Properly Learning Poisson Binomial Distributions in Almost Polynomial Time

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Abstract
We give an algorithm for properly learning Poisson binomial distributions. A Poisson binomial distribution (PBD) of order $n \in \mathbb{Z}^+$ is the discrete probability distribution of the sum of $n$ mutually independent Bernoulli random variables. Given $\tilde{O}(1/\epsilon^2)$ samples from an unknown PBD $P$, our algorithm runs in time $(1/\epsilon)^O(\log \log(1/\epsilon))$, and outputs a hypothesis PBD that is $\epsilon$-close to $P$ in total variation distance. The sample complexity of our algorithm is known to be nearly-optimal, up to logarithmic factors, as established in previous work Daskalakis et al. (2012b). However, the previously best known running time for properly learning PBDs Daskalakis et al. (2012b); Diakonikolas et al. (2015a) was $(1/\epsilon)^O(\log(1/\epsilon))$, and was essentially obtained by enumeration over an appropriate $\epsilon$-cover. We remark that the running time of this cover-based approach cannot be improved, as any $\epsilon$-cover for the space of PBDs has size $(1/\epsilon)^\Omega(\log(1/\epsilon))$ Diakonikolas et al. (2015a).

As one of our main contributions, we provide a novel structural characterization of PBDs, showing that any PBD $P$ is $\epsilon$-close to another PBD $Q$ with $O(\log(1/\epsilon))$ distinct parameters. More precisely, we prove that, for all $\epsilon > 0$, there exists an explicit collection $M$ of $(1/\epsilon)^O(\log \log(1/\epsilon))$ vectors of multiplicities, such that for any PBD $P$ there exists a PBD $Q$ with $O(\log(1/\epsilon))$ distinct parameters whose multiplicities are given by some element of $M$, such that $Q$ is $\epsilon$-close to $P$. Our proof combines tools from Fourier analysis and algebraic geometry.

Our approach to the proper learning problem is as follows: Starting with an accurate non-proper hypothesis, we fit a PBD to this hypothesis. This fitting problem can be formulated as a natural polynomial optimization problem. Our aforementioned structural characterization allows us to reduce the corresponding fitting problem to a collection of $(1/\epsilon)^O(\log \log(1/\epsilon))$ systems of low-degree polynomial inequalities. We show that each such system can be solved in time $(1/\epsilon)^O(\log \log(1/\epsilon))$, which yields the overall running time of our algorithm.

Keywords: distribution learning, proper learning, Poisson binomial distribution, optimization over polynomials with real roots

1. Introduction
The Poisson binomial distribution (PBD) is the discrete probability distribution of a sum of mutually independent Bernoulli random variables. PBDs comprise one of the most fundamental non-parametric families of discrete distributions. They have been extensively studied in probability and statistics Poisson (1837); Chernoff (1952); Hoeffding (1963); Dubhashi and Panconesi (2009), and are ubiquitous in various applications (see, e.g., Chen and Liu (1997) and references therein). Re-
cent years have witnessed a flurry of research activity on PBDs and generalizations from several perspectives of theoretical computer science, including learning Daskalakis et al. (2012b, 2013); Diakonikolas et al. (2015a); Daskalakis et al. (2015b); Diakonikolas et al. (2015b), pseudorandomness and derandomization Gopalan et al. (2011); Bhaskara et al. (2012); De (2015); Gopalan et al. (2015), property testing Acharya and Daskalakis (2015); Canonne et al. (2015), and computational game theory Daskalakis and Papadimitriou (2007, 2009, 2014a,b); Goldberg and Turchetta (2014).

Despite their seeming simplicity, PBDs have surprisingly rich structure, and basic questions about them can be unexpectedly challenging to answer. We cannot do justice to the probability literature studying the following question: Under what conditions can we approximate PBDs by simpler distributions? See Section 1.2 of Daskalakis et al. (2015a) for a summary. In recent years, a number of works in theoretical computer science Daskalakis and Papadimitriou (2007, 2009); Daskalakis et al. (2012b); Daskalakis and Papadimitriou (2014a); Diakonikolas et al. (2015a) have studied, and essentially resolved, the following questions: Is there a small set of distributions that approximately cover the set of all PBDs? What is the number of samples required to learn an unknown PBD?

We study the following natural computational question: Given independent samples from an unknown PBD \( P \), can we efficiently find a hypothesis PBD \( Q \) that is close to \( P \), in total variation distance? That is, we are interested in properly learning PBDs, a problem that has resisted recent efforts Daskalakis et al. (2012b); Diakonikolas et al. (2015a) at designing efficient algorithms. In this work, we propose a new approach to this problem that leads to a significantly faster algorithm than was previously known. At a high-level, we establish an interesting connection of this problem to algebraic geometry and polynomial optimization. By building on this connection, we provide a new structural characterization of the space of PBDs, on which our algorithm relies, that we believe is of independent interest. In the following, we motivate and describe our results in detail, and elaborate on our ideas and techniques.

**Distribution Learning.** We recall the standard definition of learning an unknown probability distribution from samples Kearns et al. (1994); Devroye and Lugosi (2001): Given access to independent samples drawn from an unknown distribution \( P \) in a given family \( \mathcal{C} \), and an error parameter \( \epsilon > 0 \), a learning algorithm for \( \mathcal{C} \) must output a hypothesis \( H \) such that, with probability at least 9/10, the total variation distance between \( H \) and \( P \) is at most \( \epsilon \). The performance of a learning algorithm is measured by its sample complexity (the number of samples drawn from \( P \)) and its computational complexity.

In non-proper learning (density estimation), the goal is to output an approximation to the target distribution without any constraints on its representation. In proper learning, we require in addition that the hypothesis \( H \) is a member of the family \( \mathcal{C} \). Note that these two notions of learning are essentially equivalent in terms of sample complexity (given any accurate hypothesis, we can do a brute-force search to find its closest distribution in \( \mathcal{C} \)), but not necessarily equivalent in terms of computational complexity. A typically more demanding notion of learning is that of parameter estimation. The goal here is to identify the parameters of the unknown model, e.g., the means of the individual Bernoulli components for the case of PBDs, up to a desired accuracy \( \epsilon \).

**Discussion.** In many learning situations, it is desirable to compute a proper hypothesis, i.e., one that belongs to the underlying distribution family \( \mathcal{C} \). A proper hypothesis is typically preferable due to its interpretability. In the context of distribution learning, a practitioner may not want to use a density estimate, unless it is proper. For example, one may want the estimate to have the
properties of the underlying family, either because this reflects some physical understanding of the inference problem, or because one might only be using the density estimate as the first stage of a more involved procedure. While parameter estimation may arguably provide a more desirable guarantee than proper learning in some cases, its sample complexity is typically prohibitively large.

For the class of PBDs, we show (Proposition 15, Appendix A) that parameter estimation requires $2^{\Omega(1/\epsilon)}$ samples, for PBDs with $n = \Omega(1/\epsilon)$ Bernoulli components, where $\epsilon > 0$ is the accuracy parameter. In contrast, the sample complexity of (non-)proper learning is known to be $\tilde{O}(1/\epsilon^2)$ Daskalakis et al. (2012b). Hence, proper learning serves as an attractive middle ground between non-proper learning and parameter estimation. Ideally, one could obtain a proper learner for a given family whose running time matches that of the best non-proper algorithm.

Recent work by the authors Diakonikolas et al. (2015a) has characterized the computational complexity of non-properly learning PBDs, which was shown to be $\tilde{O}(1/\epsilon^2)$, i.e., nearly-linear in the sample complexity of the problem. Motivated by this progress, a natural research direction is to obtain a computationally efficient proper learning algorithm, i.e., one that runs in time $\text{poly}(1/\epsilon)$ and outputs a PBD as its hypothesis. Besides practical applications, we feel that this is an interesting algorithmic problem, with intriguing connections to algebraic geometry and polynomial optimization (as we point out in this work). We remark that several natural approaches fall short of yielding a polynomial–time algorithm for this problem. More specifically, the proper learning of PBDs can be phrased as a structured non-convex optimization problem, albeit it is unclear whether any such formulation may lead to a polynomial–time algorithm. As part of our contribution, we formulate this optimization problem in terms of univariate polynomials with real roots. We show that our techniques yields an algorithm with a similar running time for this optimization problem.

This work is part of a broader agenda of systematically investigating the computational complexity of proper distribution learning. We believe that this is a fundamental goal that warrants study for its own sake. The complexity of proper learning has been extensively investigated in the supervised setting of PAC learning Boolean functions Kearns and Vazirani (1994); Feldman (2015), with several algorithmic and computational intractability results obtained in the past couple of decades. In sharp contrast, very little is known about the complexity of proper learning in the unsupervised setting of learning probability distributions.

1.1. Preliminaries

For $n, m \in \mathbb{Z}_+$ with $m \leq n$, we will denote $[n] \overset{\text{def}}{=} \{0, 1, \ldots, n\}$ and $[m, n] \overset{\text{def}}{=} \{m, m+1, \ldots, n\}$. For a distribution $\mathbf{P}$ supported on $[n]$, $m \in \mathbb{Z}_+$, we write $\mathbf{P}(i)$ to denote the value $\Pr_{X \sim \mathbf{P}}[X = i]$ of the probability mass function (pmf) at point $i$. The total variation distance between two distributions $\mathbf{P}$ and $\mathbf{Q}$ supported on a finite domain $A$ is $d_{TV}(\mathbf{P}, \mathbf{Q}) \overset{\text{def}}{=} \max_{S \subseteq A} |\mathbf{P}(S) - \mathbf{Q}(S)| = (1/2) \cdot \|\mathbf{P} - \mathbf{Q}\|_1$. If $X$ and $Y$ are random variables, their total variation distance $d_{TV}(X, Y)$ is defined as the total variation distance between their distributions.

**Poisson Binomial Distribution.** A Poisson binomial distribution of order $n \in \mathbb{Z}_+$ or $n$-PBD is the discrete probability distribution of the sum $\sum_{i=1}^{n} X_i$ of $n$ mutually independent Bernoulli random variables $X_1, \ldots, X_n$. An $n$-PBD $\mathbf{P}$ can be represented uniquely as the vector of its $n$ parameters $p_1, \ldots, p_n$, i.e., as $(p_i)_{i=1}^{n}$, where we can assume that $0 \leq p_1 \leq p_2 \leq \ldots \leq p_n \leq 1$. To go from $\mathbf{P}$ to its corresponding vector, we find a collection $X_1, \ldots, X_n$ of mutually independent Bernoulis such that $\sum_{i=1}^{n} X_i$ is distributed according to $\mathbf{P}$ with $\mathbb{E}[X_1] \leq \ldots \leq \mathbb{E}[X_n]$, and we set $p_i = \mathbb{E}[X_i]$ for all $i$. An equivalent unique representation of an $n$-PBD with parameter vector $(p_i)_{i=1}^{n}$ is via the...
vector of its distinct parameters $p_1', \ldots, p_k'$, where $1 \leq k \leq n$, and $p_i' \neq p_j'$ for $i \neq j$, together with their corresponding integer multiplicities $m_1, \ldots, m_k$. Note that $m_i \geq 1, 1 \leq i \leq k$, and $\sum_{i=1}^{k} m_i = n$. This representation will be crucial for the results and techniques of this paper.

**Discrete Fourier Transform.** For $x \in \mathbb{R}$ we will denote $e(x) \equiv \exp(2\pi i x)$. The **Discrete Fourier Transform (DFT)** modulo $M$ of a function $F : [n] \to \mathbb{C}$ is the function $\hat{F} : [M-1] \to \mathbb{C}$ defined as

$$\hat{F}(\xi) = \sum_{j=0}^{n} e(-\xi j/M) F(j),$$

for integers $\xi \in [M-1]$. The DFT modulo $M$, $\hat{P}$, of a distribution $P$ is the DFT modulo $M$ of its probability mass function. The **inverse DFT modulo** $M$ onto the range $[m, m+M-1]$ of $\hat{F} : [M-1] \to \mathbb{C}$, is the function $F : [m, m+M-1] \cap \mathbb{Z} \to \mathbb{C}$ defined by

$$F(j) = \frac{1}{M} \sum_{\xi=0}^{M-1} e(\xi j/M) \hat{F}(\xi),$$

for $j \in [m, m+M-1] \cap \mathbb{Z}$. The $L_2$ norm of the DFT is defined as $\|\hat{F}\|_2 = \sqrt{\frac{1}{M} \sum_{\xi=0}^{M-1} |\hat{F}(\xi)|^2}$.

### 1.2. Our Results and Comparison to Prior Work

We are ready to formally describe the main contributions of this paper. As our main algorithmic result, we obtain a near-sample optimal and almost polynomial-time algorithm for properly learning PBDs:

**Theorem 1 (Proper Learning of PBDs)** For all $n \in \mathbb{Z}_+$ and $\epsilon > 0$, there is a proper learning algorithm for $n$-PBDs with the following performance guarantee: Let $P$ be an unknown $n$-PBD. The algorithm uses $\tilde{O}(1/\epsilon^2)$ samples from $P$, runs in time $O(\log \log(1/\epsilon))$, and outputs (a succinct description of) an $n$-PBD $Q$ such that with probability at least $9/10$ it holds that $d_{TV}(Q, P) \leq \epsilon$.

**Remark 2** We remark that our proper learning algorithm can easily be made agnostic (robust to model misspecification). See Theorem 16 in Appendix D. More specifically, in Appendix D we point out that the problem of agnostic proper learning of PBDs can be reduced to the following optimization problem: Given a real univariate polynomial $p$, find a polynomial $q$ with non-positive real roots such that the sum of the absolute values of the coefficients of $p - q$ is minimized. We believe that this non-convex optimization problem may be of independent interest. In Appendix D.2, we show (Theorem 21) that our proper learning algorithm can be easily adapted to solve this polynomial optimization problem with a similar running time.

We now provide a comparison of Theorem 1 to previous work. The problem of learning PBDs was first explicitly considered by Daskalakis et al. (2012b), who gave two main results: (i) a non-proper learning algorithm with sample complexity and running time $\tilde{O}(1/\epsilon^3)$, and (ii) a proper learning algorithm with sample complexity $\tilde{O}(1/\epsilon^2)$ and running time $O(1/\epsilon)^{\text{polylog}(1/\epsilon)}$. In recent work Diakonikolas et al. (2015a), the authors obtained a near-optimal sample and time algorithm to non-properly learn a more general family of discrete distributions (containing PBDs). For the special case of PBDs, the aforementioned work Diakonikolas et al. (2015a) yields the following implications: (i) a non-proper learning algorithm with sample and time complexity $\tilde{O}(1/\epsilon^2)$, and (ii) a proper learning algorithm with sample complexity $\tilde{O}(1/\epsilon^2)$ and running time $(1/\epsilon)^{\Theta(\log(1/\epsilon))}$. Prior to this paper, this was the fastest algorithm for properly learning PBDs. Hence, Theorem 1 represents a super-polynomial improvement in the running time, while still using a near-optimal sample size.

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1. We work in the standard “word RAM” model in which basic arithmetic operations on $O(\log n)$-bit integers are assumed to take constant time.
In addition to obtaining a significantly more efficient algorithm, the proof of Theorem 1 offers a novel approach to the problem of properly learning PBDs. The proper algorithms of Daskalakis et al. (2012b); Diakonikolas et al. (2015a) exploit the cover structure of the space of PBDs, and (essentially) proceed by running an appropriate tournament procedure over an $\epsilon$-cover (see, e.g., Lemma 10 in Daskalakis et al. (2015a))\(^2\). This cover-based approach, when applied to an $\epsilon$-covering set of size $N$, clearly has runtime $\Omega(N)$, and can be easily implemented in time $O(N^2/\epsilon^2)$. Daskalakis et al. (2012b) applies the cover-based approach to the $\epsilon$-cover construction of Daskalakis and Papadimitriou (2014a), which has size $(1/\epsilon)^{O(\log^2(1/\epsilon))}$, while Diakonikolas et al. (2015a) proves and uses a new cover construction of size $(1/\epsilon)^{O(\log(1/\epsilon))}$. Observe that if there existed an explicit $\epsilon$-cover of size $\text{poly}(1/\epsilon)$, the aforementioned cover-based approach would immediately yield a poly$(1/\epsilon)$ time proper learning algorithm. Perhaps surprisingly, it was shown in Diakonikolas et al. (2015a) that any $\epsilon$-cover for $n$-PBDs with $n = \Omega(\log(1/\epsilon))$ Bernoulli coordinates has size $(1/\epsilon)^{\Omega(\log(1/\epsilon))}$. In conclusion, the cover-based approach for properly learning PBDs inherently leads to runtime of $(1/\epsilon)^{\Omega(\log(1/\epsilon))}$.

In this work, we circumvent the $(1/\epsilon)^{\Omega(\log(1/\epsilon))}$ cover size lower bound by establishing a new structural characterization of the space of PBDs. Very roughly speaking, our structural result allows us to reduce the proper learning problem to the case that the underlying PBD has $O(\log(1/\epsilon))$ distinct parameters. Indeed, as a simple corollary of our main structural result (Theorem 5 in Section 2), we obtain the following:

**Theorem 3 (A “Few” Distinct Parameters Suffice)** For all $n \in \mathbb{Z}_+$ and $\epsilon > 0$ the following holds: For any $n$-PBD $\mathbf{P}$, there exists an $n$-PBD $\mathbf{Q}$ with $d_{TV}(\mathbf{P}, \mathbf{Q}) \leq \epsilon$ such that $\mathbf{Q}$ has $O(\log(1/\epsilon))$ distinct parameters.

We note that in subsequent work Diakonikolas et al. (2015b) the authors generalize the above theorem to Poisson multinomial distributions.

**Remark.** We remark that Theorem 3 is quantitatively tight, i.e., $O(\log(1/\epsilon))$ distinct parameters are in general necessary to $\epsilon$-approximate PBDs. This follows directly from the explicit cover lower bound construction of Diakonikolas et al. (2015a).

We view Theorem 3 as a natural structural result for PBDs. Alas, its statement does not quite suffice for our algorithmic application. While Theorem 3 guarantees that $O(\log(1/\epsilon))$ distinct parameters are enough to consider for an $\epsilon$-approximation, it gives no information on the multiplicities these parameters may have. In particular, the upper bound on the number of different combinations of multiplicities one can derive from it is $(1/\epsilon)^{O(\log(1/\epsilon))}$, which is not strong enough for our purposes. The following stronger structural result (see Theorem 5 and Lemma 6 for detailed statements) is critical for our improved proper algorithm:

**Theorem 4 (A “Few” Multiplicities and Distinct Parameters Suffice)** For all $n \in \mathbb{Z}_+$ and $\epsilon > 0$ the following holds: For any $\sigma > 0$, there exists an explicit collection $\mathcal{M}$ of $(1/\epsilon)^{O(\log \log(1/\epsilon))}$ vectors of multiplicities computable in $\text{poly}(|\mathcal{M}|)$ time, so that for any $n$-PBD $\mathbf{P}$ with variance $\Theta(\sigma^2)$ there exists a PBD $\mathbf{Q}$ with $O(\log(1/\epsilon))$ distinct parameters whose multiplicities are given by some element of $\mathcal{M}$, such that $d_{TV}(\mathbf{P}, \mathbf{Q}) \leq \epsilon$.

\(^2\) Note that any $\epsilon$-cover for the space of $n$-PBDs has size $\Omega(n)$. However, for the task of properly learning PBDs, by a simple (known) reduction, one can assume without loss of generality that $n = \text{poly}(1/\epsilon)$. Hence, the tournament-based algorithm only needs to consider $\epsilon$-covers over PBDs with poly$(1/\epsilon)$ Bernoulli components.
Now suppose we would like to properly learn an unknown PBD with $O(\log(1/\epsilon))$ distinct parameters and known multiplicities for each parameter. Even for this very restricted subset of PBDs, the construction of Diakonikolas et al. (2015a) implies a cover lower bound of $(1/\epsilon)^{\Omega(\log(1/\epsilon))}$. To handle such PBDs, we combine ingredients from Fourier analysis and algebraic geometry with careful Taylor series approximations, to construct an appropriate system of low-degree polynomial inequalities whose solution approximately recovers the unknown distinct parameters.

In the following subsection, we provide a detailed intuitive explanation of our techniques.

1.3. Techniques

The starting point of this work lies in the non-proper learning algorithm from our recent work Diakonikolas et al. (2015a). Roughly speaking, our new proper algorithm can be viewed as a two-step process: We first compute an accurate non-proper hypothesis $H$ using the algorithm in Diakonikolas et al. (2015a), and we then post-process $H$ to find a PBD $Q$ that is close to $H$. We note that the non-proper hypothesis $H$ output by Diakonikolas et al. (2015a) is represented succinctly via its Discrete Fourier Transform; this property is crucial for the computational complexity of our proper algorithm. (We note that the description of our proper algorithm and its analysis, presented in Section 3, are entirely self-contained. The above description is for the sake of the intuition.)

We now proceed to explain the connection in detail. The crucial fact, established in Diakonikolas et al. (2015a) for a more general setting, is that the Fourier transform of a PBD has small effective support (and in particular the effective support of the Fourier transform has size roughly inverse to the effective support of the PBD itself). Hence, in order to learn an unknown PBD $P$, it suffices to find another PBD, $Q$, with similar mean and standard deviation to $P$, so that the Fourier transform of $Q$ approximates the Fourier transform of $P$ on this small region. (The non-proper algorithm of Diakonikolas et al. (2015a) for PBDs essentially outputs the empirical DFT of $P$ over its effective support.)

Note that the Fourier transform of a PBD is the product of the Fourier transforms of its individual component variables. By Taylor expanding the logarithm of the Fourier transform, we can write the log Fourier transform of a PBD as a Taylor series whose coefficients are related to the moments of the parameters of $P$ (see Equation (11)). We show that for our purposes it suffices to find a PBD $Q$ so that the first $O(\log(1/\epsilon))$ moments of its parameters approximate the corresponding moments for $P$. Unfortunately, we do not actually know the moments for $P$, but since we can easily approximate the Fourier transform of $P$ from samples, we can derive conditions that are sufficient for the moments of $Q$ to satisfy. This step essentially gives us a system of polynomial inequalities in the moments of the parameters of $Q$ that we need to satisfy.

A standard way to solve such a polynomial system is by appealing to Renegar’s algorithm Renegar (1992b,a), which allows us to solve a system of degree-$d$ polynomial inequalities in $k$ real variables in time roughly $d^k$. In our case, the degree $d$ will be at most poly-logarithmic in $1/\epsilon$, but the number of variables $k$ corresponds to the number of parameters of $Q$, which is $k = \text{poly}(1/\epsilon)$. Hence, this approach is insufficient to obtain a faster proper algorithm.

To circumvent this obstacle, we show that it actually suffices to consider only PBDs with $O(\log(1/\epsilon))$ many distinct parameters (Theorem 3). To prove this statement, we use a recent result from algebraic geometry due to Riener (2011) (Theorem 7), that can be used to relate the number of distinct parameters of a solution of a polynomial system to the degree of the polynomials involved. Note that the problem of matching $O(\log(1/\epsilon))$ moments can be expressed as
a system of polynomial equations, where each polynomial has degree $O(\log(1/\epsilon))$. We can thus find a PBD $Q$, which has the same first $O(\log(1/\epsilon))$ moments as $P$, with $O(\log(1/\epsilon))$ distinct parameters such that $d_{TV}(Q, P) \leq \epsilon$. For PBDs with $O(\log(1/\epsilon))$ distinct parameters and known multiplicities for these parameters, we can reduce the runtime of solving the polynomial system to $O(\log(1/\epsilon)O(\log(1/\epsilon)) = (1/\epsilon)O(\log(1/\epsilon))$.

Unfortunately, the above structural result is not strong enough, as in order to set up an appropriate system of polynomial inequalities for the parameters of $Q$, we must first guess the multiplicities to which the distinct parameters appear. A simple counting argument shows that there are roughly $k^{\log(1/\epsilon)}$ ways to choose these multiplicities. To overcome this second obstacle, we need the following refinement of our structural result on distinct parameters: We divide the parameters of $Q$ into categories based on how close they are to 0 or 1. We show that there is a tradeoff between the number of parameters in a given category and the number of distinct parameters in that category (see Theorem 5). With this more refined result in hand, we show that there are only $(1/\epsilon)O(\log(1/\epsilon))$ many possible collections of multiplicities that need to be considered (see Lemma 6).

Given this stronger structural characterization, our proper learning algorithm is fairly simple. We enumerate over the set of possible collections of multiplicities as described above. For each such collection, we set up a system of polynomial equations in the distinct parameters of $Q$, so that solutions to the system will correspond to PBDs whose distinct parameters have the specified multiplicities which are also $\epsilon$-close to $P$. For each system, we attempt to solve it using Renegar’s algorithm. Since there exists at least one PBD $Q$ close to $P$ with such a set of multiplicities, we are guaranteed to find a solution, which in turn must describe a PBD close to $P$.

One technical issue that arises in the above program occurs when $\text{Var}[P] \ll \log(1/\epsilon)$. In this case, the effective support of the Fourier transform of $P$ cannot be restricted to a small subset. This causes problems with the convergence of our Taylor expansion of the log Fourier transform for parameters near $1/2$. However, then only $O(\log(1/\epsilon))$ parameters are not close to 0 and 1, and we can deal with such parameters separately.

1.4. Related Work

Distribution learning is a classical problem in statistics with a rich history and extensive literature (see e.g., Barlow et al. (1972); Devroye and Györfi (1985); Silverman (1986); Scott (1992); Devroye and Lugosi (2001)). During the past couple of decades, a body of work in theoretical computer science has been studying these questions from a computational complexity perspective; see e.g., Kearns et al. (1994); Freund and Mansour (1999); Arora and Kannan (2001); Cryan et al. (2002); Vempala and Wang (2002); Feldman et al. (2005); Belkin and Sinha (2010); Kalai et al. (2010); Daskalakis et al. (2012a,b, 2013); Chan et al. (2013, 2014a,b); Acharya et al. (2015b).

We remark that the majority of the literature has focused either on non-proper learning (density estimation) or on parameter estimation. Regarding proper learning, a number of recent works in the statistics community have given proper learners for structured distribution families, by using a maximum likelihood approach. See e.g., Dumbgen and Rufibach (2009); Gao and Wellner (2009); Walther (2009); Doss and Wellner (2013); Chen and Samworth (2013); Kim and Samworth (2014); Balabdaoui and Doss (2014) for the case of continuous log-concave densities. Alas, the computational complexity of these approaches has not been analyzed. Two recent works Acharya et al. (2015a); Canonne et al. (2015) yield computationally efficient proper learners for discrete log-concave distributions, by using an appropriate convex formulation. Proper learning has also been
recently studied in the context of mixture models Feldman et al. (2005); Daskalakis and Kamath (2014); Suresh et al. (2014); Li and Schmidt (2015). Here, the underlying optimization problems are non-convex, and efficient algorithms are known only when the number of components is small.

1.5. Organization

In Section 2, we prove our main structural result, and in Section 3, we describe our algorithm and prove its correctness. In Section 4, we conclude with some directions for future research. Most of the proofs have been deferred to an Appendix.

2. Main Structural Result

In this section, we prove our main structural result, and in Section 3, we describe our algorithm and prove its correctness. In Section 4, we conclude with some directions for future research. Most of the proofs have been deferred to an Appendix.

Theorem 5  Given any $n$-PBD $P$ with $\text{Var}[P] = \text{poly}(1/\epsilon)$, there is an $n$-PBD $Q$ with $d_{TV}(P, Q) \leq \epsilon$ such that $\mathbb{E}[Q] = \mathbb{E}[P]$ and $\text{Var}[P] - \epsilon^3 \leq \text{Var}[Q] \leq \text{Var}[P]$, satisfying the following properties:

Let $R \overset{\text{def}}{=} \min\{1/4, \sqrt{\ln(1/\epsilon)/\text{Var}[P]}\}$. Let $B_i \overset{\text{def}}{=} R^2i$, for the integers $0 \leq i \leq \ell$, where $\ell = O(\log \log (1/\epsilon))$ is selected such that $B_{\ell} = \text{poly}(\epsilon)$. Consider the partition $\mathcal{I} = \{I_i, J_i\}_{i=0}^{\ell+1}$ of $[0, 1]$ into the following set of intervals: $I_0 = [B_0, 1/2], I_{i+1} = [B_i + 1, B_i], 0 \leq i \leq \ell - 1, I_{\ell+1} = (0, B_\ell);$ and $J_0 = (1/2, 1 - B_0), J_{i+1} = (1 - B_i, 1 - B_{i+1}], 0 \leq i \leq \ell - 1, J_{\ell+1} = (1 - B_\ell, 1]$.

Then we have the following:

(i) For each $0 \leq i \leq \ell$, each of the intervals $I_i$ and $J_i$ contains at most $O(\log(1/\epsilon)/\log(1/B_i))$ distinct parameters of $Q$.

(ii) $Q$ has at most one parameter in each of the intervals $I_{\ell+1}$ and $J_{\ell+1} \setminus \{1\}$.

(iii) The number of parameters of $Q$ equal to 1 is within an additive $\text{poly}(1/\epsilon)$ of $\mathbb{E}[P]$.

(iv) For each $0 \leq i \leq \ell$, each of the intervals $I_i$ and $J_i$ contains at most $2\text{Var}[P]/B_i$ parameters of $Q$.

Theorem 5 implies that one needs to only consider $(1/\epsilon)^{\text{O}(\log \log(1/\epsilon))}$ different combinations of multiplicities:

Lemma 6  For every $P$ as in Theorem 5, there exists an explicit set $\mathcal{M}$ of multisets of triples $(m_i, a_i, b_i)_{1 \leq i \leq k}$ so that

(i) For each element of $\mathcal{M}$ and each $i$, $[a_i, b_i]$ is either one of the intervals $I_i$ or $J_i$ as in Theorem 5 or $[0, 0]$ or $[1, 1]$.

(ii) For each element of $\mathcal{M}$, $k = O(\log(1/\epsilon))$.

(iii) There exist an element of $\mathcal{M}$ and a PBD $Q$ as in the statement of Theorem 5 with $d_{TV}(P, Q) < \epsilon^2$ so that $Q$ has a parameter of multiplicity $m_i$ between $a_i$ and $b_i$ for each $1 \leq i \leq k$ and no other parameters.
(iv) $\mathcal{M}$ has size $(\frac{1}{2})^{O(\log \log (1/\epsilon))}$ and can be enumerated in $\text{poly}(|\mathcal{M}|)$ time.

This is proved in Appendix B.1 by a simple counting argument. We multiply the number of multiplicities for each interval, which is at most the maximum number of parameters to the power of the maximum number of distinct parameters in that interval, giving $(1/\epsilon)^{O(\log \log (1/\epsilon))}$ possibilities.

We now proceed to prove Theorem 5. We will require the following result from algebraic geometry:

**Theorem 7 (Part of Theorem 4.2 from Riener (2011))** Given $m + 1$ symmetric polynomials in $n$ variables $F_j(x), 0 \leq j \leq m, x \in \mathbb{R}^n$, let $K = \{x \in \mathbb{R}^n \mid F_j(x) \geq 0, \text{for all } 1 \leq j \leq m\}$. Let $k = \max\{2, \lceil \deg(F_0)/2 \rceil, \deg(F_1), \deg(F_2), \ldots, \deg(F_m)\}$. Then, the minimum value of $F_0$ on $K$ is achieved by a point with at most $k$ distinct co-ordinates.

As an immediate corollary, we obtain the following:

**Corollary 8** If a set of multivariate polynomial equations $F_i(x) = 0, x \in \mathbb{R}^n, 1 \leq i \leq m$, with the degree of each $F_i(x)$ being at most $d$ has a solution $x \in [a, b]^n$, then it has a solution $y \in [a, b]^n$ with at most $d$ distinct values of the variables in $y$.

The following lemma will be crucial:

**Lemma 9** Let $\epsilon > 0$. Let $P$ and $Q$ be $n$-PBDs with $P$ having parameters $p_1, \ldots, p_k \leq 1/2$ and $p_1', \ldots, p_m' > 1/2$ and $Q$ having parameters $q_1, \ldots, q_k \leq 1/2$ and $q_1', \ldots, q_m' > 1/2$. Suppose furthermore that $\text{Var}[P] = \text{Var}[Q] = V$ and let $C > 0$ be a sufficiently large constant. Suppose furthermore that for $A = \min(3, C \sqrt{\log (1/\epsilon)}/V)$ and for all positive integers $\ell$ it holds

$$A^\ell \left(\left|\sum_{i=1}^{k} p_i^\ell - \sum_{i=1}^{k} q_i^\ell\right| + \left|\sum_{i=1}^{m} (1-p_i')^\ell - \sum_{i=1}^{m} (1-q_i')^\ell\right|\right) < \epsilon / C \log (1/\epsilon).$$

Then $d_{TV}(P, Q) < \epsilon$.

In practice, we shall only need to deal with a finite number of $\ell$’s, since we will be considering the case where all $p_i, q_i$ or $1-p_i', 1-q_i'$ that do not appear in pairs will have size less than $1/(2A)$. Therefore, the size of the sum in question will be sufficiently small automatically for $\ell$ larger than $\Omega(\log((k + m)/\epsilon))$.

The basic idea of the proof will be to show that the Fourier transforms of $P$ and $Q$ are close to each other. In particular, we will need to make use of the following intermediate lemma:

**Lemma 10** Let $P, Q$ be PBDs with $|\mathbb{E}[P] - \mathbb{E}[Q]| = O(\text{Var}[P]^{1/2})$ and $\text{Var}[P] + 1 = \Theta(\text{Var}[Q] + 1)$. Let $M = \Theta(\log (1/\epsilon) + \sqrt{\text{Var}[P] \log (1/\epsilon)})$ and $\ell = \Theta(\log (1/\epsilon))$ be positive integers with the implied constants sufficiently large. If $\sum_{-\ell \leq \xi \leq \ell} |\hat{P}(\xi) - \hat{Q}(\xi)|^2 \leq \epsilon^2/16$, then $d_{TV}(P, Q) \leq \epsilon$.

The proof of Lemma 10, which is given in Appendix B.2, is similar to (part of) the correctness analysis of the non-proper learning algorithm in Diakonikolas et al. (2015a). The proof of Lemma 9 requires Lemma 10 and is given in Appendix B.3. Finally, the proof of Theorem 5 is deferred to Appendix B.4.
3. Proper Learning Algorithm

Given samples from an unknown PBD $P$, and given a collection of intervals and multiplicities as described in Theorem 5, we wish to find a PBD $Q$ with those multiplicities that approximates $P$. By Lemma 9, it is sufficient to find such a $Q$ so that $Q(\xi)$ is close to $P(\xi)$ for all small $\xi$. On the other hand, by Equation (11) the logarithm of the Taylor series of $Q$ is given by an appropriate expansion in the parameters. Note that if $|\xi|$ is small, due to the $(e(\xi/M) - 1)^{\ell}$ term, the terms of our sum with $\ell \gg \log(1/\epsilon)$ will automatically be small. By truncating the Taylor series, we get a polynomial in the parameters that gives us an approximation to $\log(Q(\xi))$. By applying a truncated Taylor series for the exponential function, we obtain a polynomial in the parameters of $Q$ which approximates its Fourier coefficients. This procedure yields a system of polynomial equations whose solution gives the parameters of a PBD that approximates $P$. Our main technique will be to solve this system of equations to obtain our output distribution using the following result:

**Theorem 11 (Renegar (1992b,a))** Let $P_i : \mathbb{R}^n \to \mathbb{R}$, $i = 1, \ldots, m$, be $m$ polynomials over the reals each of degree at most $d$. Let $K = \{x \in \mathbb{R}^n : P_i(x) \geq 0, \text{ for all } i = 1, \ldots, m\}$. If the coefficients of the $P_i$’s are rational numbers with bit complexity at most $L$, there is an algorithm that runs in time $\text{poly}(L, (d \cdot m)^n)$ and decides if $K$ is empty or not. Further, if $K$ is non-empty, the algorithm runs in time $\text{poly}(L, (d \cdot m)^n, \log(1/\delta))$ and outputs a point in $K$ up to an $L_2$ error $\delta$.

In order to set up the necessary system of polynomial equations, we have the following theorem:

**Theorem 12** Consider a PBD $P$ with $\text{Var}[P] < \text{poly}(1/\epsilon)$, and real numbers $\bar{\sigma} \in [\sqrt{\text{Var}[P]}/2, 2\sqrt{\text{Var}[P]} + 1]$ and $\hat{\mu}$ with $|E[P] - \hat{\mu}| \leq \bar{\sigma}$. Let $M$ be as above and let $\ell$ be a sufficiently large multiple of $\log(1/\epsilon)$. Let $h_\xi$ be complex numbers for each integer $\xi$ with $|\xi| \leq \ell$ so that $\sum_{|\xi| \leq \ell} |h_\xi - \hat{P}(\xi)|^2 < \epsilon^2/16$.

Consider another PBD with parameters $q_i$ of multiplicity $m_i$ contained in intervals $[a_i, b_i]$ as described in Theorem 5. There exists an explicit system $P$ of $O(\log(1/\epsilon))$ real polynomial inequalities each of degree $O(\log(1/\epsilon))$ in the $q_i$ so that:

(i) If there exists such a PBD of the form of $Q$ with $d_{TV}(P, Q) < \epsilon/\ell$, $E[Q] = E[P]$, and $\text{Var}[P] \geq \text{Var}[Q] \geq \text{Var}[P]/2$, then its parameters $q_i$ yield a solution to $P$.

(ii) Any solution $\{q_i\}$ to $P$ corresponds to a PBD $Q$ with $d_{TV}(P, Q) < \epsilon/2$.

Furthermore, such a system can be found with rational coefficients of encoding size $O(\log^2(1/\epsilon))$ bits.

**Proof** For technical reasons, we begin by considering the case that $\text{Var}[P]$ is larger than a sufficiently large multiple of $\log(1/\epsilon)$, as we will need to make use of slightly different techniques in the other case. In this case, we construct our system $P$ in the following manner. We begin by putting appropriate constraints on the mean and variance of $Q$ and requiring that the $q_i$’s lie in appropriate intervals.

\[
\bar{\mu} - 2\bar{\sigma} \leq \sum_{j=1}^{k} m_j a_j \leq \bar{\mu} + 2\bar{\sigma}
\]

\[
\bar{\sigma}^2/2 - 1 \leq \sum_{j=1}^{k} m_j p_j (1 - p_j) \leq 2\bar{\sigma}^2
\]

\[
a_j \leq p_j \leq b_j,
\]
Next, we need a low-degree polynomial to express the condition that Fourier coefficients of \( Q \) are approximately correct. To do this, we let \( S \) denote the set of indices \( i \) so that \([a_i, b_i] \subset [0, 1/2] \) and \( T \) the set so that \([a_i, b_i] \subset [1/2, 1] \) and let \( m = \sum_{i \in T} m_i \). We let

\[
g_\xi = 2\pi i \xi m/M + \sum_{k=1}^\ell \frac{(-1)^{k+1}}{k} \left( (e(\xi/M) - 1)^k \sum_{i \in S} m_i q_i^k + (e(-\xi/M) - 1)^k \sum_{i \in T} m_i (1 - q_i)^k \right)
\]

be an approximation to the logarithm of \( \hat{Q}(\xi) \). We next define \( \exp' \) to be a Taylor approximation to the exponential function

\[
\exp'(z) := \sum_{k=0}^\ell \frac{z^k}{k!}.
\]

By Taylor’s theorem, we have that \(| \exp'(z) - \exp(z) | \leq \frac{z^{\ell+1} \exp(z)}{(\ell+1)!} \), and in particular that if \( |z| < \ell/3 \) that \(| \exp'(z) - \exp(z) | = \exp(-\Omega(\ell)) \).

We would ideally like to use \( \exp'(g_\xi) \) as an approximation to \( \hat{Q}(\xi) \). Unfortunately, \( g_\xi \) may have a large imaginary part. To overcome this issue, we let \( o_\xi \), defined as the nearest integer to \( \tilde{\mu}_\xi/M \), be an approximation to the imaginary part, and we set

\[
q_\xi = \exp'(g_\xi + 2\pi io_\xi).
\]

We complete our system \( \mathcal{P} \) with the final inequality:

\[
\sum_{-\ell \leq \xi \leq \ell} |q_\xi - h_\xi|^2 \leq \epsilon^2/8.
\]

In order for our analysis to work, we will need for \( q_\xi \) to approximate \( \hat{Q}(\xi) \). Thus, we make the following claim:

**Claim 13** If Equations (2), (3), (4), (5), and (6) hold, then \( |q_\xi - \hat{Q}(\xi)| < \epsilon^3 \) for all \( |\xi| \leq \ell \).

This is proved in Appendix C by showing that \( g_\xi \) is close to a branch of the logarithm of \( \hat{Q}(\xi) \) and that \(|g_\xi + 2\pi io_\xi| \leq O(\log(1/\epsilon)) \), so \( \exp' \) is a good enough approximation to the exponential.

Hence, our system \( \mathcal{P} \) is defined as follows:

**Variables:**

- \( q_i \) for each distinct parameter \( i \) of \( Q \).
- \( g_\xi \) for each \( |\xi| \leq \ell \).
- \( q_\xi \) for each \( |\xi| \leq \ell \).

**Equations:** Equations (2), (3), (4), (5), (6), and (7).

To prove (i), we note that such a \( Q \) will satisfy (2) and (3), because of the bounds on its mean and variance, and will satisfy Equation (4) by assumption. Therefore, by Claim 13, \( q_\xi \) is approximately \( \hat{Q}(\xi) \) for all \( \xi \). On the other hand, since \( d_{TV}(\mathcal{P}, Q) < \epsilon/\ell \), we have that \( |\hat{P}(\xi) - \hat{Q}(\xi)| < \epsilon/\ell \) for all \( \xi \). Therefore, setting \( g_\xi \) and \( q_\xi \) as specified, Equation (7) follows. To prove (ii), we note that a \( Q \) whose parameters satisfy \( \mathcal{P} \) will by Claim 13 satisfy the hypotheses of Lemma 10. Therefore, \( d_{TV}(\mathcal{P}, Q) \leq \epsilon/2 \).
As we have defined it so far, the system $P$ does not have rational coefficients. Equation (5) makes use of $e(±\xi/M)$ and $\pi$, as does Equation (6). To fix this issue, we note that if we approximate the appropriate powers of $(±1 ± e(±\xi/M))$ and $q\pi i$ each to accuracy $(\epsilon/\sum_{i∈S} m_i)^{10}$, this produces an error of size at most $\epsilon^4$ in the value $g_\xi$, and therefore an error of size at most $\epsilon^3$ for $q_\xi$, and this leaves the above argument unchanged.

Also, as defined above, the system $P$ has complex constants and variables and many of the equations equate complex quantities. The system can be expressed as a set of real inequalities by doubling the number of equations and variables to deal with the real and imaginary parts separately. Doing so introduces binomial coefficients into the coefficients, which are no bigger than $2^{O(\log(1/\epsilon))} = \text{poly}(1/\epsilon)$ in magnitude. To express $\exp'$, we need denominators with a factor of $\ell! = \log(1/\epsilon)^{Θ(\log(1/\epsilon))}$. All other constants can be expressed as rationals with numerator and denominator bounded by $\text{poly}(1/\epsilon)$. So, the encoding size of any of the rationals that appear in the system is $\log(\log(1/\epsilon)) = O\log(1/\epsilon)$.

One slightly more difficult problem is that the proof of Claim 13 depended upon the fact that $\text{Var}[P] \gg \log(1/\epsilon)$. If this is not the case, we will in fact need to slightly modify our system of equations. In particular, we redefine $S$ to be the set of indices, $i$, so that $b_i ≤ 1/4$ (rather than $≤ 1/2$), and let $T$ be the set of indices $i$ so that $a_i ≥ 3/4$. Finally, we let $R$ be the set of indices for which $[a_i, b_i] \subset [1/4, 3/4]$. We note that, since each $i ∈ R$ contributes at least $m_i/8$ to $\sum_i m_i q_i (1−q_i)$, if Equations (4) and (3) both hold, we must have $|R| = O(\text{Var}[P]) = O(\log(1/\epsilon))$.

We then slightly modify Equation (6), replacing it by

$$q_\xi = \exp'(g_\xi) \prod_{i∈R} (q_i e(\xi/M) + (1−q_i))^{m_i}. \quad (8)$$

Note that by our bound on $\sum_{i∈R} m_i$, this is of degree $O(\log(1/\epsilon))$.

We now need only prove the analogue of Claim 13 in order for the rest of our analysis to follow.

**Claim 14** If Equations (2), (3), (4), (5), and (8) hold, then $|q_\xi − ̂Q(\xi)| < \epsilon^3$ for all $|\xi| ≤ \ell$.

We prove this in Appendix C, by proving similar bounds to those needed for Claim 13. This completes the proof of our theorem in the second case.

Our algorithm for properly learning PBDs is given in pseudocode below:
**Algorithm** Proper-Learn-PBD

Input: sample access to a PBD $P$ and $\epsilon > 0$.
Output: A hypothesis PBD that is $\epsilon$-close to $P$ with probability at least $9/10$.

Let $C$ be a sufficiently large universal constant.

1. Draw $O(1)$ samples from $P$ and with confidence probability $19/20$ compute: (a) $\tilde{\sigma}^2$, a factor 2 approximation to $\Var_{X \sim P}[X] + 1$, and (b) $\tilde{\mu}$, an approximation to $\mathbb{E}_{X \sim P}[X]$ to within one standard deviation. Set $M \overset{\text{def}}{=} \lceil C(\log(1/\epsilon) + \tilde{\sigma}\sqrt{\log(1/\epsilon)}) \rceil$. Let $\ell \overset{\text{def}}{=} \lceil C^2 \log(1/\epsilon) \rceil$.

2. If $\tilde{\sigma} > \Omega(1/\epsilon^3)$, then we draw $O(1/\epsilon^2)$ samples and use them to learn a shifted binomial distribution, using algorithms Learn-Poisson and Locate-Binomial from Daskalakis et al. (2015a). Otherwise, we proceed as follows:

3. Draw $N = C^3(1/\epsilon^2) \ln^2(1/\epsilon)$ samples $s_1, \ldots, s_N$ from $P$. For integers $\xi$ with $|\xi| \leq \ell$, set $h_\xi$ to be the empirical DFT modulo $M$. Namely, $h_\xi \overset{\text{def}}{=} \frac{1}{N} \sum_{i=1}^N e(-\xi s_i/M)$.

4. Let $\mathcal{M}$ be the set of multisets of multiplicities described in Lemma 6. For each element $m \in \mathcal{M}$, let $P_m$ be the corresponding system of polynomial equations as described in Theorem 12.

5. For each such system, use the algorithm from Theorem 11 to find a solution to precision $\epsilon/(2k)$, where $k$ is the sum of the multiplicities not corresponding to 0 or 1, if such a solution exists. Once such a solution is found, return the PBD $Q$ with parameters $q_i$ to multiplicity $m_i$, where $m_i$ are the terms from $m$ and $q_i$ in the approximate solution to $P_m$.

The proof of Theorem 1 is given in Appendix C.2.

### 4. Conclusions and Open Problems

In this work, we gave a nearly-sample optimal algorithm for properly learning PBDs that runs in almost polynomial time. We also provided a structural characterization for PBDs that may be of independent interest. The obvious open problem is to obtain a polynomial-time proper learning algorithm. We conjecture that such an algorithm is possible, and our mildly super-polynomial runtime may be viewed as an indication of the plausibility of this conjecture. Currently, we do not know of a poly$(1/\epsilon)$ time algorithm even for the special case of an $n$-PBD with $n = \tilde{O}(\log(1/\epsilon))$.

A related open question concerns obtaining faster proper algorithms for learning more general families of discrete distributions that are amenable to similar techniques, e.g., sums of independent integer-valued random variables Daskalakis et al. (2013); Diakonikolas et al. (2015a), and Poisson multinomial distributions Daskalakis et al. (2015b); Diakonikolas et al. (2015b). Here, we believe that progress is attainable via a generalization of our techniques.

The recently obtained cover size lower bound for PBDs Diakonikolas et al. (2015a) is a bottleneck for other non-convex optimization problems as well, e.g., the problem of computing approximate Nash equilibria in anonymous games Daskalakis and Papadimitriou (2014b). The fastest known algorithms for these problems proceed by enumerating over an $\epsilon$-cover. Can we obtain faster algorithms in such settings, by avoiding enumeration over a cover?
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References


Appendix

Appendix A. Sample Complexity Lower Bound for Parameter Estimation

Proposition 15 Suppose that \( n \geq 1/\epsilon \). Any learning algorithm that takes \( N \) samples from an \( n \)-PBD and returns estimates of these parameters to additive error at most \( \epsilon \) with probability at least \( 2/3 \) must have \( N \geq 2^{\Omega(1/\epsilon)} \).

Proof We may assume that \( n = \Theta(1/\epsilon) \) (as we could always make the remaining parameters all 0) and demonstrate a pair of PBDs whose parameters differ by \( \Omega(\epsilon) \), and yet have variation distance \( 2^{-\Omega(1/\epsilon)} \). Therefore, if such an algorithm is given one of these two PBDs, it will be unable to distinguish which one it is given, and therefore unable to learn the parameters to \( \epsilon \) accuracy with at least \( 2^{\Omega(1/\epsilon)} \) samples.

In order to make this construction work, we take \( P \) to have parameters \( p_j := (1 + \cos \left( \frac{2\pi j}{n} \right)) / 8 \), and let \( Q \) have parameters \( q_j := (1 + \cos \left( \frac{2\pi j + \pi}{n} \right)) / 8 \). Suppose that \( j = n/4 + O(1) \). We claim that none of the \( q_i \) are closer to \( p_j \) that \( \Omega(1/n) \). This is because for all \( i \) we have that \( \frac{2\pi i + \pi}{n} \) is at least \( \Omega(1/n) \) from \( \frac{2\pi j}{n} \) and \( \frac{2\pi (n-j)}{n} \).

On the other hand, it is easy to see that the \( p_j \) are roots of the polynomial \( (T_n(8x-1)-1) \), and \( q_j \) are the roots of \( (T_n(8x-1)+1) \), where \( T_n \) is the \( n^{th} \) Chebyshev polynomial. Since these polynomials have the same leading term and identical coefficients other than their constant terms, it follows that the elementary symmetric polynomials in \( p_j \) of degree less than \( n \) equal the corresponding polynomials in the \( q_j \). From this, by the Newton-Girard formulae, we have that \( \sum_{i=1}^{n} p_i^l = \sum_{i=1}^{n} q_i^l \) for \( 1 \leq l \leq n-1 \). For any \( l \geq n \), we have that \( 3^l (\sum_{i=1}^{n} (p_i^l - q_i^l)) \leq n(3/4)^n \), and so by Lemma 9, we have that \( d_{TV}(P, Q) = 2^{-\Omega(n)} \). This completes our proof. \( \blacksquare \)
Appendix B. Omitted Proofs from Section 2

B.1. Proof of Lemma 6

For completeness, we restate the lemma below.

**Lemma 6.** For every $P$ as in Theorem 5, there exists an explicit set $M$ of multisets of triples $(m_i, a_i, b_i)_{1 \leq i \leq k}$ so that

(i) For each element of $M$ and each $i$, $[a_i, b_i]$ is either one of the intervals $I_i$ or $J_i$ as in Theorem 5 or $[0, 0]$ or $[1, 1]$.

(ii) For each element of $M$, $k = O(\log(1/\epsilon))$.

(iii) There exists an element of $M$ and a PBD $Q$ as in the statement of Theorem 5 with \(d_{TV}(P, Q) < \epsilon^2\) so that $Q$ has a parameter of multiplicity $m_i$ between $a_i$ and $b_i$ for each $1 \leq i \leq k$ and no other parameters.

(iv) $M$ has size $(\frac{1}{2})^{O(\log \log(1/\epsilon))}$ and can be enumerated in $\text{poly}(|M|)$ time.

**Proof** [Proof of Lemma 6 assuming Theorem 5] Replacing $\epsilon$ in Theorem 5 by $\epsilon^2$, we take $M$ to be the set of all possible ways to have at most $O(\log(1/\epsilon)/\log(1/B_i))$ terms with $[a_i, b_i]$ equal to $I_i$ or $J_i$ and having the sum of the corresponding $m_i$’s at most $4\text{Var}[P]/B_i$, having one term with $a_i = b_i = 1$ and $m_i = \mathbb{E}[P] + \text{poly}(1/\epsilon)$, and one term with $a_i = b_i = 0$ and $m_i$ such that the sum of all of the $m_i$’s equals $n$.

For this choice of $M$, (i) is automatically satisfied, and (iii) follows immediately from Theorem 5. To see (ii), we note that the total number of term in an element of $M$ is at most

\[
O(1) + \sum_{i=1}^{\ell} O(\log(1/\epsilon) / \log(1/B_i)) = O(1) + \sum_{i=1}^{\ell} O(\log(1/\epsilon)2^{-i}) = O(\log(1/\epsilon)).
\]

To see (iv), we need a slightly more complicated counting argument. To enumerate $M$, we merely need to enumerate each integer of size $\mathbb{E}[P] + \text{poly}(1/\epsilon)$ for the number of 1’s, and enumerate for each $0 \leq i \leq \ell$ all possible multi-sets of $m_i$ of size at most $O(\log(1/\epsilon)/\log(1/B_i))$ with sum at most $2\text{Var}[P]/B_i$ to correspond to the terms with $[a_i, b_i] = I_i$, and again for the terms with $[a_i, b_i] = J_i$. This is clearly enumerable in $\text{poly}(|M|)$ time, and the total number of possible multi-sets is at most

\[
\text{poly}(1/\epsilon) \prod_{i=0}^{\ell} (2\text{Var}[P]/B_i)^{O(\log(1/\epsilon)/\log(1/B_i))}.
\]
Therefore, we have that

\[
|\mathcal{M}| \leq \text{poly}(1/\epsilon) \prod_{i=0}^{\ell} \left(2\text{Var}[\mathbf{P}] / B_i\right)^{O(\log(1/\epsilon) / \log(1/B_i))}
\]

\[
= \text{poly}(1/\epsilon) \prod_{i=0}^{\ell} B_i^{-O(\log(1/B_i)/\epsilon)} \prod_{i=0}^{\ell} O(\text{Var}[\mathbf{P}])^{O(\log(1/\epsilon) / (2^i \log(1/B_0)))}
\]

\[
= \text{poly}(1/\epsilon) \prod_{i=0}^{\ell} \text{poly}(1/\epsilon) O(\text{Var}[\mathbf{P}])^{O(\log(1/\epsilon) / \log(1/B_0))}
\]

\[
= (1/\epsilon)^{O(\log(1/\epsilon)/\log(1/B_0))} O(\text{Var}[\mathbf{P}])^{O(\log(1/\epsilon)/\log(1/B_0))}
\]

\[
= (1/\epsilon)^{O(\log(1/\epsilon))}.
\]

The last equality above requires some explanation. If \(\text{Var}[\mathbf{P}] < \log^2(1/\epsilon)\), then

\[
O(\text{Var}[\mathbf{P}])^{O(\log(1/\epsilon)/\log(1/B_0))} \leq (1/\epsilon)^{O(\log(1/\epsilon))} = (1/\epsilon)^{O(\log(1/\epsilon))}.
\]

Otherwise, if \(\text{Var}[\mathbf{P}] \geq \log^2(1/\epsilon), \log(1/B_0) \gg \log(\text{Var}[\mathbf{P}])\), and thus

\[
O(\text{Var}[\mathbf{P}])^{O(\log(1/\epsilon)/\log(1/B_0))} \leq \text{poly}(1/\epsilon).
\]

This completes our proof. \(\blacksquare\)

### B.2. Proof of Lemma 10

For completeness, we restate the lemma below.

**Lemma 10.** Let \(\mathbf{P}, \mathbf{Q}\) be PBDs with \(|E[\mathbf{P}] - E[\mathbf{Q}]| = O(\text{Var}[\mathbf{P}]^{1/2})\) and \(\text{Var}[\mathbf{P}] = \Theta(\text{Var}[\mathbf{Q}])\). Let \(M = \Theta(\log(1/\epsilon) + \sqrt{\text{Var}[\mathbf{P}]} \log(1/\epsilon))\) and \(\ell = \Theta(\log(1/\epsilon))\) be positive integers with the implied constants sufficiently large. If \(\sum_{-\ell \leq \xi \leq \ell} |\hat{\mathbf{P}}(\xi) - \hat{\mathbf{Q}}(\xi)|^2 \leq \epsilon^2 / 16\), then \(d_{TV}(\mathbf{P}, \mathbf{Q}) \leq \epsilon\).

**Proof** The proof of this lemma is similar to the analysis of correctness of the non-proper learning algorithm in Diakonikolas et al. (2015a).

The basic idea of the proof is as follows. By Bernstein’s inequality, \(\mathbf{P}\) and \(\mathbf{Q}\) both have nearly all of their probability mass supported in the same interval of length \(M\). This means that it suffices to show that the distributions \(\mathbf{P} \pmod{M}\) and \(\mathbf{Q} \pmod{M}\) are close. By Plancherel’s Theorem, it suffices to show that the DFTs \(\hat{\mathbf{P}}\) and \(\hat{\mathbf{Q}}\) are close. However, it follows by Lemma 6 of Diakonikolas et al. (2015a) that these DFTs are small in magnitude outside of \(-\ell \leq \xi \leq \ell\).

Let \(m\) be the nearest integer to the expected value of \(\mathbf{P}\). By Bernstein’s inequality, it follows that both \(\mathbf{P}\) and \(\mathbf{Q}\) have \(1 - \epsilon/10\) of their probability mass in the interval \(I = [m - M/2, m + M/2]\). We note that any given probability distribution \(X\) over \(\mathbb{Z}/M\mathbb{Z}\) has a unique lift to a distribution taking values in \(I\). We claim that \(d_{TV}(\mathbf{P}, \mathbf{Q}) \leq \epsilon/5 + d_{TV}(\mathbf{P} \pmod{M}, \mathbf{Q} \pmod{M})\). This is because after throwing away the at most \(\epsilon/5\) probability mass where \(\mathbf{P}\) or \(\mathbf{Q}\) take values outside of \(I\), there is a one-to-one mapping between values in \(I\) taken by \(\mathbf{P}\) or \(\mathbf{Q}\) and the values taken by \(\mathbf{P} \pmod{M}\) or \(\mathbf{Q} \pmod{M}\). Thus, it suffices to show that \(d_{TV}(\mathbf{P} \pmod{M}, \mathbf{Q} \pmod{M}) \leq 4\epsilon/5\).
By Cauchy-Schwarz, we have that
\[ d_{TV}(\mathbf{P} \pmod{M}, \mathbf{Q} \pmod{M}) \leq \sqrt{M} \| \mathbf{P} \pmod{M} - \mathbf{Q} \pmod{M} \|_2. \]

By Plancherel’s Theorem, the RHS above is
\[ \sqrt{\sum_{\xi \pmod{M}} |\hat{\mathbf{P}}(\xi) - \hat{\mathbf{Q}}(\xi)|^2}. \] (9)

By assumption, the sum of the above over all $|\xi| \leq \ell$ is at most $\epsilon^2/16$. However, applying Lemma 6 of Diakonikolas et al. (2015a) with $k = 2$, we find that for any $|\xi| \leq M/2$ that each of $|\hat{\mathbf{P}}(\xi)|$, $|\hat{\mathbf{Q}}(\xi)|$ is $\exp(-\Omega(\xi^2/\text{Var}[\mathbf{P}]/M^2)) = \exp(-\Omega(\xi^2/\log(1/\epsilon)))$. Therefore, the sum above over $\xi$ not within $\ell$ of some multiple of $M$ is at most
\[ \sum_{n>\ell} \exp(-\Omega(n^2/\log(1/\epsilon))) \]
\[ \leq \sum_{n>\ell} \exp(-((\ell^2 + (n-\ell))\ell)/\log(1/\epsilon))) \]
\[ \leq \sum_{n>\ell} \exp(-(n-\ell)) \exp(-\Omega(\ell^2/\log(1/\epsilon))) \leq \epsilon^2/16 \]
assuming that the constant defining $\ell$ is large enough. Therefore, the sum in (9) is at most $\epsilon^2/8$. This completes the proof. \[ \blacksquare \]

B.3. Proof of Lemma 9

For completeness, we restate the lemma below.

**Lemma 9.** Let $\epsilon > 0$. Let $\mathbf{P}$ and $\mathbf{Q}$ be $n$-PBDs with $\mathbf{P}$ having parameters $p_1, \ldots, p_k \leq 1/2$ and $p'_1, \ldots, p'_m > 1/2$ and $\mathbf{Q}$ having parameters $q_1, \ldots, q_k \leq 1/2$ and $q'_1, \ldots, q'_m > 1/2$. Suppose furthermore that $\text{Var}[\mathbf{P}] = \text{Var}[\mathbf{Q}] = V$ and let $C > 0$ be a sufficiently large constant. Suppose furthermore that for $A = \min(3, C\sqrt{\log(1/\epsilon)/V})$ and for all positive integers $\ell$ it holds
\[ A^\ell \left( \sum_{i=1}^k p_i^\ell - \sum_{i=1}^k q_i^\ell \right) + \sum_{i=1}^m (1 - p'_i)^\ell - \sum_{i=1}^m (1 - q'_i)^\ell \leq \epsilon/C \log(1/\epsilon). \] (10)

Then $d_{TV}(\mathbf{P}, \mathbf{Q}) < \epsilon$.

**Proof** We proceed by means of Lemma 10. We need only show that for all $\xi$ with $|\xi| = O(\log(1/\epsilon))$ that $|\hat{\mathbf{P}}(\xi) - \hat{\mathbf{Q}}(\xi)| \ll \epsilon/\sqrt{\log(1/\epsilon)}$. For this we note that
\[ \hat{\mathbf{P}}(\xi) = \prod_{i=1}^k ((1 - p_i) + p_i e(\xi/M)) \prod_{i=1}^m ((1 - p'_i) + p'_i e(\xi/M)) \]
\[ = e(m\xi/M) \left( \prod_{i=1}^k (1 + p_i(e(\xi/M) - 1)) \prod_{i=1}^m (1 + (1 - p'_i)(e(-\xi/M) - 1)) \right). \]
Taking a logarithm and Taylor expanding, we find that
\[
\log(\hat{P}(\xi)) = 2\pi im\xi/M + \sum_{\ell=1}^{\infty} \frac{(-1)^{1+\ell}}{\ell} \left( e(\xi/M) - 1 \right)^{\ell} \sum_{i=1}^{k} p_i^\ell + (e(-\xi/M) - 1)^{\ell} \sum_{i=1}^{m} (1 - q_i^\ell) \right).
\]

(11)

A similar formula holds for \(\log(\hat{Q}(\xi))\). Therefore, we have that
\[
|\hat{P}(\xi) - \hat{Q}(\xi)| \leq |\log(\hat{P}(\xi)) - \log(\hat{Q}(\xi))|,
\]

which is at most
\[
\sum_{\ell=1}^{\infty} |e(\xi/M) - 1|^\ell \left( \left| \sum_{i=1}^{k} p_i^\ell - \sum_{i=1}^{k} q_i^\ell \right| + \left| \sum_{i=1}^{m} (1 - p_i^\ell) - \sum_{i=1}^{m} (1 - q_i^\ell) \right| \right)
\]
\[
\leq \sum_{\ell=1}^{\infty} (2A/3)^\ell \left( \left| \sum_{i=1}^{k} p_i^\ell - \sum_{i=1}^{k} q_i^\ell \right| + \left| \sum_{i=1}^{m} (1 - p_i^\ell) - \sum_{i=1}^{m} (1 - q_i^\ell) \right| \right)
\]
\[
\leq \sum_{\ell=1}^{\infty} (2/3)^\ell \epsilon/C \log(1/\epsilon)
\]
\[
\ll \epsilon/C \log(1/\epsilon).
\]

An application of Lemma 10 completes the proof.

B.4. Proof of Theorem 5

The basic idea of the proof is as follows. First, we will show that it is possible to modify \(P\) in order to satisfy (ii) without changing its mean, increasing its variance (or decreasing it by too much), or changing it substantially in total variation distance. Next, for each of the other intervals \(I_i\) or \(J_i\), we will show that it is possible to modify the parameters that \(P\) has in this interval to have the appropriate number of distinct parameters, without substantially changing the distribution in variation distance. Once this holds for each \(i\), conditions (iii) and (iv) will follow automatically.

To begin with, we modify \(P\) to have at most one parameter in \(I_{\ell+1}\) in the following way. We repeat the following procedure. So long as \(P\) has two parameters, \(p\) and \(p'\) in \(I_{\ell+1}\), we replace those parameters by 0 and \(p + p'\). We note that this operation has the following properties:

- The expectation of \(P\) remains unchanged.
- The total variation distance between the old and new distributions is \(O(pp')\), as is the change in variances between the distributions.
- The variance of \(P\) is decreased.
- The number of parameters in \(I_{\ell+1}\) is decreased by 1.

All of these properties are straightforward to verify by considering the effect of just the sum of the two changed variables. By repeating this procedure, we eventually obtain a new PBD, \(P'\) with the same mean as \(P\), smaller variance, and at most one parameter in \(I_{\ell+1}\). We also claim that
$d_{TV}(P, P')$ is small. To show this, we note that in each replacement, the error in variation distance is at most a constant times the increase in the sum of the squares of the parameters of the relevant PBD. Therefore, letting $p_i$ be the parameters of $P$ and letting $p_i'$ be the parameters of $P'$, we have that $d_{TV}(P, P') = O(\sum (p_i')^2 - p_i^2)$. We note that this difference is entirely due to the parameters that were modified by this procedure. Therefore, it is at most $(2B_\ell)^2$ times the number of non-zero parameters created. Note that all but one of these parameters contributes at least $B_\ell/2$ to the variance of $P'$. Therefore, this number is at most $2\text{Var}[P]/B_\ell + 1$. Hence, the total variation distance between $P$ and $P'$ is at most $O((B_\ell)^2)(\text{Var}[P]/B_\ell + 1) \leq \epsilon^3$. Similarly, the variance of our distribution is decreased by at most this much. This implies that it suffices to consider $P$ that have at most one parameter in $I_{\ell+1}$. Symmetrically, we can also remove all but one of the parameters in $J_{\ell+1}$, and thus it suffices to consider $P$ that satisfy condition (ii).

Next, we show that for any such $P$ that it is possible to modify the parameters that $P$ has in $I_i$ or $J_i$, for any $i$, so that we leave the expectation and variance unchanged, introduce at most $\epsilon^2$ error in variation distance, and leave only $O(\log(1/\epsilon) / \log(1/B_i))$ distinct parameters in this range. The basic idea of this is as follows. By Lemma 9, it suffices to keep $\sum p_i^\ell$ or $\sum (1 - p_i)^\ell$ constant for parameters $p_i$ in that range for some range of values of $\ell$. On the other hand, Theorem 7 implies that this can be done while producing only a small number of distinct parameters.

Without loss of generality assume that we are dealing with the interval $I_i$. Note that if $i = 0$ and $\text{Var}[P] < \log(1/\epsilon)$, then $B_0 = 1/4$, and there can be at most $O(\log(1/\epsilon))$ parameters in $I_0$ to begin with. Hence, in this case there is nothing to show. Thus, assume that either $i \geq 0$ or that $\text{Var}[P] \approx \log(1/\epsilon)$ with a sufficiently large constant. Let $p_1, \ldots, p_m$ be the parameters of $P$ that lie in $I_i$. Consider replacing them with parameters $q_1, \ldots, q_m$ also in $I_i$ to obtain $Q$. By Lemma 9, we have that $d_{TV}(P, Q) < \epsilon^2$ so long as the first two moments of $P$ and $Q$ agree and

$$\min(3, C\sqrt{\log(1/\epsilon)/\text{Var}[P]})^\ell \left| \sum_{j=1}^m p_j^\ell - \sum_{j=1}^m q_j^\ell \right| < \epsilon^3,$$

for all $\ell$ (the terms in the sum in Equation (10) coming from the parameters not being changed cancel out). Note that $\min(3, C\sqrt{\log(1/\epsilon)/\text{Var}[P]}) \max(p_j, q_j) \leq B_i^{O(1)}$. This is because by assumption either $i > 0$ and $\max(p_j, q_j) \leq \sqrt{B_i} \leq 1/4$ or $i = 0$ and $B_i = \sqrt{\log(1/\epsilon)/\text{Var}[P]} \ll 1$. Furthermore, note that $\text{Var}[P] \geq mB_{\ell+1}$. Therefore, $m \leq \text{poly}(1/\epsilon)$. Combining the above, we find that Equation (12) is automatically satisfied for any $q_j \in I_i$ so long as $\ell$ is larger than a sufficiently large multiple of $\log(1/\epsilon)/\log(1/B_i)$. On the other hand, Theorem 7 implies that there is some choice of $q_j \in I_i$ taking on only $O(\log(1/\epsilon)/\log(1/B_i))$ distinct values, so that $\sum_{j=1}^m q_j^\ell$ is exactly $\sum_{j=1}^m p_j^\ell$ for all $\ell$ in this range. Thus, replacing the $p_j$’s in this range by these $q_j$’s, we only change the total variation distance by $\epsilon^2$, leave the expectation and variance the same (as we have fixed the first two moments), and have changed our distribution in variation distance by at most $\epsilon^2$.

Repeating the above procedure for each interval $I_i$ or $J_i$ in turn, we replace $P$ by a new PBD, $Q$ with the same expectation and smaller variance and $d_{TV}(P, Q) < \epsilon$, so that $Q$ satisfies conditions (i) and (ii). We claim that (iii) and (iv) are necessarily satisfied. Condition (iii) follows from noting that the number of parameters not 0 or 1 is at most $2 + 2\text{Var}[P]/B_\ell$, which is $\text{poly}(1/\epsilon)$. Therefore, the expectation of $Q$ is the number of parameters equal to 1 + $\text{poly}(1/\epsilon)$. Condition (iv) follows upon noting that $\text{Var}[Q] \leq \text{Var}[P]$ is at least the number of parameters in $I_i$ or $J_i$ times $B_i/2$ (as each contributes at least $B_i/2$ to the variance). This completes the proof of Theorem 5.
Appendix C. Omitted Proofs from Section 3

C.1. Proofs of Claims 13 and 14

In this section, we prove Claims 13 and 14 which we restate here.

Claim 13. If Equations (2), (3), (4), (5), and (6) hold, then \(|q_\xi - \hat{Q}(\xi)| < \varepsilon^3\) for all \(|\xi| \leq \ell\).

Proof First we begin by showing that \(g_\xi\) approximates \(\log(\hat{Q}(\xi))\). By Equation (11), we would have equality if the sum over \(k\) were extended to all positive integers. Therefore, the error between \(g_\xi\) and \(\log(\hat{Q}(\xi))\) is equal to the sum over all \(k > \ell\). Since \(\hat{\sigma} \gg \log(1/\varepsilon)\), we have that \(M \gg \ell\) and therefore, \(|1 - e(\xi/m)|\) and \(|e(-\xi/M) - 1|\) are both less than \(1/2\). Therefore, the term for a particular value of \(k\) is at most \(2^{-k} \left( \sum_{i \in S} m_i q_i + \sum_{i \in T} m_i(1 - q_i) \right) \gg 2^{-k} \hat{\sigma}\). Summing over \(k > \ell\), we find that
\[
|g_\xi - \log(\hat{Q}(\xi))| < \varepsilon^4.
\]

We have left to prove that \(\exp(g_\xi - 2\pi i o_\xi)\) is approximately \(\exp(g_\xi) = \exp(g_\xi - 2\pi i o_\xi)\). By the above, it suffices to prove that \(|g_\xi - 2\pi i o_\xi| < \ell/3\). We note that
\[
g_\xi = 2\pi i \xi m/M + \sum_{k=1}^{\ell} \frac{(-1)^{k+1}}{k} \left( e(\xi/M) - 1 \right)^k \sum_{i \in S} m_i q_i^k + \left( e(-\xi/M) - 1 \right)^k \sum_{i \in T} m_i(1 - q_i)^k \\
= 2\pi i \xi m/M + (e(\xi/M) - 1) \sum_{i \in S} m_i q_i + (e(-\xi/M) - 1) \sum_{i \in T} m_i(1 - q_i) + \\
+ O \left( \sum_{k=2}^{\ell} \frac{\xi^2}{M^2} 2^{-k} \left( \sum_i m_i q_i(1 - q_i) \right) \right)
\]
\[
= 2\pi i \xi m/M + 2\pi i \xi/M \left( \sum_{i \in S} m_i q_i - \sum_{i \in T} m_i(1 - q_i) \right) + O(\|\xi^2/M^2 \hat{\sigma}^2)
\]
\[
= 2\pi i \xi M \sum_i m_i q_i + O(\|\xi^2/M^2 \hat{\sigma}^2)
\]
\[
= 2\pi i o_\xi + O(\log(1/\varepsilon)).
\]
This completes the proof.

Claim 14. If Equations (2), (3), (4), (5), and (8) hold, then \(|q_\xi - \hat{Q}(\xi)| < \varepsilon^3\) for all \(|\xi| \leq \ell\).

Proof Let \(Q'\) be the PBD obtained from \(Q\) upon removing all parameters corresponding to elements of \(R\). We note that
\[
\hat{Q}(\xi) = \hat{Q}'(\xi) \prod_{i \in R} (q_i e(\xi/M) + (1 - q_i))^{m_i}.
\]
Therefore, it suffices to prove our claim when \(R = \emptyset\).

Once again it suffices to show that \(g_\xi\) is within \(\varepsilon^4\) of \(\log(\hat{Q}(\xi))\) and that \(|g_\xi| < \ell/3\). For the former claim, we again note that, by Equation (11), we would have equality if the sum over \(k\) were extended to all integers, and therefore only need to bound the sum over all \(k > \ell\). On the other
hand, we note that \( q_i \leq 1/4 \) for \( i \in S \) and \( (1 - q_i) \leq 1/4 \) for \( i \in T \). Therefore, the \( k^{th} \) term in the sum would have absolute value at most

\[
O \left( 2^{-k} \left( \sum_{i \in S} m_i q_i + \sum_{i \in T} m_i (1 - q_i) \right) \right) = O(2^{-k} \sigma_i).
\]

Summing over \( k > \ell \), proves the appropriate bound on the error. Furthermore, summing this bound over \( 1 \leq k \leq \ell \) proves that \(| g_\xi | < \ell/3 \), as required. Combining these results with the bounds on the Taylor error for \( \exp' \) completes the proof.

\[\square\]

C.2. Proof of Theorem 1

We first note that the algorithm succeeds in the case that \( \text{Var}_{X \sim \mathbf{P}}[X] = \Omega(1/\epsilon^6) \): Daskalakis et al. (2015a) describes procedures Learn-Poisson and Locate-Binomial that draw \( O(1/\epsilon^2) \) samples, and return a shifted binomial \( \epsilon \)-close to a PBD \( \mathbf{P} \), provided \( \mathbf{P} \) is not close to a PBD in “sparse form” in their terminology. This holds for any PBD with effective support \( \Omega(1/\epsilon^3) \), since by definition a PBD in “sparse form” has support of size \( O(1/\epsilon^3) \).

It is clear that the sample complexity of our algorithm is \( O(\epsilon^{-2} \log^2(1/\epsilon)) \). The runtime of the algorithm is dominated by Step 5. We note that by Lemma 6, \( |\mathcal{M}| = (1/\epsilon) O(\log \log(1/\epsilon)) \). Furthermore, by Theorems 11 and 12, the runtime for solving the system \( \mathcal{P}_m \) is \( O(\log(1/\epsilon)) O(\log(1/\epsilon)) = (1/\epsilon) O(\log \log(1/\epsilon)) \). Therefore, the total runtime is \( (1/\epsilon) O(\log \log(1/\epsilon)) \).

It remains to show correctness. We first note that each \( h_\xi \) is an average of independent random variables \( e(-\xi p_i / M) \), with expectation \( \hat{\mathbf{P}}(\xi) \). Therefore, by standard Chernoff bounds, with high probability we have that \(| h_\xi - \hat{\mathbf{P}}(\xi) | = O(\sqrt{\log(\ell)}/\sqrt{N}) \ll \epsilon/\sqrt{\ell} \) for all \( \xi \), and therefore we have that

\[
\sum_{|\xi| \leq \ell} | h_\xi - \hat{\mathbf{P}}(\xi) |^2 < \epsilon^2/8.
\]

Now, by Lemma 6, for some \( m \in \mathcal{M} \) there will exist a PBD \( \mathbf{Q} \) whose distinct parameters come in multiplicities given by \( m \) and lie in the corresponding intervals so that \( d_{TV}(\mathbf{P}, \mathbf{Q}) \leq \epsilon^2 \). Therefore, by Theorem 12, the system \( \mathcal{P}_m \) will have a solution. Therefore, at least one \( \mathcal{P}_m \) will have a solution and our algorithm will necessarily return some PBD \( \mathbf{Q} \).

On the other hand, any \( \mathbf{Q} \) returned by our algorithm will correspond to an approximation of some solution of \( \mathcal{P}_m \), for some \( m \in \mathcal{M} \). By Theorem 12, any solution to any \( \mathcal{P}_m \) will give a PBD \( \mathbf{Q} \) with \( d_{TV}(\mathbf{P}, \mathbf{Q}) \leq \epsilon/2 \). Therefore, the actual output of our algorithm is a PBD \( \mathbf{Q}' \), whose parameters approximate those of such a \( \mathbf{Q} \) to within \( \epsilon/(2k) \). On the other hand, from this it is clear that \( d_{TV}(\mathbf{Q}, \mathbf{Q}') \leq \epsilon/2 \), and therefore, \( d_{TV}(\mathbf{P}, \mathbf{Q}') \leq \epsilon \). In conclusion, our algorithm will always return a PBD that is within \( \epsilon \) total variation distance of \( \mathbf{P} \).

Appendix D. Agnostic Proper Learning of PBDs and Optimization for Real-Rooted Polynomials

D.1. Agnostic Proper Learning

In this section, we establish the following:
Theorem 16  Given $\epsilon > 0$ and sample access to a distribution $Q$ over $[n]$ there is an algorithm that draws $\tilde{O}(1/e^2)$ samples from $Q$, runs in time $(1/e)^{O(\log \log(1/\epsilon))}$, and outputs an explicit PBD $P$ such that $d_{TV}(P, Q) \leq O(\text{opt} \cdot \log^2(1/\text{opt})) + \epsilon$, where $\text{opt}$ is the minimum total variation distance between $Q$ and the set of PBDs.

The algorithm in the above theorem does not a priori know the value of $\text{opt}$. By a standard doubling trick followed by a hypothesis selection procedure (see, e.g., Theorem 6 in Chan et al. (2014b)), the agnostic learning problem can be reduced to the case that $\text{opt} = O(\epsilon)$. The latter case is handled in the following proposition:

Proposition 17  Given $\epsilon > 0$ and sample access to a distribution $Q$ over $[n]$ there is an algorithm that draws $\tilde{O}(1/e^2)$ samples from $Q$, runs in time $(1/e)^{O(\log \log(1/\epsilon))}$, and has the following performance guarantee: If there exists a PBD $P$ such that $d_{TV}(P, Q) \leq \epsilon$, the algorithm outputs an explicit PBD $P'$ such that $d_{TV}(P', P) \leq O(\epsilon \log^2(1/\epsilon))$.

The algorithm is a small modification of our algorithm $\text{Proper-Learn-PBD}$. The main difference is that we start by obtaining robust estimates of the mean and variance of $P$. The modified algorithm is given in pseudocode below.

**Algorithm** Agnostic-proper-Learn-PBD  
Input: sample access to a distribution $Q$ and $\epsilon > 0$ such that there is a PBD $P$ with $d_{TV}(P, Q) \leq \epsilon$. 
Output: A hypothesis PBD that is $O(\epsilon \log^2(1/\epsilon))$-close to $P$ with probability at least $9/10$.

1. Draw $O(1/e^2)$ samples from $Q$ and find the greatest $a \in [n]$ and least $b \in [n]$ such that at most a $2\epsilon$ fraction of the samples are less than $a$ and at most a $2\epsilon$ fraction of the samples are greater than $b$.
2. Draw $O(1/e^2)$ samples from $Q$ that lie in $[a, b]$ (discarding samples not in $[a, b]$) and compute the sample mean $\tilde{\mu}$, and $\tilde{\sigma}^2$, defined as $1/2$ plus the sample variance.
3. If $\tilde{\sigma} \geq \Omega(1/e^3)$, return a shifted binomial distribution using $\text{Locate Binomial}(\tilde{\mu}, \tilde{\sigma}^2, n)$ from Daskalakis et al. (2015a).
   
   <!-- Code to compute locate binomial -->

4. Draw $N = C^3(1/e^2) \log^2(1/\epsilon')$ samples $s_1, \ldots, s_N$ from $P$. For integers $\xi$ with $|\xi| \leq \ell$, set $h_\xi$ to be the empirical DFT modulo $M$. Namely, $h_\xi := \frac{1}{N} \sum_{i=1}^N e^{-\xi s_i/M}$.
5. Let $M$ be the set of multisets of multiplicities described in Lemma 6 (with $\epsilon$ set to $\epsilon'$). For each element $m \in M$, let $P_m$ be the corresponding system of polynomial equations as described in Theorem 12.
6. For each such system, use the algorithm from Theorem 11 to find a solution to precision $\epsilon'/(2k)$, where $k$ is the sum of the multiplicities not corresponding to 0 or 1, if such a solution exists. Once such a solution is found, return the PBD $P'$ with parameters $q_i$ to multiplicity $m_i$, where $m_i$ are the terms from $m$ and $q_i$ in the approximate solution to $P_m$. 

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First we show that our estimates of the mean and variance suffice.

**Lemma 18** With high constant probability over the samples, we have that $|\mu - \bar{\mu}| \leq O((1 + \sigma)e \log(1/\epsilon))$ and $\sigma^2 - 1/2 - \sigma^2 \leq O((1 + \sigma)^2 e \log^2(1/\epsilon))$. Thus, we have that $|\mu - \bar{\mu}| \leq \tilde{\sigma}$ and $\sigma^2 + 1 \in [(\sigma^2 + 1)/2, 2(\sigma^2 + 1)]$.

**Proof** First, we note that with high constant probability over our choice of samples in Step 1 it holds $Pr(P < a), Pr(P > b) = \Theta(\epsilon)$. Using standard bounds on the tails of PBDs, we note that this implies that $|a - \mu|, |b - \mu| = O(\log(1/\epsilon)(1 + \sigma))$. We condition on this event throughout the rest of the proof.

Informally, standard PBD tail bounds will imply that the contribution to the mean and standard deviation of $P$ coming from points outside of $[a, b]$ will be small. Furthermore, the contribution to these coming from the discrepancy between $P$ and $Q$ will also be small because we have restricted ourselves to a small interval.

Note that the first conditions, that $|\mu - \bar{\mu}| \leq O((1+\sigma)e \log(1/\epsilon))$ and $|\sigma^2 - 1/2 - \sigma^2| \leq O((1+\sigma)^2 e \log^2(1/\epsilon))$, imply the second conditions that $|\mu - \bar{\mu}| \leq \tilde{\sigma}$ and $\sigma^2 + 1 \in [(\sigma^2 + 1)/2, 2(\sigma^2 + 1)]$.

Let $P_1$ be $P$ conditioned on lying in the interval $[a, b]$ and $Q_1$ be $Q$ conditioned on $Q$ lying in $[a, b]$. Notice that

$$|\mu - E_{X \sim P_1}[X]| = O((1 + \sigma)e \log(1/\epsilon)),$$

and

$$|\sigma^2 - E_{X \sim P_1}[(X - \mu)^2]| = O((1 + \sigma)^2 e \log^2(1/\epsilon)).$$

This is because $P$ has at most $O(\epsilon)$ mass outside of the interval $[a, b]$, and because standard bounds on the tails of PBDs imply that $Pr_{X \sim P}(|X - \mu| > t(1 + \sigma)) \ll \exp(-t)$.

We also have that

$$|E_{Y \sim Q_1}[Y] - E_{X \sim P_1}[X]| = O((1 + \sigma)e \log(1/\epsilon)),$$

and

$$|E_{Y \sim Q_1}[(Y - \mu)^2] - E_{X \sim P_1}[(X - \mu)^2]| = O((1 + \sigma)^2 e \log^2(1/\epsilon)).$$

This is because $d_{TV}(P_1, Q_1) = O(\epsilon)$ and because both are bounded in the range $[a, b]$.

Therefore, we have that

$$E_{Y \sim Q_1}[Y] = \mu + O((1 + \sigma)e \log(1/\epsilon)), E_{Y \sim Q_1}[(Y - \mu)^2] = \sigma^2 + O((1 + \sigma)^2 e \log^2(1/\epsilon)).$$

It remains to prove that the sample means of $Q_1$ and $(Y - \mu)^2$ agree with their expectations to within an appropriate error. However, this follows with 90% probability based on Chebyshev bounds after noting that $Q_1$ and $(Y - \mu)^2$ have standard deviations of at most $b - a = O((1 + \sigma) \log(1/\epsilon))$ and $(b - a)^2 = O((1 + \sigma)^2 \log^2(1/\epsilon))$, respectively. This completes the proof.

**Proof [Proof of Proposition 17]** Note that we take $N = C^3(1/\epsilon^2) \log^2(1/\epsilon') = O((1/\epsilon^2) \log^4(1/\epsilon))$ samples in Step 4 of Proper-Learn-PBD. This dominates the sample complexity. The running time of the overall algorithm is easily seen to be $O((1/\epsilon')^O(\log \log 1/\epsilon')) = (1/\epsilon')^O(\log \log 1/\epsilon')$.

Most of the proof of this Proposition is identical to that of Theorem 1. To show correctness, it is enough to show that $\tilde{\mu}, \tilde{\sigma}$ and $h_\xi$ satisfy the same guarantees as those required in the proof of Theorem 1, as these are the only quantities we calculate from the samples and use in Steps 4 and 5.
of Proper-Learn-PBD. Lemma 18 gives that $\tilde{\mu}$ and $\tilde{\sigma}$ satisfy the same bounds as the estimates obtained in Step 1 of Proper-Learn-PBD.

Note that the expected value of each $h_\xi$ is $\hat{Q}(\xi)$. Because each Fourier coefficient is an expectation of a function whose absolute value is at most 1, we have $|\hat{P} - \hat{Q}| \leq 2d TV(P, Q) \leq 2\epsilon$. By Chernoff bounds, with high probability for all $\xi$, we have that $|h_\xi - \hat{Q}(\xi)| = O(\sqrt{\log(\xi)/\sqrt{N}}) \ll \epsilon'/\sqrt{\ell}$, and therefore $|h_\xi - \hat{P}(\xi)| = O(\epsilon'/\sqrt{\ell}) + 2\epsilon = O(\epsilon'/\sqrt{\ell})$. Thus, we have

$$\sum_{|\xi| \leq \ell} |h_\xi - \hat{P}(\xi)|^2 < \epsilon^2/8.$$ 

In the case when $\hat{\sigma} \geq \Omega(1/\epsilon^3)$, Lemma 18 gives that $|\hat{\sigma}^2 - \sigma^2| \leq O(\epsilon \log^2(1/\epsilon)\sigma^2)$ and $|\mu - \tilde{\mu}| \leq O(\epsilon \log^2(1/\epsilon)\sigma^2)$. These conditions and $\sigma^2 = \Omega(1/\epsilon^3) \geq C''(1/\epsilon^2 \log^4(1/\epsilon)^2)$ for some sufficiently large universal constant $C''$ are enough to show that the output of Locate-Binomial is within $O(\epsilon \log^2(1/\epsilon))$ of $P$ as required. This follows from the analysis in Daskalakis et al. (2015a). In particular, Claim 7 of that paper shows that under these conditions there is a translated Poisson distribution $TP(\hat{\mu}, \hat{\sigma}^2)$ with $d TV(P, TP(\hat{\mu}, \hat{\sigma}^2)) \leq O(\epsilon \log^2(1/\epsilon))$. Then, the analysis of Locate-Binomial (pages 17-20) shows that the output shifted binomial is similarly close to the translated Poisson distribution.

The above suffices to show that when there is a PBD $P$ with $d TV(P, Q) \leq \epsilon$, the algorithm satisfies the stated performance guarantee. Note that when $Q$ is an arbitrary distribution, we still obtain the same time and sample complexity. This completes the proof.

D.2. Projection onto Polynomials with Non-Positive Real Roots

In this section, we point out that (using our non-proper learning algorithm) proper learning of PBDs can be reduced to an interesting non-convex optimization problem over real-rooted univariate polynomials. In particular, we abstract out our proper learning algorithm to obtain an algorithm with similar running time for this polynomial optimization problem.

We start with the following simple fact:

**Lemma 19** For a distribution $P$ on $[n]$, the probability generating function $p(x) \overset{\text{def}}{=} \mathbb{E}_{X \sim P}[x^X]$ is a polynomial with non-positive roots if and only if $P$ is a PBD.

**Proof** If $P$ is a PBD whose distinct parameters are $p_i$ with multiplicities $m_i$, then

$$p(x) = \prod_i ((1 - p_i) + p_i x)^{m_i}.$$ 

Note that this polynomial has roots $\alpha_i = -(1 - p_i)/p_i$ with multiplicities $m_i$.

Conversely, if $p(x)$ is a polynomial with nonnegative coefficients such that $p(1) = 1$, and with only nonpositive real roots $\alpha_i$ with multiplicities $m_i$, then

$$p(x) = \frac{\prod_i (x - \alpha_i)^{m_i}}{\prod_i (1 - \alpha_i)^{m_i}} = \prod_i (x/(1 - \alpha_i) - \alpha_i/(1 - \alpha_i))^{m_i}.$$ 

Note that this is exactly the probability generating function of a PBD $P$ whose distinct parameters are $p_i = 1/(1 - \alpha_i)$ and the corresponding multiplicities. Finally, note that all distributions on $[n]$
have probability generating functions which are polynomials with non-negative coefficients. This completes the proof.

Roughly speaking, using the above lemma, we can translate results about PBDs to results about polynomials with nonpositive real roots. To formally define our optimization problem, we will need the following definition:

**Definition 20** (*L₁*-length of a polynomial) Let \( p \) be a univariate real polynomial. We define \( \| p \|_1 \), the \( L_1 \)-length of \( p \), to be the sum of the absolute values of \( p \)'s coefficients.

We define the following polynomial optimization problem:

*Given a real univariate polynomial \( q \) (via its coefficients), compute a polynomial \( p \) with non-positive real roots that minimizes \( \| q - p \|_1 \), the \( L_1 \)-length of the difference \( p - q \).*

Our proper learning algorithm for PBDs can be easily adapted to yield the following theorem ³:

**Theorem 21** Given \( \epsilon > 0 \) and a degree \( n \) polynomial \( q(x) \) (via its coefficients), there is an algorithm with the following guarantee: Let \( \text{opt} = \min_p \| q - p \|_1 \) be the smallest \( L_1 \)-norm between \( q \) and any polynomial \( p \) with non-positive real roots. There is a deterministic algorithm that runs in time \( (1/\epsilon)^O(\log \log 1/\epsilon) + n\text{polylog}(n, \log 1/\epsilon) \) and outputs the roots of a polynomial \( r(x) \) with nonpositive real roots such that \( \| r - q \|_1 \leq O(\text{opt} \cdot \log (2 + \| q \|_1 / \text{opt})) + \epsilon \cdot \| q \|_1 \).

**Proof** First, note that we can round any negative coefficients of \( q(x) \) to 0. This does not affect the closest polynomial with non-positive roots, since each such polynomial has nonnegative coefficients. We assume from now on that \( q(x) \) has only non-negative coefficients.

Second, we note that the optimization problem is scale invariant. Therefore, it suffices to consider the problem when \( \| q \|_1 = 1 \). The problem can then be solved for general \( q(x) \) by letting \( p(x) \) be the solution corresponding to \( q(x)/\| q \|_1 \) and return \( p(x)/\| q \|_1 \).

Our main observation is that our optimization problem is exactly that of given an explicit distribution \( Q \) (whose density function is given by the coefficients of \( q(x) \)) that is \( O(\text{opt}) \)-close to a PBD, to find an explicit PBD that is \( O(\text{opt} \log (1/\epsilon) + \epsilon) \)-close to \( Q \). We note that this problem is effectively already solved in the previous subsection. In particular, if we knew the value of \( \text{opt} \), we could simply set \( \epsilon' = \max(\epsilon, \text{opt}) \), and use the algorithm from Proposition 17 with this \( \epsilon' \) in place of \( \epsilon \). Without knowing \( \text{opt} \), one can instead run this algorithm using the values \( 2^i \epsilon \) in place of \( \epsilon \), for \( i = 0, 1, \ldots, O(\log (1/\epsilon)) \), and noting that for some value of \( i \), \( 2^i \epsilon \) will be \( \Theta(\text{opt}) \), and this run of the algorithm will return an appropriately close \( P' \). By running this algorithm for all \( i \) up to \( \log_2(1/\epsilon) \), we return the \( P' \) found that is closest to \( Q \).

This method gives an obvious randomized algorithm for our problem. In particular, in order to get the samples required by the algorithm from Proposition 17, we will need to simulate samples from \( Q \).

This algorithm is very easy to derandomize. In particular, we note that the analysis in Proposition 17 only requires a few things from its choice of random variables. First, it requires that

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³ Note the theorem implies the existence of a similar algorithm for finding close polynomials with nonnegative real roots.
Pr(Q < a), Pr(Q > b) = Θ(ε). It is trivial to find a and b satisfying these bounds given explicit access to the distribution of Q. Second, it requires that the sample mean and standard deviation of the samples taken in Step 2, that lie in [a, b], are close to the actual mean and standard deviations of Q restricted to this interval. Instead, we can merely let ̂μ be the mean of Q conditioned on lying in [a, b] and ̂σ be 1/2 plus the standard deviation. Both of these can be computed efficiently given Q. Thirdly, we require that the h_ξ are within ε of ̂Q(ξ). This can be fixed by setting h_ξ to be ̂Q(ξ) rather than a sample average. Finally, we need that the samples taken in Step 7 choose a sufficiently close P' from our list. This can be derandomized by choosing the P' with smallest L_1 error (explicitly computed) from Q. This completes the derandomization, and proves the theorem. ■