## Supplementary Material

## S1. Adaptive Decoding

Limited training data in practical settings can limit the inferential accuracy of the learned autoencoder model, and we may have $x_{0} \neq D\left(E\left(x_{0}\right)\right)$ for a given to-be-revised sequence $x_{0}$ (particularly if $p_{X}\left(x_{0}\right)$ is low). In this case, even when $z^{*}=E\left(x_{0}\right)$ solves our latent-factor optimization, our REVISE procedure can return a different sequence than $x_{0}$ (despite not expecting any associated outcome-improvement).

To ensure that our methods simply return the initial $x_{0}$ when no superior revision can be identified, we replace our decoder model $p_{D}(x \mid z)$ with an adaptive variant $p_{D_{x_{0}}}(x \mid z)$ that is efficiently defined once $x_{0}=\left(s_{1}^{\left(x_{0}\right)}, \ldots, s_{T_{x_{0}}}^{\left(x_{0}\right)}\right)$ is specified at test time. Like before, we write $D_{x_{0}}(z)$ to denote the (beam-search approximated) most-likely decoding with respect to $p_{D_{x_{0}}}$. Recall from our definition in (4), $\pi_{t}$ is the vector of symbol-probabilities output by our decoder RNN $\mathcal{D}$ to compute $p_{D}$. Using the indexing notation $\pi_{t}\left[s_{t}\right]$ to denote the decoder RNN's approximation of $p\left(s_{t}, \mid s_{1} \ldots, s_{t-1}\right)$, we let $\pi_{t}^{\left(x_{0}\right)}$ denote particular conditional-probability values output by $\mathcal{D}$ when the initial hidden state is $z=E\left(x_{0}\right)$.

For any $x=\left(s_{1}, \ldots, s_{T}\right) \in \mathcal{X}$, we define:

$$
\begin{align*}
& p_{D_{x_{0}}}(x \mid z)=\prod_{t=1}^{T} \widetilde{\pi}_{t}\left[s_{t}\right] \quad \text { where for } t=1, \ldots, T, s \in \mathcal{S}: \quad \widetilde{\pi}_{t}[s]= \begin{cases}\pi_{t}[s]+\beta_{t}^{\left(x_{0}\right)} & \text { if } s=s_{t}^{\left(x_{0}\right)} \\
\pi_{t}[s]-\frac{1}{|\mathcal{S}|} \beta_{t}^{\left(x_{0}\right)} & \text { otherwise }\end{cases}  \tag{15}\\
& \text { and } \beta_{t}^{\left(x_{0}\right)}=\max _{s \in \mathcal{S}} \pi_{t}^{\left(x_{0}\right)}[s]-\pi_{t}^{\left(x_{0}\right)}\left[s_{t}^{\left(x_{0}\right)}\right] \geqslant 0 \text { for } t=1, \ldots, T_{x_{0}}
\end{align*}
$$

At each time step, the $\beta_{t}^{\left(x_{0}\right)}$ measure any probability gap between the most likely symbol under $p_{D}$ and the actual sequence $x_{0}$ when our decoder model $\mathcal{D}$ is applied to $E\left(x_{0}\right)$. Thus, the definition in (15) ensures $D_{x_{0}}\left(E\left(x_{0}\right)\right)=x_{0}$. When revising sequences using this adaptive decoding procedure, we compute all $\beta_{t}^{\left(x_{0}\right)}$ by first decoding from $E\left(x_{0}\right)$ before beginning the latent $z$-optimization in the REVISE procedure. These values are stored so that we can subsequently decode from the optimal latent-configuration $z^{*}$ with respect to $p_{D_{x_{0}}}$ rather than $p_{D}$.
According to our adaptive decoding definition, $x_{0}$ is more likely than any other sequence under $p_{D_{x_{0}}}\left(x \mid E\left(x_{0}\right)\right)$, and $p_{D_{x_{0}}}$ is very easy to derive from $p_{D}$ (no additional model besides our original $\mathcal{D}$ is needed). Furthermore, the (beam-search) maximizer of $p_{D_{x_{0}}}$ can be used to decode from any latent $z$ values, resulting in a mapping that is slightly more biased toward $x_{0}$ than decoding with respect to $p_{D}$. Finally, we note that if $x^{*}$ is produced by $D_{x_{0}}$ rather than $D$, Theorem 3 continues to hold if we replace $D$ with $D_{x_{0}}$ in assumption (A6). Theorems 1 and 2 remain valid without any change, since:

$$
p_{D_{x_{0}}}\left(x^{*} \mid z^{*}\right) \geqslant p_{D_{x_{0}}}\left(x_{0} \mid z^{*}\right) \text { and } p_{D_{x_{0}}}\left(x_{0} \mid z^{*}\right)-p_{D}\left(x_{0} \mid z^{*}\right) \geqslant p_{D_{x_{0}}}\left(x^{*} \mid z^{*}\right)-p_{D}\left(x^{*} \mid z^{*}\right)
$$

together imply that $p_{D}\left(x^{*} \mid z^{*}\right) \geqslant p_{D}\left(x_{0} \mid z^{*}\right)$, as required for expression (16) in our original proofs.

## S2. Experiment Details and Additional Results

Automatic differentiation in TensorFlow is used to obtain gradients for both our revision procedure and the (stochastic) learning of neural network parameters. Throughout our applications, the GRU input is a vector-representation of each symbol in the sequence, taken from a dictionary of embeddings that is learned jointly with the neural network parameters via the Adam optimization algorithm of Kingma \& Ba (2015). To ensure the decoder can actually generate variable-length sequences, a special <End $>$ symbol is always included in $\mathcal{S}$ and appended at the end of each sequence in the training data. Note that all $\alpha$-values stated in the text were actually first rescaled by $(2 \pi)^{-d / 2}$ before the REVISE procedure (to avoid confounding from the choice of latent-dimensionality $d$ in the relationship between the listed $\alpha$ and characteristics of the resulting revisions).

## S2.1. Simulation Study

When sampling a sequence for this simulation, we first draw its length uniformly from the range [10,20], and subsequently draw the symbols at each position following the probabilistic grammar of Table S1. Before its quality is evaluated, any proposed sequence whose length violates the $[10,20]$ range is either truncated or extended via repeated duplication of the last symbol. In all models we apply, the encoder/decoder GRUs operate on input-embeddings of size 8 , and the outcomeprediction model $\mathcal{F}$ is a feedforward network with one tanh hidden layer of size 128.

| Rule | Probability |
| :--- | ---: |
| $s_{t}=A \mid s_{t-1}=C$ | 0.50 |
| $s_{t}=B \mid s_{t-1}=A$ | 0.95 |
| $s_{t}=D \mid s_{t-3}=D$ | 0.95 |
| $s_{t}=E \mid s_{t-5}=E$ | 0.95 |
| $s_{t}=J \mid s_{t-2}=H, s_{t-1}=I$ | 0.95 |
| $s_{t}=I \mid s_{t-2}=I, s_{t-1}=H$ | 0.95 |
| $s_{t}=B \mid s_{t-3}=B, s_{t-2}=C$ | 0.95 |
| $s_{t}=F \mid s_{t-1}=F, t \geqslant 11$ | 0.95 |
| $s_{7}=G \mid s_{6}=F$ | 0.95 |
| $s_{8}=G \mid s_{7}=F$ | 0.50 |
| $s_{5}=C$ | 0.50 |
| $s_{10}=C$ | 0.50 |
| $s_{15}=C$ | 0.50 |
| $s_{20}=C$ | 0.50 |

Table $S 1$. Probabilistic grammar used to generate sequences $\left(s_{1}, \ldots, s_{T}\right)$ in our simulation. All events not listed here are assumed to occur randomly (uniformly among the remaining probability mass). When one or more conditioning statements are valid at a given $t$, we renormalize the probabilities for $s_{t} \mid s_{1}, \ldots, s_{t-1}$ before sampling the next character.

In the SEARCH procedure, evaluating 100 candidates took similar computation time as a typical run of our REVISE algorithm. Note that in this small scale simulation study, SEARCH is able to examine a nontrivial subset of the possible sequences around $x_{0}$. However, exponentially more randomly generated revisions would be needed to retain the performance of this SEARCH approach under longer sequences with larger vocabularies, whereas the computational complexity of our REvise procedure scales linearly with such increases. Whereas the SEARCH method changes nearly every given initial sequence by a relatively similar amount, our REVISE procedure tends to either make larger changes or no change at all. As is desirable, our approach (particularly with adaptive decoding) tends to favor no change for $x_{0}$ where the corresponding latent posterior has high uncertainty, both because the VAE training objective urges all decodings in a large region around $E\left(x_{0}\right)$ to heavily favor $x_{0}$ and the invariance term $\mathcal{L}_{\text {inv }}$ encourages $F$ to be more flat in such regions.

## S2.2. Improving Sentence Positivity

For simplicity, our analysis of the beer reviews only considers sentences that are short ( $\leqslant 30$ words) and entirely composed of words that appear in $\geqslant 100$ other sentences. This restricts the size of the vocabulary to $|\mathcal{S}| \approx 5,500$. In this analysis, the SEARCH procedure is allowed to score 1000 candidate sequences, which is now far slower than our REVISE algorithm. In our models, GRUs $\mathcal{E}$ and $\mathcal{D}$ employ an embedding layer of size 128 , the latent representations (and GRU hidden states $h_{t}$ ) have $d=256$ dimensions, and $\mathcal{F}$ is feedforward network with one hidden layer of the same size (and tanh activations)


Figure S1. Behavior of the REvise procedure in our simulation study. (A) Relationship between $\alpha$ and properties of revised sequence (averaged over same 1000 initial sequences $x_{0} \sim p_{X}$, with units rescaled so that all curves share the same range): outcome improvement (black), edit distance (blue), marginal log-likelihood (red). (B) Likelihood of each original sequences vs. its revised version, when $\log \alpha=-10000$. The diagonal red line depicts the identity relationship $y=x$. (C) Boxplot of $\left\|z^{*}-E\left(x_{0}\right)\right\|_{2}$ values for each resulting value of $d\left(x_{0}, x^{*}\right)$ observed when $\log \alpha=-10000$. Note there were very few revisions where $d\left(x_{0}, x^{*}\right)>8$.
followed by a sigmoid output layer. The language model $L$ shares the same GRU architecture as our decoder network $\mathcal{D}$.
Examining the REVISE output, we find that punctuation patterns are quite often perfectly preserved in revisions (this is interesting since all punctuation characters are simply treated as elements of the vocabulary in the sequences). There exist many initialization-points where if unconstrained gradient ascent is run for a vast number of iterations with a large step-size, the resulting decoding produces the sentence: "excellent excellent excellent excellent excellent excellent excellent.", which is has near-optimal VADER sentiment but low marginal likelihood. Starting from other $z$-initializations, the decoding which results from a massive shift in the latent space often reverts to repetitions of a safe choice where each decoded word has high marginal likelihood, such as: "the the a the the the a the" or "tasting tasting tasting tasting tasting tasting tasting ".

## S2.3. Revising Modern Text in the Language of Shakespeare

Sentences used in this analysis were taken either from the concatenated works of Shakespeare (Karpathy, 2015) or from various more contemporary texts (non-Shakespeare-authored works from the Brown, Reuters, Gutenberg, and FrameNet corpora in Python's NLTK library (Bird et al., 2009)). Here, we use the same architecture for networks $\mathcal{F}, \mathcal{E}, \mathcal{D}$ as in the previous beer-reviews application.

| Model | Sentence | $\Delta_{Y}\left(x^{*}\right)$ | $\Delta_{L}\left(x^{*}\right)$ | $d\left(x^{*}, x_{0}\right)$ |
| :---: | :---: | :---: | :---: | :---: |
| $x_{0}$ | caramel, fruit, sweetness, and a soft floral bitterness. | - | - | - |
| $\log \alpha=-10000$ | caramel, fresh, sweetness, quite soft and a good bitterness. | +1.88 | -5.1 | 6 |
| Adaptive | caramel, fresh, sweetness, quite soft and a good bitterness. | +1.88 | -5.1 | 6 |
| $\log \alpha=-1$ | caramel, fruit sweetness, and a soft floral nose. | +1.17 | +0.2 | 1 |
| $\lambda_{\text {inv }}=\lambda_{\text {pri }}=0$ | caramel, fruit sweetness, and a soft floral and tangy nose. | +1.17 | -16.4 | 3 |
| SEARCH | caramel, fruit sweetness, and a soft floral, cocoa. | +1.17 | -7.0 | 2 |
| $x_{0}$ | i like to support san diego beers. | - | - | - |
| $\log \alpha=-10000$ | i love to support craft beers! | +0.5 | +1.6 | 4 |
| Adaptive | i like to support san diego beers. | 0 | 0 | 0 |
| $\log \alpha=-1$ | i like to support craft beers! | +0.1 | +2.6 | 3 |
| $\lambda_{\text {inv }}=\lambda_{\text {pri }}=0$ | i like to support you know. | 0 | +3.7 | 3 |
| SEARCH | i like to super support san diego. | +0.7 | -2.9 | 2 |
| $x_{0}$ | good carbonation makes for a smooth drinking experience. | - | - | - |
| $\log \alpha=-10000$ | good carbonation makes a great smooth drinking stuff. | +1.1 | -1.1 | 3 |
| Adaptive | good carbonation makes a great smooth drinking stuff. | +1.1 | -1.1 | 3 |
| $\log \alpha=-1$ | good carbonation makes for great smooth drinking. | + 1.1 | +3.0 | 2 |
| $\lambda_{\text {inv }}=\lambda_{\text {pri }}=0$ | good carbonation makes for a smooth drinking like experience. | +0.7 | -9.2 | 1 |
| SEARCH | good carbonation makes for a drinking nice experience! | +0.9 | -4.1 | 3 |
| $x_{0}$ | i'm not sure how old the bottle is. | - | - | - |
| $\log \alpha=-10000$ | i definitely enjoy how old is the bottle is. | +3.0 | -3.6 | 4 |
| Adaptive | $i$ definitely enjoy how old is the bottle is. | +3.0 | -3.6 | 4 |
| $\log \alpha=-1$ | i'm sure not sure how old the bottle is. | +2.5 | -6.8 | 1 |
| $\lambda_{\text {inv }}=\lambda_{\text {pri }}=0$ | $i ' m$ sure better is the highlights when cheers. | +3.3 | -9.2 | 6 |
| SEARCH | i 'm not sure how the bottle is love. | +2.3 | -3.3 | 2 |
| $x_{0}$ | what a great afternoon! | - | - | - |
| $\log \alpha=-10000$ | what a great afternoon! | 0 | 0 | 0 |
| Adaptive | what a great afternoon! | 0 | 0 | 0 |
| $\log \alpha=-1$ | what a great afternoon! | 0 | 0 | 0 |
| $\lambda_{\text {inv }}=\lambda_{\text {pri }}=0$ | what a great afternoon lace! | 0 | -8.2 | 1 |
| SEARCH | what a solid great! | +0.19 | -7.1 | 2 |
| $x_{0}$ | the finish is a nice hoppy bitter, with ample spice. | - | - | - |
| $\log \alpha=-10000$ | the finish is a nice hoppy plant, with ample spice and great mouthfeel. | +2.5 | -6.4 | 4 |
| Adaptive | the finish is a nice hoppy plant, with ample spice. | +1.3 | -0.8 | 1 |
| $\log \alpha=-1$ | the finish is a nice hoppy plant, with ample spice. | +1.3 | -0.8 | 1 |
| $\lambda_{\text {inv }}=\lambda_{\text {pri }}=0$ | the finish is a nice hoppy bitter, with ample spice. | 0 | 0 | 0 |
| SEARCH | the finish is a nice hoppy bitter best, with ample spice. | +2.0 | -7.9 | 1 |

Table $S 2$. Additional examples of held-out beer reviews $x_{0}$ (in bold) revised to improve their VADER sentiment. Underneath each sentence, we show the revision produced by each different method along with the true outcome improvement $\Delta_{Y}\left(x^{*}\right)=\mathbb{E}\left[Y \mid X=x^{*}\right]-\mathbb{E}\left[Y \mid X=x_{0}\right]$ (rescaled by the standard deviation of outcomes in the training data), estimated change in marginal likelihood $\Delta_{L}\left(x^{*}\right)=\log L\left(x^{*}\right)-\log L\left(x_{0}\right)$, and Levenshtein (edit) distance $d\left(x^{*}, x_{0}\right)$.

| \# Steps | Sentence |
| :---: | :---: |
| $x_{0}$ | you find the evidence of that in the chart on this page. |
| 100 | you find the evidence of that in the chart on this page. |
| 1000 | you find the chart of action in this page. |
| 5000 | you find the chart of the chart that page of action in this page. |
| 10000 | find you in this page of the way of your highness. |
| $x^{*}$ | you speak of the chart in this page of the lord. |
| $x_{0}$ | somewhere, somebody is bound to love us. |
| 100 | somewhere, somebody is bound to love us. |
| 1000 | courage, honey, somebody is bound to love us! |
| 5000 | courage man; 'tis love that is lost to us. |
| 10000 | thou, within courage to brush and such us brush. |
| $x^{*}$ | courage man; somebody is bound to love us. |
| $x_{0}$ | the story of the fatal crash is not fully known |
| 100 | the story of the injured is not known. |
| 1000 | the story of our virtue is not yet known. |
| 5000 | the story of our virtue is not given me yet. |
| 10000 | the virtue of our story is not yet. |
| $x^{*}$ | the story of our virtue is not yet known. |
| $x_{0}$ | this is the root issue for which the united states should stand. |
| 100 | this is the root issue which is an issue on the united states. |
| 1000 | the root issue is that the dialogue itself should stand provided. |
| 5000 | the general is for the root chief held for which is thy tale. |
| 10000 | this the shallow is sworn thee. shallow for thee. |
| $x^{*}$ | the root issue is the national dialogue from thine. |
| $x_{0}$ | there is no such magic in man-made laws. |
| 100 | there is no such magic of man in such magic. |
| 1000 | there is no magic of man in such magic. |
| 5000 | there is no magic question with such a man in man. |
| 10000 | there is no magic in revolution and made no such india. |
| $x^{*}$ | there is no magic in such noble birth; |
| $x_{0}$ | check the quality of the water. |
| 100 | check the quality of the water. |
| 1000 | check the quality of thy water. |
| 5000 | check the quality of thy quality. |
| 10000 | check the king of gloucester. |
| $x^{*}$ | check the quality of thy water. |
| $x_{0}$ | what are you doing here? |
| 100 | what are you doing here? |
| 1000 | what are you doing here? |
| 5000 | cardinal what does thou live here? |
| 10000 | cardinal what does thou live here? |
| $x^{*}$ | does thou live here? |

Table S3. Adaptive decoding from various latent $Z$ configurations encountered at the indicated number of (unconstrained) gradient steps from $E\left(x_{0}\right)$, for the model trained to distinguish sentences from Shakespeare vs. contemporary authors. Shown first and last are the initial sequence $x_{0}$ and the revision $x^{*}$ returned by our REVISION procedure (constrained with $\log \alpha=-10000$ ).

## S3. Proofs and Auxiliary Lemmas

## Proof of Theorem 1.

By the definition of $x^{*}$, we have:

$$
\begin{align*}
& p_{D}\left(x^{*} \mid z^{*}\right) \geqslant p_{D}\left(x_{0} \mid z^{*}\right)  \tag{16}\\
\Longrightarrow & p_{X}\left(x^{*}\right) \geqslant \frac{p\left(z^{*} \mid x_{0}\right)}{p\left(z^{*} \mid x^{*}\right)} \cdot p_{X}\left(x_{0}\right) \\
& \geqslant \frac{\gamma q_{E}\left(z^{*} \mid x_{0}\right)}{p\left(z^{*} \mid x^{*}\right)} \cdot p_{X}\left(x_{0}\right) \text { with probability } \geqslant 1-\delta
\end{align*}
$$

by assumptions (A1) and (A2) combined via the union bound. Finally, from the definitions in REVISE, we have that $z^{*} \in \mathcal{C}_{x_{0}}$, which implies $q_{E}\left(z^{*} \mid x^{*}\right) \geqslant \alpha$.

Lemma 1. If (Al) holds, then for $z^{*}$ defined in REVISE: $z^{*} \in B_{R}(0)$ with probability $\geqslant 1-\frac{\delta}{2}$ (over $x_{0} \sim p_{X}$ ).
Proof. Recall that $B_{R}(0)$ is defined as the Euclidean ball of radius $R$ centered around 0 . We show:

$$
\begin{equation*}
\left\|z^{*}-E\left(x_{0}\right)\right\| \leqslant \frac{1}{2} R \tag{17}
\end{equation*}
$$

and with probability $\geqslant 1-\frac{\delta}{2}$ :

$$
\begin{equation*}
\left\|E\left(x_{0}\right)\right\| \leqslant \frac{1}{2} R \tag{18}
\end{equation*}
$$

Subsequently, the triangle inequality completes the proof.
To prove (17), we recall that from our definition in (3): $q_{E}\left(z \mid x_{0}\right)$ is a Gaussian distribution with mean $E\left(x_{0}\right)$ and diagonal covariance $\Sigma_{z \mid x}$ where each entry is $\leqslant 1$. Furthermore, the definitions in REVISE ensure $z^{*} \in \mathcal{C}_{x_{0}} \Longrightarrow q\left(z^{*} \mid x_{0}\right) \geqslant \alpha$. Defining $K=-2 \log \left[(2 \pi)^{d / 2}\left|\Sigma_{z \mid x}\right|^{1 / 2} \alpha\right]$ which specifies the level- $\alpha$ isocontour of the $N\left(0, \Sigma_{z \mid x}\right)$ density, we have:

$$
\begin{aligned}
& q\left(z^{*} \mid E\left(x_{0}\right) \geqslant \alpha\right. \\
\Longrightarrow & \left(z^{*}-E\left(x_{0}\right)\right)^{T} \Sigma_{z \mid x}^{-1}\left(z^{*}-E\left(x_{0}\right)\right) \leqslant K \\
\Longrightarrow & \left\|z^{*}-E\left(x_{0}\right)\right\| \leqslant \sqrt{K \cdot \lambda_{\max }\left(\Sigma_{z \mid x}\right)} \leqslant \frac{1}{2} R_{1}
\end{aligned}
$$

where $\lambda_{\max }\left(\Sigma_{z \mid x}\right)$ is the largest eigenvalue of $\Sigma_{z \mid x}$ and $\lambda_{\max }\left(\Sigma_{z \mid x}\right) \leqslant 1,\left|\Sigma_{z \mid x}\right|^{1 / 2} \leqslant 1$ for our $q_{E}(z \mid x)$.
Now, define $\mathcal{R}=\left\{x \in \mathcal{X}: E(x)>\frac{1}{2} R\right\}$, and let $\widetilde{Z} \sim q_{Z}$ as defined in (10). To prove (18), we note that for all $x \in \mathcal{R}$ : $q_{E}(z \mid x)$ is a diagonal Gaussian distribution centered around $E(x)$ which has norm $>R / 2$. Thus:

$$
\begin{aligned}
\frac{\gamma}{4} \cdot p_{X}(\mathcal{R}) & <\gamma \sum_{x \in \mathcal{R}} \int_{\|z\| \geqslant \frac{1}{2} R} q_{E}(z \mid x) \mathrm{d} z p(x)=\gamma \cdot \operatorname{Pr}\left(\|\widetilde{Z}\| \geqslant \frac{1}{2} R\right) \\
& \leqslant \operatorname{Pr}\left(\|Z\| \geqslant \frac{1}{2} R\right) \quad \text { by the second condition in (A1) } \\
& \leqslant \operatorname{Pr}\left(\|Z\| \geqslant \frac{1}{2} R_{2}\right) \quad \text { as we defined } R \geqslant R_{2}
\end{aligned}
$$

Since $Z \sim N(0, \mathbf{I})$ under our prior, $\|Z\|^{2} \sim \chi_{d}^{2}$.
Applying the Chernoff bound to the tail of the $\chi^{2}$ distribution (Dasgupta \& Gupta, 2002), we thus obtain:

$$
\operatorname{Pr}\left(\|Z\|^{2} \geqslant \frac{1}{4} R_{2}^{2}\right) \leqslant\left[\frac{1}{4} R_{2}^{2} \cdot \exp \left(1-\frac{1}{4} R_{2}^{2}\right)\right]^{d / 2} \leqslant\left[\exp \left(1-\frac{1}{16} R_{2}^{2}\right)\right]^{d / 2}
$$

which implies $p_{X}(\mathcal{R})<\delta / 2$ by our definition of $R_{2}$.

## Proof of Theorem 2.

For $\epsilon \in(0,1]$, let $B_{\epsilon}(z)$ denote the $\epsilon$-ball centered at $z$. We have:

$$
\begin{aligned}
& p_{X}\left(x^{*}\right)=\int p_{D}\left(x^{*} \mid z\right) p_{Z}(z) \mathrm{d} z \\
\geqslant & \operatorname{Pr}\left(Z \in B_{\epsilon}\left(z^{*}\right)\right)\left[p_{D}\left(x^{*} \mid z^{*}\right)-L \epsilon\right]
\end{aligned}
$$

assuming $z^{*} \in B_{R}(0)$, which occurs with probability $\geqslant 1-\delta / 2$ by Lemma 1

$$
\begin{align*}
& \geqslant \operatorname{Pr}\left(Z \in B_{\epsilon}\left(z^{*}\right)\right)\left[p_{D}\left(x_{0} \mid z^{*}\right)-L \epsilon\right]  \tag{16}\\
& =\operatorname{Pr}\left(Z \in B_{\epsilon}\left(z^{*}\right)\right)\left[\frac{p\left(z^{*} \mid x_{0}\right)}{p_{Z}\left(z^{*}\right)} p_{X}\left(x_{0}\right)-L \epsilon\right] \\
& \geqslant \operatorname{Pr}\left(Z \in B_{\epsilon}\left(z^{*}\right)\right)\left[\gamma \frac{q_{E}\left(z^{*} \mid x_{0}\right)}{p_{Z}\left(z^{*}\right)} p_{X}\left(x_{0}\right)-L \epsilon\right]
\end{align*}
$$

assuming $z^{*} \in B_{R}(0)$ and $x_{0}$ satisfies the (A1) inequality, which occurs with probability $\geqslant 1-\delta$ by the union bound $\geqslant \frac{\operatorname{Pr}\left(Z \in B_{\epsilon}\left(z^{*}\right)\right)}{p_{Z}\left(z^{*}\right)}\left[\gamma \alpha p_{X}\left(x_{0}\right)-L \epsilon\right] \quad$ since $p_{Z}\left(z^{*}\right)<1$ and $z^{*} \in \mathcal{C}_{x_{0}} \Longrightarrow q_{E}\left(z^{*} \mid x_{0}\right) \geqslant \alpha$

$$
\begin{aligned}
& \quad \min p_{Z}\left(z^{*}+\Delta\right) \\
& p_{Z}\left(z^{*}\right) \\
& \operatorname{Vol}\left(B_{\epsilon}\left(z^{*}\right)\right)\left[\gamma \alpha p_{X}\left(x_{0}\right)-L \epsilon\right] \\
& \geqslant \exp \left(-\frac{1}{2}\left[\left\|z^{*}\right\| \epsilon+\epsilon^{2}\right]\right) \operatorname{Vol}\left(B_{\epsilon}\left(z^{*}\right)\right)\left[\gamma \alpha p_{X}\left(x_{0}\right)-L \epsilon\right]
\end{aligned}
$$

$$
\text { where } \operatorname{Vol}(\cdot) \text { denotes the Lebesgue measure }
$$

by exploiting the fact that $p_{Z}=N(0, I)$ and subsequent application of the Cauchy-Schwarz inequality

$$
\geqslant \exp \left(-\frac{\left\|z^{*}\right\|+1}{2}\right) \cdot \operatorname{Vol}\left(B_{\epsilon}\left(z^{*}\right)\right) \cdot\left[\gamma \alpha p_{X}\left(x_{0}\right)-L \epsilon\right]
$$

$$
\geqslant \exp \left(-\frac{R+1}{2}\right) \cdot \operatorname{Vol}\left(B_{\epsilon}\left(z^{*}\right)\right) \cdot\left[\gamma \alpha p_{X}\left(x_{0}\right)-L \epsilon\right] \quad \text { since we already assumed } z^{*} \in B_{R}(0)
$$

We conclude the proof by selecting $\epsilon=\frac{\gamma \alpha(d+1)}{L(d+2)} p_{X}\left(x_{0}\right)$ which maximizes the lower bound given above.

## Proof of Theorem 3.

Suppose for $x_{0} \in \mathcal{R}$, the corresponding revision $x^{*} \notin \mathcal{E}$. Then:

$$
\begin{aligned}
\operatorname{Pr}(X \in \mathcal{E} \cap \mathcal{R}) & \leqslant 1-p_{X}\left(x^{*}\right)-\operatorname{Pr}(X \in \mathcal{E} \backslash \mathcal{R}) \\
& \leqslant 1-\kappa-\operatorname{Pr}(X \in \mathcal{E} \backslash \mathcal{R})
\end{aligned}
$$

Since (A5) implies $\operatorname{Pr}\left(X \in \mathcal{E}^{C}\right)<\kappa$, we also have:

$$
\begin{aligned}
\operatorname{Pr}(X \in \mathcal{E} \cap \mathcal{R}) & =1-\operatorname{Pr}\left(X \in \mathcal{E}^{C}\right)-\operatorname{Pr}(X \in \mathcal{E} \backslash \mathcal{R}) \\
& >1-\kappa-\operatorname{Pr}(X \in \mathcal{E} \backslash \mathcal{R})
\end{aligned}
$$

which is a contradiction. Thus, we must have $x^{*} \in \mathcal{E}$ if $x_{0} \in \mathcal{R}$, which occurs with probability $\geqslant 1-\delta / 2$.
Lemma 1 ensures that under (A1): $z^{*} \in B_{R}(0)$ with probability $\geqslant 1-\delta / 2$, implying $\left|F\left(z^{*}\right)-F\left(E\left(D\left(z^{*}\right)\right)\right)\right| \leqslant \epsilon_{\text {inv }}$ with the same probability. Consequently, we have:

$$
\begin{array}{rlr} 
& \left.F\left(z^{*}\right)\right)-F\left(E\left(x_{0}\right)\right) \leqslant F\left(E\left(D\left(z^{*}\right)\right)-F\left(E\left(x_{0}\right)\right)+\epsilon_{\mathrm{inv}}\right. & \quad \text { with probability } \geqslant 1-\frac{\delta}{2} \\
\leqslant & F\left(E\left(x^{*}\right)\right)-\mathbb{E}\left[Y \mid X=x_{0}\right]+\epsilon_{\mathrm{inv}}+\epsilon_{\mathrm{mse}} \quad \text { with probability } \geqslant 1-\frac{\delta}{2}-\kappa \text { by the union bound } \\
\leqslant & \mathbb{E}\left[Y \mid X=x^{*}\right]-\mathbb{E}\left[Y \mid X=x_{0}\right]+\epsilon_{\mathrm{inv}}+2 \epsilon_{\mathrm{mse}} \quad \text { with probability } \geqslant 1-\frac{\delta}{2}-\kappa-\frac{\delta}{2} \text { by the union bound }
\end{array}
$$

The inequality in the other direction is proved via similar reasoning.

## Additional References for the Supplementary Material

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