Crowdsourcing with Arbitrary Adversaries

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Abstract
Most existing works on crowdsourcing assume that the workers follow the Dawid-Skene model, or the one-coin model as its special case, where every worker makes mistakes independently of other workers and with the same error probability for every task. We study a significant extension of this restricted model. We allow almost half of the workers to deviate from the one-coin model and for those workers, their probabilities of making an error to be task-dependent and to be arbitrarily correlated. In other words, we allow for arbitrary adversaries, for which not only error probabilities can be high, but which can also perfectly collude. In this adversarial scenario, we design an efficient algorithm to consistently estimate the workers’ error probabilities.

1. Introduction
Crowdsourcing is an omnipresent phenomenon: it has emerged as an integral part of the machine learning pipeline in recent years, and one reason for the great advances in deep learning is the presence of large data sets that have been labeled by the crowd (e.g., Deng et al., 2009; Krizhevsky, 2009). Crowdsourcing is also at the heart of peer grading systems (e.g., Alfaro & Shavlovsky, 2014), which help with rising enrollment at universities, and online rating systems (e.g., Liao et al., 2014), which many of us rely on when choosing the next restaurant, to provide just a few examples.

A crowdsourcing scenario consists of a set of workers and a set of tasks that need to be solved. A data curator utilizing crowdsourcing can aim at estimating various quantities of interest. The first goal might be to estimate the true labels or answers for the tasks at hand. Typically, additional constraints are involved here such as a worker not being willing to solve too many tasks and the data curator wanting to get high-quality labels at a low price. The canonical example of this case is the Amazon Mechanical Turk™. There one cannot track specific workers as they are fleeting. However, in scenarios such as peer grading or online rating systems, a second goal might be to estimate worker qualities, especially if workers can be reused at a later time.

In a seminal paper, Dawid & Skene (1979) proposed a formal model that involves worker quality parameters for crowdsourcing scenarios in the context of classification. The Dawid-Skene model has become a standard theoretical framework and has led to a flurry of research over the past few years (Liu et al., 2012; Raykar & Yu, 2012; Li et al., 2013; Gao et al., 2016; Zhang et al., 2016; Khetan et al., 2017), in particular in its special symmetric form usually referred to as one-coin model (Ghosh et al., 2011; Karger et al., 2011a;b; Dalvi et al., 2013; Gao & Zhou, 2013; Karger et al., 2014; Bonald & Combes, 2017; Ma et al., 2017). In its general form for binary classification problems, the Dawid-Skene model assumes that for each worker, the probability of providing the wrong label only depends on the true label of the task, but not on the task itself. Moreover, given the true label, the responses provided by different workers are independent. The one-coin model additionally assumes that for each worker, the probability of providing the wrong label is the same for both classes. We will formally introduce the one-coin model in Section 2. A discussion of prior work is provided in Section 5 and Appendix A.

The crucial limitation of the Dawid-Skene and one-coin model is the assumption that workers’ error probabilities are task-independent. In particular, this excludes the possibility of colluding adversaries (other than those that provide the wrong label all of the time), which might make these models a poor approximation of the real world encountered in such applications as peer grading or online rating. In this paper, we study a significant extension of the one-coin model that allows for arbitrary, highly colluding adversaries. We provide an algorithm for estimating the workers’ error probabilities and prove that it asymptotically recovers the true error probabilities. Using our estimates of the error probabilities in weighted majority votes, we also provide strategies to estimate ground-truth labels of the tasks. Experiments on both synthetic and real data show that our approach clearly outperforms existing methods in the presence of adversaries.
2. Setup and problem formulation

We first describe a general model for crowdsourcing with non-adaptive workers and binary classification tasks: there are \( n \) workers \( w_1, \ldots, w_n \) and an i.i.d. sample of \( m \) task-label pairs \((x_i, y_i)\) for \( i = 1, \ldots, m \), where \( D \) is a joint probability distribution over tasks \( x \in \mathcal{X} \) and corresponding labels \( y \in \{-1, +1\} \). There is a variable \( g_{ij} \in \{0, 1\} \), indicating whether worker \( w_j \) is present with task \( x_i \) (for \( k \in \mathbb{N} \), we use \( |k| \) to denote the set \( \{1, \ldots, k\} \)). If \( w_j \) is present with \( x_i \), that is \( g_{ij} = 1 \), \( w_j \) provides an estimate \( w_j(x_i) \in \{-1, +1\} \) of the ground-truth label \( y_i \). Let \( A \subseteq \{-1, 0, +1\}^{m \times n} \) be a matrix that stores all the responses collected from the workers: \( A_{ij} = w_j(x_i) \) if \( g_{ij} = 1 \) and \( A_{ij} = 0 \) if \( g_{ij} = 0 \).

We assume that each worker \( w_j \) follows some (probabilistic or deterministic) strategy such that \( w_j(x_i) \) only depends on \( x_i \). In particular, given \( x_i \), any two different workers’ responses \( w_j(x_i) \) and \( w_k(x_i) \) and the ground-truth label \( y_i \) are independent. Let \( \varepsilon_{w_j}(x, y) \in [0, 1] \) be the conditional error probability that, given \( x \) and \( y \), \( w_j(x) \) does not equal \( y \), that is

\[
\varepsilon_{w_j}(x, y) := \Pr_{x,y \sim D, w_j}[w_j(x) \neq y \mid (x, y)].
\]

Note that the unconditional probability of \( w_j(x) \) being incorrect, before seeing \( x \) and \( y \), is given by

\[
\Pr_{x,y \sim D, w_j}[w_j(x) \neq y] = \mathbb{E}_{x,y \sim D}\varepsilon_{w_j}(x, y) =: \varepsilon_{w_j}.
\]

Now one may study the following questions:

(i) Given only the matrix \( A \), how can we estimate the ground-truth labels \( y_1, \ldots, y_n \)?

(ii) Given only the matrix \( A \), how can we estimate the workers’ unconditional error probabilities \( \varepsilon_{w_1}, \ldots, \varepsilon_{w_n} \)?

(iii) If we can choose \( g_{ij} \) (either in advance of collecting workers’ responses or adaptively while doing so), how should we choose it such that we can achieve (i) or (ii) with a minimum number of collected responses?

In case of \( \varepsilon_{w_j}(x, y) \) as defined in (1) being constant on \( \mathcal{X} \times \{-1, +1\} \), that is \( \varepsilon_{w_j}(x, y) \equiv \varepsilon_{w_j} \), for all \( j \in [n] \), our model boils down to what is usually referred to as the one-coin model (e.g., Szepesvari, 2015), for which (i) to (iii) have been studied extensively (see Section 5 and Appendix A for references and a detailed discussion). With this paper we initiate the study of a significant extension of the one-coin model. We will allow almost half of the workers to deviate from the one-coin model and for such a worker \( w_j \), the conditional error probability \( \varepsilon_{w_j}(x, y) \) to be a completely arbitrary random variable. In other words, we will allow for arbitrary adversaries, for which not only error probabilities can be high, but for which error probabilities can be arbitrarily correlated. We mainly study (ii) in this scenario. We then make use of existing results for the one-coin model to answer (i) satisfactorily for our purposes. We do not deal with (iii), but instead assume that \( g_{ij} \) has been specified in advance.

3. General outline of our approach

In this section we want to present the general outline of our approach. A key insight is that the unconditional probability of workers \( w_j \) and \( w_k \) being agreeing is given by

\[
\Pr_{(x,y) \sim D, w_j, w_k}[w_j(x) = w_k(x)] = 1 - \varepsilon_{w_j} - \varepsilon_{w_k} + 2\varepsilon_{w_j}\varepsilon_{w_k} + 2\text{Cov}_{(x,y) \sim D}[\varepsilon_{w_j}(x, y), \varepsilon_{w_k}(x, y)].
\]

(2)

\[
\text{Cov}_{(x,y) \sim D}[\varepsilon_{w_j}(x, y), \varepsilon_{w_k}(x, y)]
\]

denotes the covariance between random variables \( \varepsilon_{w_j}(x, y) \) and \( \varepsilon_{w_k}(x, y) \), that is

\[
\text{Cov}_{(x,y) \sim D}[\varepsilon_{w_j}(x, y), \varepsilon_{w_k}(x, y)] = \mathbb{E}_{(x,y) \sim D}[\varepsilon_{w_j}(x, y) - \varepsilon_{w_j}][\varepsilon_{w_k}(x, y) - \varepsilon_{w_k}].
\]

A proof of (2) can be found in Appendix B. The probability on the left-hand side of (2) can be easily estimated from \( A \) by the ratio of the number of tasks that \( w_j \) and \( w_k \) agreed on to the number of tasks they were both presented with:

\[
\Pr[w_j(x) = w_k(x)] \approx \frac{\sum_{i=1}^m g_{ij}g_{ik}1\{A_{ij} = A_{ik}\}}{\sum_{i=1}^m g_{ij}g_{ik}} =: p_{jk}.
\]

(3)

This suggests to solve the system of equations

\[
1 - \varepsilon_j - \varepsilon_k + 2\varepsilon_j\varepsilon_k + 2c_{jk} = p_{jk}, \quad 1 \leq j < k \leq n,
\]

(4)

in the unknowns \( \varepsilon_j, l \in [n] \), and \( c_{jk}, 1 \leq j < k \leq n \), in order to obtain estimates of the workers’ unconditional error probabilities \( \varepsilon_{w_1}, \ldots, \varepsilon_{w_n} \). However, there is a catch: in general, the system (4) is not identifiable and has several solutions. We will assume that at least \( n^2 + 2 \) of the workers follow the one-coin model and have error probabilities smaller than one half. A worker \( w_j \) following the one-coin model implies

\[
\text{Cov}_{(x,y) \sim D}[\varepsilon_{w_j}(x, y), \varepsilon_{w_k}(x, y)] = 0, \quad \forall k \neq j,
\]

(5)

and hence under this assumption we can restrict the search for solutions of (4) to \( \varepsilon_j, l \in [n] \), and \( c_{jk}, 1 \leq j < k \leq n \), with the property that

\[
\exists L \subseteq [n] \text{ with } |L| \geq n/2 + 2 \text{ such that } \forall j \in L : (\varepsilon_j < 1/2 \land [\forall k \neq j : c_{jk} = 0]).
\]

(6)

Throughout the paper, we set \( c_{jk} = c_{kj} \) if \( j > k \). We also assume \( p_{jk} = p_{kj} \).
Proof. is 4.2. Identifiability and approximate solution equality and the union bound yields the result.

If the workers satisfy our assumption and \( p_{jk} \) on the right-hand side of (4) are actually true agreement probabilities, then \( \varepsilon_l = \varepsilon_{w_1} \) and \( c_{jk} = \text{Cov}[\varepsilon_{w_j}(x,y), \varepsilon_{w_k}(x,y)] \) is the unique solution of (4) that satisfies (6). But if \( p_{jk} \) are not exactly true agreement probabilities, there might be no solution of (4) with property (6) at all. We prove that if estimates \( p_{jk} \) are not too bad, we can solve (4) together with (6) approximately, and our approximate solution is guaranteed to be close to true error probabilities \( \varepsilon_{w_1}, \ldots, \varepsilon_{w_n} \), and covariances \( \text{Cov}[\varepsilon_{w_j}(x,y), \varepsilon_{w_k}(x,y)] \), \( j < k \). This answers (ii) from Section 2 and is the main contribution of our paper:

**Main result.** Assume that at least \( \frac{n}{2} + 2 \) of the workers follow the one-coin model and have error probabilities not greater than \( \gamma_{\text{TR}} < \frac{1}{2} \). If \( |\text{Pr}[w_j(x) = w_k(x)] - p_{jk}| \leq \beta \) for all \( j \neq k \) and \( \beta \) sufficiently small, we can compute estimates \( \hat{\varepsilon}_{w_1}, \ldots, \hat{\varepsilon}_{w_n} \) of \( \varepsilon_{w_1}, \ldots, \varepsilon_{w_n} \) such that

\[
|\varepsilon_{w_i} - \hat{\varepsilon}_{w_i}| \leq C(\gamma_{\text{TR}}) \cdot \beta^{1/4}.
\]

We answer (i) from Section 2 and provide two ways to predict ground-truth labels \( y_1, \ldots, y_m \) by taking weighted majority votes over the responses provided by the workers. In these majority votes, the weights depend on our estimates of true error probabilities \( \varepsilon_{w_1}, \ldots, \varepsilon_{w_n} \).

4. Details and analysis

4.1. Estimating agreement probabilities

If \( g_{ij} \) has been specified in advance, we have the following guarantee on the quality of the estimates \( p_{jk} \) (see (3)):

**Lemma 1.** Assume \( \sum_{i=1}^{m} g_{ij} g_{ik} > 0 \), \( j \neq k \). Let \( \delta > 0 \) and

\[
\beta_{jk} = \min \left\{ 1, \left[ \ln(2n^2/\delta)/\left(2\sum_{i=1}^{m} g_{ij} g_{ik}\right) \right]^{1/2} \right\}.
\]

Then we have with probability at least \( 1 - \delta \) over the sample \((x_i, y_i)_{i=1}^{m}\) and the randomness in workers’ strategies that

\[
|\text{Pr}[w_j(x) = w_k(x)] - p_{jk}| \leq \beta_{jk}, \quad 1 \leq j < k \leq n.
\]

**Proof.** A straightforward application of Hoeffding’s inequality and the union bound yields the result.

4.2. Identifiability and approximate solution

If all workers follow the one-coin model, that is \( \varepsilon_{w_j}(x,y) \equiv \varepsilon_{w_j} \) for all \( j \in [n] \), we have

\[
\text{Cov}(x,y)_{x,y} \sim D[\varepsilon_{w_j}(x,y), \varepsilon_{w_k}(x,y)] = 0, \quad 1 \leq j < k \leq n,
\]

and system (4) reduces to

\[
1 - \varepsilon_{j} - \varepsilon_{k} + 2\varepsilon_{j}\varepsilon_{k} = p_{jk}, \quad 1 \leq j < k \leq n,
\]

in the unknowns \( \varepsilon_{l}, \ l \in [n] \). It is well known that, in general, even (7) is not identifiable. For example, if \( p_{jk} = 1 \) for all \( 1 \leq j < k \leq n \), there are the two solutions \( \varepsilon_{l} = 0, \ l \in [n] \), and \( \varepsilon_{l} = 1, \ l \in [n] \), corresponding to either all perfect or all completely erroneous workers. On the other hand, the system (7) is identifiable if we assume that on average workers are better than random guessing, that is

\[
\frac{1}{n} \sum_{j=1}^{n} \varepsilon_{w_j} < \frac{1}{2},
\]

and there are at least three informative workers with \( \varepsilon_{w_j} \neq \frac{1}{2} \) (Bonald & Combès, 2017).

Clearly, these two conditions do not guarantee identifiability of the general system (4). The next lemma shows that even if we additionally assume half of the workers to follow the one-coin model, the system (4) is not identifiable. Here we only state an informal version of the lemma. A detailed version and its proof can be found in Appendix B. 

**Lemma 2.** There exists an instance of the system (4), where \( n \) is even, that has two different solutions. In both solutions, it holds that \( \varepsilon_{l} < \frac{1}{2}, \ l \in [n] \). Furthermore:

(a) In the first solution, \( c_{jk} = 0 \) for all \( j \in [\frac{n}{2}] \) and \( k \neq j \), and \( \varepsilon_{l} \) is small if \( l \in [\frac{n}{2}] \) and big if \( l \in [n\setminus\frac{n}{2}] \).

(b) In the second solution, \( c_{jk} = 0 \) for all \( j \in [n\setminus\frac{n}{2}] \) and \( k \neq j \), and \( \varepsilon_{l} \) is small if \( l \in [n\setminus\frac{n}{2}] \) and big if \( l \in [\frac{n}{2}] \).

We want to mention that a solution of (4) does not necessarily correspond to actual workers, that is given \( \varepsilon_{l}, \ l \in [n] \), and \( c_{jk}, \ 1 \leq j < k \leq n \), there might be no collection of workers \( w_1, \ldots, w_n \) such that \( \varepsilon_{w_j} = \varepsilon_{l} \) and \( \text{Cov}[\varepsilon_{w_j}(x,y), \varepsilon_{w_k}(x,y)] = c_{jk} \). By the Bhattacharya-Davis inequality (Bhatia & Davis, 2010) it holds that

\[
\text{Var}[\varepsilon_{w_j}(x,y)] \leq \varepsilon_{w_j} - \varepsilon_{w_2}^2.
\]

Hence, a necessary condition for a solution to correspond to actual workers is that \( c_{jk} \leq (\varepsilon_{j} - \varepsilon_{k}^2)^{1/2} (\varepsilon_{k} - \varepsilon_{2}^2)^{1/2} \) (in addition to \( \varepsilon_{l} \in [0, 1] \)). The two solutions in Lemma 2 correspond to actual workers.

From now on we assume that at least \( \frac{n}{2} + 2 \) workers follow the one-coin model and have error probabilities smaller than one half:

**Assumption A.** There exists \( L \subseteq [n] \) with \( |L| \geq n/2 + 2 \) such that for all \( j \in L \), the worker \( w_j \) follows the one-coin model with error probability \( \varepsilon_{w_j} < 1/2 \).

This corresponds to considering (4) together with the constraint (6). The system (4) together with (6) is identifiable: 

**Proposition 1.** There exists at most one solution of system (4) that has property (6).

2All results of Section 4.2 hold true if we assume, more generally, the existence of \( L \subseteq [n] \) with \( |L| \geq n/2 + 2 \) such that (5) together with \( \varepsilon_{w_j} < 1/2 \) holds for all \( j \in L \).
Proof. Assuming there are two solutions \((\varepsilon_1^{S_1})_{i \in [n]}, (c_{jk}^{S_1})_{1 \leq j < k \leq n}\) and \((\varepsilon_1^{S_2})_{i \in [n]}, (c_{jk}^{S_2})_{1 \leq j < k \leq n}\) with \(L_1\) and \(L_2\) satisfying (6), there have to be pairwise different \(i_1, i_2, i_3 \in L_1 \cap L_2\). It is easy to see that \((\varepsilon_1^{S_1}, i_1, c_{i_1}^{S_1})\) and \((\varepsilon_1^{S_2}, i_2, c_{i_2}^{S_2})\) and consequently also all the other components of the two solutions have to coincide. Details can be found in Appendix B. \(\square\)

If \(p_{jk}\) at the right-hand side of (4) are true agreement probabilities, the true error probabilities \(\varepsilon_{w_1}, \ldots, \varepsilon_{w_n}\) and covariances \(\text{Cov} [\varepsilon_{w_1}(x, y), \varepsilon_{w_2}(x, y)]\), \(j < k\), make up the unique solution of (4) that satisfies (6), but if \(p_{jk}\) are not exactly true agreement probabilities, there might be no solution of (4) that satisfies (6) at all. Our goal is then to find a solution of (4) that satisfies (6) approximately and to show that our approximate solution has to be close to \(\varepsilon_{w_1}, \ldots, \varepsilon_{w_n}\) and \(\text{Cov} [\varepsilon_{w_1}(x, y), \varepsilon_{w_2}(x, y)]\), \(j < k\). As a first step towards this goal, we shall need a generalization of Proposition 1:

**Proposition 2.** Let \(\gamma < 1/2\) and \(\nu < 1/8 - \gamma/2 + \gamma^2/2\). If there exist two solutions \((\varepsilon_1^{S_1})_{i \in [n]}, (c_{jk}^{S_1})_{1 \leq j < k \leq n}\), \(i \in \{1, 2\}\), of system (4) (where \(p_{jk} \in [0, 1]\) with the property that \(\varepsilon_i^{S_1} \in [0, 1], i \in [n]\), and

\[
\exists L_i \subseteq [n] \text{ with } |L_i| \geq n/2 + 2 \text{ such that } \\
\forall j \in L_i : \left( \varepsilon_j^{S_1} \leq \gamma \wedge \left[ \forall k \neq j : |c_{jk}^{S_1}| \leq \nu \right] \right),
\]

then

\[
|\varepsilon_1^{S_1} - \varepsilon_2^{S_1}| \leq G(\gamma, \nu) \sqrt{\nu}, \\
|c_{jk}^{S_1} - c_{jk}^{S_2}| \leq 3G(\gamma, \nu) \sqrt{\nu}
\]

for \(l \in [n], j < k\), where \(G(\gamma, \nu) \rightarrow G(\gamma) > 0\) as \(\nu \rightarrow 0\).

The proof of Proposition 2, which provides an explicit expression for \(G(\gamma, \nu)\), can be found in Appendix B.

In a next step, we assume that we are given pairwise different \(i_1, i_2, i_3 \in [n]\) such that \(w_{i_1}, w_{i_2}, w_{i_3}\) follow the one-coin model with \(\varepsilon_{w_{i_1}}, \varepsilon_{w_{i_2}}, \varepsilon_{w_{i_3}} < 1/2\). In this case, assuming that estimates \(p_{jk}\) are close to true agreement probabilities, we can construct a solution of (4) that is guaranteed to be close to the true error probabilities and covariances (and hence approximately satisfies (6)). This is made precise in the next lemma (its proof can be found in Appendix B).

**Lemma 3.** Let \(\gamma_{TR} < 1/2\) and consider the system (4) with \(p_{jk}^{TR} \in [0, 1]\) as right-hand side. Assume there exists a solution \(^3(\varepsilon_1^{TR})_{i \in [n]}, (c_{jk}^{TR})_{1 \leq j < k \leq n}\) with the property that \(\varepsilon_1^{TR} \in [0, 1]\) and

\[
\exists L^{TR} \subseteq [n] \text{ with } |L^{TR}| \geq n/2 + 2 \text{ such that } \\
\forall j \in L^{TR} : \left( \varepsilon_j^{TR} \leq \gamma_{TR} \wedge \left[ \forall k \neq j : c_{jk}^{TR} = 0 \right] \right).
\]

Now consider the system (4) with \(p_{jk} \in [0, 1]\) as right-hand side. Assume that \(|p_{jk}^{TR} - p_{jk}| \leq \beta\) for all \(j \neq k\), where

\[\beta\] satisfies \(\beta < 1/2 - 2\gamma_{TR} + 2\nu_{TR}\). Let \(i_1, i_2, i_3 \in [n]\) be pairwise different and set

\[
B := -2 + 4p_{i_1 i_3}, \\
C := 1 + 2p_{i_2 i_3} - p_{i_2 i_3} - p_{i_1 i_2} - p_{i_1 i_3} - p_{i_2 i_3}, \\
\varepsilon_{i_2}^{R} := \frac{1}{2} - \frac{\sqrt{B + 4C}}{2\sqrt{B}}, \\
\varepsilon_{i_2}^{S} := \min(\gamma_{TR}, \max(0, \varepsilon_{i_2}^{R}))
\]

and for all \(l \neq i_2\) and for all \(1 \leq j < k \leq n\)

\[
\varepsilon_{i_l}^{R} := \frac{p_{l i_2} - \varepsilon_{i_2}^{S}}{2\varepsilon_{i_2}^{S} - 1}, \\
\varepsilon_{i_l}^{S} := \begin{cases} 
\min(\gamma_{TR}, \max(0, \varepsilon_{i_l}^{R})) & \text{if } l \in \{i_1, i_3\} \\
\min(1, \max(0, \varepsilon_{i_l}^{R})) & \text{if } l \notin \{i_1, i_3\}, 
\end{cases}
\]

\[
c_{jk}^{S} := \frac{p_{jk} - \left( 1 - \varepsilon_{j}^{S} - \varepsilon_{k}^{S} + 2\varepsilon_{j}^{S}\varepsilon_{k}^{S} \right)}{2}
\]
Assuming that every worker is presented with every task, the property (8) too, Proposition 2 guarantees that
\[ |\varepsilon_{TR}^{i} - \varepsilon_{TR}^{S}| \leq \sqrt{3H(\gamma_{TR}, \beta)^{\sqrt{3} \beta + \frac{\beta}{2}}} \cdot \\
G \left( \gamma_{TR} + H(\gamma_{TR}, \beta)^{\sqrt{3} \beta} \cdot 3H(\gamma_{TR}, \beta)^{\sqrt{3} \beta + \frac{\beta}{2}} \right) \sim \beta^{1/4} \cdot \text{(14)} \]
for all \( l \in [n] \) and a similar bound on \( |\varepsilon_{TR}^{i} - \varepsilon_{TR}^{S}| \), \( j < k \).
If \((\varepsilon_{TR}^{S})_{i \in [n]}, (c_{jk}^{S})_{1 \leq j < k \leq n}\) does not satisfy (8), we discard \((i_1, i_2, i_3)\) and start anew. Note that under our Assumption A, the probability of choosing \(i_1, i_2, i_3\) such that \(i_1, i_2, i_3 \in L^{TR}\) is greater than 1/8. In expectation we have to discard \((i_1, i_2, i_3)\) for not more than eight times before finding a solution that satisfies (8) and hence (14).

Assuming that every worker is presented with every task, that is \(g_{ij} = 1\) for all \(i \in [m]\) and \(j \in [n]\), it follows from Lemma 1 and (14) that \(m\) has to scale as \(\ln(n^2/\delta)/\rho^2\) in order that the described strategy is guaranteed to yield, with probability at least \(1 - \delta\), estimates \(\varepsilon_{TR}^{S}, \ldots, \varepsilon_{TR}^{S}\) satisfying \(|\varepsilon_{TR}^{i} - \varepsilon_{TR}^{S}| \leq \rho, l \in [n]\). This is significantly larger than the rate \(m \sim \ln(n^2/\delta)/\rho^2\) required by the TE algorithm, which solves the estimation problem for the error probabilities in the one-coin model and is claimed to be minimax optimal (Bonald & Combes, 2017). We suspect that our rate with its dependence on \(\rho^{-2}\) is not optimal and consider it to be an interesting follow-up question to study the minimax rate for our extension of the one-coin model.

Although the convergence rate that we can guarantee for the described strategy is slow, we might still hope that the strategy performs better in practice. However, there is an issue that we have to overcome. Unless \(\beta\) is very small, \(\gamma\) and \(\nu\) as specified in (13) are too big for being meaningful, that is any solution \((\varepsilon_{TR}^{S})_{i \in [n]}, (c_{jk}^{S})_{1 \leq j < k \leq n}\) as defined in (10) and (11) will satisfy (8) with these values. We will not discard any \((i_1, i_2, i_3)\), regardless of whether \(i_1, i_2, i_3 \in L^{TR}\) holds or not. We deal with this issue by adapting the strategy as follows: for every \(p = (i_1, i_2, i_3) \in P\), we construct \((\varepsilon_{TR}^{S}(p))_{i \in [n]}, (c_{jk}^{S}(p))_{1 \leq j < k \leq n}\) as defined in (10) and (11). We set \(Q^P = [n]\) unless \(\gamma\) as specified in (13) is smaller than one, in which case we set \(Q^P = \{l \in [n]: \varepsilon_{TR}^{S}(p) \leq \gamma\}\) and discard any solution \((\varepsilon_{TR}^{S}(p))_{i \in [n]}, (c_{jk}^{S}(p))_{1 \leq j < k \leq n}\) for which \(|Q^P| < \frac{n}{2} + 2\). Let \(\nu^P\) be the \(\frac{n}{2} + 2\)-th smallest element of \(\{\max_{k \in [n]\setminus\{l\}}|\varepsilon_{TR}^{S}(p)|: l \in Q^P\}\). Then we finally return the solution \((\varepsilon_{TR}^{S}(p_0))_{i \in [n]}, (c_{jk}^{S}(p_0))_{1 \leq j < k \leq n}\) for which \(\nu^P\) is smallest, that is \(p_0 = \arg\min_{p} \nu^P\).

If \(\gamma\) is small enough, it follows from Proposition 2 that
\[ |\varepsilon_{TR}^{i} - \varepsilon_{TR}^{S}(p_0)| \leq \sqrt{\max\{\nu^P, \beta/2\}} \cdot \\
G \left( \gamma_{TR} + H(\gamma_{TR}, \beta)^{\sqrt{3} \beta} \cdot \max\{\nu^P, \beta/2\} \right) \cdot \text{(15)} \]

Note that if \(P\) contains at least one triple of indices \(i_1, i_2, i_3 \in L^{TR}\), then \(\nu_{i_1} \leq 3H(\gamma_{TR}, \beta)^{\sqrt{3} \beta + \frac{\beta}{2}}\), so that the guarantee (15) is at least as good as (14). We also expect \(\nu^P\) to be smaller the larger \(P\) is. Hence, we should choose \(P\) as large as we can afford due to computational reasons, but in practice, there is one more aspect that we have to consider. Depending on how \(g_{ij}\) has been chosen, there might be workers \(w_i\) and \(w_j\) that were presented with only a few common tasks or no common tasks at all. In this case, the estimate \(p_{jk}\) of the agreement probability between \(w_i\) and \(w_j\) is only poor and there is no uniform bound \(\beta\) on \(|p_{jk}^{TR} - p_{jk}|\) (where \(p_{jk}^{TR}\) are true agreement probabilities). We can deal with this aspect by choosing \(P\) in a way such that for all \(p \in P\), all estimates \(p_{jk}\) that are involved in the computation of \((\varepsilon_{TR}^{S}(p))_{i \in [n]}\) are somewhat reliable. We present a concrete implementation of this in Algorithm 1 below.

### 4.3. Predicting ground-truth labels

Once we have estimates \(\hat{\varepsilon}_{w_1}, \ldots, \hat{\varepsilon}_{w_n}\) of the true error probabilities \(\varepsilon_{w_1}, \ldots, \varepsilon_{w_n}\), we predict ground-truth labels \(y_i\) by taking a weighted majority vote over the responses collected for the task \(x_i\). Our estimate for \(y_i\) is given by
\[ \hat{y}_i = \text{sign} \left( \sum_{l=1}^{n} f(\hat{\varepsilon}_{w_l}) \cdot A_{il} \right), \hspace{1cm} (16) \]
where \(f : [0, 1] \rightarrow [-\infty, +\infty]\). Ties are broken uniformly at random. We consider two choices for the function \(f\).

It is well-known that if all workers follow the one-coin model with known error probabilities \(\varepsilon_{w_1}, \ldots, \varepsilon_{w_n}\), ground-truth labels are balanced, that is \(\text{Pr}(x,y)\sim_{D}[y = +1] = \text{Pr}(x,y)\sim_{D}[y = -1]\), and \(g_{ij}\) are independent Bernoulli random variables with common success probability \(\alpha > 0\), then the optimal estimator for the ground-truth label \(y_i\) is given by the weighted majority vote (16) with \(f(\hat{\varepsilon}_{w_l})\) replaced by \(f(\hat{\varepsilon}_{w_l}) = \ln((1 - \varepsilon_{w_l})/\varepsilon_{w_l})\) (Nitzan & Paroush, 1982; Berend & Kontorovitch, 2015; Bonald & Combes, 2017). Hence, a common approach for the one-coin model is to first estimate the true error probabilities and then to estimate ground-truth labels by using the majority vote (16) with \(f(\hat{\varepsilon}_{w_l}) = \ln((1 - \hat{\varepsilon}_{w_l})/\hat{\varepsilon}_{w_l})\) (Bonald & Combes, 2017; Ma et al., 2017). We propose to use the same majority vote, but restricted to answers from workers that we believe to follow the one-coin model. Using the notation from Section 4.2, this means that we set \(f(\hat{\varepsilon}_{w_l}) = \ln((1 - \hat{\varepsilon}_{w_l})/\hat{\varepsilon}_{w_l})\) for \(l \in Q^{p_0}\) with \(\max_{k \in [n]\setminus\{l\}}|\varepsilon_{TR}^{S}(p_0)| \leq \nu^{p_0}\) and \(f(\hat{\varepsilon}_{w_l}) = 0\) otherwise. Alternatively, we suggest to set \(f(\hat{\varepsilon}_{w_l}) = 1 - 2\hat{\varepsilon}_{w_l}\) for \(l \in [n]\). With this choice of \(f\) we make use of the responses provided by all workers. The same choice has been used for the one-coin model too (Dalvi et al., 2013). A third option would be to set \(f(\hat{\varepsilon}_{w_l}) = 1 - 2\hat{\varepsilon}_{w_l}\) for \(l \in Q^{p_0}\) with \(\max_{k \in [n]\setminus\{l\}}|\varepsilon_{TR}^{S}(p_0)| \leq \nu^{p_0}\) and \(f(\hat{\varepsilon}_{w_l}) = 0\) otherwise, but we do not consider this choice any further.
4.4. Algorithm

In the interests of clarity, we present our approach as self contained Algorithm 1. Choosing $P$ as the set of triples such that involved pairs of workers have been provided with at least ten or three common tasks might seem somewhat arbitrary here. Indeed, one could introduce two parameters to the algorithm instead. Without optimizing for these parameters, we chose them as ten and three in all our experiments on real data, and hence we state Algorithm 1 as is.

Our analysis best applies to the setting of a full matrix $A$ (or variables $g_{ij}$ that are independent Bernoulli random variables with common success probability, as it is assumed by Bonald & Combes, 2017, for example). In this case, which we consider in our experiments on synthetic data, choosing $P$ as stated in Algorithm 1 reduces to choosing $P$ as the set of all triples of pairwise different indices. If the number of workers $n$ is small, this is the best one can do. If $n$ is large, it is infeasible to choose $P$ as the set of all triples though since the running time of Algorithm 1 is in $O(n^2(m + |P|))$. If $n$ is large and $A$ full, one should sample $P$ uniformly at random. For $|P| \geq \ln \delta / \ln(7/8)$ our error guarantee (14) holds with probability at least $1 - \delta$ then (compare with Section 4.2).

5. Related work

We briefly survey related work here. A complete discussion can be found in Appendix A. As discussed in Sections 1 and 2, in crowdsourcing one might be interested in estimating ground-truth labels and/or worker qualities given the response matrix $A$, but also in optimal task assignment. In their seminal paper, Dawid & Skene (1979) proposed an EM based algorithm to address the first two goals. Since then numerous works have followed addressing all three goals for the Dawid-Skene and one-coin model (Ghosh et al., 2011; Karger et al., 2011a;b; 2013; 2014; Dalvi et al., 2013; Gao & Zhou, 2013; Gao et al., 2016; Zhang et al., 2016; Bonald & Combes, 2017; Ma et al., 2017). There have also been efforts to study generalizations of the Dawid-Skene model (Jaffe et al., 2016; Khetan & Oh, 2016; Shah et al., 2016) as well as to explicitly deal with adversaries (Raykar & Yu, 2012; Jagabathula et al., 2017). However, none of the prior work can handle a number of arbitrary adversaries almost as large as the number of reliable workers as we do.

6. Experiments

On both synthetic and real data, we compared our proposed Algorithm 1 to straightforward majority voting for predicting labels (referred to as Maj) and the following methods from the literature: the spectral algorithms by Ghosh et al. (2011) (GKM), Dalvi et al. (2013) (RoE and EoR) and Karger et al. (2013) (KOS), the two-stage procedure by Zhang et al. (2016) (S-EM1 and S-EM10, where we run one or ten iterations of the EM algorithm) and the recent method by Bonald & Combes (2017) (TE). We used the Matlab implementation of KOS, S-EM1 and S-EM10 made available by Zhang et al. (2016). In our implementations of the other methods, we adapted GKM, RoE and EoR as to assume that the average error of the workers is smaller than one half rather than assuming that the error of the first worker is. We always called Algorithm 1 with parameters $\gamma_{TR} = 0.4$ and $\delta = 0.1$, which resulted in $\gamma$ being set to 1

\[
\text{Algorithm 1}
\]

<table>
<thead>
<tr>
<th>Input:</th>
<th>crowdsourced labels stored in $A \in {-1, 0, +1}^{m \times n}$, upper bound $0 &lt; \gamma_{TR} &lt; \frac{1}{2}$ on the error probabilities of $\lfloor \frac{n}{2} + 1 \rfloor$ workers that follow the one-coin model, confidence parameter $0 &lt; \delta &lt; 1$</th>
</tr>
</thead>
<tbody>
<tr>
<td>Output:</td>
<td>estimates $(\hat{\varepsilon}<em>{i}^{F})</em>{i \in [n]}$, $(c_{j,k}^{F})<em>{j,k &lt; k}$, $(\hat{y}</em>{i})_{i \in [n]}$ of error probabilities, covariances and ground-truth labels</td>
</tr>
</tbody>
</table>

- **Estimating agreement probabilities**
  - set $g_{ij} = 1\{A_{ij} \neq 0\}$, $i, j \in [n]$
  - set $q_{jk} = \sum_{i=1}^{n} g_{ij} g_{ik}$, $j, k \in [n]$
  - set $p_{jk}$ as in (3), $j, k \in [n]$ ($p_{jk} = \text{NaN}$ if $q_{jk} = 0$)

- **Estimating error probabilities and covariances**
  - set $\beta = \left[ \ln(2n^2/\delta) / (2 \min_{j,k} q_{jk}) \right]^{1/2} \in (0, +\text{Inf})$
  - set $\gamma = 1$
  - set $\nu_{\text{old}} = \text{Inf}$, $(c_{j,k}^{F})_{i \in [n]} = 0$, $(c_{j,k}^{F})_{i \leq j < k \leq n} = 0$, $L = \emptyset$
  - for $(i_1, i_2, i_3) \in P$
    - if not all expressions in (10) or (11) are defined then break
    - compute $(\hat{\varepsilon}_{i}^{S})_{i \in [n]}$, $(c_{j,k}^{S})_{1 \leq j < k \leq n}$ as in (10) and (11)
    - set $Q = \{l \in [n] : \hat{\varepsilon}_{l}^{S} \leq \gamma\}$
    - set $\nu = \left[ \frac{n}{2} + 1 \right]$-th smallest element of $\left\{ \max_{k \in [n] \setminus \{l\}} |c_{j,k}^{S}| : l \in Q \right\}$ ($\nu = \text{NaN}$ if $Q = \emptyset$)
    - if $|Q| \geq \frac{n}{2} + 2$ AND $\nu < \nu_{\text{old}}$ then
      - set $(c_{j,k}^{S})_{i \in [n]} = (\hat{\varepsilon}_{l}^{S})_{i \in [n]}$, $(c_{j,k}^{S})_{j,k < k} = (c_{j,k}^{S})_{j,k < k}$
      - set $L = \{l \in Q : \max_{k \in [n] \setminus \{l\}} |c_{j,k}^{S}| \leq \nu\}$
      - set $\nu_{\text{old}} = \nu$
    - end if
  - end for

- **Estimating ground-truth labels**
  - set $f(\hat{\varepsilon}_{w_{l}}) = \ln \left( (1 - \hat{\varepsilon}_{w_{l}}) / \hat{\varepsilon}_{w_{l}} \right) \in [-\text{Inf}, +\text{Inf}], l \in L$, and $f(\hat{\varepsilon}_{w_{l}}) = 0$, $l \in [n] \setminus L$
  - (alternatively set $f(\hat{\varepsilon}_{w_{l}}) = 1 - 2\hat{\varepsilon}_{w_{l}}, l \in [n]$)
  - set $\hat{y}_{i}$ as in (16), $i \in [n]$
in the execution of the algorithm in all our experiments. We refer to Algorithm 1 with the logarithmic weights in (16) as Alg. 1 and and with the linear weights as Alt-Alg. 1. In the following, all results are average results obtained from running an experiment for 100 times.

6.1. Synthetic data

In our first experiment, we consider $n = 50$ workers and $m = 5000$ tasks with balanced ground-truth labels. Every worker is presented with every task. For $0 \leq t \leq 25$, we choose $t$ workers at random. These workers are corrupted workers that all provide the same random response to every task, which is incorrect with error probability 0.5. The remaining $n - t$ workers provide responses according to the one-coin model, where the error probability of each of these workers is 0.4. Figure 1 shows the prediction error for estimating ground-truth labels and the estimation error for estimating error probabilities in both the maximum norm and the normalized 1-norm for the various methods as a function of $t$. The prediction error is given by $\frac{1}{m} \sum_{i=1}^{m} \mathbb{1}\{y_i \neq \hat{y}_i\}$ for ground-truth labels $y_i$ and estimates $\hat{y}_i$ and the estimation error is given by $\max_{l \in [n]} |\epsilon_{w_l} - \hat{\epsilon}_{w_l}|$ or $\frac{1}{n} \sum_{l=1}^{n} |\epsilon_{w_l} - \hat{\epsilon}_{w_l}|$ for true error probabilities $\epsilon_{w_l}$ and estimates $\hat{\epsilon}_{w_l}$. The methods Maj and KOS, by default, do not provide estimates of the workers’ error probabilities. We adapt these two methods in order to return estimates of the error probabilities too as follows: if the method returns label estimates $\hat{y}_1, \ldots, \hat{y}_m$ and worker $w_l$ provides responses $A_{1l}, \ldots, A_{ml}$ then the method returns $\frac{1}{m} \sum_{i=1}^{m} \mathbb{1}\{y_i \neq A_{il}\}$ as estimate $\hat{\epsilon}_{w_l}$ of $\epsilon_{w_l}$.

Our Algorithm 1 is the only method that can handle up to $23 = \frac{n}{2} - 2$ corrupted workers (in accordance with our theoretical results). Its estimation error is constant as the number of corrupted workers increases from 0 to 23. Its prediction error depends on which weights we use in (16): the prediction error of Alg. 1 is constant in this range too, the one of Alt-Alg. 1 is slightly increasing. If only a few workers are corrupted, Alt-Alg.1 performs better than Alg. 1, while it is the other way round if more than 13 workers are corrupted. The methods from the literature predict ground-truth labels as badly as random guessing already in the presence of only six corrupted workers. All these methods are outperformed by majority voting. We do not have an explanation for the non-monotonic behavior of the estimation error of S-EM10 in the maximum norm. In Appendix C we present similar experiments, in which the error probability of the workers following the one-coin model is smaller or the error probabilities of the corrupted workers are less correlated. Still, the overall picture there is the same.

One might wonder whether one can combine the considered methods from the literature with one of the algorithms by Jagabathula et al. (2017) in order to first sort the corrupted workers out and then apply the method only to the remaining workers and their responses. However, those algorithms cannot deal with the corrupted workers considered in this experiment, which are perfectly colluding, at all. Even though provided with the correct number $t$ of corrupted workers as input, when $t \geq 3$, the soft-penalty algorithm by Jagabathula et al. (2017) was not able to identify any of the corrupted workers in any of the 100 runs of the experiment.

In our next experiment, we study the convergence rate of Algorithm 1. We consider $n = 50$ workers, out of which $t = 23$ are corrupted in the same way as above. Figure 2 shows the prediction and estimation error of Algorithm 1 as a function of the number of tasks $m$ varying from 5000 to 20000. The prediction error of Alg. 1 decreases only slightly as $m$ increases, the prediction error of Alt-Alg. 1 decreases more significantly. Most interesting is the decay of the estimation error. Apparently, in this experiment it
We performed another experiments on these data sets by corrupting some of the workers (chosen at random). Like in the experiments of Section 6.1, the corrupted workers provide the same random response to every task. Figure 3 shows the prediction errors for the various methods and the first three data sets as functions of the number of corrupted workers. Similar plots for the other data sets are shown in Figure 7 in Appendix C. On none of the data sets, any method can handle more corrupted workers than Alt-Alg. 1.

7. Discussion

In this work, we studied an extension of the well-known one-coin model for crowdsourcing that allows for colluding adversaries. Our results show that even if almost half of the workers are adversarial, one can consistently estimate the workers’ error probabilities with an efficient algorithm.

For future work, it would be interesting to relax the assumption that the reliable workers follow the one-coin model and to allow for task-dependent error probabilities also for them. It would also be interesting to see whether our approach can be extended to multiclass classification problems. Another direction concerns improving the sufficient rate \( m \sim \rho^{-8} \), which we obtained for our algorithm for recovering worker qualities up to error \( \rho \). In the absence of adversaries one can achieve a rate \( m \sim \rho^{-2} \), and we would like to understand whether this gap is inherent or an artifact of our algorithm/proo.
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References


Appendix

A. Related work

In the context of the Dawid-Skene model, one might be interested in estimating ground-truth labels and/or worker qualities given the response matrix $A$ (ii) and (ii) from Section 2). At the same time, there have been works addressing the problem of optimal task assignment (iii) from Section 2). In their seminal paper, Dawid & Skene (1979) propose an EM based algorithm, which comes without theoretical guarantees, to simultaneously estimate ground-truth labels and worker qualities. Ghosh et al. (2011) provide a spectral algorithm to infer ground-truth labels in the one-coin model. They also provide a simple strategy to infer worker qualities as part of an online algorithm for estimating ground-truth labels. The work by Karger et al. (2011a;b; 2014) is the first to provide near-optimal estimators for the ground-truth labels in the one-coin model when the data curator is free to choose the task assignment graph $G$. Surprisingly, Karger et al. (2014) show that a non-adaptively chosen task assignment graph results in a near-optimal algorithm even when comparing to adaptive task assignment schemes (a crucial assumption made there is that workers are fleeting). The work by Karger et al. (2011a;b) has been carried on by Karger et al. (2013) in the general Dawid-Skene model and for multiclassification problems. Dalvi et al. (2013) study estimation of both ground-truth labels and worker qualities in the one-coin model when the task assignment graph $G$ is fixed and provide error guarantees in terms of the expansion gap of $G$ (the expansion gap of $G$ is the gap between the first and the second eigenvalue of $G^T G$). A projected EM algorithm for the one-coin model, assuming every worker is presented with every tasks, is analyzed in Gao & Zhou (2013). Minimax rates for estimating ground-truth labels in the general Dawid-Skene model are studied by Gao et al. (2016). Zhang et al. (2016) propose an EM based algorithm together with a spectral method for initialization to estimate both ground-truth labels and worker qualities in the general Dawid-Skene model. They prove their algorithm to converge to the true parameters at a near-optimal rate, even when performing only one iteration of EM. Another near-optimal estimator for worker qualities in the one-coin model is provided by Bonald & Combles (2017). Their approach bears some resemblance to ours by considering system (7) and solving it using three of its equations at a time. Ma et al. (2017) study estimating worker qualities in the one-coin model in the case of sparsely interacting workers (where $\sum_{i=1}^{m} g_{ij}g_{ik} = 0$ for most $j \neq k$).

Assuming that the true worker qualities are known in the one-coin model, Berend & Kontorovich (2015) analyze the weighted majority vote (16) with $f(\hat{\epsilon}_{w_i})$ replaced by $f(\hat{\epsilon}_{w_i}) = \ln \left( \frac{(1 - \epsilon_{w_i})}{\hat{\epsilon}_{w_i}} \right)$ for estimating ground-truth labels. They also analyze the weighted majority vote (16) with $f(\hat{\epsilon}_{w_i})$ set to $f(\hat{\epsilon}_{w_i}) = \ln \left( \frac{(1 - \hat{\epsilon}_{w_i})}{\hat{\epsilon}_{w_i}} \right)$ or $f(\hat{\epsilon}_{w_i}) = 1 - 2\hat{\epsilon}_{w_i}$, where $\hat{\epsilon}_{w_i}$ is an estimate of the true error probability $\epsilon_{w_i}$. However, they assume that $\hat{\epsilon}_{w_i}$ is obtained as a relative frequency of incorrectly solved tasks (i.e., for some set of tasks, the number of tasks that worker $w_i$ solved incorrectly divided by the total number of tasks that worker $w_i$ solved), and hence they assume access to certain gold standard tasks for which the ground-truth label is known.

Several extensions of the Dawid-Skene model have been suggested. Zhou et al. (2012) consider a general model, in which for all workers, error probabilities can be task-dependent. They propose an algorithm based on a minimax entropy principle and empirically demonstrate its effectiveness, but do not provide any theoretical guarantees. Khetan & Oh (2016) build on the work by Karger et al. (2011a;b; 2014) and study a generalized Dawid-Skene model, where the workers’ error probabilities are task-dependent as a specific expression of both a task and a worker quality parameter. In the model of Jaffe et al. (2016), workers can be clustered into groups such that answers of workers in different groups are independent given the ground-truth label while answers of workers in the same group are independent given a group specific latent variable. Jaffe et al. (2016) show that in their model the worker-worker covariance matrix is a combination of two rank-one matrices. Note that in our model almost half of the workers can be arbitrarily correlated and the worker-worker covariance matrix does not necessarily have a low-rank structure. Shah et al. (2016) study a model where there is a hidden permutation of the workers and also a hidden permutation of the tasks such that the probability of worker $w_j$ solving task $x_i$ correctly monotonically depends on both the position of $w_j$ and of $x_i$ in the permutations. They provide an efficient and consistent estimator for their model. They also show that their estimator is near-optimal for an intermediate model that is a special case of their permutation-based model, but still a strict generalization of the one-coin model.

There has also been work on crowdsourcing in the presence of adversaries. Raykar & Yu (2012) study the problem of eliminating spammers in the general Dawid-Skene model, where spammers are workers that assign labels randomly. Jagabathula et al. (2017) try to identify adversaries when honest workers follow the one-coin model. Also their theoretical analysis applies only to specific types of adversarial behavior (e.g., all adversaries provide a label $+1$). Note that, on the contrary, our model allows for arbitrary adversaries. Another line of work focuses on identifying adversaries when having access to gold standard tasks (Snow et al., 2008; Le et al., 2010).
B. Proofs and detailed version of Lemma 2

Here we provide the proof of (2), the detailed version of Lemma 2 and its proof, and the proofs of Proposition 1, Proposition 2 and Lemma 3.

Proof of (2):

\[
\Pr_{(x,y) \sim D, w_j, w_k}[w_j(x) = w_k(x)] = \\
= \mathbb{E}_{(x,y) \sim D}[\Pr_{w_j, w_k|(x,y)}[w_j(x) = w_k(x) | (x, y)]] \\
= \mathbb{E}_{(x,y) \sim D}[\Pr_{w_j, w_k|(x,y)}[w_j(x) = y \wedge w_k(x) = y | (x, y)] + \Pr_{w_j, w_k|(x,y)}[w_j(x) \neq y \wedge w_k(x) \neq y | (x, y)]] \\
= \mathbb{E}_{(x,y) \sim D}[\Pr_{w_j|(x,y)}[w_j(x) = y | (x, y)] \cdot \Pr_{w_k|(x,y)}[w_k(x) = y | (x, y)] + \\
\Pr_{w_j|(x,y)}[w_j(x) \neq y | (x, y)] \cdot \Pr_{w_k|(x,y)}[w_k(x) \neq y | (x, y)]] \\
= \mathbb{E}_{(x,y) \sim D}[(1 - \varepsilon_{w_j}(x,y))(1 - \varepsilon_{w_k}(x,y)) + \varepsilon_{w_j}(x,y)\varepsilon_{w_k}(x,y)] \\
= 1 - \varepsilon_{w_j} - \varepsilon_{w_k} + 2\mathbb{E}_{(x,y) \sim D}[\varepsilon_{w_j}(x,y)\varepsilon_{w_k}(x,y)] \\
= 1 - \varepsilon_{w_j} - \varepsilon_{w_k} + 2\varepsilon_{w_j}\varepsilon_{w_k} + 2\text{Cov}_{(x,y) \sim D}[^{\gamma}_{x,w_j}(x,y), \varepsilon_{w_k}(x,y)]. \\
\]

From (17) to (18) we used the fact that \(w_j(x), w_k(x), y \in \{-1, +1\}\). From (18) to (19) we used that \(w_j(x)\) and \(w_k(x)\), given \(x\), are independent. We plugged in the definition of \(\varepsilon_{w_j}(x,y)\) and \(\varepsilon_{w_k}(x,y)\) (see (1)) in order to derive (20) from (19). Equation (22) follows from (21) because of

\[
\text{Cov}_{(x,y) \sim D}[\varepsilon_{w_j}(x,y), \varepsilon_{w_k}(x,y)] = \mathbb{E}_{(x,y) \sim D}[(\varepsilon_{w_j}(x,y) - \varepsilon_{w_j}) \cdot (\varepsilon_{w_k}(x,y) - \varepsilon_{w_k})] \\
= \mathbb{E}_{(x,y) \sim D}[\varepsilon_{w_j}(x,y)\varepsilon_{w_k}(x,y)] - \varepsilon_{w_j}\varepsilon_{w_k}. \\
\]

\[
\square
\]

Lemma 2 (Detailed version). Let \(0 < \gamma < \frac{1}{2}\) and \(n \in \mathbb{N}\) be even. Consider the system of equations

\[
1 - \varepsilon_j - \varepsilon_k + 2\varepsilon_j\varepsilon_k + 2c_{jk} = p_{jk}, \quad 1 \leq j \leq k \leq n,
\]

with

\[
p_{jk} = \begin{cases} 
\frac{8\gamma}{100} & \text{for } 1 \leq j < k \leq \frac{n}{2}, \\
1 - 2\gamma + 4\gamma^2 & \text{for } \frac{n}{2} + 1 \leq j < k \leq n,
\end{cases}
\]

in the unknowns \((\varepsilon_l)_{l \in [n]}\) and \((c_{jk})_{1 \leq j < k \leq n}\). One solution of this system is given by \((\varepsilon_l^{S_1})_{l \in [n]}\) and \((c_{jk}^{S_1})_{1 \leq j < k \leq n}\) with

\[
\varepsilon_l^{S_1} = \begin{cases} 
\frac{1}{10} & \text{for } l \in \left[\frac{n}{2}\right], \\
\gamma & \text{for } l \in [n] \setminus \left[\frac{n}{2}\right]
\end{cases}
\]

and

\[
c_{jk}^{S_1} = \begin{cases} 
0 & \text{for } j \in \left[\frac{n}{2}\right] \text{ and } k \neq j, \\
\gamma^2 & \text{for } \frac{n}{2} + 1 \leq j < k \leq n.
\end{cases}
\]

If \(X = [0, 1] \subseteq \mathbb{R}\) and \(D\) is the uniform distribution on \([0, 1] \times \{-1, +1\}\), this solution corresponds to workers \(w_1^{S_1}, \ldots, w_n^{S_1}\) with

\[
\varepsilon_{w_l^{S_1}}(x,y) = \begin{cases} 
1 \quad & l \in \left[\frac{n}{2}\right], \\
\gamma & l \in [n] \setminus \left[\frac{n}{2}\right], \text{ and}
\end{cases}
\]

\[
\varepsilon_{w_l^{S_1}}(x,y) = 2\gamma \cdot \mathbb{1}\{x > 0.5\}, \quad l \in [n] \setminus \left[\frac{n}{2}\right].
\]

Another solution of the system is given by \((\varepsilon_l^{S_2})_{l \in [n]}\) and \((c_{jk}^{S_2})_{1 \leq j < k \leq n}\) with

\[
\varepsilon_l^{S_2} = \begin{cases} 
\frac{5\sqrt{8\gamma^2 - 4\gamma + 1} + 8\gamma - 4}{10\sqrt{8\gamma^2 - 4\gamma + 1}} & \text{for } l \in \left[\frac{n}{2}\right], \\
\frac{1}{2} - \frac{\sqrt{8\gamma^2 - 4\gamma + 1}}{2} & \text{for } l \in [n] \setminus \left[\frac{n}{2}\right], \text{ and}
\end{cases}
\]

\[
c_{jk}^{S_2} = \begin{cases} 
\frac{16\gamma^2}{200\gamma^2 - 100\gamma + 25} & \text{for } 1 \leq j < k \leq \frac{n}{2}, \\
0 & \text{for } j \in [n] \setminus \left[\frac{n}{2}\right] \text{ and } k \neq j,
\end{cases}
\]

which corresponds to workers \(w_1^{S_2}, \ldots, w_n^{S_2}\) with

\[
\varepsilon_{w_l^{S_2}}(x,y) = 2\gamma \cdot \mathbb{1}\{x > l\}, \quad l \in \left[\frac{n}{2}\right], \quad \text{and}
\]

\[
\varepsilon_{w_l^{S_2}}(x,y) = \frac{1}{2} - \frac{\sqrt{8\gamma^2 - 4\gamma + 1}}{2}, \quad l \in [n] \setminus \left[\frac{n}{2}\right].
\]
For example, if $\gamma = \frac{1}{10}$, then
\[
\varepsilon_{x,y}^{S_2} \approx \begin{cases} 
0.403 & \text{for } l \in \left[ \frac{n}{2} \right], \\
0.088 & \text{for } l \in [n] \setminus \left[ \frac{n}{2} \right], 
\end{cases}
\]
and
\[
c_{j,k}^{S_2} \approx \begin{cases} 
0.151 & \text{for } 1 \leq j < k \leq \frac{n}{2}, \\
0 & \text{for } j \in [n] \setminus \left[ \frac{n}{2} \right] \text{ and } k \neq j,
\end{cases}
\]
and
\[
\varepsilon_{\omega_1}^{S_2}(x,y) \approx 0.776 \cdot 1\{x > 0.481\}, \quad l \in \left[ \frac{n}{2} \right], \quad \text{and} \quad \varepsilon_{\omega_1}^{S_2}(x,y) \approx 0.088, \quad l \in [n] \setminus \left[ \frac{n}{2} \right].
\]

**Proof.** Note that $8\gamma^2 - 4\gamma + 1 > 0$ for all $\gamma \in \mathbb{R}$. Also note that
\[
\mathbb{E}_{(x,y) \sim D} = \mathbb{E}_{x \sim \mathcal{U}[0,1]}[2\gamma \cdot 1\{x > \lambda\}] = 2\gamma(1 - \lambda)
\]
and
\[
\text{Cov}_{(x,y) \sim D}[2\gamma \cdot 1\{x > \lambda\}, 2\gamma \cdot 1\{x > \lambda\}] = \text{Cov}_{x \sim \mathcal{U}[0,1]}[(2\gamma \cdot 1\{x > \lambda\} - 2\gamma(1 - \lambda))^2]
\]
\[
= \lambda \cdot 4\gamma^2(1 - \lambda)^2 + (1 - \lambda) \cdot 4\gamma^2\lambda^2,
\]
where $\mathcal{U}[0,1]$ denotes the uniform distribution on $[0,1]$. It is straightforward to verify that both $(\varepsilon_{i}^{S_1})_{i \in [n]}$ and $(c_{j,k}^{S_1})_{1 \leq j < k \leq n}$ and $(\varepsilon_{i}^{S_2})_{i \in [n]}$ and $(c_{j,k}^{S_2})_{1 \leq j < k \leq n}$ are solutions of the system and correspond to workers $w_1^{S_1}, \ldots, w_n^{S_1}$ and $w_1^{S_2}, \ldots, w_n^{S_2}$, respectively. \hfill \Box

**Proof of Proposition 1:**

Assume there were two solutions $(\varepsilon_{i}^{S_1})_{i \in [n]}$, $(c_{j,k}^{S_1})_{1 \leq j < k \leq n}$ and $(\varepsilon_{i}^{S_2})_{i \in [n]}$, $(c_{j,k}^{S_2})_{1 \leq j < k \leq n}$ satisfying (6) with $L_1$ and $L_2$, respectively. Because of $|L_1|, |L_2| \geq \frac{n}{2} + 2$ we have $|L_1 \cap L_2| \geq 4 > 3$. Consequently, there exist $i_1, i_2, i_3$ (pairwise different) with
\[
\varepsilon_{i_1}^{S_1}, \varepsilon_{i_2}^{S_1}, \varepsilon_{i_3}^{S_1} < \frac{1}{2} \quad \wedge \quad \left[ \forall j \not= i_1 : c_{i_1 j}^{S_1} = 0 \quad \wedge \quad \forall j \not= i_2 : c_{i_2 j}^{S_1} = 0 \quad \wedge \quad \forall j \not= i_3 : c_{i_3 j}^{S_1} = 0 \right],
\]
\[
\varepsilon_{i_1}^{S_2}, \varepsilon_{i_2}^{S_2}, \varepsilon_{i_3}^{S_2} < \frac{1}{2} \quad \wedge \quad \left[ \forall j \not= i_1 : c_{i_1 j}^{S_2} = 0 \quad \wedge \quad \forall j \not= i_2 : c_{i_2 j}^{S_2} = 0 \quad \wedge \quad \forall j \not= i_3 : c_{i_3 j}^{S_2} = 0 \right].
\]

Both $(\varepsilon_{i_1}^{S_1}, \varepsilon_{i_2}^{S_1}, \varepsilon_{i_3}^{S_1})$ and $(\varepsilon_{i_1}^{S_2}, \varepsilon_{i_2}^{S_2}, \varepsilon_{i_3}^{S_2})$ are a solution to the system

\begin{align*}
1 - \varepsilon_{i_1} - \varepsilon_{i_2} + 2\varepsilon_{i_1} \varepsilon_{i_2} &= p_{i_1 i_2} \\
1 - \varepsilon_{i_2} - \varepsilon_{i_3} + 2\varepsilon_{i_2} \varepsilon_{i_3} &= p_{i_2 i_3} \\
1 - \varepsilon_{i_1} - \varepsilon_{i_3} + 2\varepsilon_{i_1} \varepsilon_{i_3} &= p_{i_1 i_3}.
\end{align*}

We show that the system (23) has at most one solution $\varepsilon_{i_1}^{S_1}, \varepsilon_{i_2}^{S_1}, \varepsilon_{i_3}^{S_1}$ that satisfies $\varepsilon_{i_1}^{S_1}, \varepsilon_{i_2}^{S_1}, \varepsilon_{i_3}^{S_1} < \frac{1}{2}$. Assuming that $\varepsilon_{i_2} \neq \frac{1}{2}$, the first and the third equation of (23) are equivalent to

\[
\varepsilon_{i_1} = \frac{p_{i_1 i_2} - 1 + \varepsilon_{i_2}}{2\varepsilon_{i_2} - 1}, \quad \varepsilon_{i_3} = \frac{p_{i_2 i_3} - 1 + \varepsilon_{i_2}}{2\varepsilon_{i_2} - 1}
\]

and it follows from the second equation that

\[
A \varepsilon_{i_2}^2 + B \varepsilon_{i_2} + C = 0
\]
Appendix to Crowdsourcing with Arbitrary Adversaries

with

\[
A = 2 - 4p_{i_1i_3}, \quad B = -2 + 4p_{i_1i_3}, \quad C = 1 + 2p_{i_1i_2}p_{i_2i_3} - p_{i_1i_2} - p_{i_1i_3} - p_{i_2i_3}.
\]

Because of \(-B/(2A) = \frac{1}{2}\) there is at most one solution \(\varepsilon^S_{i_2}\) of (25) with \(\varepsilon_{i_2} < \frac{1}{2}\), which uniquely determines \(\varepsilon^S_{i_1}\) and \(\varepsilon^S_{i_3}\) due to (24). It follows that \((\varepsilon^S_{i_1}, \varepsilon^S_{i_2}, \varepsilon^S_{i_3}) = (\varepsilon^S_{i_2}, \varepsilon^S_{i_1}, \varepsilon^S_{i_3})\). Because of \(c_{i_1j} = c_{i_1j} = 0, j \neq i_1\), and both \((\varepsilon^S_{i_1})_{i \in [n]}\), \((\varepsilon^S_{i_2})_{1 \leq j < k \leq n}\) and \((\varepsilon^S_{i_3})_{i \in [n]}\), \((c_{jk})_{1 \leq j < k \leq n}\) are a solution of (4), we also have

\[
\varepsilon^S_{i_1} = \frac{p_{i_1j} - 1 + \varepsilon^S_{i_1}}{2\varepsilon^S_{i_1} - 1} = \frac{p_{i_1j} - 1 + \varepsilon^S_{i_1}}{2\varepsilon^S_{i_1} - 1} = \varepsilon^S_{i_2}, \quad j \neq i_1,
\]

and

\[
c^S_{jk} = \frac{p_{jk} - 1 + \varepsilon^S_{i_1} + \varepsilon^S_{i_1} - 2\varepsilon^S_{i_1} \varepsilon^S_{i_1}}{2} = \frac{p_{jk} - 1 + \varepsilon^S_{i_1} + \varepsilon^S_{i_1} - 2\varepsilon^S_{i_1} \varepsilon^S_{i_1}}{2} = c^S_{jk}, \quad j \neq k.
\]

\[\square\]

For the proofs of Proposition 2 and Lemma 3 we need the following lemma:

**Lemma 4.** Consider \(f : [0, 1] \times [0, 1] \to \mathbb{R}\) with \(f(x, y) = x + y - 2xy\). We have:

(i) \(0 \leq f(x, y) \leq \frac{1}{2}\) for all \((x, y) \in [0, \frac{1}{2}] \times [0, \frac{1}{2}]\) and \(0 < f(x, y) < \frac{1}{2}\) for all \((x, y) \in (0, \frac{1}{2}) \times (0, \frac{1}{2})\).

(ii) \(\forall \gamma < \frac{1}{2} : f(x, y) \leq 2\gamma - 2\gamma^2 = f(\gamma, \gamma) < \frac{1}{2}\) for all \((x, y) \in [0, \gamma] \times [0, \gamma]\).

(iii) \(0 \leq f(x, y) \leq \frac{1}{2}\) for all \((x, y) \in [\frac{1}{2}, 1] \times [\frac{1}{2}, 1]\) and \(0 < f(x, y) < \frac{1}{2}\) for all \((x, y) \in (\frac{1}{2}, 1) \times (\frac{1}{2}, 1)\).

(iv) \(\forall \gamma > \frac{1}{2} : f(x, y) \leq 2\gamma - 2\gamma^2 = f(\gamma, \gamma) < \frac{1}{2}\) for all \((x, y) \in [\gamma, 1] \times [\gamma, 1]\).

**Proof.**

(i) We have \(f(x, 0) = \) if \(0 < x < \frac{1}{2}\) and \(f(x, y) = \frac{1}{2}\) for all \(0 < x < \frac{1}{2}\). For \(f(x, 0) = \frac{1}{2}\) if \(x < \frac{1}{2}\) and \(f(x, y) = \frac{1}{2}\) for all \(x < \frac{1}{2}\). For \(0 < x < \frac{1}{2}\) let \(f_x(y) = f(x, y)\). We have

\[
f'_x(y) = 1 - 2x > 0 \text{ for all } 0 < x < \frac{1}{2} \text{ and all } y, \text{ and it follows that } 0 < f(x, y) < \frac{1}{2} \text{ for all } (x, y) \in (0, \frac{1}{2}) \times (0, \frac{1}{2}).
\]

(ii) For \(0 \leq x, y < \frac{1}{2}\) let \(f_x(y) = f_y(x) = f(x, y)\). It is \(f'_x(y) = 1 - 2x\) and \(f'_y(x) = 1 - 2y\). Because of \(f'_x, f'_y > 0\) on \([0, \gamma]\), it follows that \(f(x, y) \leq f(\gamma, \gamma) = 2\gamma - 2\gamma^2\).

(iii) Follows from (i) because of \(f(x, 1 - y) = f(x, y)\).

(iv) For \(\frac{1}{2} < x, y \leq 1\) let \(f_x(y) = f_y(x) = f(x, y)\). It is \(f'_x(y) = 1 - 2x\) and \(f'_y(x) = 1 - 2y\). Because of \(f'_x, f'_y < 0\) on \([\gamma, 1]\), it follows that \(f(x, y) \leq f(\gamma, \gamma) = 2\gamma - 2\gamma^2\).

\[\square\]

**Proof of Proposition 2:**

We set \(L : = 1 - 2\gamma + 2\gamma^2 - 2\nu\). Because of \(\nu < 1/8 - \gamma/2 + \gamma^2/2\), we have \(L > \frac{1}{2} + 2\nu\). Note that \(L \leq 1 - 2\nu\) and \(\nu \leq 1/8\). The proof is similar to the one of Proposition 1. Assume there were two solutions \((\varepsilon^S_{i_1})_{i \in [n]}, (c^S_{jk})_{1 \leq j < k \leq n}\) and \((\varepsilon^S_{i_2})_{i \in [n]}, (c^S_{jk})_{1 \leq j < k \leq n}\) satisfying (8) with \(L_1\) and \(L_2\), respectively. Because of \(|L_1|, |L_2| \geq \frac{1}{2} + 2\) we have \(|L_1 \cap L_2| \geq 4 > 3\). Consequently, there exist \(i_1, i_2, i_3\) (pairwise different) with

\[
\begin{align*}
\varepsilon^S_{i_1}, \varepsilon^S_{i_2}, \varepsilon^S_{i_3} &\leq \gamma \wedge \forall j \neq i_1 : |c^S_{i_1j}| \leq \nu \wedge \forall j \neq i_2 : |c^S_{i_2j}| \leq \nu \wedge \forall j \neq i_3 : |c^S_{i_3j}| \leq \nu, \\
\varepsilon^S_{i_1}, \varepsilon^S_{i_2}, \varepsilon^S_{i_3} &\leq \gamma \wedge \forall j \neq i_1 : |c^S_{i_1j}| \leq \nu \wedge \forall j \neq i_2 : |c^S_{i_2j}| \leq \nu \wedge \forall j \neq i_3 : |c^S_{i_3j}| \leq \nu.
\end{align*}
\]

(26)
Appendix to Crowdsourcing with Arbitrary Adversaries

Both \((\varepsilon_i^{S_1}, \varepsilon_i^{S_2}, \varepsilon_i^{S_3}), (\varepsilon_i^{S_1}, \varepsilon_i^{S_1}, \varepsilon_i^{S_1}), (\varepsilon_i^{S_2}, \varepsilon_i^{S_2}, \varepsilon_i^{S_2}), (\varepsilon_i^{S_1}, \varepsilon_i^{S_2}, \varepsilon_i^{S_3})\) are a solution to the system

\[
\begin{align*}
1 - \varepsilon_i^1 - \varepsilon_i^2 + 2\varepsilon_i^1 \varepsilon_i^2 + 2c_{i1i2} &= p_{i1i2} \\
1 - \varepsilon_i^1 - \varepsilon_i^3 + 2\varepsilon_i^1 \varepsilon_i^3 + 2c_{i1i3} &= p_{i1i3} \\
1 - \varepsilon_i^2 - \varepsilon_i^3 + 2\varepsilon_i^2 \varepsilon_i^3 + 2c_{i2i3} &= p_{i2i3}.
\end{align*}
\]  

(27)

Assuming that \(\varepsilon_i^2 \neq \frac{1}{2}\), the first and the third equation of (27) are equivalent to

\[
\varepsilon_i^1 = \frac{p_{i1i2} - 2c_{i1i2} - 1 + \varepsilon_i^2}{2\varepsilon_i^2 - 1}, \quad \varepsilon_i^3 = \frac{p_{i2i3} - 2c_{i2i3} - 1 + \varepsilon_i^2}{2\varepsilon_i^2 - 1}
\]  

(28)

and it follows from the second equation that

\[
A \varepsilon_i^2 + B \varepsilon_i^2 + C = 0
\]  

(29)

with

\[
A = 2 - 4(p_{i1i3} - 2c_{i1i3}) = 2 - 4p_{i1i3} + 8c_{i1i3},
B = -2 + 4(p_{i1i3} - 2c_{i1i3}) = -2 + 4p_{i1i3} - 8c_{i1i3} = -A,
C = 1 + 2(p_{i1i2} - 2c_{i1i2})/(p_{i2i3} - 2c_{i2i3}) - (p_{i1i3} - 2c_{i1i3}) - (p_{i2i3} - 2c_{i2i3})
\]

\[
= 1 + 2\varepsilon_i^1 p_{i1i2} - p_{i1i3} - p_{i2i3} - 4p_{i1i2} c_{i1i3} + 8c_{i1i2} c_{i2i3} + 2c_{i1i2} + 2c_{i1i3} + 2c_{i2i3}.
\]

It follows from (26), (27) and Lemma 4 (ii) that \(p_{i1i2}, p_{i1i3}, p_{i2i3} \geq 1 - 2\gamma + 2\gamma^2 - 2\nu = L\). Recall that \(p_{jk} \in [0, 1]\), \(1 \leq j < k \leq n\). It follows that

\[-3 \leq -2 - 8\nu \leq A \leq 2 - 4L + 8\nu < 0, \quad 0 < -2 + 4L - 8\nu \leq B \leq 2 + 8\nu \leq 3.\]

(30)

and

\[-3 \leq 1 - (2L - 2L^2) - 1 - 15\nu \leq C \leq 1 - L + 15\nu \leq 3.\]

(31)

In the lower bound on \(C\) we used Lemma 4 (iv). Because of \(-B/(2A) = 0.5\), for fixed values of \(c_{i1i2}, c_{i1i3}, c_{i2i3}\) there is at most one solution \(\varepsilon_i^S\) of (29) with \(\varepsilon_i^S < \frac{1}{2}\). Allowing \((c_{i1i2}, c_{i1i3}, c_{i2i3})\) to vary in \([-\nu, +\nu]^3\), we consider all equations

\[
A(c_{i1i2}, c_{i1i3}, c_{i2i3}) \varepsilon_i^2 + B(c_{i1i2}, c_{i1i3}, c_{i2i3}) \varepsilon_i^2 + C(c_{i1i2}, c_{i1i3}, c_{i2i3}) = 0.
\]

We abbreviate \(A = A(c_{i1i2}, c_{i1i3}, c_{i2i3}), B = B(c_{i1i2}, c_{i1i3}, c_{i2i3}), C = C(c_{i1i2}, c_{i1i3}, c_{i2i3})\) and \(\hat{A} = A(\hat{c}_{i1i2}, \hat{c}_{i1i3}, \hat{c}_{i2i3}), \hat{B} = B(\hat{c}_{i1i2}, \hat{c}_{i1i3}, \hat{c}_{i2i3}), \hat{C} = C(\hat{c}_{i1i2}, \hat{c}_{i1i3}, \hat{c}_{i2i3})\). For \(u, v, u', v' \in \mathbb{R}\) it holds that

\[
|uv - u'v'| \leq |v| \cdot |u - u'| + |u'| \cdot |v - v'|,
\]

(32)

and it is straightforward to verify that

\[
|A - \hat{A}| \leq 16\nu, \quad |B - \hat{B}| \leq 16\nu, \quad |C - \hat{C}| \leq 28\nu + 32\nu^2 \leq 32\nu.
\]

(33)

A solution \(\varepsilon_i^{S_2}\) of \(A \varepsilon_i^2 + B \varepsilon_i^2 + C = 0\) and a solution \(\varepsilon_i^{S_3}\) of \(\hat{A} \varepsilon_i^2 + \hat{B} \varepsilon_i^2 + \hat{C} = 0\), with \(\varepsilon_i^{S_2}, \varepsilon_i^{S_3} < \frac{1}{2}\) and given by

\[
\varepsilon_i^{S_2} = -B \quad 2A + \sqrt{B^2 - 4AC} = \frac{1}{2} - \sqrt{B^2 - 4AC} = \frac{1}{2} - \frac{\sqrt{B + 4C}}{2\sqrt{B}}, \quad \varepsilon_i^{S_3} = \frac{1}{2} - \frac{\sqrt{B + 4C}}{2\sqrt{B}},
\]

can differ by

\[
|\varepsilon_i^{S_2} - \varepsilon_i^{S_3}| = \frac{\sqrt{B + 4C}}{2\sqrt{B}} - \frac{\sqrt{B + 4C}}{2\sqrt{B}}
\]

\[
\leq \frac{1}{2} (-2 + 4L - 8\nu)^{-1} \cdot \sqrt{B\sqrt{B + 4C}} \leq \frac{1}{2} (-2 + 4L - 8\nu)^{-1} \cdot \sqrt{B\sqrt{B + 4C}} \leq \frac{1}{2} (-2 + 4L - 8\nu)^{-1} \cdot \sqrt{B\sqrt{B + 4C}}
\]

\[
\frac{1}{2} (-2 + 4L - 8\nu)^{-1} \cdot \sqrt{B\sqrt{B + 4C}} \leq \frac{1}{2} (-2 + 4L - 8\nu)^{-1} \cdot \sqrt{B\sqrt{B + 4C}} \leq \frac{1}{2} (-2 + 4L - 8\nu)^{-1} \cdot \sqrt{B\sqrt{B + 4C}}
\]

(30)

(32)

(30/k31)
For $u, v > 0$ it holds that

$$|\sqrt{u} - \sqrt{v}| \leq \sqrt{|u - v|},$$

and it follows that

$$|\varepsilon_{i_2}^{S} - \varepsilon_{i_2}^{S}| \leq \frac{1}{2} (-2 + 4L - 8\nu)^{-1} \cdot \left[ 16\sqrt{\nu} + 2\sqrt{|B + 4C - \hat{B} - 4\hat{C}|} \right]$$

$$\leq (-2 + 4L - 8\nu)^{-1} \cdot \left[ 8\sqrt{\nu} + \sqrt{16\nu + 4 \cdot 32\nu} \right] = \frac{20\sqrt{\nu}}{(-2 + 4L - 8\nu)}.$$

Hence, we have

$$|\varepsilon_{i_2}^{S_1} - \varepsilon_{i_2}^{S_2}| \leq \frac{20\sqrt{\nu}}{(-2 + 4L - 8\nu)},$$

and using (28) we obtain

$$|\varepsilon_{i_1}^{S} - \varepsilon_{i_1}^{S}| = \frac{|p_{i_1i_2} - 2c_{i_1i_2} - 1 + \varepsilon_{i_1}^{S} - \varepsilon_{i_2}^{S} - 2c_{i_2}^{S_2} - 1|}{2c_{i_2}^{S_1} - 1} \leq \left( \frac{1}{1 - 2\gamma} \right)^2 \frac{|(\varepsilon_{i_2}^{S_2} - \varepsilon_{i_2}^{S_1})(2p_{i_1i_2} - 1) + 2(c_{i_1i_2} - c_{i_2}^{S_2} - 1 + 4(\varepsilon_{i_1}^{S} - \varepsilon_{i_2}^{S} - \varepsilon_{i_2}^{S_1})|}{(1 - 2\gamma)^2}$$

$$\leq 3 \left( \frac{20\sqrt{\nu}}{(-2 + 4L - 8\nu)} \right),$$

Similarly, we have

$$|\varepsilon_{i_3}^{S} - \varepsilon_{i_3}^{S}| \leq 36(1 - 2\gamma)^{-2} \frac{\sqrt{\nu}}{(-2 + 4L - 8\nu)}.$$

It also holds for all other $l \neq i_2$ that

$$\varepsilon_{i_1}^{S_1} = \frac{p_{i_1i_2} - 2c_{i_1i_2} - 1 + \varepsilon_{i_1}^{S_1}}{2c_{i_2}^{S_1} - 1}, \quad \varepsilon_{i_2}^{S_2} = \frac{p_{i_2i_1} - 2c_{i_2}^{S_2} - 1 + \varepsilon_{i_2}^{S_2}}{2c_{i_2}^{S_2} - 1}$$

and

$$|\varepsilon_{i_1}^{S_1} - \varepsilon_{i_2}^{S_2}| \leq \frac{20\sqrt{\nu}}{(-2 + 4L - 8\nu)}.$$

For $j < k$ we have

$$c_{j}^{S_1} = \frac{p_{jk} - 1 + \varepsilon_{j}^{S_1} + \varepsilon_{k}^{S_1} - 2\varepsilon_{j}^{S} \varepsilon_{k}^{S_1}}{2}, \quad c_{k}^{S_2} = \frac{p_{jk} - 1 + \varepsilon_{j}^{S_2} + \varepsilon_{k}^{S_2} - 2\varepsilon_{j}^{S} \varepsilon_{k}^{S_2}}{2}$$

and

$$|c_{j}^{S_1} - c_{k}^{S_2}| \leq \frac{1}{2} |\varepsilon_{j}^{S_1} - \varepsilon_{j}^{S_2}| + \frac{1}{2} |\varepsilon_{k}^{S_1} - \varepsilon_{k}^{S_2}| + |\varepsilon_{j}^{S_1} \varepsilon_{k}^{S_1} - \varepsilon_{j}^{S_2} \varepsilon_{k}^{S_2}|$$

$$\leq \left( \frac{20\sqrt{\nu}}{(-2 + 4L - 8\nu)} \right)^2.$$
The claim of Proposition 2 follows with
\[ G(\gamma, \nu) := 36(1 - 2\gamma)^{-2}(-2 + 4L - 8\nu)^{-1} = 36(1 - 2\gamma)^{-2}(2 - 8\gamma + 8\gamma^2 - 16\nu)^{-1}. \]

\[ \square \]

**Proof of Lemma 3:**
Clearly, if all expressions in (10) and (11) are defined, then \((\varepsilon^S_i)_{i \in [n]}, (c^S_{jk})_{i < j \leq n}^S\) is a solution of (4) with \(p_{jk}\) as right-hand side because of the choice of \(c^S_{jk}\). We need to show that if \(i_1, i_2, i_3 \in L^{\text{TR}}\), then all expressions are defined and
\[ |\varepsilon_i^\text{TR} - \varepsilon_i^S| \leq H(\gamma^{\text{TR}}, \beta)\sqrt{\beta}, \quad |c^\text{TR}_{jk} - c^S_{jk}| \leq 3H(\gamma^{\text{TR}}, \beta)\sqrt{\beta + \beta/2}, \]
where we set
\[ H(\gamma^{\text{TR}}, \beta) := \frac{14}{(1 - 2\gamma^{\text{TR}})^2 \sqrt{1 - 4\gamma^{\text{TR}}} + 4\gamma^{\text{TR}} \sqrt{1 - 4\gamma^{\text{TR}} + 4\gamma^{\text{TR}}_2 - 2\beta}}. \]
The proof of this claim is similar to the one of Proposition 2.

Let \(i_1, i_2, i_3 \in L^{\text{TR}}\) be pairwise distinct. We have \(\varepsilon_i^\text{TR}, \varepsilon_i^\text{TR} = \varepsilon_i^\text{TR} \leq \gamma^{\text{TR}} < \frac{1}{2}\) and
\[
\begin{align*}
1 - \varepsilon_i^\text{TR} - \varepsilon_i^\text{TR} + 2\varepsilon_i^\text{TR} \varepsilon_i^\text{TR} & = p_{i_1i_2}^\text{TR}, \\
1 - \varepsilon_i^\text{TR} - \varepsilon_i^\text{TR} + 2\varepsilon_i^\text{TR} \varepsilon_i^\text{TR} & = p_{i_2i_3}^\text{TR}, \\
1 - \varepsilon_i^\text{TR} - \varepsilon_i^\text{TR} + 2\varepsilon_i^\text{TR} \varepsilon_i^\text{TR} & = p_{i_1i_3}^\text{TR}.
\end{align*}
\]
(35)

It is
\[ \varepsilon_i^\text{TR} = \frac{p_{i_1i_2}^\text{TR} - 1 + \varepsilon_i^\text{TR}}{2\varepsilon_i^\text{TR} - 1}, \quad \varepsilon_i^\text{TR} = \frac{p_{i_2i_3}^\text{TR} - 1 + \varepsilon_i^\text{TR}}{2\varepsilon_i^\text{TR} - 1} \]
and \(\varepsilon_i^\text{TR}\) has to be the smaller solution of
\[ A^{\text{TR}}\varepsilon_i^2 + B^{\text{TR}}\varepsilon_i + C^{\text{TR}} = 0 \] (36)
with
\[ A^{\text{TR}} = 2 - 4p_{i_1i_3}^\text{TR}, \quad B^{\text{TR}} = -2 + 4p_{i_1i_3}^\text{TR} = -A^{\text{TR}}, \quad C^{\text{TR}} = 1 + 2p_{i_1i_2}^\text{TR} - p_{i_1i_3}^\text{TR} - p_{i_2i_3}^\text{TR}.
\]
We set
\[ A := 2 - 4p_{i_1i_3}, \quad B := -2 + 4p_{i_1i_3} = -A, \quad C := 1 + 2p_{i_1i_2} - p_{i_1i_3} - p_{i_2i_3}. \]

and consider
\[ B^2 - 4AC = 32p_{i_1i_2}p_{i_1i_3}p_{i_2i_3} - 16p_{i_1i_2}p_{i_1i_3} - 16p_{i_1i_2}p_{i_2i_3} - 16p_{i_1i_2}p_{i_2i_3} + 8p_{i_1i_3} + 8p_{i_1i_3} + 8p_{i_2i_3} - 4. \]

Let \(r > \frac{1}{2}\) and \(f : [r, 1]^3 \to \mathbb{R}\) with \(f(x, y, z) = 32xyz - 16xy - 16xz - 16yz + 8x + 8y + 8z - 4\). Let \(f_{x,y}(x) = f_{x,y}(z) = f(x, y, z)\). Using Lemma 4 (iv) we have
\[ f'_{y,z}(x) = 32yz - 16y - 16z + 8 = 16(2yz - y - z) + 8 \geq 16(-2r + 2r^2) + 8 > 0 \]
and similarly \(f'_{x,z}(y) > 0\) and \(f'_{x,y}(z) > 0\) for all \((x, y, z) \in [r, 1]^3\). It follows that
\[ 4 = f(1, 1, 1) \geq f(x, y, z) \geq f(r, r, r) = 32(r - 1/2)^3 > 0, \quad (x, y, z) \in [r, 1]^3. \]

Set \(\Gamma^{\text{TR}} := 1 - 2\gamma^{\text{TR}} + 2\gamma^{\text{TR}}_2\). Note that \(1/2 < \Gamma^{\text{TR}} < 1\). It follows from Lemma 4 (ii) and (35) that
\[ p_{i_1i_2}^\text{TR}, p_{i_1i_3}^\text{TR}, p_{i_2i_3}^\text{TR} \geq \Gamma^{\text{TR}}. \] (37)
Because of $|p_{jk} - p_{jk}| \leq \beta$, $j \neq k$, and the assumption on $\beta$, we have

$$p_{i_1i_2}, p_{i_1i_3}, p_{i_2i_3} \geq \Gamma_{TR} - \beta > 1/2.$$  \hfill (38)

Consequently, $B_{TR} > 0$ and

$$B > 0, \quad B^2 - 4AC \geq 32 (\Gamma_{TR} - \beta - 1/2)^3 > 0, \quad B + 4C = (B^2 - 4AC)/B > 0,$$

and all expressions in (10) and (11) are defined. It is

$$\varepsilon_{i_2}^R = \frac{1}{2} - \frac{\sqrt{B + 4C}}{2\sqrt{B}}, \quad \varepsilon_{i_2}^{TR} = \frac{1}{2} - \frac{\sqrt{B_{TR} + 4C_{TR}}}{2\sqrt{B_{TR}}}$$

by definition (see (10)) and since $\varepsilon_{i_2}^{TR}$ is the smaller solution of (36), respectively. Because of (37), (38), $|p_{jk} - p_{jk}| \leq \beta$, $j \neq k$, and $p_{jk}, p_{jk} \in [0, 1]$ we have

$$4\Gamma_{TR} - 2 \leq B_{TR} \leq 2, \quad 4(\Gamma_{TR} - \beta) - 2 \leq B \leq 2, \quad |B_{TR} - B| \leq 4\beta, \quad C_{TR}, C \leq 1, \quad |C_{TR} - C| \leq 7\beta.$$  \hfill (39)

It follows that

$$|\varepsilon_{i_2}^R - \varepsilon_{i_2}^{TR}| \leq \frac{1}{2 |\sqrt{B_{TR}} + \sqrt{B}|} \left[ \sqrt{|B - B_{TR}|} \cdot \sqrt{B + 4C + \sqrt{B} \cdot \sqrt{B_{TR} + 4C_{TR} - (B + 4C)}} \right]$$

$$\leq \frac{1}{2 \sqrt{2\Gamma_{TR} - 1}} \left[ 2\sqrt{\beta} \cdot \sqrt{6} + \sqrt{2} \cdot \sqrt{32\beta} \right]$$

and since $\varepsilon_{i_2}^{TR} \in [0, \gamma_{TR}]$ that

$$|\varepsilon_{i_2}^S - \varepsilon_{i_2}^{TR}| \leq |\varepsilon_{i_2}^R - \varepsilon_{i_2}^{TR}| \leq \frac{4\sqrt{\beta}}{\sqrt{2\Gamma_{TR} - 1} \sqrt{2(\Gamma_{TR} - \beta)} - 1}.$$  \hfill (40)

For $l \neq i_2$ we have

$$\varepsilon_{l}^R = \frac{p_{i_2l} - 1 + \varepsilon_{i_2}^S}{2\varepsilon_{i_2}^S - 1}, \quad \varepsilon_{l}^{TR} = \frac{p_{i_2l}^{TR} - 1 + \varepsilon_{i_2}^{TR}}{2\varepsilon_{i_2}^{TR} - 1}$$

by definition (see (11)) and since $(\varepsilon_{ik}^{TR})_{i \in [n]}$, $(c_{jk}^{TR})_{1 \leq j < k \leq n}$ is a solution of (4) with $p_{jk}^{TR}$ as right-hand side that satisfies (9) and $i_2 \in L_{TR}$. Because of

$$\varepsilon_{i_2}^{S}, \varepsilon_{i_2}^{TR} \in [0, \gamma_{TR}]$$  \hfill (41)
with $\gamma_{TR} < \frac{1}{2}$, we have

$$|\varepsilon_i^R - \varepsilon_i^{TR}| = \left| \frac{p_{i2l} - 1 + \varepsilon_{i2}^S}{2\varepsilon_{i2}^S - 1} - \frac{p_{i2l}^{TR} - 1 + \varepsilon_{i2}^{TR}}{2\varepsilon_{i2}^{TR} - 1} \right|$$

\(\leq\) \(\frac{|\varepsilon_{i2}^{TR} - \varepsilon_{i2}^S| + |p_{i2l}^{TR} - p_{i2l}| + 2|\varepsilon_{i2}^S p_{i2l}^{TR} - \varepsilon_{i2}^{TR} p_{i2l}|}{(1 - 2\gamma_{TR})^2}\)

\(\leq \frac{3|\varepsilon_{i2}^{TR} - \varepsilon_{i2}^S| + 2|p_{i2l}^{TR} - p_{i2l}|}{(1 - 2\gamma_{TR})^2}\)

\(\leq \frac{12\sqrt{\beta}}{(1 - 2\gamma_{TR})^2 \sqrt{2\gamma_{TR} - 1} \sqrt{2(1 - \beta)}} - 1 + \frac{2\beta}{(1 - 2\gamma_{TR})^2}\)

\(= H(\gamma_{TR}, \beta) \sqrt{\beta}.\) (42)

Since $\varepsilon_i^{TR} \in [0, 1], l \in [n]$, and $\varepsilon_{i2}^{TR}, \varepsilon_{i2}^S \in [0, \gamma_{TR}],$ this yields

$$|\varepsilon_i^S - \varepsilon_i^{TR} | \leq |\varepsilon_i^R - \varepsilon_i^{TR} | \leq H(\gamma_{TR}, \beta) \sqrt{\beta}.\) (42)

For $j < k$, it is

$$c_{jk}^S = \frac{p_{jk} - (1 - \varepsilon_j^S - \varepsilon_k^S + 2\varepsilon_j^S \varepsilon_k^S)}{2}, \quad c_{jk}^{TR} = \frac{p_{jk}^{TR} - (1 - \varepsilon_j^{TR} - \varepsilon_k^{TR} + 2\varepsilon_j^{TR} \varepsilon_k^{TR})}{2},$$

and because of $\varepsilon_i^S, \varepsilon_i^{TR} \in [0, 1], l \in [n],$

$$|c_{jk}^S - c_{jk}^{TR}| = \frac{1}{2} |p_{jk} - (1 - \varepsilon_j^S - \varepsilon_k^S + 2\varepsilon_j^S \varepsilon_k^S) - [p_{jk}^{TR} - (1 - \varepsilon_j^{TR} - \varepsilon_k^{TR} + 2\varepsilon_j^{TR} \varepsilon_k^{TR})]|$$

\(\leq \frac{1}{2} |p_{jk} - p_{jk}^{TR}| + \frac{1}{2} |\varepsilon_j^S - \varepsilon_j^{TR}| + \frac{1}{2} |\varepsilon_k^S - \varepsilon_k^{TR}| + |\varepsilon_j^S \varepsilon_k^S - \varepsilon_j^{TR} \varepsilon_k^{TR}|\)

\(\leq \frac{1}{2} |p_{jk} - p_{jk}^{TR}| + \frac{3}{2} |\varepsilon_j^S - \varepsilon_j^{TR}| + \frac{3}{2} |\varepsilon_k^S - \varepsilon_k^{TR}|\)

\(\leq \frac{1}{2} \beta + 3H(\gamma_{TR}, \beta) \sqrt{\beta}.\) (42)

□
C. Further experiments and characteristic values of the real world data sets

Figure 4 shows three experiments that are similar to the first experiment of Section 6.1:

In the experiment shown in the first row, the setup is the same as in the experiment of Section 6.1, but here we restrict $0 \leq t \leq 24$ to be even and divide the corrupted workers into two groups. For each group, the workers in the group provide the same random responses, independently from the responses of the corrupted workers in the other group. Hence, the error probabilities of a corrupted worker from the one group and of a corrupted worker from the other group are uncorrelated and the problem is more similar to an instance of the one-coin model. Indeed, the methods from the literature perform slightly better than in the experiment of Section 6.1. However, the overall picture is the same.

In the experiment shown in the second row, tasks are uniformly distributed on the unit interval $[0,1]$ and for every task the ground-truth label is $+1$. For $0 \leq t \leq 25$, we consider $t$ corrupted workers that all have the same conditional error probability $\varepsilon(x, +1) = x$, $x \in [0,1]$. Compared to the experiment of Section 6.1, where the covariance between the error probabilities of two corrupted workers is $1/4$, in this experiment this covariance is only $1/12$. Like in the experiment of Section 6.1 and the one shown in the first row, workers that are not corrupted follow the one-coin model with error probability 0.4. Interestingly, KOS, S-EM1 and S-EM10 cannot deal with this setup even in the case when there are no corrupted workers at all. The reason is that these methods assume that both $Pr_{(x,y)\sim D}[y = +1]$ and $Pr_{(x,y)\sim D}[y = -1]$ are strictly positive. GKM, RoE and EoR can handle up to six corrupted workers. TE can handle only two corrupted workers. Our Algorithm 1 can perfectly handle up to 23 corrupted workers.

Finally, in the third row we can see the same experiment as in Section 6.1, but here the error probability of the workers that are not corrupted and follow the one-coin model is only 0.15 instead of 0.4. The methods from the literature perform much better here. Except for TE, all methods can handle 16 or more corrupted workers. Still, again our Algorithm 1 is the only method that can perfectly handle up to 23 corrupted workers.
### Table 2. Real world data sets: characteristic values after removing workers that provided fewer than 50 labels.

<table>
<thead>
<tr>
<th>Data set</th>
<th># tasks</th>
<th># workers</th>
<th>(# +1) / (# -1)</th>
<th># crowdsourced labels (overall)</th>
<th>average (min/max) # labels / worker</th>
<th>average (min/max) # workers / task</th>
</tr>
</thead>
<tbody>
<tr>
<td>Bird</td>
<td>108</td>
<td>39</td>
<td>0.8</td>
<td>4212</td>
<td>108 (108 / 108)</td>
<td>39 (39 / 39)</td>
</tr>
<tr>
<td>Dog</td>
<td>807</td>
<td>49</td>
<td>1.07</td>
<td>7213</td>
<td>147.2 (53 / 345)</td>
<td>8.9 (4 / 10)</td>
</tr>
<tr>
<td>Duchenne</td>
<td>160</td>
<td>10</td>
<td>0.57</td>
<td>1072</td>
<td>107.2 (50 / 160)</td>
<td>6.7 (5 / 8)</td>
</tr>
<tr>
<td>RTE</td>
<td>800</td>
<td>23</td>
<td>1</td>
<td>4840</td>
<td>210.4 (60 / 800)</td>
<td>6 (4 / 9)</td>
</tr>
<tr>
<td>Temp</td>
<td>462</td>
<td>21</td>
<td>0.78</td>
<td>3754</td>
<td>178.8 (50 / 462)</td>
<td>8.1 (6 / 10)</td>
</tr>
<tr>
<td>Web</td>
<td>2653</td>
<td>54</td>
<td>0.77</td>
<td>13797</td>
<td>255.5 (50 / 1225)</td>
<td>5.2 (1 / 10)</td>
</tr>
</tbody>
</table>

**Figure 5.** Real world data sets: histograms of the error probabilities of the workers.

Table 2 provides the characteristic values of the real world data sets used in the experiments of Section 6.2.

Figure 5 shows for each of the real world data sets a histogram of the error probabilities of the workers.

Figure 6 shows for each of the real world data sets a heat map of the matrix $(\text{Cov} (\varepsilon_{wj}(x, y), \varepsilon_{wk}(x, y)))_{j,k=1}^n$.

Figure 7 corresponds to Figure 3 of Section 6.2 and shows the plots for the remaining data sets.
Figure 6. Real world data sets: heat maps of the matrices $|\text{Cov}[\varepsilon_{w_j}(x, y), \varepsilon_{w_k}(x, y)]|_{j, k=1}^n$ (if workers $w_j$ and $w_k$ were not presented with at least one common task, we set $\text{Cov}[\varepsilon_{w_j}(x, y), \varepsilon_{w_k}(x, y)] = \text{NaN}$).

Figure 7. Real world data sets: prediction error of the various methods as a function of the number of corrupted workers.