Ordered Weighted ℓ_1 Regularized Regression with Strongly Correlated Covariates: Theoretical Aspects (Supplementary Material)

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Proofs of the Lemmas in Section 2

Proof of Lemma 2.1

Recall that x_i and x_j are non-negative and let l and m be their respective rank orders, *i.e.*, $x_i = x_{[l]}$ and $x_j = x_{[m]}$; of course, l < m, because $x_i = x_{[l]} > x_{[m]} = x_j$. Now let l + a and m - b be the rank orders of z_i and z_j , respectively, *i.e.*, $x_i - \varepsilon = z_i = z_{[l+a]}$ and $x_j + \varepsilon = z_j = z_{[m-b]}$. Of course, it may happen that a or b (or both) are zero, if ε is small enough not to change the rank orders of one (or both) of the affected components of x. Furthermore, the condition $\varepsilon < (x_i - x_j)/2$ implies that $x_i - \varepsilon > x_j + \varepsilon$, thus l + a < m - b. A key observation is that x_{\downarrow} and z_{\downarrow} only differ in positions l to l + a and m - b to m, thus we can write

$$\Omega_{\boldsymbol{w}}(\boldsymbol{x}) - \Omega_{\boldsymbol{w}}(\boldsymbol{z}) = \sum_{k=l}^{l+a} w_k \left(x_{[k]} - z_{[k]} \right) + \sum_{k=m-b}^m w_k \left(x_{[k]} - z_{[k]} \right).$$
(i)

In the range from l to l + a, the relationship between z_{\downarrow} and x_{\downarrow} is

$$z_{[l]} = x_{[l+1]}, \ z_{[l+1]} = x_{[l+2]}, \ \dots, \ z_{[l+a-1]} = x_{[l+a]}, \ z_{[l+a]} = x_{[l]} - \varepsilon$$

whereas in the range from m - b to m, we have

$$z_{[m-b]} = x_{[m]} + \varepsilon, \ z_{[m-b+1]} = x_{[m-b]}, \ \dots, \ z_{[m]} = x_{[m-1]}$$

Plugging these equalities into (i) yields

$$\Omega_{\boldsymbol{w}}(\boldsymbol{x}) - \Omega_{\boldsymbol{w}}(\boldsymbol{z}) = \sum_{k=l}^{l+a-1} w_{k} \underbrace{\left(x_{[k]} - x_{[k+1]}\right)}_{\geq 0} + \sum_{k=m-b+1}^{m} w_{k} \underbrace{\left(x_{[k]} - x_{[k-1]}\right)}_{\leq 0} \\
+ w_{l+a} \left(x_{[l+a]} - x_{[l]} + \varepsilon\right) + w_{m-b} \left(x_{[m-b]} - x_{[m]} - \varepsilon\right) \\
\stackrel{(a)}{\geq} w_{l+a} \sum_{k=l}^{l+a-1} \left(x_{[k]} - x_{[k+1]}\right) + w_{m-b} \sum_{k=m-b+1}^{m} \left(x_{[k]} - x_{[k-1]}\right) \\
+ w_{l+a} \left(x_{[l+a]} - x_{[l]} + \varepsilon\right) + w_{m-b} \left(x_{[m-b]} - x_{[m]} - \varepsilon\right) \\
= w_{l+a} \left(\sum_{k=l}^{l+a-1} \left(x_{[k]} - x_{[k+1]}\right) + \left(x_{[l+a]} - x_{[l]} + \varepsilon\right)\right) \\
+ w_{m-b} \left(\sum_{k=m-b+1}^{m} \left(x_{[k]} - x_{[k-1]}\right) + \left(x_{[m-b]} - x_{[m]} - \varepsilon\right)\right) \\
\stackrel{(c)}{=} \varepsilon \left(w_{l+a} - w_{m-b}\right) \stackrel{(c)}{\geq} \varepsilon \Delta_{\boldsymbol{w}},$$

where inequality (a) results from $x_{[k]} - x_{[k+1]} \ge 0$, $x_{[k]} - x_{[k-1]} \le 0$, and the components of w forming a non-increasing sequence, thus $w_{l+a} \le w_k$, for k = l, ..., l+a-1, and $w_{m-b} \ge w_k$, for k = m-b+1, ..., m; equality (c) is a consequence of the cancellation of the remains of the telescoping sums with the two other terms; inequality (c) results from the fact that (see above) l + a < m - b and the definition of Δ_w given in Section 1 of the paper.

Proof of Lemma 2.2

Let l and m be the rank orders of x_i and x_j , respectively, *i.e.*, $x_i = x_{[l]}$ and $x_j = x_{[m]}$; without loss of generality, assume that m > l. Furthermore, let l + a and m + b be the rank orders of s_i and s_j in s (*i.e.*, $s_i = s_{[l+a]}$ and $s_j = s_{[m+b]}$); naturally, $a, b \ge 0$. Then,

$$\Omega_{\boldsymbol{w}}(\boldsymbol{x}) - \Omega_{\boldsymbol{w}}(\boldsymbol{s}) \geq w_{l} x_{i} + w_{m} x_{j} - w_{l+a}(x_{i} - \varepsilon) - w_{m+b}(x_{j} - \varepsilon)$$

$$\geq \underbrace{(w_{l} - w_{l+a})}_{\geq 0} x_{i} + \underbrace{(w_{m} - w_{m+b})}_{\geq 0} x_{j} + \underbrace{(w_{l+a} + w_{m+b})}_{\geq \Delta_{\boldsymbol{w}}} \varepsilon \geq \Delta_{\boldsymbol{w}} \varepsilon,$$

where the inequality $w_{l+a} + w_{m+b} \ge \Delta_w$ results from the definition of Δ_w , which implies that $w_1, ..., w_{p-1} \ge \Delta_w$ (only w_p can be less than Δ_w , maybe even zero).

Proof of Lemma 2.4

The proof is a direct consequence of the triangle inequality. Letting g = Ax - y, we have

$$egin{array}{rcl} L_1(m{v}) - L_1(m{x}) &= & \|m{g} - arepsilon m{a}_i + arepsilon m{a}_j \|_1 - \|m{g}\|_1 \ &\leq & \|m{g}\|_1 + |arepsilon| \|m{a}_i - m{a}_j\|_1 - \|m{g}\|_1 \ &= & |arepsilon| \|m{a}_i - m{a}_j\|_1. \end{array}$$

Proof of Theorem 3.2

The bound stated in Theorem 3.2 follows from the deviation inequality

$$\mathbb{E}\sup_{\boldsymbol{u}\in\mathcal{T}}\left|\frac{1}{n}\sum_{i=1}^{n}|\langle\boldsymbol{a}_{i},\boldsymbol{u}\rangle|-\sqrt{\frac{2}{\pi}}\left(\boldsymbol{u}^{T}\boldsymbol{C}^{T}\boldsymbol{C}\boldsymbol{u}\right)^{1/2}\right| \leq \frac{4}{\sqrt{n}}\mathbb{E}\sup_{\boldsymbol{u}\in\mathcal{T}}|\langle\boldsymbol{C}^{T}\boldsymbol{g},\boldsymbol{u}\rangle|,$$
(ii)

where a_i denotes the *i*th row of A. To see this, note that the inequality holds if we replace the set \mathcal{T} on the left hand side by the smaller set $\mathcal{T}_{\varepsilon}$. For $u \in \mathcal{T}_{\varepsilon}$ we have by assumption that

$$rac{1}{n}\sum_{i=1}^n |\langle oldsymbol{a}_i,oldsymbol{u}
angle| = rac{1}{n}\|oldsymbol{A}oldsymbol{u}\|_1 \leq arepsilon,$$

and the bound in the theorem follows by the triangle inequality.

To prove (ii), the first thing to note is that

$$\mathbb{E} |\langle oldsymbol{a}_i,oldsymbol{u}
angle| = \mathbb{E} |\langle oldsymbol{C}^T oldsymbol{b}_i,oldsymbol{u}
angle| \; = \; \mathbb{E} |\langle oldsymbol{b}_i,oldsymbol{C}oldsymbol{u}
angle| \; ,$$

where b_i is the *i*th row of **B**. Because the Gaussian distribution of b_i is rotationally invariant, it follows that

$$\mathbb{E} |\langle oldsymbol{b}_i, oldsymbol{C}oldsymbol{u}
angle| \ = \ \sqrt{rac{2}{\pi}} \left(oldsymbol{u}^Toldsymbol{C}^Toldsymbol{C}oldsymbol{u}
ight)^{1/2}$$

Using the symmetrization and contraction inequalities from a proposition by Vershynin (2014, Proposition 5.2), we have the bound

$$\begin{split} \mathbb{E}\sup_{\boldsymbol{u}\in T} \left| \frac{1}{n} \sum_{i=1}^{n} |\langle \boldsymbol{a}_{i}, \boldsymbol{u} \rangle| - \sqrt{\frac{2}{\pi}} \left(\boldsymbol{u}^{T} \boldsymbol{C}^{T} \boldsymbol{C} \boldsymbol{u} \right)^{1/2} \right| &\leq 4 \mathbb{E}\sup_{\boldsymbol{u}\in T} \left| \frac{1}{n} \sum_{i=1}^{n} \varepsilon_{i} \langle \boldsymbol{b}_{i}, \boldsymbol{C} \boldsymbol{u} \rangle \right| \\ &= 4 \mathbb{E}\sup_{\boldsymbol{u}\in T} \left| \left\langle \frac{1}{n} \sum_{i=1}^{n} \varepsilon_{i} \boldsymbol{b}_{i}, \boldsymbol{C} \boldsymbol{u} \right\rangle \right| \,, \end{split}$$

where each ε_i independently takes values -1 and +1 with probabilities 1/2. Note that vector

$$\boldsymbol{g} := rac{1}{\sqrt{n}} \sum_{i=1}^n arepsilon_i \boldsymbol{b}_i \sim \mathcal{N}(0, \mathbf{I}_q),$$

thus,

$$4\mathbb{E}\sup_{\boldsymbol{u}\in T}\left|\left\langle\frac{1}{n}\sum_{i=1}^{n}\varepsilon_{i}\boldsymbol{b}_{i},\boldsymbol{C}\boldsymbol{u}\right\rangle\right| = \frac{4}{\sqrt{n}}\mathbb{E}\sup_{\boldsymbol{u}\in T}\left|\langle\boldsymbol{g},\boldsymbol{C}\boldsymbol{u}\rangle\right| = \frac{4}{\sqrt{n}}\mathbb{E}\sup_{\boldsymbol{u}\in T}\left|\langle\boldsymbol{C}^{T}\boldsymbol{g},\boldsymbol{u}\rangle\right|,$$

which completes the proof.

References

R. Vershynin. Estimation in high dimensions: A geometric perspective. Technical report, http://arxiv.org/abs/1405.5103, 2014.