## A. Overview of the Appendix

In Section B, we derive the optimal solution $U^{*}$ for (2.4), which was used in Section 2. Next, we clarify the implementation details of Algorithm 1 in Section C. We illustrate more experiments in Section D. In Section F, we prove our theoretical results and some preliminary lemmas are given in Section E.

## B. Optimal solution $U^{*}$ for (2.4)

The optimal solution $U$ for (2.4) is given by the first order optimality condition:

$$
\frac{\partial \tilde{h}(Y, D, U)}{\partial U}=U+\lambda_{3}\left(Y^{\top} Y U-Y^{\top} D\right)=0
$$

which implies

$$
\begin{aligned}
U^{*} & =\left(\frac{1}{\lambda_{3}} I_{p}+Y^{\top} Y\right)^{-1} Y^{\top} D \\
& =\lambda_{3} \sum_{j=0}^{+\infty}\left(-\lambda_{3} Y^{\top} Y\right)^{j} Y^{\top} D \\
& =\lambda_{3} Y^{\top}\left[\sum_{j=0}^{+\infty}\left(-\lambda_{3} Y Y^{\top}\right)^{j}\right] D \\
& =Y^{\top}\left(\frac{1}{\lambda_{3}} I_{p}+Y Y^{\top}\right)^{-1} D
\end{aligned}
$$

Then, its transpose is given by

$$
U^{* \top}=D^{\top}\left(\frac{1}{\lambda_{3}} I_{p}+\sum_{i=1}^{n} \boldsymbol{y}_{i} \boldsymbol{y}_{i}^{\top}\right)^{-1} Y
$$

Note that $\boldsymbol{u}_{i}$ is the column of $U^{\top}$. So for each $i \in[n]$,

$$
\begin{aligned}
\boldsymbol{u}_{i}^{*} & =D^{\top}\left(\frac{1}{\lambda_{3}} I_{p}+\sum_{i=1}^{n} \boldsymbol{y}_{i} \boldsymbol{y}_{i}^{\top}\right)^{-1} \boldsymbol{y}_{i} \\
& =\frac{1}{n} D^{\top}\left(\frac{1}{\lambda_{3} n} I_{p}+\frac{1}{n} N_{n}\right)^{-1} \boldsymbol{y}_{i}
\end{aligned}
$$

where we denote $N_{n}=\sum_{i=1}^{n} \boldsymbol{y}_{i} \boldsymbol{y}_{i}^{\top}$.

Also, we have

$$
\begin{aligned}
Y U^{* \top} & =Y\left(\frac{1}{\lambda_{3}} I_{p}+Y^{\top} Y\right)^{-1} Y^{\top} D \\
& =\lambda_{3} Y\left(I_{p}+\lambda_{3} Y^{\top} Y\right)^{-1} Y^{\top} D \\
& =\lambda_{3} Y\left[\sum_{j=0}^{+\infty}\left(-\lambda_{3} Y^{\top} Y\right)^{j}\right] Y^{\top} D \\
& =\lambda_{3} \sum_{j=0}^{+\infty}\left(-\lambda_{3}\right)^{j}\left(Y Y^{\top}\right)^{j+1} D \\
& =D-\left(I_{p}+\lambda_{3} Y Y^{\top}\right)^{-1} D \\
& =D-\left(I_{p}+\lambda_{3} \sum_{i=1}^{n} \boldsymbol{y}_{i} \boldsymbol{y}_{i}^{\top}\right)^{-1} D \\
& =D-\frac{1}{n}\left(\frac{1}{n} I_{p}+\frac{\lambda_{3}}{n} N_{n}\right)^{-1} D .
\end{aligned}
$$

Thus,

$$
\begin{aligned}
h(Y, D)= & \sum_{i=1}^{n} \frac{1}{2}\left\|\frac{1}{n} D^{\top}\left(\frac{1}{\lambda_{3} n} I_{p}+\frac{1}{n} N_{n}\right)^{-1} \boldsymbol{y}_{i}\right\|_{2}^{2} \\
& +\frac{\lambda_{3}}{2}\left\|\frac{1}{n}\left(\frac{1}{n} I_{p}+\frac{\lambda_{3}}{n} N_{n}\right)^{-1} D\right\|_{F}^{2} \\
= & \frac{1}{n^{2}} \sum_{i=1}^{n} \frac{1}{2}\left\|D^{\top}\left(\frac{1}{\lambda_{3} n} I_{p}+\frac{1}{n} N_{n}\right)^{-1} \boldsymbol{y}_{i}\right\|_{2}^{2} \\
& +\frac{\lambda_{3}}{2 n^{2}}\left\|\left(\frac{1}{n} I_{p}+\frac{\lambda_{3}}{n} N_{n}\right)^{-1} D\right\|_{F}^{2}
\end{aligned}
$$

## C. Algorithm Details

```
Algorithm 2 Solving \(v\) and \(e\)
Require: \(D \in \mathbb{R}^{p \times d}, \boldsymbol{z} \in \mathbb{R}^{p}\), parameters \(\lambda_{1}\) and \(\lambda_{2}\)
Ensure: Optimal \(\boldsymbol{v}\) and \(\boldsymbol{e}\).
    1: Set \(\boldsymbol{e}=\mathbf{0}\).
    2: repeat
    3: Update \(\boldsymbol{v}\) :
\[
\boldsymbol{v}=\left(D^{\top} D+\frac{1}{\lambda_{1}} I\right)^{-1} D^{\top}(\boldsymbol{z}-\boldsymbol{e})
\]
```

4: Update $e$ :

$$
e=\mathcal{S}_{\lambda_{2} / \lambda_{1}}[\boldsymbol{z}-D \boldsymbol{v}]
$$

until convergence

For Algorithm 2, we set a threshold $\epsilon=10^{-3}$. Let $\left\{\boldsymbol{v}^{\prime}, \boldsymbol{e}^{\prime}\right\}$ and $\left\{\boldsymbol{v}^{\prime \prime}, \boldsymbol{e}^{\prime \prime}\right\}$ be the two consecutive iterates. If the maximum of $\left\|\boldsymbol{v}^{\prime}-\boldsymbol{v}^{\prime \prime}\right\|_{2} /\left\|\boldsymbol{v}^{\prime}\right\|_{2}$ and $\left\|\boldsymbol{e}^{\prime}-\boldsymbol{e}^{\prime \prime}\right\|_{2} /\left\|\boldsymbol{e}^{\prime}\right\|_{2}$ is less than $\epsilon$, then we stop Algorithm 2.

```
Algorithm 3 Solving \(D\)
Require: \(D \in \mathbb{R}^{p \times d}\) in the previous iteration, accumula-
    tion matrix \(M, A\) and \(B\), parameters \(\lambda_{1}\) and \(\lambda_{3}\).
Ensure: Optimal \(D\) (updated).
    Denote \(\widehat{A}=\lambda_{1} A+\lambda_{3} I\) and \(\widehat{B}=\lambda_{1} B+\lambda_{3} M\).
    repeat
        for \(j=1\) to \(d\) do
            Update the \(j\) th column of \(D\) :
\[
\boldsymbol{d}_{j} \leftarrow \boldsymbol{d}_{j}-\frac{1}{\widehat{A}_{j j}}\left(D \widehat{\boldsymbol{a}}_{j}-\widehat{\boldsymbol{b}}_{j}\right)
\]
        end for
    until convergence
```

For Algorithm 3, we observe that a one-pass update on the dictionary $D$ is enough for the final convergence of $D$, as we shown in the experiments. This is also observed in Mairal et al. (2010).

## D. More Experiments

We also investigate the performance of subspace clustering on MNIST-7K and MNIST-10K. In this way, one can see how the computational time changes with the number of samples.

Table 4. Clustering accuracy (\%) and computational time (seconds).

|  | OLRSC | ORPCA | LRR | LRR2 | SSC |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Mush- | $\mathbf{8 5 . 0 9}$ | 65.26 | 58.44 | 56.38 | 54.16 |
| rooms | 8.78 | 8.30 | 46.82 | 8.55 | 32 min |
| DNA | $\mathbf{6 7 . 1 1}$ | 53.11 | 44.01 | 45.32 | 52.23 |
|  | 2.58 | 2.09 | 23.67 | 1.65 | 3 min |
| Protein | 43.30 | 40.22 | 40.31 | 40.00 | $\mathbf{4 4 . 2 7}$ |
|  | 24.66 | 22.90 | 921.58 | 98.33 | 65 min |
| USPS | $\mathbf{6 5 . 9 5}$ | 55.70 | 52.98 | 58.69 | 47.58 |
|  | 33.93 | 27.01 | 257.25 | 71.15 | 50 min |
| MNIST- | $\mathbf{5 8 . 0 4}$ | 55.40 | 54.77 | 54.27 | 45.56 |
| 7K | 42.99 | 39.84 | 512.37 | 95.21 | 26 min |
| MNIST- | $\mathbf{5 6 . 7 9}$ | 54.66 | 55.15 | 53.67 | 44.90 |
| 10K | 67 | 56 | 24 min | 153 | 84 min |
| MNIST- | $\mathbf{5 7 . 7 4}$ | 54.10 | 55.23 | 54.53 | 43.91 |
| 20K | 129 | 121 | 32 min | 360 | 7 hours |
|  |  |  |  |  |  |

## E. Proof Preliminaries

Lemma 3 (Corollary of Thm. 4.1 (Bonnans \& Shapiro, 1998)). Let $f: \mathbb{R}^{p} \times \mathbb{R}^{q} \rightarrow \mathbb{R}$. Suppose that for all $\boldsymbol{x} \in \mathbb{R}^{p}$ the function $f(\boldsymbol{x}, \cdot)$ is differentiable, and that $f$ and $\nabla_{\boldsymbol{u}} f(\boldsymbol{x}, \boldsymbol{u})$ are continuous on $\mathbb{R}^{p} \times \mathbb{R}^{q}$. Let $\boldsymbol{v}(\boldsymbol{u})$ be
the optimal value function $\boldsymbol{v}(\boldsymbol{u})=\min _{\boldsymbol{x} \in \mathcal{C}} f(\boldsymbol{x}, \boldsymbol{u})$, where $\mathcal{C}$ is a compact subset of $\mathbb{R}^{p}$. Then $\boldsymbol{v}(\boldsymbol{u})$ is directionally differentiable. Furthermore, if for $\boldsymbol{u}_{0} \in \mathbb{R}^{q}, f\left(\cdot, \boldsymbol{u}_{0}\right)$ has unique minimizer $\boldsymbol{x}_{0}$ then $\boldsymbol{v}(\boldsymbol{u})$ is differentiable in $\boldsymbol{u}_{0}$ and $\nabla_{\boldsymbol{u}} \boldsymbol{v}\left(\boldsymbol{u}_{0}\right)=\nabla_{\boldsymbol{u}} f\left(\boldsymbol{x}_{0}, \boldsymbol{u}_{0}\right)$.
Lemma 4 (Corollary of Donsker theorem (van der Vaart, 2000)). Let $F=\left\{f_{\theta}: \mathcal{X} \rightarrow \mathbb{R}, \theta \in \Theta\right\}$ be a set of measurable functions indexed by a bounded subset $\Theta$ of $\mathbb{R}^{d}$. Suppose that there exists a constant $K$ such that

$$
\left|f_{\theta_{1}}(x)-f_{\theta_{2}}(x)\right| \leq K\left\|\theta_{1}-\theta_{2}\right\|_{2}
$$

for every $\theta_{1}$ and $\theta_{2}$ in $\Theta$ and $x$ in $\mathcal{X}$. Then, $F$ is $P$-Donsker. For any $f$ in $F$, let us define $\mathbb{P}_{n} f, \mathbb{P} f$ and $\mathbb{G}_{n} f$ as

$$
\begin{aligned}
& \mathbb{P}_{n} f=\frac{1}{n} \sum_{i=1}^{n} f\left(X_{i}\right), \\
& \mathbb{P} f=\mathbb{E}[f(X)], \\
& \mathbb{G}_{n} f=\sqrt{n}\left(\mathbb{P}_{n} f-\mathbb{P} f\right) .
\end{aligned}
$$

Let us also suppose that for all $f, \mathbb{P} f^{2}<\delta^{2}$ and $\|f\|_{\infty}<$ $M$ and that the random elements $X_{1}, X_{2}, \cdots$ are Borelmeasurable. Then, we have

$$
\mathbb{E}\|\mathbb{G}\|_{F}=O(1)
$$

where $\|\mathbb{G}\|_{F}=\sup _{f \in F}\left|\mathbb{G}_{n} f\right|$.
Lemma 5 (Sufficient condition of convergence for a stochastic process (Bottou, 1998)). Let $(\Omega, \mathcal{F}, P)$ be a measurable probability space, $u_{t}$, for $t \geq 0$, be the realization of a stochastic process and $\mathcal{F}_{t}$ be the filtration by the past information at time $t$. Let

$$
\delta_{t}= \begin{cases}1 & \text { if } \mathbb{E}\left[u_{t+1}-u_{t} \mid \mathcal{F}_{t}\right]>0 \\ 0 & \text { otherwise }\end{cases}
$$

If for all $t$, $u_{t} \geq 0$ and $\sum_{t=1}^{\infty} \mathbb{E}\left[\delta_{t}\left(u_{t+1}-u_{t}\right)\right]<\infty$, then $u_{t}$ is a quasi-martingale and converges almost surely. Moreover,

$$
\sum_{t=1}^{\infty}\left|\mathbb{E}\left[u_{t+1}-u_{t} \mid \mathcal{F}_{t}\right]\right|<+\infty \text { a.s. }
$$

Lemma 6 (Lemma 8 from Mairal et al. (2010)). Let $a_{t}$, $b_{t}$ be two real sequences such that for all $t, a_{t} \geq 0, b_{t} \geq$ $0, \sum_{t=1}^{\infty} a_{t}=\infty, \sum_{t=1}^{\infty} a_{t} b_{t}<\infty, \exists K>0$, such that $\left|b_{t+1}-b_{t}\right|<K a_{t}$. Then, $\lim _{t \rightarrow+\infty} b_{t}=0$.

## F. Proof Details

## F.1. Proof of Boundedness

Proposition 7. Let $\left\{\boldsymbol{u}_{t}\right\},\left\{\boldsymbol{v}_{t}\right\},\left\{\boldsymbol{e}_{t}\right\}$ and $\left\{D_{t}\right\}$ be the optimal solutions produced by Algorithm 1. Then,

1. $\boldsymbol{v}_{t}, \boldsymbol{e}_{t}, \frac{1}{t} A_{t}$ and $\frac{1}{t} B_{t}$ are uniformly bounded.
2. $M_{t}$ is uniformly bounded.
3. $D_{t}$ is supported by some compact set $\mathcal{D}$.
4. $\boldsymbol{u}_{t}$ is uniformly bounded.

Proof. Let us consider the optimization problem of solving $\boldsymbol{v}$ and $\boldsymbol{e}$. As the trivial solution $\left\{\boldsymbol{v}_{t}^{\prime}, \boldsymbol{e}_{t}^{\prime}\right\}=\left\{\mathbf{0}, \boldsymbol{z}_{t}\right\}$ are feasible, we have

$$
\tilde{\ell}_{1}\left(\boldsymbol{z}_{t}, D_{t-1}, \boldsymbol{v}_{t}^{\prime}, \boldsymbol{e}_{t}^{\prime}\right)=\lambda_{2}\left\|\boldsymbol{z}_{t}\right\|_{1}
$$

Therefore, the optimal solution should satisfy:
$\frac{\lambda_{1}}{2}\left\|\boldsymbol{z}_{t}-D_{t-1} \boldsymbol{v}_{t}-\boldsymbol{e}_{t}\right\|_{2}^{2}+\frac{1}{2}\left\|\boldsymbol{v}_{t}\right\|_{2}^{2}+\lambda_{2}\left\|\boldsymbol{e}_{t}\right\|_{1} \leq \lambda_{2}\left\|\boldsymbol{z}_{t}\right\|_{1}$, which implies

$$
\begin{aligned}
\frac{1}{2}\left\|\boldsymbol{v}_{t}\right\|_{2}^{2} & \leq \lambda_{2}\left\|\boldsymbol{z}_{t}\right\|_{1} \\
\lambda_{2}\left\|\boldsymbol{e}_{t}\right\|_{1} & \leq \lambda_{2}\left\|\boldsymbol{z}_{t}\right\|_{1}
\end{aligned}
$$

Since $\boldsymbol{z}_{t}$ is uniformly bounded (Assumption 1), $\boldsymbol{v}_{t}$ and $\boldsymbol{e}_{t}$ are uniformly bounded.

To examine the uniform bound for $\frac{1}{t} A_{t}$ and $\frac{1}{t} B_{t}$, note that

$$
\begin{aligned}
\frac{1}{t} A_{t} & =\frac{1}{t} \sum_{i=1}^{t} \boldsymbol{v}_{i} \boldsymbol{v}_{i}^{\top} \\
\frac{1}{t} B_{t} & =\frac{1}{t} \sum_{i=1}^{t}\left(\boldsymbol{z}_{i}-\boldsymbol{e}_{i}\right) \boldsymbol{v}_{i}^{\top}
\end{aligned}
$$

Since for each $i, \boldsymbol{v}_{i}, \boldsymbol{e}_{i}$ and $\boldsymbol{z}_{i}$ are uniformly bounded, $\frac{1}{t} A_{t}$ and $\frac{1}{t} B_{t}$ are uniformly bounded.
Now we derive the bound for $M_{t}$. All the information we have is:

1. $M_{t}=\sum_{i=1}^{t} \boldsymbol{y}_{i} \boldsymbol{u}_{i}^{\top}$ (definition of $M_{t}$ ).
2. $\boldsymbol{u}_{t}=\left(\left\|\boldsymbol{y}_{t}\right\|_{2}^{2}+\frac{1}{\lambda_{3}}\right)^{-1}\left(D_{t-1}-M_{t-1}\right)^{\top} \boldsymbol{y}_{t}$ (closed form solution).
3. $D_{t}\left(\lambda_{1} A_{t}+\lambda_{3} I\right)=\lambda_{1} B_{t}+\lambda_{3} M_{t}$ (first order optimality condition for $D_{t}$ ).
4. $\frac{1}{t} A_{t}, \frac{1}{t} B_{t}, \frac{1}{t} N_{t}$ are uniformly upper bounded (Claim 1).
5. The smallest singular values of $\frac{1}{t} N_{t}$ and $\frac{1}{t} A_{t}$ are uniformly lower bounded away from zero (Assumption 2 and 3).

For simplicity, we write $D_{t}$ as:

$$
\begin{equation*}
D_{t}=\left(\lambda_{1} B_{t}+\lambda_{3} M_{t}\right) Q_{t}^{-1} \tag{F.1}
\end{equation*}
$$

where

$$
Q_{t}=\lambda_{1} A_{t}+\lambda_{3} I
$$

Note that as we assume $\frac{1}{t} A_{t}$ is positive definite, $Q_{t}$ is always invertible.
From the definition of $M_{t}$ and (3.4), we know that

$$
\begin{align*}
& M_{t+1}-M_{t} \\
= & \boldsymbol{y}_{t+1} \boldsymbol{u}_{t+1}^{\top} \\
= & \left(\left\|\boldsymbol{y}_{t+1}\right\|_{2}^{2}+\frac{1}{\lambda_{3}}\right)^{-1} \boldsymbol{y}_{t+1} \boldsymbol{y}_{t+1}^{\top}\left(D_{t}-M_{t}\right) \\
= & P_{t} D_{t}-P_{t} M_{t} \\
= & P_{t}\left(\lambda_{1} B_{t}+\lambda_{3} M_{t}\right) Q_{t}^{-1}-P_{t} M_{t} \tag{F.2}
\end{align*}
$$

where

$$
P_{t}=\left(\left\|\boldsymbol{y}_{t+1}\right\|_{2}^{2}+\frac{1}{\lambda_{3}}\right)^{-1} \boldsymbol{y}_{t+1} \boldsymbol{y}_{t+1}^{\top}
$$

By multiplying $Q_{t}$ on both sides of (F.2), we have

$$
\begin{equation*}
M_{t+1}=\left(M_{t}-\lambda_{1} P_{t} M_{t} A_{t} Q_{t}^{-1}\right)+\lambda_{1} P_{t} B_{t} Q_{t}^{-1} \tag{F.3}
\end{equation*}
$$

By applying the Taylor expansion on $Q_{t}^{-1}$, we have

$$
Q_{t}^{-1}=\left(\lambda_{1} A_{t}+\lambda_{3} I_{d}\right)^{-1}=\frac{1}{\lambda_{3}} \sum_{i=0}^{+\infty}\left(-\frac{\lambda_{1}}{\lambda_{3}} A_{t}\right)^{i}
$$

Thus,

$$
\begin{aligned}
A_{t} Q_{t}^{-1} & =\frac{1}{\lambda_{3}} \sum_{i=0}^{+\infty}\left(-\frac{\lambda_{1}}{\lambda_{3}}\right)^{i}\left(A_{t}\right)^{i+1} \\
& =-\frac{1}{\lambda_{1}} \sum_{i=0}^{+\infty}\left(-\frac{\lambda_{1}}{\lambda_{3}} A_{t}\right)^{i+1} \\
& =-\frac{1}{\lambda_{1}}\left[\sum_{i=-1}^{+\infty}\left(-\frac{\lambda_{1}}{\lambda_{3}} A_{t}\right)^{i+1}-I_{d}\right] \\
& =-\frac{1}{\lambda_{1}}\left(I_{d}+\frac{\lambda_{1}}{\lambda_{3}} A_{t}\right)^{-1}+\frac{1}{\lambda_{1}} I_{d}
\end{aligned}
$$

So $M_{t+1}$ is given by

$$
\begin{align*}
M_{t+1}= & \left(I_{d}-P_{t}\right) M_{t} \\
& +\underbrace{P_{t} M_{t}\left(I_{d}+\frac{\lambda_{1}}{\lambda_{3}} A_{t}\right)^{-1}+\lambda_{1} P_{t} B_{t} Q_{t}^{-1}}_{W_{t}} \tag{F.4}
\end{align*}
$$

We first show that $P_{t} B_{t} Q_{t}^{-1}$ is uniformly bounded.

$$
\begin{aligned}
\left\|P_{t} B_{t} Q_{t}^{-1}\right\| & =\left\|P_{t}\left(\frac{1}{t} B_{t}\right)\left(\frac{1}{t} Q_{t}\right)^{-1}\right\| \\
& \leq\left\|P_{t}\right\| \cdot\left\|\frac{1}{t} B_{t}\right\| \cdot\left\|\left(\frac{1}{t} Q_{t}\right)^{-1}\right\| .
\end{aligned}
$$

Since we assume that $\left\{\boldsymbol{z}_{t}\right\}$ are uniformly upper bounded (Assumption 1), there exists a constant $\alpha_{1}$, such that for all $t>0$,

$$
\left\|\boldsymbol{z}_{t}\right\|_{2} \leq \alpha_{1}
$$

So we have

$$
\left\|P_{t+1}\right\| \leq \frac{\lambda_{3} \alpha_{1}^{2}}{\lambda_{3} \alpha_{1}^{2}+1}
$$

Next, as we have shown that $\frac{1}{t} B_{t}$ can be uniformly bounded, there exists a constant $c_{1}$, such that for all $t>0$,

$$
\left\|\frac{1}{t} B_{t}\right\| \leq c_{1} .
$$

And,

$$
\begin{aligned}
\left\|\left(\frac{1}{t} Q_{t}\right)^{-1}\right\| & =\frac{1}{\sigma_{\min }\left(\frac{1}{t} Q_{t}\right)} \\
& =\frac{1}{\sigma_{\min }\left(\frac{\lambda_{1}}{t} A_{t}+\frac{\lambda_{3}}{t} I_{d}\right)} \\
& =\frac{1}{\frac{\lambda_{3}}{t}+\lambda_{1} \sigma_{\min }\left(\frac{1}{t} A_{t}\right)} \\
& \leq \frac{1}{\lambda_{3}+\lambda_{1} \beta_{0}} .
\end{aligned}
$$

Thus, $\lambda_{1} P_{t} B_{t} Q_{t}^{-1}$ is uniformly bounded by a constant, say $c_{2}$. That is,

$$
\begin{equation*}
\left\|\lambda_{1} P_{t} B_{t} Q_{t}^{-1}\right\| \leq c_{2} \tag{F.5}
\end{equation*}
$$

It follows that $W_{t}$ can be bounded:

$$
\begin{align*}
\left\|W_{t}\right\| & \leq\left\|P_{t}\right\| \cdot\left\|M_{t}\right\| \cdot\left\|\left(I_{d}+\frac{\lambda_{1}}{\lambda_{3}} A_{t}\right)^{-1}\right\|+c_{2} \\
& \stackrel{\zeta_{1}}{\leq} \frac{\alpha_{1}^{2}}{\alpha_{1}^{2}+\frac{1}{\lambda_{3}}} \cdot \frac{\lambda_{3}}{\lambda_{3}+\lambda_{1} \beta_{0} t}\left\|M_{t}\right\|+c_{2}  \tag{F.6}\\
& \leq \frac{c_{3}}{t}\left\|M_{t}\right\|+c_{2}
\end{align*}
$$

where $\zeta_{1}$ is derived by utilizing the assumption that $\boldsymbol{z}$ is upper bounded by $\alpha_{1}$ and the smallest singular value of $\frac{1}{t} A_{t}$ is lower bounded by $\beta_{0}$. The last inequality always holds for some uniform constant $c_{3}$.

From Assumption 2, we know that the singular values of $\frac{1}{t} \sum_{i=1}^{t} \boldsymbol{z}_{i} \boldsymbol{z}_{i}^{\top}$ should uniformly span the diagonal. Thus, there exists a constant $\tau$, such that for all $i>0$, $\frac{1}{\tau} \sum_{i}^{i+\tau} \boldsymbol{z}_{i} \boldsymbol{z}_{i}^{\top}$ is uniformly bounded away from zero with high probability.

Let $m_{1}=\left\|M_{1}\right\|$. Now we pick a constant $t^{*}$, such that

$$
\begin{equation*}
\frac{c_{3} \tau}{t^{*}}\left(\frac{1}{\alpha_{0}}+1\right) \leq 0.5 \tag{F.7}
\end{equation*}
$$

We also have a constant $w^{*}$, such that for all $t \leq t^{*}$,

$$
\begin{align*}
\left\|W_{t}\right\| & \leq w^{*}, \\
\frac{c_{3}}{t} m_{1}+0.5 w^{*}+c_{2} & \leq w^{*} \tag{F.8}
\end{align*}
$$

Based on this, we first derive a bound for all $\left\|M_{t}\right\|$, with $t \leq t^{*}$. We know that there exists an integer $k^{*}$ (which is a uniform constant), such that $k^{*}(\tau+1) \leq t^{*}<\left(k^{*}+\right.$ $1)(\tau+1)$. Our strategy is to bound $\left\|M_{t}\right\|$ in each interval $[(k-1)(\tau+1), k(\tau+1)]$. We start our reasoning from the first interval $[1, \tau+1]$.
It is easy to induce from (F.4) that for all $t>0$,
$M_{t+1}=\prod_{i=1}^{t}\left(I_{p}-P_{i}\right) M_{1}+\sum_{j=1}^{t-1} \prod_{i=j+1}^{t}\left(I_{p}-P_{i}\right) W_{j}+W_{t}$.
Thus,

$$
\begin{aligned}
& \left\|M_{\tau+1}\right\| \\
= & \left\|\prod_{i=1}^{\tau}\left(I_{p}-P_{i}\right) M_{1}+\sum_{j=1}^{\tau-1} \prod_{i=j+1}^{\tau}\left(I_{p}-P_{i}\right) W_{j}+W_{\tau}\right\| \\
\leq & \left\|\prod_{i=1}^{\tau}\left(I_{p}-P_{i}\right) M_{1}\right\|+\left\|\sum_{j=1}^{\tau-1} \prod_{i=j+1}^{\tau}\left(I_{p}-P_{i}\right) W_{j}+W_{\tau}\right\| \\
& \underline{\zeta_{1}} \leq \prod_{i=1}^{\tau}\left(I_{p}-P_{i}\right)\|\cdot\| M_{1} \|+\tau w^{*} \\
& \zeta_{2}\left(1-\alpha_{0}\right) m_{1}+\tau w^{*} .
\end{aligned}
$$

Here, $\zeta_{1}$ holds because $\left\|\prod_{i=j+1}^{\tau}\left(I_{p}-P_{i}\right)\right\| \leq 1$ for all $j \in[\tau-1]$. $\zeta_{2}$ holds because the singular values of $P_{i}$ 's have span over the diagonal so the largest singular value of $\prod_{i=1}^{\tau}\left(I_{p}-P_{i}\right)$ is $1-\alpha_{0}$, where $\alpha_{0}$ is the lower bound for all $\boldsymbol{z}_{i}$ 's (see Assumption 1).
For $M_{2(\tau+1)}$, we can similarly obtain

$$
\left\|M_{2(\tau+1)}\right\| \leq\left(1-\alpha_{0}\right)^{2} m_{1}+\left(1-\alpha_{0}\right) \tau w^{*}+\tau w^{*} .
$$

More generally, for any integer $k \leq k^{*}$,

$$
\begin{aligned}
\left\|M_{k(\tau+1)}\right\| & \leq\left(1-\alpha_{0}\right)^{k} m_{1}+\sum_{j=0}^{k-1}\left(1-\alpha_{0}\right)^{j} \tau w^{*} \\
& \leq m_{1}+\frac{\tau w^{*}}{\alpha_{0}}
\end{aligned}
$$

Hence, we obtain a uniform bound for $\left\|M_{k(\tau+1)}\right\|$, with $k \in\left[k^{*}\right]$. For any $i \in((k-1)(\tau+1), k(\tau+1))$, they can simply bounded by

$$
\begin{aligned}
\left\|M_{i}\right\| & \leq m_{1}+\frac{\tau w^{*}}{\alpha_{0}}+(i-(k-1)(\tau+1)) w^{*} \\
& \leq m_{1}+\frac{\tau w^{*}}{\alpha_{0}}+\tau w^{*}
\end{aligned}
$$

Therefore, for all the current $M_{t}$ 's, we can bound them as follows:

$$
\begin{equation*}
\left\|M_{t}\right\| \leq m_{1}+\frac{\tau w^{*}}{\alpha_{0}}+\tau w^{*}, \forall t=1,2, \cdots, t^{*} \tag{F.9}
\end{equation*}
$$

From (F.8) and (F.9), we know that for all $t \leq t^{*}$,

$$
\begin{aligned}
\left\|W_{t}\right\| & \leq w^{*} \\
\left\|M_{t}\right\| & \leq m_{1}+\frac{\tau w^{*}}{\alpha_{0}}+\tau w^{*}
\end{aligned}
$$

Next, we show that the bounds still hold for $\left\|W_{t^{*}+1}\right\|$ and $\left\|M_{t^{*}+1}\right\|$, which completes our induction.
For $\left\|M_{t^{*}+1}\right\|$, it can simply be bounded in the same way as aforementioned because all the $W_{t}$ 's are bounded by $w^{*}$ for $t<t^{*}+1$. That is,

$$
\begin{align*}
\left\|M_{t^{*}+1}\right\| & \leq\left\|M_{k^{*}(\tau+1)}\right\|+\left(t^{*}+1-k^{*}(\tau+1)\right) w^{*} \\
& \leq m_{1}+\frac{\tau w^{*}}{\alpha_{0}}+\tau w^{*} \tag{F.10}
\end{align*}
$$

For $\left\|W_{t^{*}+1}\right\|$, from (F.6), we know

$$
\begin{align*}
\left\|W_{t^{*}+1}\right\| & \leq \frac{c_{3}}{t^{*}+1}\left\|M_{t^{*}+1}\right\|+c_{2} \\
& \leq \frac{c_{3}}{t^{*}+1}\left(m_{1}+\frac{\tau w^{*}}{\alpha_{0}}+\tau w^{*}\right)+c_{2} \\
& =\frac{c_{3} m_{1}}{t^{*}+1}+\frac{c_{3} \tau}{t^{*}+1}\left(\frac{1}{\alpha_{0}}+1\right) w^{*}+c_{2} \\
& \leq \frac{\zeta_{1}}{t_{3} m_{1}}+0.5 w^{*}+c_{2} \\
& \leq w^{*}+1 \tag{F.11}
\end{align*}
$$

Here, $\zeta_{1}$ is derived by utilizing (F.7) and $\zeta_{2}$ is derived by (F.8).

From (F.10) and (F.11), we know that the bound for $\left\|M_{t}\right\|$ and $\left\|W_{t}\right\|$ 's, with $t \leq t^{*}$, still holds for $t=t^{*}+1$. Thus
we complete the induction and conclude that for all $t>0$, we have

$$
\begin{aligned}
\left\|M_{t}\right\| & \leq m_{1}+\frac{\tau w^{*}}{\alpha_{0}}+\tau w^{*} \\
\left\|W_{t}\right\| & \leq w^{*}
\end{aligned}
$$

Thus, $M_{t}$ is uniformly bounded.
From (F.1), we know that

$$
\begin{aligned}
D_{t}= & \lambda_{1} B_{t}\left(\lambda_{1} A_{t}+\lambda_{3} I_{d}\right)^{-1}+\lambda_{3} M_{t}\left(\lambda_{1} A_{t}+\lambda_{3} I_{d}\right)^{-1} \\
= & \lambda_{1}\left(\frac{1}{t} B_{t}\right)\left(\frac{\lambda_{1}}{t} A_{t}+\frac{\lambda_{3}}{t} I_{d}\right)^{-1} \\
& +\frac{\lambda_{3}}{t} M_{t}\left(\frac{\lambda_{1}}{t} A_{t}+\frac{\lambda_{3}}{t} I_{d}\right)^{-1}
\end{aligned}
$$

Since $\frac{1}{t} A_{t}, \frac{1}{t} B_{t}$ and $M_{t}$ are all uniformly bounded, $D_{t}$ is also uniformly bounded.
By examining the closed form of $\boldsymbol{u}_{t}$, and note that we have proved the uniform boundedness of $D_{t}$ and $M_{t}$, we conclude that $\left\{\boldsymbol{u}_{t}\right\}$ are uniformly bounded.

Corollary 8. Let $\boldsymbol{v}_{t}, \boldsymbol{e}_{t}, \boldsymbol{u}_{t}$ and $D_{t}$ be the optimal solutions produced by Algorithm 1.

1. $\tilde{\ell}\left(\boldsymbol{z}_{t}, D_{t}, \boldsymbol{v}_{t}, \boldsymbol{e}_{t}\right)$ and $\ell\left(\boldsymbol{z}_{t}, D_{t}\right)$ are uniformly bounded.
2. $\frac{1}{t} \tilde{h}(Z, D, U)$ is uniformly bounded.
3. The surrogate function $g_{t}\left(D_{t}\right)$ defined in (3.5) is uniformly bounded and Lipschitz.

Proof. To show Claim 1, we just need to examine the definition of $\tilde{\ell}\left(\boldsymbol{z}_{t}, D_{t}, \boldsymbol{v}_{t}, \boldsymbol{e}_{t}\right)$ and notice that $\boldsymbol{z}_{t}, D_{t}$, $\boldsymbol{v}_{t}$ and $\boldsymbol{e}_{t}$ are all uniformly bounded. This implies that $\tilde{\ell}\left(\boldsymbol{z}_{t}, D_{t}, \boldsymbol{v}_{t}, \boldsymbol{e}_{t}\right)$ is uniformly bounded and so is $\ell\left(\boldsymbol{z}_{t}, D_{t}\right)$. Likewise, we show that $\frac{1}{t} \tilde{h}(Z, D, U)$ is uniformly bounded.

The uniform boundedness of $g_{t}\left(D_{t}\right)$ follows immediately as $\tilde{\ell}\left(\boldsymbol{z}_{t}, D_{t}, \boldsymbol{v}_{t}, \boldsymbol{e}_{t}\right)$ and $\frac{1}{t} \tilde{h}(Z, D, U)$ are both uniformly bounded. To show that $g_{t}(D)$ is Lipschitz, we show that the gradient of $g_{t}(D)$ is uniformly bounded for all $D \in \mathcal{D}$.

$$
\begin{aligned}
\left\|\nabla g_{t}(D)\right\|_{F}= & \left\|\lambda_{1} D\left(\frac{A_{t}}{t}+\frac{\lambda_{3}}{t} I_{d}\right)-\lambda_{1} \frac{B_{t}}{t}-\frac{\lambda_{3}}{t} M_{t}\right\|_{F} \\
\leq & \lambda_{1}\|D\|_{F}\left(\left\|\frac{A_{t}}{t}\right\|_{F}+\left\|\frac{\lambda_{3}}{t} I_{d}\right\|_{F}\right) \\
& +\lambda_{1}\left\|\frac{B_{t}}{t}\right\|_{F}+\left\|\frac{\lambda_{3}}{t} M_{t}\right\|_{F} .
\end{aligned}
$$

Notice that each term on the right side of the inequality is uniformly bounded. Thus the gradient of $g_{t}(D)$ is uniformly bounded and $g_{t}(D)$ is Lipschitz.

Proposition 9. Let $D \in \mathcal{D}$ and denote the minimizer of $\tilde{\ell}(\boldsymbol{z}, D, \boldsymbol{v}, \boldsymbol{e}) a s:$

$$
\left\{\boldsymbol{v}^{\prime}, \boldsymbol{e}^{\prime}\right\}=\underset{\boldsymbol{v}, \boldsymbol{e}}{\arg \min } \tilde{\ell}(\boldsymbol{z}, D, \boldsymbol{v}, \boldsymbol{e})
$$

Then, the function $\ell(\boldsymbol{z}, L)$ is continuously differentiable and

$$
\nabla_{D} \ell(\boldsymbol{z}, D)=\left(D \boldsymbol{v}^{\prime}+\boldsymbol{e}^{\prime}-\boldsymbol{z}\right) \boldsymbol{v}^{\top \top}
$$

Furthermore, $\ell(\boldsymbol{z}, \cdot)$ is uniformly Lipschitz.

Proof. By fixing the variable $\boldsymbol{z}$, the function $\tilde{\ell}$ can be seen as a mapping:

$$
\begin{aligned}
\mathbb{R}^{d+p} \times \mathcal{D} & \rightarrow \mathbb{R} \\
([\boldsymbol{v} ; \boldsymbol{e}], D) & \mapsto \tilde{\ell}(\boldsymbol{z}, D, \boldsymbol{v}, \boldsymbol{e})
\end{aligned}
$$

It is easy to show that for all $[\boldsymbol{v} ; \boldsymbol{e}] \in \mathbb{R}^{d+p}, \tilde{\ell}(\boldsymbol{z}, \cdot, \boldsymbol{v}, \boldsymbol{e})$ is differentiable. Also $\tilde{\ell}(\boldsymbol{z}, \cdot, \cdot, \cdot)$ is continuous on $\mathbb{R}^{d+p} \times$ $\mathcal{D} . \nabla_{D} \tilde{\ell}(\boldsymbol{z}, D, \boldsymbol{v}, \boldsymbol{e})=(D \boldsymbol{v}+\boldsymbol{e}-\boldsymbol{z}) \boldsymbol{v}^{\top}$ is continuous on $\mathbb{R}^{d+p} \times \mathcal{D} . \forall D \in \mathcal{D}$, since $\tilde{\ell}(\boldsymbol{z}, D, \boldsymbol{v}, \boldsymbol{e})$ is strongly convex w.r.t. $\boldsymbol{v}$, it has a unique minimizer $\left\{\boldsymbol{v}^{\prime}, \boldsymbol{e}^{\prime}\right\}$. Thus Lemma 3 applies and we prove that $\ell(\boldsymbol{z}, D)$ is differentiable in $D$ and

$$
\nabla_{D} \ell(\boldsymbol{z}, D)=\left(D \boldsymbol{v}^{\prime}+\boldsymbol{e}^{\prime}-\boldsymbol{z}\right) \boldsymbol{v}^{\prime \top}
$$

Since every term in $\nabla_{D} \ell(\boldsymbol{z}, D)$ is uniformly bounded (Assumption 1 and Proposition 7), we conclude that the gradient of $\ell(\boldsymbol{z}, D)$ is uniformly bounded, implying that $\ell(\boldsymbol{z}, D)$ is uniformly Lipschitz w.r.t. $D$.

Corollary 10. Let $f_{t}(D)$ be the empirical loss function defined in (2.6). Then $f_{t}(D)$ is uniformly bounded and Lipschitz.

Proof. Since $\ell(\boldsymbol{z}, L)$ can be uniformly bounded (Corollary 8 ), we only need to show that $\frac{1}{t} h(Z, D)$ is uniformly bounded. Note that we have derived the form for $h(Z, D)$ as follows:

$$
\begin{aligned}
\frac{1}{t} h(Z, D)= & \frac{1}{t^{3}} \sum_{i=1}^{t} \frac{1}{2}\left\|D^{\top}\left(\frac{1}{\lambda_{3} t} I_{p}+\frac{1}{t} N_{t}\right)^{-1} \boldsymbol{z}_{i}\right\|_{2}^{2} \\
& +\frac{\lambda_{3}}{2 t^{3}}\left\|\left(\frac{1}{t} I_{p}+\frac{\lambda_{3}}{t} N_{t}\right)^{-1} D\right\|_{F}^{2}
\end{aligned}
$$

where $N_{t}=\sum_{i=1}^{t} \boldsymbol{z}_{i} \boldsymbol{z}_{i}^{\top}$. Since every term in the above equation can be uniformly bounded, $h(Z, D)$ is uniformly bounded and so is $f_{t}(D)$.

To show that $f_{t}(D)$ is uniformly Lipschitz, we show that its gradient can be uniformly bounded.

$$
\begin{aligned}
& \nabla f_{t}(D) \\
= & \frac{1}{t} \sum_{i=1}^{t} \nabla \ell\left(\boldsymbol{z}_{i}, D\right)+\frac{1}{t} \nabla h(Z, D) \\
= & \frac{1}{t} \sum_{i=1}^{t}\left(D \boldsymbol{v}_{i}+\boldsymbol{e}_{i}-\boldsymbol{z}_{i}\right) \boldsymbol{v}_{i}^{\top} \\
& +\frac{1}{t^{3}} \sum_{i=1}^{t}\left(\frac{1}{\lambda_{3} t} I_{p}+\frac{1}{t} N_{t}\right)^{-1} \boldsymbol{z}_{i} \boldsymbol{z}_{i}^{\top}\left(\frac{1}{\lambda_{3} t} I_{p}+\frac{1}{t} N_{t}\right)^{-1} D \\
& +\frac{\lambda_{3}}{t^{3}}\left(\frac{1}{t} I_{p}+\frac{\lambda_{3}}{t} N_{t}\right)^{-2} D .
\end{aligned}
$$

Then the Frobenius norm of $\nabla f_{t}(D)$ can be bounded by:

$$
\begin{aligned}
& \left\|\nabla f_{t}(D)\right\|_{F} \\
\leq & \frac{1}{t} \sum_{i=1}^{t}\left\|D \boldsymbol{v}_{i}+\boldsymbol{e}_{i}-\boldsymbol{z}_{i}\right\|_{2} \cdot\left\|\boldsymbol{v}_{i}\right\|_{2} \\
& +\frac{1}{t^{3}} \sum_{i=1}^{t}\left\|\left(\frac{1}{\lambda_{3} t} I_{p}+\frac{1}{t} N_{t}\right)^{-1}\right\|_{F}^{2} \cdot\left\|\boldsymbol{z}_{i}\right\|_{2}^{2} \cdot\|D\|_{F} \\
& +\frac{\lambda_{3}}{t^{3}}\left\|\left(\frac{1}{t} I_{p}+\frac{\lambda_{3}}{t} N_{t}\right)^{-1}\right\|_{F}^{2} \cdot\|D\|_{F}
\end{aligned}
$$

One can easily check that the right side of the inequality is uniformly bounded. Thus $\left\|\nabla f_{t}(D)\right\|_{F}$ is uniformly bounded, implying that $f_{t}(D)$ is uniformly Lipschitz.

## F.2. Proof of P-Donsker

Proposition 11. Let $f_{t}^{\prime}(D)=\frac{1}{t} \sum_{i=1}^{t} \ell\left(\boldsymbol{z}_{i}, D\right)$ and $f(D)$ be the expected loss function defined in (2.8). Then we have

$$
\mathbb{E}\left[\sqrt{t}\left\|f_{t}^{\prime}-f\right\|_{\infty}\right]=\mathcal{O}(1)
$$

Proof. Let us consider $\{\ell(\boldsymbol{z}, D)\}$ as a set of measurable functions indexed by $D \in \mathcal{D}$. As we showed in Proposition 7, $\mathcal{D}$ is a compact set. Also, we have proved that $\ell(\boldsymbol{z}, D)$ is uniformly Lipschitz over $D$ (Proposition 9). Thus, $\{\ell(\boldsymbol{z}, D)\}$ is P-Donsker (see the definition in Lemma 4). Furthermore, as $\ell(\boldsymbol{z}, D)$ is nonnegative and uniformly bounded, so is $\ell^{2}(\boldsymbol{z}, D)$. So we have $\mathbb{E}_{\boldsymbol{z}}\left[\ell^{2}(\boldsymbol{z}, D)\right]$ being uniformly bounded. Since we have verified all the hypotheses in Lemma 4, we obtain the result that

$$
\mathbb{E}\left[\sqrt{t}\left\|f_{t}^{\prime}-f\right\|_{\infty}\right]=\mathcal{O}(1)
$$

## F.3. Proof of convergence of $g_{t}(D)$

Theorem 12 (Convergence of the surrogate function $g_{t}\left(D_{t}\right)$ ). The surrogate function $g_{t}\left(D_{t}\right)$ we defined in (3.5) converges almost surely, where $D_{t}$ is the solution produced by Algorithm 1.

Proof. Note that $g_{t}\left(D_{t}\right)$ can be viewed as a stochastic positive process since every term in $g_{t}\left(D_{t}\right)$ is non-negative and the samples are drawn randomly. We define

$$
u_{t}=g_{t}\left(D_{t}\right)
$$

To show the convergence of $u_{t}$, we need to bound the difference of $u_{t+1}$ and $u_{t}$ :

$$
\begin{align*}
& u_{t+1}-u_{t} \\
= & g_{t+1}\left(D_{t+1}\right)-g_{t}\left(D_{t}\right) \\
= & g_{t+1}\left(D_{t+1}\right)-g_{t+1}\left(D_{t}\right)+g_{t+1}\left(D_{t}\right)-g_{t}\left(D_{t}\right) \\
= & g_{t+1}\left(D_{t+1}\right)-g_{t+1}\left(D_{t}\right) \\
& +\frac{1}{t+1} \ell\left(\boldsymbol{z}_{t+1}, D_{t}\right)-\frac{1}{t+1} g_{t}^{\prime}\left(D_{t}\right) \\
& +\left[\frac{1}{t+1} \sum_{i=1}^{t+1} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2}+\frac{\lambda_{3}}{2(t+1)}\left\|D_{t}-M_{t+1}\right\|_{F}^{2}\right. \\
& \left.-\frac{1}{t} \sum_{i=1}^{t} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2}-\frac{\lambda_{3}}{2 t}\left\|D_{t}-M_{t}\right\|_{F}^{2}\right] \\
= & g_{t+1}\left(D_{t+1}\right)-g_{t+1}\left(D_{t}\right)+\frac{f_{t}^{\prime}\left(D_{t}\right)-g_{t}^{\prime}\left(D_{t}\right)}{t+1} \\
& +\frac{\ell\left(\boldsymbol{z}_{t+1}, D_{t}\right)-f_{t}^{\prime}\left(D_{t}\right)}{t+1} \\
& +\left[\frac{1}{t+1} \sum_{i=1}^{t+1} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2}+\frac{\lambda_{3}}{2(t+1)}\left\|D_{t}-M_{t+1}\right\|_{F}^{2}\right. \\
& \left.-\frac{1}{t} \sum_{i=1}^{t} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2}-\frac{\lambda_{3}}{2 t}\left\|D_{t}-M_{t}\right\|_{F}^{2}\right] . \tag{F.12}
\end{align*}
$$

Here,

$$
\begin{equation*}
g_{t}^{\prime}\left(D_{t}\right)=\frac{1}{t} \sum_{i=1}^{t} \tilde{\ell}\left(\boldsymbol{z}_{i}, D, \boldsymbol{v}_{i}, \boldsymbol{e}_{i}\right) . \tag{F.13}
\end{equation*}
$$

First, we bound the last four terms. We have

$$
\begin{align*}
& \frac{1}{t+1} \sum_{i=1}^{t+1} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2}-\frac{1}{t} \sum_{i=1}^{t}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2} \\
= & \frac{-1}{t(t+1)} \sum_{i=1}^{t} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2}+\frac{1}{2(t+1)}\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2} \\
\leq & \frac{1}{2(t+1)}\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2} . \tag{F.14}
\end{align*}
$$

And

$$
\begin{align*}
& \frac{\lambda_{3}}{2(t+1)}\left\|D_{t}-M_{t+1}\right\|_{F}^{2}-\frac{\lambda_{3}}{2 t}\left\|D_{t}-M_{t}\right\|_{F}^{2} \\
= & \frac{-\lambda_{3}}{2 t(t+1)}\left\|D_{t}-M_{t}\right\|_{F}^{2}+\frac{\lambda_{3}}{2(t+1)}\left\|\boldsymbol{z}_{t+1} \boldsymbol{u}_{t+1}^{\top}\right\|_{F}^{2} \\
& -\frac{\lambda_{3}}{t+1} \operatorname{Tr}\left(\left(D_{t}-M_{t}\right)^{\top} \boldsymbol{z}_{t+1} \boldsymbol{u}_{t+1}^{\top}\right) \\
= & \frac{-\lambda_{3}}{2 t(t+1)}\left\|D_{t}-M_{t}\right\|_{F}^{2}+\frac{\lambda_{3}}{2(t+1)}\left\|\boldsymbol{z}_{t+1} \boldsymbol{u}_{t+1}^{\top}\right\|_{F}^{2} \\
& -\frac{\lambda_{3}}{t+1}\left(\left\|\boldsymbol{z}_{t+1}\right\|_{2}^{2}+\frac{1}{\lambda_{3}}\right)\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2} \\
\leq & \frac{1}{t+1}\left(\frac{\lambda_{3}}{2}\left\|\boldsymbol{z}_{t+1} \boldsymbol{u}_{t+1}^{\top}\right\|_{F}^{2}-\left(\lambda_{3}\left\|\boldsymbol{z}_{t+1}\right\|_{2}^{2}+1\right)\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2}\right) \\
\leq & \frac{1}{t+1}\left(-\frac{\lambda_{3}}{2}\left\|\boldsymbol{z}_{t+1}\right\|_{2}^{2}\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2}-\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2}\right), \quad(\mathrm{F} .15) \tag{F.15}
\end{align*}
$$

where the first equality is derived by the fact that $M_{t+1}=$ $M_{t}+\boldsymbol{z}_{t+1} \boldsymbol{u}_{t+1}^{\top}$, and the second equality is derived by the closed form solution of $\boldsymbol{u}_{t+1}$ (see (3.4)).

Combining (F.14) and (F.15), we know that

$$
\begin{aligned}
& \frac{1}{t+1} \sum_{i=1}^{t+1} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2}-\frac{1}{t} \sum_{i=1}^{t}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2} \\
& +\frac{\lambda_{3}}{2(t+1)}\left\|D_{t}-M_{t+1}\right\|_{F}^{2}-\frac{\lambda_{3}}{2 t}\left\|D_{t}-M_{t}\right\|_{F}^{2} \\
\leq & \frac{1}{2(t+1)}\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2}+\frac{1}{t+1}\left(-\frac{\lambda_{3}}{2}\left\|\boldsymbol{z}_{t+1}\right\|_{2}^{2}\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2}\right. \\
& \left.-\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2}\right) \\
= & \frac{1}{t+1}\left(-\frac{\lambda_{3}}{2}\left\|\boldsymbol{z}_{t+1}\right\|_{2}^{2}\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2}-\frac{1}{2}\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2}\right) \leq 0 .
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
u_{t+1}-u_{t} \leq & g_{t+1}\left(D_{t+1}\right)-g_{t+1}\left(D_{t}\right)+\frac{1}{t+1} \ell\left(\boldsymbol{z}_{t+1}, D_{t}\right) \\
& -\frac{1}{t+1} g_{t}^{\prime}\left(D_{t}\right) \\
= & g_{t+1}\left(D_{t+1}\right)-g_{t+1}\left(D_{t}\right)+\frac{f_{t}^{\prime}\left(D_{t}\right)-g_{t}^{\prime}\left(D_{t}\right)}{t+1} \\
& +\frac{\ell\left(\boldsymbol{z}_{t+1}, D_{t}\right)-f_{t}^{\prime}\left(D_{t}\right)}{t+1} \\
\leq & \frac{\ell\left(\boldsymbol{z}_{t+1}, D_{t}\right)-f_{t}^{\prime}\left(D_{t}\right)}{t+1},
\end{aligned}
$$

where $f_{t}^{\prime}(D)$ is defined in Proposition 11, and the last inequality holds because $D_{t+1}$ is the minimizer of $g_{t+1}(D)$ and $g_{t}^{\prime}(D)$ is a surrogate function of $f_{t}^{\prime}(D)$.

Let $\mathcal{F}_{t}$ be the filtration of the past information. We take the
expectation on the above equation conditioned on $\mathcal{F}_{t}$ :

$$
\begin{aligned}
\mathbb{E}\left[u_{t+1}-u_{t} \mid \mathcal{F}_{t}\right] & \leq \frac{\mathbb{E}\left[\ell\left(\boldsymbol{z}_{t+1}, D_{t}\right) \mid \mathcal{F}_{t}\right]-f_{t}^{\prime}\left(D_{t}\right)}{t+1} \\
& \leq \frac{f\left(D_{t}\right)-f_{t}^{\prime}\left(D_{t}\right)}{t+1} \\
& \leq \frac{\left\|f-f_{t}^{\prime}\right\|_{\infty}}{t+1}
\end{aligned}
$$

From Proposition 11, we know

$$
\mathbb{E}\left[\left\|f-f_{t}^{\prime}\right\|_{\infty}\right]=\mathcal{O}\left(\frac{1}{\sqrt{t}}\right)
$$

Thus,

$$
\begin{aligned}
\mathbb{E}\left[\mathbb{E}\left[u_{t+1}-u_{t} \mid \mathcal{F}_{t}\right]^{+}\right] & =\mathbb{E}\left[\max \left\{\mathbb{E}\left[u_{t+1}-u_{t} \mid \mathcal{F}_{t}\right], 0\right\}\right] \\
& \leq \frac{c}{\sqrt{t}(t+1)}
\end{aligned}
$$

where $c$ is some constant.
Now let us define the index set

$$
\mathcal{T}=\left\{t \mid \mathbb{E}\left[u_{t+1}-u_{t} \mid \mathcal{F}_{t}\right]>0\right\}
$$

and the indicator

$$
\delta_{t}= \begin{cases}1, & \text { if } t \in \mathcal{T} \\ 0, & \text { otherwise }\end{cases}
$$

We have

$$
\begin{aligned}
\sum_{t=1}^{\infty} \mathbb{E}\left[\delta_{t}\left(u_{t+1}-u_{t}\right)\right] & =\sum_{t \in \mathcal{T}} \mathbb{E}\left[u_{t+1}-u_{t}\right] \\
& =\sum_{t \in \mathcal{T}} \mathbb{E}\left[\mathbb{E}\left[u_{t+1}-u_{t} \mid \mathcal{F}_{t}\right]\right] \\
& =\sum_{t=1}^{\infty} \mathbb{E}\left[\mathbb{E}\left[u_{t+1}-u_{t} \mid \mathcal{F}_{t}\right]^{+}\right] \\
& \leq+\infty
\end{aligned}
$$

Thus, Lemma 5 applies. That is, $g_{t}\left(D_{t}\right)$ is a quasimartingale and converges almost surely. Moreover,

$$
\begin{equation*}
\sum_{t=1}^{\infty}\left|\mathbb{E}\left[u_{t+1}-u_{t} \mid \mathcal{F}_{t}\right]\right|<+\infty, \text { a.s. } \tag{F.16}
\end{equation*}
$$

## F.4. Proof of Convergence of $D_{t}$

Proposition 13. Let $\left\{D_{t}\right\}_{t=1}^{\infty}$ be the basis sequence produced by the Algorithm 1. Then,

$$
\begin{equation*}
\left\|D_{t+1}-D_{t}\right\|_{F}=\mathcal{O}\left(\frac{1}{t}\right) \tag{F.17}
\end{equation*}
$$

Proof. According the strong convexity of $g_{t}(D)$ (Assumption 3), we have,

$$
\begin{equation*}
g_{t}\left(D_{t+1}\right)-g_{t}\left(D_{t}\right) \geq \frac{\beta_{0}}{2}\left\|D_{t+1}-D_{t}\right\|_{F}^{2} \tag{F.18}
\end{equation*}
$$

On the other hand,

$$
\begin{align*}
& g_{t}\left(D_{t+1}\right)-g_{t}\left(D_{t}\right) \\
= & g_{t}\left(D_{t+1}\right)-g_{t+1}\left(D_{t+1}\right)+g_{t+1}\left(D_{t+1}\right)-g_{t+1}\left(D_{t}\right) \\
& +g_{t+1}\left(D_{t}\right)-g_{t}\left(D_{t}\right) \\
\leq & g_{t}\left(D_{t+1}\right)-g_{t+1}\left(D_{t+1}\right)+g_{t+1}\left(D_{t}\right)-g_{t}\left(D_{t}\right) \\
\stackrel{\text { def }}{=} & G_{t}\left(D_{t+1}\right)-G_{t}\left(D_{t}\right) . \tag{F.19}
\end{align*}
$$

Note that the inequality is derived by the fact that $g_{t+1}\left(D_{t+1}\right)-g_{t+1}\left(D_{t}\right) \leq 0$, as $D_{t+1}$ is the minimizer of $g_{t+1}(D)$. We denote $g_{t}(D)-g_{t+1}(D)$ by $G_{t}(D)$.
By a simple calculation, we obtain the gradient of $G_{t}(D)$ :
$\nabla G_{t}(D)$

$$
=\nabla g_{t}(D)-\nabla g_{t+1}(D)
$$

$$
=\frac{1}{t}\left[D\left(\lambda_{1} A_{t}+\lambda_{3} I_{d}\right)-\left(\lambda_{1} B_{t}+\lambda_{3} M_{t}\right)\right]
$$

$$
-\frac{1}{t+1}\left[D\left(\lambda_{1} A_{t+1}+\lambda_{3} I_{d}\right)-\left(\lambda_{1} B_{t+1}+\lambda_{3} M_{t+1}\right)\right]
$$

$$
=\frac{1}{t}\left[D\left(\lambda_{1} A_{t}+\lambda_{3} I_{d}-\frac{\lambda_{1} t}{t+1} A_{t+1}-\frac{\lambda_{3} t}{t+1} I_{d}\right)\right.
$$

$$
\left.+\frac{\lambda_{1} t}{t+1} B_{t+1}-\lambda_{1} B_{t}+\frac{\lambda_{3} t}{t+1} M_{t+1}-\lambda_{3} M_{t}\right]
$$

$$
=\frac{1}{t}\left[D\left(\frac{\lambda_{1}}{t+1} A_{t+1}-\lambda_{1} \boldsymbol{v}_{t+1} \boldsymbol{v}_{t+1}^{\top}+\frac{\lambda_{3}}{t+1} I_{d}\right)\right.
$$

$$
+\lambda_{1}\left(\boldsymbol{z}_{t+1}-\boldsymbol{e}_{t+1}\right) \boldsymbol{v}_{t+1}^{\top}-\frac{\lambda_{1}}{t+1} B_{t+1}
$$

$$
\left.+\lambda_{3} \boldsymbol{z}_{t+1} \boldsymbol{u}_{t+1}^{\top}-\frac{\lambda_{3}}{t+1} M_{t+1}\right]
$$

So the Frobenius norm of $\nabla G_{t}(D)$ follows immediately:

$$
\begin{aligned}
& \left\|\nabla G_{t}(D)\right\|_{F} \\
\leq & \frac{1}{t}\left[\| D \| _ { F } \left(\lambda_{1}\left\|\frac{A_{t+1}}{t+1}\right\|_{F}+\lambda_{1}\left\|\boldsymbol{v}_{t+1} \boldsymbol{v}_{t+1}^{\top}\right\|_{F}\right.\right. \\
& \left.+\frac{\lambda_{3}}{t+1}\left\|I_{d}\right\|_{F}\right)+\lambda_{1}\left\|\left(\boldsymbol{z}_{t+1}-\boldsymbol{e}_{t+1}\right) \boldsymbol{v}_{t+1}^{\top}\right\|_{F} \\
& +\lambda_{1}\left\|\frac{B_{t+1}}{t+1}\right\|_{F}+\lambda_{3}\left\|\boldsymbol{z}_{t+1} \boldsymbol{u}_{t+1}^{\top}\right\|_{F} \\
& \left.+\frac{\lambda_{3}}{t+1}\left\|M_{t+1}\right\|_{F}\right] \\
= & \frac{1}{t}\left[\|D\|_{F}\left(\lambda_{1}\left\|\frac{A_{t+1}}{t+1}\right\|_{F}+\lambda_{1}\left\|\boldsymbol{v}_{t+1} \boldsymbol{v}_{t+1}^{\top}\right\|_{F}\right)\right. \\
& +\lambda_{1}\left\|\left(\boldsymbol{z}_{t+1}-\boldsymbol{e}_{t+1}\right) \boldsymbol{v}_{t+1}^{\top}\right\|_{F} \\
& \left.+\lambda_{1}\left\|\frac{B_{t+1}}{t+1}\right\|_{F}+\lambda_{3}\left\|\boldsymbol{z}_{t+1} \boldsymbol{u}_{t+1}^{\top}\right\|_{F}\right] \\
& +\frac{\lambda_{3}}{t(t+1)}\left[\left\|I_{d}\right\|_{F}+\left\|M_{t+1}\right\|_{F}\right]
\end{aligned}
$$

We know from Proposition 7 that all the terms in the above equation are uniformly bounded. Thus, there exist constants $c_{1}, c_{2}$ and $c_{3}$, such that

$$
\left\|\nabla G_{t}(D)\right\|_{F} \leq \frac{1}{t}\left[c_{1}\|D\|_{F}+c_{2}\right]+\frac{c_{3}}{t(t+1)}
$$

According to the first order Taylor expansion,

$$
\begin{aligned}
& G_{t}\left(D_{t+1}\right)-G_{t}\left(D_{t}\right) \\
= & \operatorname{Tr}\left(\left(D_{t+1}-D_{t}\right)^{\top} \nabla G_{t}\left(\alpha D_{t}+(1-\alpha) D_{t+1}\right)\right) \\
\leq & \left\|D_{t+1}-D_{t}\right\|_{F} \cdot\left\|\nabla G_{t}\left(\alpha D_{t}+(1-\alpha) D_{t+1}\right)\right\|_{F},
\end{aligned}
$$

where $\alpha$ is a constant between 0 and 1 . According to Proposition 7, $D_{t}$ and $D_{t+1}$ are uniformly bounded, so $\alpha D_{t}+(1-\alpha) D_{t+1}$ is uniformly bounded. Thus, there exists a constant $c_{4}$, such that

$$
\left\|\nabla G_{t}\left(\alpha L_{t}+(1-\alpha) L_{t+1}\right)\right\|_{F} \leq \frac{c_{4}}{t}+\frac{c_{3}}{t(t+1)}
$$

resulting in
$G_{t}\left(D_{t+1}\right)-G_{t}\left(D_{t}\right) \leq\left(\frac{c_{4}}{t}+\frac{c_{3}}{t(t+1)}\right)\left\|D_{t+1}-D_{t}\right\|_{F}$.
Combining (F.18), (F.19) and the above equation, we have

$$
\left\|D_{t+1}-D_{t}\right\|_{F}=\frac{2 c_{4}}{\beta_{0}} \cdot \frac{1}{t}+\frac{2 c_{3}}{\beta_{0}} \cdot \frac{1}{t(t+1)}
$$

## F.5. Proof for convergence of $f_{t}\left(D_{t}\right)$

Theorem 14 (Convergence of $f_{t}\left(D_{t}\right)$ ). Let $f_{t}\left(D_{t}\right)$ be the empirical loss function defined in (2.6) and $D_{t}$ be the solution produced by the Algorithm 1. Let $b_{t}=g_{t}\left(D_{t}\right)-$ $f_{t}\left(D_{t}\right)$. Then, $b_{t}$ converges almost surely to 0 . Thus, $f_{t}\left(D_{t}\right)$ converges almost surely to the same limit of $g_{t}\left(D_{t}\right)$.

Proof. Let $f_{t}^{\prime}(D)$ and $g_{t}^{\prime}(D)$ be those defined in Proposition 11 and Theorem 12 respectively. Then,

$$
\begin{aligned}
b_{t}= & g_{t}\left(D_{t}\right)-f_{t}\left(D_{t}\right) \\
= & g_{t}^{\prime}\left(D_{t}\right)-f_{t}^{\prime}\left(D_{t}\right)+\left[\frac{1}{t} \sum_{i=1}^{t} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2}+\frac{\lambda_{3}}{2 t}\left\|D_{t}-M_{t}\right\|_{F}^{2}\right. \\
& -\frac{1}{t^{3}} \sum_{i=1}^{t} \frac{1}{2}\left\|D_{t}^{\top}\left(\frac{1}{\lambda_{3}} I_{p}+\frac{1}{t} N_{t}\right)^{-1} \boldsymbol{z}_{i}\right\|_{2}^{2} \\
& \left.-\frac{\lambda_{3}}{2 t^{3}}\left\|\left(\frac{1}{t} I_{p}+\frac{\lambda_{3}}{t} N_{t}\right)^{-1} D_{t}\right\|_{F}^{2}\right] \\
= & g_{t}^{\prime}\left(D_{t}\right)-f_{t}^{\prime}\left(D_{t}\right)+q_{t}\left(D_{t}\right)
\end{aligned}
$$

where $q_{t}\left(D_{t}\right)$ denotes the last four terms. Combining F.12, we have

$$
\begin{aligned}
\frac{b_{t}}{t+1}= & \frac{g_{t}^{\prime}\left(D_{t}\right)-f_{t}^{\prime}\left(D_{t}\right)}{t+1}+\frac{q_{t}\left(D_{t}\right)}{t+1} \\
= & g_{t+1}\left(D_{t+1}\right)-g_{t+1}\left(D_{t}\right)+\frac{\ell\left(\boldsymbol{z}_{t+1}, D_{t}\right)-f_{t}^{\prime}\left(D_{t}\right)}{t+1} \\
& +u_{t}-u_{t+1} \\
& +\left[\frac{q_{t}\left(D_{t}\right)}{t+1}+\frac{1}{t+1} \sum_{i=1}^{t+1} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2}\right. \\
& +\frac{\lambda_{3}}{2(t+1)}\left\|D_{t}-M_{t+1}\right\|_{F}^{2}-\frac{1}{t} \sum_{i=1}^{t} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2} \\
& \left.-\frac{\lambda_{3}}{2 t}\left\|D_{t}-M_{t}\right\|_{F}^{2}\right] .
\end{aligned}
$$

Note that we naturally have

$$
\begin{aligned}
\frac{q_{t}\left(D_{t}\right)}{t+1} & \leq \frac{1}{t(t+1)} \sum_{i=1}^{t} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2}+\frac{\lambda_{3}}{2 t(t+1)}\left\|D_{t}-M_{t}\right\|_{F}^{2} \\
& \leq \frac{1}{t(t+1)} \sum_{i=1}^{t} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2}+\frac{c}{2 t(t+1)},
\end{aligned}
$$

where the second inequality holds as $D_{t}$ and $M_{t}$ are both uniformly bounded (see Proposition 7).

Also, from (F.14), we know

$$
\begin{aligned}
& \frac{1}{t+1} \sum_{i=1}^{t+1} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2}-\frac{1}{t} \sum_{i=1}^{t}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2} \\
= & \frac{-1}{t(t+1)} \sum_{i=1}^{t} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2}+\frac{1}{2(t+1)}\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2}
\end{aligned}
$$

And from (F.15)

$$
\begin{aligned}
& \frac{\lambda_{3}}{2(t+1)}\left\|D_{t}-M_{t+1}\right\|_{F}^{2}-\frac{\lambda_{3}}{2 t}\left\|D_{t}-M_{t}\right\|_{F}^{2} \\
\leq & \frac{1}{t+1}\left(-\frac{\lambda_{3}}{2}\left\|\boldsymbol{z}_{t+1}\right\|_{2}^{2}\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2}-\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2}\right) .
\end{aligned}
$$

Thus,

$$
\begin{aligned}
& \frac{q_{t}\left(D_{t}\right)}{t+1}+\frac{1}{t+1} \sum_{i=1}^{t+1} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2} \\
& +\frac{\lambda_{3}}{2(t+1)}\left\|D_{t}-M_{t+1}\right\|_{F}^{2} \\
& -\frac{1}{t} \sum_{i=1}^{t} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2}-\frac{\lambda_{3}}{2 t}\left\|D_{t}-M_{t}\right\|_{F}^{2} \\
\leq & \frac{c}{2 t(t+1)}+\frac{1}{2(t+1)}\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2} \\
& +\frac{1}{t+1}\left(-\frac{\lambda_{3}}{2}\left\|\boldsymbol{z}_{t+1}\right\|_{2}^{2}\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2}-\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2}\right) \\
= & \frac{c}{2 t(t+1)}-\frac{1}{2(t+1)}\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2} \\
& -\frac{\lambda_{3}}{2(t+1)}\left\|\boldsymbol{z}_{t+1}\right\|_{2}^{2}\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2} \\
\leq & \frac{c}{2 t(t+1)} .
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
& \frac{b_{t}}{t+1} \\
\leq & g_{t+1}\left(D_{t+1}\right)-g_{t+1}\left(D_{t}\right)+\frac{\ell\left(\boldsymbol{z}_{t+1}, D_{t}\right)-f_{t}^{\prime}\left(D_{t}\right)}{t+1} \\
& +u_{t}-u_{t+1}+\frac{c}{2 t(t+1)} \\
\leq & \frac{\ell\left(\boldsymbol{z}_{t+1}, D_{t}\right)-f_{t}^{\prime}\left(D_{t}\right)}{t+1}+u_{t}-u_{t+1}+\frac{c}{2 t(t+1)} .
\end{aligned}
$$

By taking the expectation conditioned on the past information $\mathcal{F}_{t}$, we have

$$
\begin{aligned}
\frac{b_{t}}{t+1} & \leq \frac{f\left(D_{t}\right)-f_{t}\left(D_{t}\right)}{t+1}+\mathbb{E}\left[u_{t}-u_{t+1} \mid \mathcal{F}_{t}\right]+\frac{c}{2 t(t+1)} \\
& \leq \frac{c_{1}}{\sqrt{t}(t+1)}+\left|\mathbb{E}\left[u_{t}-u_{t+1} \mid \mathcal{F}_{t}\right]\right|+\frac{c}{2 t(t+1)},
\end{aligned}
$$

where the second inequality holds by applying Proposition 11. Thus,

$$
\begin{aligned}
& \sum_{t=1}^{\infty} \frac{b_{t}}{t+1} \\
\leq & \sum_{t=1}^{\infty} \frac{c_{1}}{\sqrt{t}(t+1)}+\sum_{t=1}^{\infty}\left|\mathbb{E}\left[u_{t}-u_{t+1} \mid \mathcal{F}_{t}\right]\right| \\
& +\sum_{t=1}^{\infty} \frac{c}{2 t(t+1)} \\
< & +\infty
\end{aligned}
$$

Here, the last inequality is derived by applying (F.16).
Next, we examine the difference between $b_{t+1}$ and $b_{t}$ :

$$
\begin{align*}
& \left|b_{t+1}-b_{t}\right| \\
= & \left|g_{t+1}\left(D_{t+1}\right)-f_{t+1}\left(D_{t+1}\right)-g_{t}\left(D_{t}\right)+f_{t}\left(D_{t}\right)\right| \\
\leq & \left|g_{t+1}\left(D_{t+1}\right)-g_{t}\left(D_{t+1}\right)\right|+\left|g_{t}\left(D_{t+1}\right)-g_{t}\left(D_{t}\right)\right| \\
& +\left|f_{t+1}\left(D_{t+1}\right)-f_{t}\left(D_{t+1}\right)\right|+\left|f_{t}\left(D_{t+1}\right)-f_{t}\left(D_{t}\right)\right| \tag{F.20}
\end{align*}
$$

For the first term on the right hand side,

$$
\begin{aligned}
& \left|g_{t+1}\left(D_{t+1}\right)-g_{t}\left(D_{t+1}\right)\right| \\
= & \left\lvert\, g_{t+1}^{\prime}\left(D_{t+1}\right)-g_{t}^{\prime}\left(D_{t+1}\right)+\frac{1}{t+1} \sum_{i=1}^{t+1} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2}\right. \\
& -\frac{1}{t} \sum_{i=1}^{t} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2}+\frac{\lambda_{3}}{2(t+1)}\left\|D_{t+1}-M_{t+1}\right\|_{F}^{2} \\
& \left.-\frac{\lambda_{3}}{2 t}\left\|D_{t+1}-M_{t}\right\|_{F}^{2} \right\rvert\, \\
= & \left\lvert\, g_{t+1}^{\prime}\left(D_{t+1}\right)-g_{t}^{\prime}\left(D_{t+1}\right)-\frac{1}{t(t+1)} \sum_{i=1}^{t} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2}\right. \\
& -\frac{1}{2(t+1)}\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2} \\
& \left.-\frac{\lambda_{3}}{2 t(t+1)}\left\|D_{t+1}-M_{t}\right\|_{F}^{2}-\frac{\lambda_{3}}{2(t+1)}\left\|\boldsymbol{z}_{t+1} \boldsymbol{u}_{t+1}^{\top}\right\|_{F}^{2} \right\rvert\, \\
\leq & \left|g_{t+1}^{\prime}\left(D_{t+1}\right)-g_{t}^{\prime}\left(D_{t+1}\right)\right|+\frac{1}{t(t+1)} \sum_{i=1}^{t} \frac{1}{2}\left\|\boldsymbol{u}_{i}\right\|_{2}^{2} \\
& +\frac{1}{2(t+1)}\left\|\boldsymbol{u}_{t+1}\right\|_{2}^{2}+\frac{\lambda_{3}}{2 t(t+1)}\left\|D_{t+1}-M_{t}\right\|_{F}^{2} \\
& +\frac{\lambda_{3}}{2(t+1)}\left\|\boldsymbol{z}_{t+1} \boldsymbol{u}_{t+1}^{\top}\right\|_{F}^{2} \\
\zeta_{1} & \left|g_{t+1}^{\prime}\left(D_{t+1}\right)-g_{t}^{\prime}\left(D_{t+1}\right)\right|+\frac{c_{1}}{t+1} \\
= & \left|\frac{1}{t+1} \ell\left(\boldsymbol{z}_{t+1}, D_{t+1}\right)-\frac{1}{t+1} g_{t}^{\prime}\left(D_{t+1}\right)\right|+\frac{c_{1}}{t+1} \\
\zeta_{2} & \frac{c_{2}}{t+1},
\end{aligned}
$$

where $c_{1}$ and $c_{2}$ are some uniform constants. Note that $\zeta_{1}$ holds because all the $\boldsymbol{u}_{i}$ 's, $D_{t+1}, M_{t}$ and $\boldsymbol{z}_{t+1}$ are uniformly bounded (see Proposition 7), and $\zeta_{2}$ holds because $\ell\left(\boldsymbol{z}_{t+1}, D_{t+1}\right)$ and $g_{t}^{\prime}\left(D_{t+1}\right)$ are uniformly bounded (see Corollary 8).

For the third term on the right hand side of (F.20), we can similarly derive

$$
\begin{aligned}
& \left|f_{t+1}\left(D_{t+1}\right)-f_{t}\left(D_{t+1}\right)\right| \\
\leq & \left|f_{t+1}^{\prime}\left(D_{t+1}\right)-f_{t}^{\prime}\left(D_{t+1}\right)\right|+\frac{c_{3}}{t+1} \\
= & \left|\frac{1}{t+1} \ell\left(\boldsymbol{z}_{t+1}, D_{t+1}\right)-\frac{1}{t+1} f_{t}^{\prime}\left(D_{t+1}\right)\right|+\frac{c_{3}}{t+1} \\
& \zeta_{3} \\
\leq & \frac{c_{4}}{t+1}
\end{aligned}
$$

where $c_{3}$ and $c_{4}$ are some uniform constants, and $\zeta_{3}$ holds as $\ell\left(\boldsymbol{z}_{t+1}, D_{t+1}\right)$ and $f_{t}^{\prime}\left(D_{t+1}\right)$ are both uniformly bounded (see Corollary 10).

From Corollary 8 and Corollary 10, we know that both $g_{t}(D)$ and $f_{t}(D)$ are uniformly Lipschitz. That is, there exists uniform constants $\kappa_{1}, \kappa_{2}$, such that

$$
\begin{aligned}
&\left|g_{t}\left(D_{t+1}\right)-g_{t}\left(D_{t}\right)\right| \leq \kappa_{1}\left\|D_{t+1}-D_{t}\right\|_{F} \stackrel{\zeta_{4}}{\leq} \frac{\kappa_{3}}{t+1} \\
&\left|f_{t}\left(D_{t+1}\right)-f_{t}\left(D_{t}\right)\right| \leq \kappa_{2}\left\|D_{t+1}-D_{t}\right\|_{F} \leq \frac{\kappa_{4}}{t+1}
\end{aligned}
$$

Here, $\zeta_{4}$ and $\zeta_{5}$ are derived by applying Proposition 13 and $\kappa_{3}$ and $\kappa_{4}$ are some uniform constants.

Finally, we have a bound for (F.20):

$$
\left|b_{t+1}-b_{t}\right| \leq \frac{\kappa_{0}}{t+1}
$$

where $\kappa_{0}$ is some uniform constant.
By applying Lemma 6, we conclude that $\left\{b_{t}\right\}$ converges to zero. That is,

$$
\lim _{t \rightarrow+\infty} g_{t}\left(D_{t}\right)-f_{t}\left(D_{t}\right)=0
$$

Since we have proved in Theorem 12 that $g_{t}\left(D_{t}\right)$ converges almost surely, we conclude that $f_{t}\left(D_{t}\right)$ converges almost surely to the same limit of $g_{t}\left(D_{t}\right)$.

Theorem 15 (Convergence of $f\left(D_{t}\right)$ ). Let $f(D)$ be the expected loss function we defined in (2.8) and let $D_{t}$ be the optimal solution produced by Algorithm 1. Then $f\left(D_{t}\right)$ converges almost surely to the same limit of $f_{t}\left(D_{t}\right)$ (or, $g_{t}\left(D_{t}\right)$.

Proof. According to the central limit theorem, we know that $\sqrt{t}\left(f\left(D_{t}\right)-f_{t}\left(D_{t}\right)\right)$ is bounded, implying

$$
\lim _{t \rightarrow+\infty} f\left(D_{t}\right)-f_{t}\left(D_{t}\right)=0, \quad \text { a.s. }
$$

## F.6. Proof of gradient of $f(D)$

Proposition 16 (Gradient of $f(D)$ ). Let $f(D)$ be the expected loss function which is defined in (2.8). Then, $f(D)$ is continuously differentiable and $\nabla f(D)=$ $\mathbb{E}_{\boldsymbol{z}}\left[\nabla_{D} \ell(\boldsymbol{z}, D)\right]$. Moreover, $\nabla f(D)$ is uniformly Lipschitz on $\mathcal{D}$.

Proof. We have shown in Proposition 9 that $\ell(\boldsymbol{z}, D)$ is continuously differentiable, $f(D)$ is also continuously differentiable and we have $\nabla f(D)=\mathbb{E}_{\boldsymbol{z}}\left[\nabla_{D} \ell(\boldsymbol{z}, D)\right]$.
Next, we prove the Lipschitz of $\nabla f(D)$. Let $\boldsymbol{v}^{\prime}\left(\boldsymbol{z}^{\prime}, D^{\prime}\right)$ and $\boldsymbol{e}^{\prime}\left(\boldsymbol{z}^{\prime}, D^{\prime}\right)$ be the minimizer of $\tilde{\ell}\left(\boldsymbol{z}^{\prime}, D^{\prime}, \boldsymbol{v}, \boldsymbol{e}\right)$. Since $\tilde{\ell}(\boldsymbol{z}, D, \boldsymbol{v}, \boldsymbol{e})$ has a unique minimum and is continuous in $\boldsymbol{z}, D, \boldsymbol{v}$ and $\boldsymbol{e}, \boldsymbol{v}^{\prime}\left(\boldsymbol{z}^{\prime}, D^{\prime}\right)$ and $\boldsymbol{e}^{\prime}\left(\boldsymbol{z}^{\prime}, D^{\prime}\right)$ is continuous in $\boldsymbol{z}$ and $D$.

Let $\Lambda=\left\{j \mid \boldsymbol{e}_{j}^{\prime} \neq 0\right\}$. According the first order optimality condition, we know that

$$
\frac{\partial \tilde{\ell}(\boldsymbol{z}, D, \boldsymbol{v}, \boldsymbol{e})}{\partial \boldsymbol{e}}=0
$$

which implies

$$
\lambda_{1}(\boldsymbol{z}-D \boldsymbol{v}-\boldsymbol{e}) \in \lambda_{2}\|\boldsymbol{e}\|_{1}
$$

Hence,

$$
\left|(\boldsymbol{z}-D \boldsymbol{v}-\boldsymbol{e})_{j}\right|=\frac{\lambda_{2}}{\lambda_{1}}, \forall j \in \Lambda
$$

Since $\boldsymbol{z}-D \boldsymbol{v}-\boldsymbol{e}$ is continuous in $\boldsymbol{z}$ and $D$, there exists an open neighborhood $\mathcal{V}$, such that for all $\left(\boldsymbol{z}^{\prime \prime}, D^{\prime \prime}\right) \in \mathcal{V}$, if $j \notin \Lambda$, then $\left|\left(z^{\prime \prime}-D^{\prime \prime} v^{\prime \prime}-e^{\prime \prime}\right)_{j}\right|<\frac{\lambda_{2}}{\lambda_{1}}$ and $\boldsymbol{e}_{j}^{\prime \prime}=0$. That is, the support set of $e^{\prime}$ will not change.
Let us denote $H=\left[D I_{p}\right], \boldsymbol{r}=\left[\boldsymbol{v}^{\top} \boldsymbol{e}^{\top}\right]^{\top}$ and define the function

$$
\begin{aligned}
\tilde{\ell}\left(\boldsymbol{z}, H, \boldsymbol{r}_{\Lambda}\right)= & \frac{\lambda_{1}}{2}\left\|\boldsymbol{z}-H_{\Lambda} \boldsymbol{r}_{\Lambda}\right\|_{2}^{2}+\frac{1}{2}\left\|\left[\begin{array}{ll}
I & 0
\end{array}\right] \boldsymbol{r}_{\Lambda}\right\|_{2}^{2} \\
& +\lambda_{2}\left\|[0 I] \boldsymbol{r}_{\Lambda}\right\|_{1}
\end{aligned}
$$

Since $\tilde{\ell}\left(\boldsymbol{z}, D_{\Lambda}, \cdot\right)$ is strongly convex, there exists a uniform constant $\kappa_{1}$, such that for all $\boldsymbol{r}_{\Lambda}^{\prime \prime}$,

$$
\begin{align*}
& \tilde{\ell}\left(\boldsymbol{z}^{\prime}, H_{\Lambda}^{\prime}, \boldsymbol{r}_{\Lambda}^{\prime \prime}\right)-\tilde{\ell}\left(\boldsymbol{z}^{\prime}, H_{\Lambda}^{\prime}, \boldsymbol{r}_{\Lambda}^{\prime}\right) \\
\geq & \kappa_{1}\left\|\boldsymbol{r}_{\Lambda}^{\prime \prime}-\boldsymbol{r}_{\Lambda}^{\prime}\right\|_{2}^{2} \\
= & \kappa_{1}\left(\left\|\boldsymbol{v}^{\prime \prime}-\boldsymbol{v}^{\prime}\right\|_{2}^{2}+\left\|\boldsymbol{e}_{\Lambda}^{\prime \prime}-\boldsymbol{e}_{\Lambda}^{\prime}\right\|_{2}^{2}\right) . \tag{F.21}
\end{align*}
$$

On the other hand,

$$
\begin{align*}
& \tilde{\ell}\left(\boldsymbol{z}^{\prime}, H_{\Lambda}^{\prime}, \boldsymbol{r}_{\Lambda}^{\prime \prime}\right)-\tilde{\ell}\left(\boldsymbol{z}^{\prime}, H_{\Lambda}^{\prime}, \boldsymbol{r}_{\Lambda}^{\prime}\right) \\
= & \tilde{\ell}\left(\boldsymbol{z}^{\prime}, H_{\Lambda}^{\prime}, \boldsymbol{r}_{\Lambda}^{\prime \prime}\right)-\tilde{\ell}\left(\boldsymbol{z}^{\prime \prime}, H_{\Lambda}^{\prime \prime}, \boldsymbol{r}_{\Lambda}^{\prime \prime}\right) \\
& +\tilde{\ell}\left(\boldsymbol{z}^{\prime \prime}, H_{\Lambda}^{\prime \prime}, \boldsymbol{r}_{\Lambda}^{\prime \prime}\right)-\tilde{\ell}\left(\boldsymbol{z}^{\prime}, D_{\Lambda}^{\prime}, \boldsymbol{r}_{\Lambda}^{\prime}\right) \\
\leq & \tilde{\ell}\left(\boldsymbol{z}^{\prime}, H_{\Lambda}^{\prime}, \boldsymbol{r}_{\Lambda}^{\prime \prime}\right)-\tilde{\ell}\left(\boldsymbol{z}^{\prime \prime}, H_{\Lambda}^{\prime \prime}, \boldsymbol{r}_{\Lambda}^{\prime \prime}\right) \\
& +\tilde{\ell}\left(\boldsymbol{z}^{\prime \prime}, H_{\Lambda}^{\prime \prime}, \boldsymbol{r}_{\Lambda}^{\prime}\right)-\tilde{\ell}\left(\boldsymbol{z}^{\prime}, H_{\Lambda}^{\prime}, \boldsymbol{r}_{\Lambda}^{\prime}\right), \tag{F.22}
\end{align*}
$$

where the last inequality holds because $\boldsymbol{r}^{\prime \prime}$ is the minimizer of $\tilde{\ell}\left(z^{\prime \prime}, H^{\prime \prime}, \boldsymbol{r}\right)$.
We shall prove that $\tilde{\ell}\left(\boldsymbol{z}^{\prime}, H_{\Lambda}^{\prime}, \boldsymbol{r}_{\Lambda}\right)-\tilde{\ell}\left(\boldsymbol{z}^{\prime \prime}, H_{\Lambda}^{\prime \prime}, \boldsymbol{r}_{\Lambda}\right)$ is Lipschitz w.r.t. $\boldsymbol{r}$, which implies the Lipschitz of $\boldsymbol{v}^{\prime}(\boldsymbol{z}, D)$ and $e^{\prime}(z, D)$.

$$
\begin{aligned}
& \nabla_{\boldsymbol{r}}\left(\tilde{\ell}\left(\boldsymbol{z}^{\prime}, H_{\Lambda}^{\prime}, \boldsymbol{r}_{\Lambda}\right)-\tilde{\ell}\left(\boldsymbol{z}^{\prime \prime}, H_{\Lambda}^{\prime \prime}, \boldsymbol{r}_{\Lambda}\right)\right) \\
= & \lambda_{1}\left[H_{\Lambda}^{\prime \top}\left(H_{\Lambda}^{\prime}-H_{\Lambda}^{\prime \prime}\right)+\left(H_{\Lambda}^{\prime}-H_{\Lambda}^{\prime \prime}\right)^{\top} H_{\Lambda}^{\prime \prime}\right. \\
& \left.+H_{\Lambda}^{\prime \top}\left(\boldsymbol{z}^{\prime \prime}-\boldsymbol{z}^{\prime}\right)+\left(H_{\Lambda}^{\prime \prime}-H_{\Lambda}^{\prime}\right)^{\top} \boldsymbol{z}^{\prime \prime}\right]
\end{aligned}
$$

Note that $\left\|H_{\Lambda}^{\prime}\right\|_{F},\left\|H_{\Lambda}^{\prime \prime}\right\|_{F}$ and $z^{\prime \prime}$ are all uniformly bounded. Hence, there exists uniform constants $c_{1}$ and $c_{2}$, such that

$$
\begin{aligned}
& \left\|\nabla_{\boldsymbol{r}}\left(\tilde{\ell}\left(\boldsymbol{z}^{\prime}, H_{\Lambda}^{\prime}, \boldsymbol{r}_{\Lambda}\right)-\tilde{\ell}\left(\boldsymbol{z}^{\prime \prime}, H_{\Lambda}^{\prime \prime}, \boldsymbol{r}_{\Lambda}\right)\right)\right\|_{2} \\
\leq & c_{1}\left\|H_{\Lambda}^{\prime}-H_{\Lambda}^{\prime \prime}\right\|_{F}+c_{2}\left\|\boldsymbol{z}^{\prime}-\boldsymbol{z}^{\prime \prime}\right\|_{2}
\end{aligned}
$$

which implies that $\tilde{\ell}\left(\boldsymbol{z}^{\prime}, H_{\Lambda}^{\prime}, \boldsymbol{r}_{\Lambda}\right)-\tilde{\ell}\left(\boldsymbol{z}^{\prime \prime}, H_{\Lambda}^{\prime \prime}, \boldsymbol{r}_{\Lambda}\right)$ is Lipschitz with Lipschitz constant $c\left(H_{\Lambda}^{\prime}, H_{\Lambda}^{\prime \prime}, \boldsymbol{z}^{\prime}, \boldsymbol{z}^{\prime \prime}\right)=$ $c_{1}\left\|H_{\Lambda}^{\prime}-H_{\Lambda}^{\prime \prime}\right\|_{F}+c_{2}\left\|z^{\prime}-z^{\prime \prime}\right\|_{2}$. Combining this fact with (F.21) and (F.22), we obtain

$$
\kappa_{1}\left\|\boldsymbol{r}_{\Lambda}^{\prime \prime}-\boldsymbol{r}_{\Lambda}^{\prime}\right\|_{2}^{2} \leq c\left(H_{\Lambda}^{\prime}, H_{\Lambda}^{\prime \prime}, \boldsymbol{z}^{\prime}, \boldsymbol{z}^{\prime \prime}\right)\left\|\boldsymbol{r}_{\Lambda}^{\prime \prime}-\boldsymbol{r}_{\Lambda}^{\prime}\right\|_{2}
$$

Therefore, $\boldsymbol{r}(\boldsymbol{z}, D)$ is Lipschitz and so are $\boldsymbol{v}(\boldsymbol{z}, D)$ and $e(\boldsymbol{z}, D)$. Note that according to Proposition 9,

$$
\begin{aligned}
& \nabla f\left(D^{\prime}\right)-\nabla f\left(D^{\prime \prime}\right) \\
= & \mathbb{E}_{\boldsymbol{z}}\left[\left(H^{\prime} \boldsymbol{r}^{\prime}-\boldsymbol{z}\right) \boldsymbol{v}^{\prime \top}-\left(H^{\prime \prime} \boldsymbol{r}^{\prime \prime}-\boldsymbol{z}\right) \boldsymbol{v}^{\prime \prime \top}\right] \\
= & \mathbb{E}_{\boldsymbol{z}}\left[H^{\prime} \boldsymbol{r}^{\prime}\left(\boldsymbol{v}^{\prime}-\boldsymbol{v}^{\prime \prime}\right)^{\top}+\left(H^{\prime}-H^{\prime \prime}\right) \boldsymbol{r}^{\prime} \boldsymbol{v}^{\prime \prime \top}\right. \\
& \left.+H^{\prime \prime}\left(\boldsymbol{r}^{\prime}-\boldsymbol{r}^{\prime \prime}\right) \boldsymbol{v}^{\prime \prime \top}+\boldsymbol{z}\left(\boldsymbol{v}^{\prime \prime}-\boldsymbol{v}^{\prime}\right)^{\top}\right] .
\end{aligned}
$$

Thus,

$$
\begin{aligned}
& \quad\left\|\nabla f\left(D^{\prime}\right)-\nabla f\left(D^{\prime \prime}\right)\right\|_{F} \\
& \stackrel{\zeta_{1}}{\leq} \mathbb{E}_{\boldsymbol{z}}\left[\left\|H^{\prime} \boldsymbol{r}^{\prime}\right\|_{2}\left\|\boldsymbol{v}^{\prime}-\boldsymbol{v}^{\prime \prime}\right\|_{2}+\left\|H^{\prime}-H^{\prime \prime}\right\|_{F}\left\|\boldsymbol{r}^{\prime} \boldsymbol{v}^{\prime \prime \top}\right\|_{F}\right. \\
& \left.\quad+\left\|H^{\prime \prime}\right\|_{F}\left\|\boldsymbol{r}^{\prime}-\boldsymbol{r}^{\prime \prime}\right\|_{2}\left\|\boldsymbol{v}^{\prime \prime}\right\|_{2}+\|\boldsymbol{z}\|_{2}\left\|\boldsymbol{v}^{\prime}-\boldsymbol{v}^{\prime \prime}\right\|_{2}\right] \\
& \stackrel{\zeta_{2}}{\leq} \mathbb{E}_{\boldsymbol{z}}\left[\left(\gamma_{1}+\gamma_{2}\|\boldsymbol{z}\|_{2}\right)\left\|H^{\prime}-H^{\prime \prime}\right\|_{F}\right] \\
& \stackrel{\zeta_{3}}{\leq} \gamma_{0}\left\|D^{\prime}-D^{\prime \prime}\right\|_{F}
\end{aligned}
$$

where $\gamma_{0}, \gamma_{1}$ and $\gamma_{2}$ are all uniform constants. Here, $\zeta_{1}$ holds because for any function $s(\boldsymbol{z})$, we have $\left\|\mathbb{E}_{\boldsymbol{z}}[s(\boldsymbol{z})]\right\|_{F} \leq \mathbb{E}_{\boldsymbol{z}}\left[\|s(\boldsymbol{z})\|_{F}\right] . \zeta_{2}$ is derived by using the result that $\boldsymbol{r}(\boldsymbol{z}, H)$ and $\boldsymbol{v}(\boldsymbol{z}, H)$ are both Lipschitz and $H^{\prime}, H^{\prime \prime}, \boldsymbol{r}^{\prime}, \boldsymbol{r}^{\prime \prime}, \boldsymbol{v}^{\prime}$ and $\boldsymbol{v}^{\prime \prime}$ are all uniformly bounded. $\zeta_{3}$ holds because $\boldsymbol{z}$ is uniformly bounded and actually $\left\|H^{\prime}-H^{\prime \prime}\right\|_{F}=\left\|D^{\prime}-D^{\prime \prime}\right\|_{F}$. Thus, we complete the proof.

## F.7. Proof of stationary point

Theorem 17 (Convergence of $D_{t}$ ). Let $\left\{D_{t}\right\}$ be the optimal basis produced by Algorithm 1 and let $f(D)$ be the expected loss function defined in (2.8). Then $D_{t}$ converges to a stationary point of $f(D)$ when $t$ goes to infinity.

Proof. Since $\frac{1}{t} A_{t}$ and $\frac{1}{t} B_{t}$ are uniformly bounded (Proposition 7), there exist sub-sequences of $\left\{\frac{1}{t} A_{t}\right\}$ and $\left\{\frac{1}{t} B_{t}\right\}$ that converge to $A_{\infty}$ and $B_{\infty}$ respectively. Then $D_{t}$ will converge to $D_{\infty}$. Let $W$ be an arbitrary matrix in $\mathbb{R}^{p \times d}$ and $\left\{h_{k}\right\}$ be any positive sequence that converges to zero.
As $g_{t}$ is a surrogate function of $f_{t}$, for all $t$ and $k$, we have

$$
g_{t}\left(D_{t}+h_{k} W\right) \geq f_{t}\left(D_{t}+h_{k} W\right)
$$

Let $t$ tend to infinity, and note that $f(D)=\lim _{t \rightarrow \infty} f_{t}(D)$, we have

$$
g_{\infty}\left(D_{\infty}+h_{k} W\right) \geq f\left(D_{\infty}+h_{k} W\right)
$$

Note that the Lipschitz of $\nabla f$ indicates that the second derivative of $f(D)$ is uniformly bounded. By a simple calculation, we can also show that it also holds for $g_{t}(D)$. This fact implies that we can take the first order Taylor expansion for both $g_{t}(D)$ and $f(D)$ even when $t$ tends to infinity (because the second order derivatives of them always exist). That is,

$$
\begin{aligned}
& \operatorname{Tr}\left(h_{k} W^{\top} \nabla g_{\infty}\left(D_{\infty}\right)\right)+o\left(h_{k} W\right) \\
\geq & \operatorname{Tr}\left(h_{k} W^{\top} \nabla f\left(D_{\infty}\right)\right)+o\left(h_{k} W\right)
\end{aligned}
$$

By multiplying $\frac{1}{h_{k}\|W\|_{F}}$ on both sides and note that $\left\{h_{k}\right\}$ is a positive sequence, it follows that

$$
\begin{aligned}
& \operatorname{Tr}\left(\frac{1}{\|W\|_{F}} W^{\top} \nabla g_{\infty}\left(D_{\infty}\right)\right)+\frac{o\left(h_{k} W\right)}{h_{k}\|W\|_{F}} \\
\geq & \operatorname{Tr}\left(\frac{1}{\|W\|_{F}} W^{\top} \nabla f\left(D_{\infty}\right)\right)+\frac{o\left(h_{k} W\right)}{h_{k}\|W\|_{F}}
\end{aligned}
$$

Now let $k$ go to infinity,

$$
\operatorname{Tr}\left(\frac{1}{\|W\|_{F}} W^{\top} \nabla g_{\infty}\left(D_{\infty}\right)\right) \geq \operatorname{Tr}\left(\frac{1}{\|W\|_{F}} W^{\top} \nabla f\left(D_{\infty}\right)\right)
$$

Note that this inequality holds for any matrix $W \in \mathbb{R}^{p \times d}$, so we actually have

$$
\nabla g_{\infty}\left(D_{\infty}\right)=\nabla f\left(D_{\infty}\right)
$$

As $D_{\infty}$ is the minimizer of $g_{\infty}(D)$, we have

$$
\nabla f\left(D_{\infty}\right)=\nabla g_{\infty}\left(D_{\infty}\right)=0
$$

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