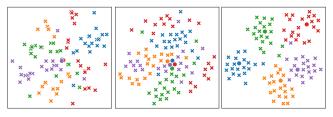
4.2. Evaluation on RepVerb

First, we compare the performance of the proposed RepVerb with state-of-the-art soft verbalizers: (i) WARP (Hambardzumyan et al., 2021)³, and (ii) ProtoVerb (Cui et al., 2022). As the focus is on evaluating verbalizers, all methods use the same discrete prompt "Topic is [MASK]", and fine-tune all parameters for 5 steps with a learning rate of 0.00005 as in Cui et al. (2022).

Results. Table 2 reports the meta-testing accuracies. As

can be seen, RepVerb outperforms WARP and ProtoVerb on both the 1-shot and 5-shot settings.

Figure 2 shows the t-SNE visualization of the embeddings $(\mathbf{h}_{\texttt{[MASK]}}(\mathbf{x})$'s) of 100 samples $(\mathbf{x}$'s)⁴ and learned label embeddings $(\mathbf{v}_y$'s) for a random 5-way 5-shot task from *Reuters*.⁵ As can be seen, the RepVerb embedding is more discriminative and compact than those of WARP and ProtoVerb. Moreover, by design, RepVerb's label embedding is consistent with the samples' feature embeddings, while those of WARP and ProtoVerb are not.



(a) WARP. (b) ProtoVerb. (c) RepVerb. *Figure 2.* t-SNE visualization of [MASK]'s embeddings (crosses) and label embeddings (circles) for a 5-way 5-shot task randomly sampled from *Reuters*.

4.3. Evaluation on MetaPrompter

We compare MetaPrompter with a variety of baselines. These include state-of-the-art prompt-based methods of (i) MetaPrompting (Hou et al., 2022), and its variants (ii) MetaPrompting+WARP / MetaPrompting+ProtoVerb / MetaPrompting+RepVerb, which combine MetaPrompting with the soft verbalizer of WARP / ProtoVerb / RepVerb, respectively. Moreover, we also compare with the non-prompt-based methods of: (iii) HATT (Gao et al., 2019), which meta-learns a prototypical network (Snell et al., 2017) with a hybrid attention mechanism; (iv) DS (Bao et al., 2020), which learns attention scores based on word frequency; (v) MLADA (Han et al., 2021), which uses an adversarial domain adaptation network to extract domain-invariant features during metatraining; and (vi) ContrastNet (Chen et al., 2022), which performs feature extraction by contrastive learning.

For MetaPrompter, hyperparameters K and L_p are chosen from $\{1,2,4,8,16,32,64\}$ using the meta-validation set. For the base learner, $\alpha=0.1$, and J=5 (resp. 15) at meta-training (resp. meta-validation or meta-testing). We train the prompt pool for T=3,000 iterations using the Adam optimizer (Kingma & Ba, 2015) with a learning rate of 0.001. To prevent overfitting, we evaluate the meta-validation performance every 50 iteration and choose the checkpoint with the best meta-validation performance for meta-testing. For the hand-crafted verbalizer used in (1), label tokens are obtained by tokenizing the class name and its synonyms as in (Hou et al., 2022; Hu et al., 2022b). Following Lester et al.

³Note that the verbalizer of WARP is the same as that of DART (Zhang et al., 2022). Its implementation is described in Appendix A.

 $^{^4}$ 5-way × (5 support samples + 15 query samples) = 100.

⁵Results on the other data sets are in Figure 7 of Appendix B.

Table 2. Meta-testing accuracy of various verbalizers on 5-way few-shot classification.

		-					
		20News	Amazon	HuffPost	Reuters	HWU64	Liu54
	WARP (Hambardzumyan et al., 2021)	61.43 ± 0.15	59.53 ± 0.20	46.31 ± 0.31	68.67 ± 0.71	68.60 ± 0.40	73.11 ± 0.26
5-shot	ProtoVerb (Cui et al., 2022)	71.33 ± 0.11	71.74 ± 0.21	57.93 ± 0.17	80.93 ± 0.54	73.43 ± 0.51	76.19 ± 0.33
	RepVerb	78.81 ± 0.08	77.56 ± 0.16	61.90 ± 0.08	88.33 ± 0.40	78.37 ± 0.49	82.14 ± 0.23
	WARP (Hambardzumyan et al., 2021)	49.87 ± 0.63	48.94 ± 0.34	38.21 ± 0.35	52.88 ± 0.67	53.20 ± 0.76	58.68 ± 0.64
1-shot	ProtoVerb (Cui et al., 2022)	54.13 ± 0.46	55.07 ± 0.27	41.40 ± 0.21	57.27 ± 0.73	55.17 ± 0.81	60.16 ± 0.37
	RepVerb	59.86 ± 0.38	59.18 ± 0.31	44.65 ± 0.20	63.63 ± 0.41	59.83 ± 0.71	66.17 ± 0.40

Table 3. Number of parameters and 5-way 5-shot classification meta-testing accuracy. Results marked with † are from Chen et al. (2022). "-" indicates that the corresponding result is not reported in Chen et al. (2022).

	#param $(\times 10^6)$	20News	Amazon	HuffPost	Reuters	HWU64	Liu54
HATT [†] (Gao et al., 2019)	0.07	55.00	66.00	56.30	56.20	-	-
DS [†] (Bao et al., 2020)	1.73	68.30	81.10	63.50	96.00	-	-
MLADA [†] (Han et al., 2021)	0.73	77.80	86.00	64.90	96.70	-	-
ContrastNet [†] (Chen et al., 2022)	109.52	71.74	85.17	65.32	95.33	92.57	93.72
MetaPrompting (Hou et al., 2022)	109.52	85.67 ± 0.44	84.19 ± 0.30	72.85 ± 1.01	95.89 ± 0.23	93.86 ± 0.97	94.01 ± 0.26
MetaPrompting+WARP	109.52	85.81 ± 0.48	85.54 ± 0.20	71.71 ± 0.72	97.28 ± 0.30	93.99 ± 0.76	94.33 ± 0.27
MetaPrompting+ProtoVerb	109.52	86.18 ± 0.51	84.91 ± 0.38	73.11 ± 0.80	97.24 ± 0.25	93.81 ± 0.81	94.38 ± 0.18
MetaPrompting+RepVerb	109.52	86.89 ± 0.39	85.98 ± 0.28	74.62 ± 0.88	97.32 ± 0.31	94.23 ± 0.67	94.45 ± 0.33
MetaPrompter	0.06	88.57 ± 0.38	86.36 ± 0.24	74.89 ± 0.75	97.63 ± 0.22	95.30 ± 0.51	95.47 ± 0.21

Table 4. Number of parameters and 5-way 1-shot Meta-testing classification accuracy. Results marked with † are from Chen et al. (2022). "—" indicates that the corresponding result is not reported in Chen et al. (2022).

	#param $(\times 10^6)$	20News	Amazon	HuffPost	Reuters	HWU64	Liu54
HATT [†] (Gao et al., 2019)	0.07	44.20	49.10	41.10	43.20	-	-
DS [†] (Bao et al., 2020)	1.73	52.10	62.60	43.00	81.80	-	-
MLADA [†] (Han et al., 2021)	0.73	59.60	68.40	64.90	82.30	-	-
ContrastNet [†] (Chen et al., 2022)	109.52	71.74	76.13	53.06	86.42	86.56	85.89
MetaPrompting (Hou et al., 2022)	109.52	82.46 ± 0.50	76.92 ± 0.77	68.62 ± 0.56	92.56 ± 0.77	91.06 ± 0.41	87.79 ± 0.29
MetaPrompting +WARP	109.52	82.93 ± 0.39	78.27 ± 0.72	67.78 ± 0.41	94.74 ± 0.56	91.30 ± 0.35	88.69 ± 0.26
MetaPrompting+ProtoVerb	109.52	83.15 ± 0.41	78.19 ± 0.65	68.96 ± 0.52	95.26 ± 0.40	91.27 ± 0.63	90.05 ± 0.15
MetaPrompting+RepVerb	109.52	84.13 ± 0.30	78.59 ± 0.43	69.02 ± 0.51	95.78 ± 0.33	91.32 ± 0.44	90.13 ± 0.20
MetaPrompter	0.06	84.62 ± 0.29	79.05 ± 0.21	67.12 ± 0.23	96.34 ± 0.20	92.11 ± 0.30	93.72 ± 0.18

(2021), prompts are initialized from input embeddings of randomly sampled label tokens for both MetaPrompting and MetaPrompter.

Results. Table 3 shows the number of parameters and meta-testing accuracy in the 5-shot setting. As can be seen, MetaPrompter is more accurate than both prompt-based and non-prompt-based baselines. Moreover, since MetaPrompter only tunes the prompt pool and keeps the language model frozen, it has much fewer meta-parameters than MetaPrompting and ContrastNet.

Furthermore, MetaPrompting+RepVerb performs better than MetaPrompting+WARP and MetaPrompting+ProtoVerb, demonstrating that the proposed RepVerb is also beneficial to MetaPrompting.

Table 4 shows the number of parameters and meta-testing accuracy in the 5-way 1-shot setting. As can be seen, the state-of-the-art prompt-based methods always achieve higher accuracies than the non-prompt-based ones. Furthermore, MetaPrompter performs the best on 5 of the 6 data sets. Besides, RepVerb is again useful to MetaPrompting on all six data sets.

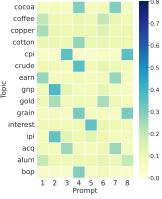


Figure 3. Distribution of attention weights on 5-way 5-shot classification of *Reuters* (15 topics).

4.4. Visualization

In this section, we visualize the meta-knowledge in the prompt pool learned from the 5-way 5-shot classification task on *Reuters*. Table 5 shows the nearest tokens to each of the K (= 8) learned prompts. Figure 3 shows the average attention weights between the K prompts and meta-training

	Table 5. Nearest tokens to the learned prompts for <i>Reuters</i> .
prompt id	nearest tokens
1	copper, steel, trading, gas, fx, aluminum, earn, coffee
2	gross, ship, index, money, gold, tin, iron, retail
3	product, cpi, industrial, acquisitions, jobs, supplying, orange, sugar
4	cocoa, production, grain, livestock, wholesale, cotton, bop, crude
5	oil, national, rubber, nat, interest, price, reserves, regional
6	nat, wholesale, sugar, golden, reserves, drinks, production, product
7	chocolate, sugar, cheat, orange, trade, fx, cash, acquiring
8	aluminum, livestock, cpc, tin, shops, wheat, petrol, supply

Table 5. Nearest tokens to the learned prompts for Reuters.

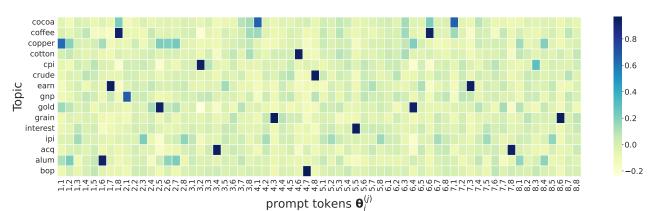


Figure 4. Cosine similarities between learned prompt tokens and topic embeddings on 5-way 5-shot classification of *Reuters*. In the x-axis, (i, j) stands for the jth row of θ_i (i.e., $\theta_i^{(j)}$)

samples belonging to class (topic) y:

$$\frac{1}{|\mathcal{T}_y|} \sum_{\tau \in \mathcal{T}_y} \frac{1}{|\mathcal{S}_{\tau,y}|} \sum_{(\mathbf{x},y) \in \mathcal{S}_{\tau,y}} \operatorname{softmax} \left(\frac{\mathbf{K}_{T,J} \mathbf{q_x}}{\sqrt{d_o}} \right),$$

where \mathcal{T}_y is the subset of tasks in \mathcal{T} having class y. As can be seen, samples from each target class prefer prompts whose tokens are related to that class. For example, samples from the topic cocoa tend to use the 4th and 7th prompts (whose tokens are close to words like cocoa, chocolate as can be seen from Table 5), while samples from the topic coffee tend to use the 1st and 6th prompts (whose tokens are close to words like coffee and sugar.

Recall that the prompt pool has K learnable prompts $\{(\mathbf{k}_i, \boldsymbol{\theta}_i) : i = 1, \dots, K\}$, with key $\mathbf{k}_i \in \mathbb{R}^{d_o}$ and value $\boldsymbol{\theta}_i \in \mathbb{R}^{L_p \times d_i}$. Let $\boldsymbol{\theta}_i^{(j)}$ be the jth row of $\boldsymbol{\theta}_i$. Moreover, let $\frac{1}{|\mathcal{V}_y|} \sum_{\mathbf{w} \in \mathcal{V}_y} \mathcal{E}(\mathbf{w})$ be the embedding of topic (class) y, where \mathcal{V}_y is a set of tokens relevant to label y (obtained from Hou et al. (2022)), and $\mathcal{E}(\cdot)$ is the input embedding. Figure 4 shows the cosine similarities between the learned prompt tokens $\{\boldsymbol{\theta}_i^{(j)} : i = 1, \dots, K, j = 1 \dots, L_p\}$ and topic embeddings. As can be seen, embedding of cocoa is close to $\boldsymbol{\theta}_4^{(1)}$ and $\boldsymbol{\theta}_7^{(1)}$. Thus, samples from cocoa prefer the 4th and 7th prompts (Figure 3). Similarly, embedding of coffee is close to $\boldsymbol{\theta}_1^{(8)}$ and $\boldsymbol{\theta}_6^{(6)}$. Thus, samples from coffee prefer the 1st and 6th prompts (Figure 3).

4.5. Ablation Study

In this section, we perform ablation study using the 5-way 5-shot setting in Section 4.3.

4.5.1. Effect of K

Figure 5 shows the 5-way 5-shot meta-testing accuracy of MetaPrompter with varying K. As K increases, more task knowledge can be extracted and the meta-testing accuracy increases. However, using a very large K (e.g., 64) is unnecessary and the accuracy flattens.

4.5.2. Effect of L_n

Figure 6 shows the 5-way 5-shot meta-testing accuracy of MetaPrompter with varying L_p . As L_p increases, the meta-testing accuracy increases as the expressive power of the prompt pool is enhanced. However, using a very large L_p is again unnecessary and the accuracy flattens.

4.5.3. Effect of Verbalizer

Table 6 shows the number of parameters and meta-testing accuracy of MetaPrompter with hand-crafted verbalizer (used in (5)) and RepVerb. As can be seen, RepVerb is better than the hand-crafted verbalizer, and combining both yields the best result.

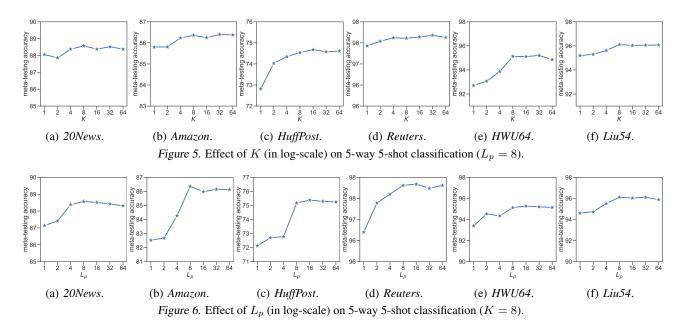


Table 6. 5-way 5-shot classification meta-testing accuracy of MetaPrompter with different verbalizers.

verbalizer hand-crafted RepVerb		20News	Amazon	HuffPost	Reuters	HWU64	Liu54
1	Х	85.91	81.96	70.37	95.91	91.89	90.32
×	✓	87.12	86.05	72.63	96.69	95.25	93.35
✓	✓	88.57	86.36	74.89	97.63	95.30	95.47

Table 7. 5-way 5-shot classification meta-testing accuracy by using BMG to learn the prompt pool.

	#param $(\times 10^6)$	20News	Amazon	HuffPost	Reuters	HWU64	Liu54
MetaPrompting+BMG	109.52	85.71	83.47	73.92	96.27	93.31	93.04
MetaPrompter+BMG	0.06	87.91	86.45	74.99	98.01	95.41	$\boldsymbol{94.52}$

4.5.4. INTEGRATION WITH OTHER META-LEARNING ALGORITHMS

While the MAML algorithm (Finn et al., 2017) is used in Algorithm 2, other meta-learning algorithms can also be used to learn the prompt pool in MetaPrompter or the meta-initialized prompt in MetaPrompting. In this experiment, we replace MAML with the state-of-the-art BMG (Flennerhag et al., 2022). Table 7 shows the meta-testing accuracy and number of parameters. As can be seen, MetaPrompter+BMG consistently outperforms MetaPrompting+BMG.

5. Conclusion

In this paper, we proposed MetaPrompter, an effective and parameter-efficient algorithm for prompt tuning. It combines structured prompting and a novel verbalizer called RepVerb. A prompt pool structure is used to construct

instance-dependent prompts by attention, while RepVerb builds label embedding by averaging feature embeddings of the corresponding training samples. The pool of prompts is meta-learned from the meta-training tasks. Experimental results demonstrate the effectiveness of the proposed MetaPrompter and RepVerb.

One limitation is that MetaPrompter is based on metalearning, and so requires the availability of a set of metatraining tasks.

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A. Implementation of WARP

WARP (Hambardzumyan et al., 2021) is developed for supervised learning with limited samples. The proposed RepVerb (Algorithm 1) is also designed for the supervised learning setting. In the meta-learning procedure in Algorithm 2, it is used in the inner level (steps 4-15) which is also supervised.

Given a meta-testing task $\tau' = (S_{\tau'}, Q_{\tau'})$ with label set $\mathcal{Y}_{\tau'}$, let $\mathbf{V} \equiv \{\mathbf{v}_y : y \in \mathcal{Y}_{\tau'}\}$ be τ' 's learnable label embeddings, and ϕ be the MLM parameter. For an input \mathbf{x} , the distribution for labels $y \in \mathcal{Y}_{\tau'}$ is predicted as:

$$\mathbb{P}(y|\mathbf{x}; \boldsymbol{\phi}, \mathbf{V}) = \frac{\exp(\mathbf{v}_y^{\top} \mathbf{h}_{[\text{MASK}]}(\tilde{\mathbf{x}}))}{\sum_{y' \in \mathcal{Y}_\tau} \exp(\mathbf{v}_{y'}^{\top} \mathbf{h}_{[\text{MASK}]}(\tilde{\mathbf{x}}))},$$
(6)

where $\mathbf{h}_{\text{[MASK]}}(\tilde{\mathbf{x}})$ is the [MASK]'s embedding of wrapped input $\tilde{\mathbf{x}}$. (ϕ, \mathbf{V}) is learned by performing T=5 gradient updates to minimize the negative log-likelihood loss on the support set $\mathcal{S}_{\tau'}$:

$$\sum_{(\mathbf{x},y)\in\mathcal{S}_{\tau'}} -\log \mathbb{P}(y|\mathbf{x}; \boldsymbol{\phi}, \mathbf{V}).$$

 ϕ is initialized by the pre-trained MLM, while V is initialized randomly. The learned (ϕ, V) is then evaluated on $\mathcal{Q}_{\tau'}$. For a test sample $(\mathbf{x}^*, \cdot) \in \mathcal{Q}_{\tau'}$, its prediction is given by (6). We run the WARP algorithm on all meta-testing tasks and report the average meta-testing accuracy in Table 2.

B. Visualization for Verbalizers

Figure 7 shows the t-SNE visualization of the embeddings ($\mathbf{h}_{[MASK]}(\mathbf{x})$'s) of 100 samples (\mathbf{x} 's) and learned label embeddings (\mathbf{v}_y 's) of a 5-way 5-shot task randomly from 20News, Amazon, HuffPost, HWU64, and Liu54. As shown, the RepVerb embedding is more discriminative and compact than WARP and ProtoVerb. Furthermore, RepVerb's label embedding is consistent with the samples' feature embeddings, while those of WARP and ProtoVerb are not.

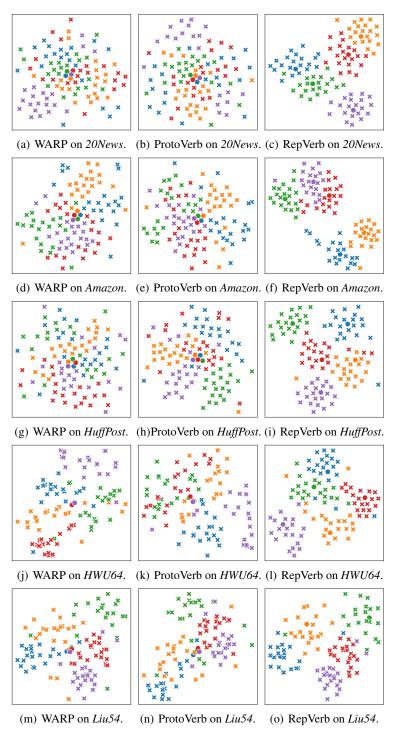


Figure 7. t-SNE visualization of [MASK]'s embeddings (crosses) and label embeddings (circles) for a 5-way 5-shot task randomly sampled from 20News, Amazon, HuffPost, HWU64, and Liu54.