Probabilistic Approximate Least-Squares (APPENDIX)

Simon Bartels Philipp Hennig Max Planck Institute for Intelligent Systems Tübingen Germany

An Upper Bound on the Approximation Error

Let $\boldsymbol{a}, \boldsymbol{b} \in \mathbb{R}^N$ be arbitrary vectors. The Gaussian measure (11) on \boldsymbol{H} implies that the scalar $\hat{\mu} := \boldsymbol{a}^{\mathsf{T}} \boldsymbol{H} \boldsymbol{b}$ is Gaussian distributed as well, with mean $\boldsymbol{a}^{\mathsf{T}} \boldsymbol{H}_M \boldsymbol{b}$ and a variance we denote with $\hat{\epsilon}^2$ (derived in the proof below).

Theorem 1. The absolute error $|\hat{\mu} - a^{\mathsf{T}}Hb|$ divided by the standard deviation $\hat{\epsilon}$ is always less than 1:

$$\frac{|\boldsymbol{a}^{\mathsf{T}}\boldsymbol{H}_{\boldsymbol{M}}\boldsymbol{b} - \boldsymbol{a}^{\mathsf{T}}\boldsymbol{H}\boldsymbol{b}|}{\hat{\epsilon}} < 1 \tag{32}$$

$$\sqrt{2}(\boldsymbol{H}-\boldsymbol{H}_M)$$
, then

$$\frac{|\boldsymbol{a}^{\mathsf{T}} \left(\boldsymbol{H} - \boldsymbol{H}_{M}\right) \boldsymbol{b}|}{\sqrt{\hat{\epsilon}^{2}}} \tag{40}$$

$$=\frac{|\boldsymbol{a}^{\mathsf{T}}\boldsymbol{W}_{M}\boldsymbol{b}|}{\sqrt{2}\sqrt{\frac{1}{2}\boldsymbol{a}^{\mathsf{T}}\boldsymbol{W}_{M}\boldsymbol{a}\cdot\boldsymbol{b}^{\mathsf{T}}\boldsymbol{W}_{M}\boldsymbol{b}+\frac{1}{2}\left(\boldsymbol{a}^{\mathsf{T}}\boldsymbol{W}_{M}\boldsymbol{b}\right)^{2}} \quad (41)$$

$$=\frac{|\boldsymbol{a}\cdot\boldsymbol{W}_{M}\boldsymbol{b}|}{\sqrt{\boldsymbol{a}^{\mathsf{T}}\boldsymbol{W}_{M}\boldsymbol{a}\cdot\boldsymbol{b}^{\mathsf{T}}\boldsymbol{W}_{M}\boldsymbol{b}+\left(\boldsymbol{a}^{\mathsf{T}}\boldsymbol{W}_{M}\boldsymbol{b}\right)^{2}}}$$
(42)

$$< \frac{|\boldsymbol{a}^{\mathsf{T}} \boldsymbol{W}_M \boldsymbol{b}|}{\sqrt{(\boldsymbol{a}^{\mathsf{T}} \boldsymbol{W}_M \boldsymbol{b})^2}} = 1$$
 (as \boldsymbol{W}_M is s.p.d.) (43)

Proof. If $\boldsymbol{v} \in \mathbb{R}^N$ is a Gaussian random vector $\mathcal{N}(\boldsymbol{v};\boldsymbol{\mu},\boldsymbol{\Sigma})$ and $\boldsymbol{A} \in \mathbb{R}^{M \times N}$ is of rank M then $\boldsymbol{A}\boldsymbol{v}$ is also Gaussian with $\mathcal{N}(\boldsymbol{A}\boldsymbol{v};\boldsymbol{A}\boldsymbol{\mu},\boldsymbol{A}^{\mathsf{T}}\boldsymbol{\Sigma}\boldsymbol{A})$. We can rewrite $\boldsymbol{a}^{\mathsf{T}}\boldsymbol{H}_M\boldsymbol{b}$ as $\overrightarrow{\boldsymbol{a}^{\mathsf{T}}\boldsymbol{H}_M\boldsymbol{b}} = (\boldsymbol{a}^{\mathsf{T}} \otimes \boldsymbol{b}^{\mathsf{T}}) \overrightarrow{\boldsymbol{H}}_M$. and it follows that $\hat{\boldsymbol{\epsilon}}$ has the form

$$\hat{\epsilon}^2 = (\boldsymbol{a}^{\mathsf{T}} \otimes \boldsymbol{b}^{\mathsf{T}}) \left(\boldsymbol{W}_M \otimes \boldsymbol{W}_M \right) \left(\boldsymbol{a} \otimes \boldsymbol{b} \right)$$
(33)

To simplify this expression we use that $\boldsymbol{a} \otimes \boldsymbol{b}$ is an N^2 dimensional vector and thus $\boldsymbol{a} \otimes \boldsymbol{b} = (\boldsymbol{a} \otimes \boldsymbol{b}) \overrightarrow{1} = \overrightarrow{\boldsymbol{a} 1 \boldsymbol{b}^{\dagger}} = \overrightarrow{\boldsymbol{a} \boldsymbol{b}^{\dagger}}$. Therefore $\hat{\epsilon}^2$ reduces to

$$\hat{\epsilon}^2 = (\boldsymbol{a}^{\mathsf{T}} \otimes \boldsymbol{b}^{\mathsf{T}}) \, \boldsymbol{\Gamma}(\boldsymbol{W}_M \otimes \boldsymbol{W}_M) \boldsymbol{\Gamma} \overline{\boldsymbol{a} \boldsymbol{b}^{\mathsf{T}}}$$
(34)

$$= \frac{1}{2} \left(\boldsymbol{a}^{\mathsf{T}} \otimes \boldsymbol{b}^{\mathsf{T}} \right) \boldsymbol{\Gamma} (\boldsymbol{W}_{M} \otimes \boldsymbol{W}_{M}) \overline{\boldsymbol{a} \boldsymbol{b}^{\mathsf{T}} + \boldsymbol{b} \boldsymbol{a}^{\mathsf{T}}}$$
(35)

$$=\frac{1}{2}\left(\boldsymbol{a}^{\mathsf{T}}\otimes\boldsymbol{b}^{\mathsf{T}}\right)\boldsymbol{\Gamma}\overline{\boldsymbol{W}_{M}\boldsymbol{a}\boldsymbol{b}^{\mathsf{T}}\boldsymbol{W}_{M}+\boldsymbol{W}_{M}\boldsymbol{b}\boldsymbol{a}^{\mathsf{T}}\boldsymbol{W}_{M}^{\mathsf{T}}}\left(36\right)$$

$$= \frac{1}{2} \left(\boldsymbol{a}^{\mathsf{T}} \otimes \boldsymbol{b}^{\mathsf{T}} \right) \overline{\boldsymbol{W}_{M} \boldsymbol{a} \boldsymbol{b}^{\mathsf{T}} \boldsymbol{W}_{M} + \boldsymbol{W}_{M} \boldsymbol{b} \boldsymbol{a}^{\mathsf{T}} \boldsymbol{W}_{M}} \quad (37)$$

$$=\frac{1}{2}\overline{\boldsymbol{a}^{\mathsf{T}}\boldsymbol{W}_{M}\boldsymbol{a}\boldsymbol{b}^{\mathsf{T}}\boldsymbol{W}_{M}\boldsymbol{b}+\boldsymbol{a}^{\mathsf{T}}\boldsymbol{W}_{M}\boldsymbol{b}\boldsymbol{a}^{\mathsf{T}}\boldsymbol{W}_{M}\boldsymbol{b}}\boldsymbol{b} \qquad (38)$$

$$= \frac{1}{2} \left(\boldsymbol{a}^{\mathsf{T}} \boldsymbol{W}_{M} \boldsymbol{a} \boldsymbol{b}^{\mathsf{T}} \boldsymbol{W}_{M} \boldsymbol{b} + (\boldsymbol{a}^{\mathsf{T}} \boldsymbol{W}_{M} \boldsymbol{b})^{2} \right)$$
(39)

If we now choose $\boldsymbol{W} = \sqrt{2}\boldsymbol{H}$, and therefore $\boldsymbol{W}_M =$

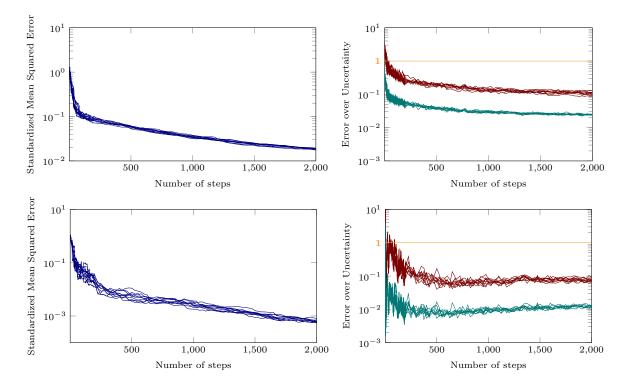


Figure 1: Ten Farthest Point Clustering initializations of the probabilistic subset of data approximation on the PUMADYN (top row) and CPU (bottom row) data sets, using the ARD Squared Exponential kernel. Left: standardized mean squared error for Subset of Data. Right: ratio between absolute error and uncertainty. The upper lines are the maximum, the lower lines the average over all test inputs. The horizontal line shows the theoretical bound at 1 that would be guaranteed if $W = \sqrt{2}H$ where estimated exactly.

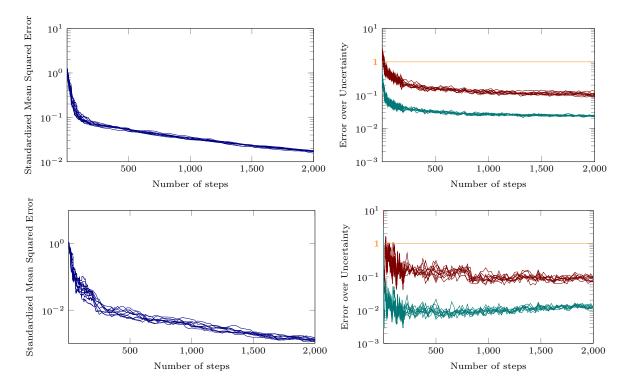


Figure 2: Same setup as Figure 1, but using the ARD Matérn ⁵/₂ kernel.