On Nesting Monte Carlo Estimators – Supplementary Material

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Appendix A  Proof of Theorem 1 - Simplified Convergence Rate

Theorem 1. If \( f \) is Lipschitz continuous and \( f(y_n, \gamma(y_n)), \phi(y_n, z_{n,m}) \in L^2 \), the mean squared error of \( I_{N,M} \) converges to 0 at rate \( O\left(\frac{1}{N} + \frac{1}{M}\right) \).

Proof. Though the Theorem follows directly from Theorem 3, we also provide the following proof for this simplified case to provide a more accessible intuition behind the result. Note that the approach taken is distinct from the proof of Theorem 3.

Using Minkowski’s inequality, we can bound the mean squared error of \( I_{N,M} \) by

\[
\mathbb{E}[(I - I_{N,M})^2] = \|I - I_{N,M}\|_2^2 \leq U^2 + V^2 + 2UV \leq 2(U^2 + V^2)
\]

where \( U = \left\| \frac{1}{N} \sum_{n=1}^{N} f(y_n, \gamma(y_n)) \right\|_2 \) and \( V = \left\| \frac{1}{N} \sum_{n=1}^{N} f(y_n, \gamma(y_n)) - I_{N,M} \right\|_2 \).

We see immediately that \( U = O\left(\frac{1}{\sqrt{N}}\right) \), since \( \frac{1}{N} \sum_{n=1}^{N} f(y_n, \gamma(y_n)) \) is a MC estimator for \( I \), noting our assumption that \( f(y_n, \gamma(y_n)) \in L^2 \). For the second term,

\[
V = \left\| \frac{1}{N} \sum_{n=1}^{N} f(y_n, \gamma(y_n)) - f(y_n, \gamma(y_n)) \right\|_2 \leq \frac{1}{N} \sum_{n=1}^{N} K \|\hat{\gamma}_M - \gamma(y_n)\|_2 + \frac{1}{N} \sum_{n=1}^{N} K \|\hat{\gamma}_M - \gamma(y_n)\|_2
\]

where \( K \) is a fixed constant, again by Minkowski and using the assumption that \( f \) is Lipschitz. We can rewrite

\[
\|\hat{\gamma}_M - \gamma(y_n)\|_2^2 = \mathbb{E}\left[\left(\|\hat{\gamma}_M - \gamma(y_n)\|_2^2\right)\bigg| y_n\right]
\]

by the tower property of conditional expectation, and note that

\[
\mathbb{E}\left[\left(\|\hat{\gamma}_M - \gamma(y_n)\|_2^2\right)\bigg| y_n\right] = \text{Var}\left(\frac{1}{M} \sum_{m=1}^{M} \phi(y_n, z_{n,m}) \bigg| y_n\right) = \frac{1}{M} \text{Var}\left(\phi(y_n, z_{n,1})\bigg| y_n\right)
\]

since each \( z_{n,m} \) is i.i.d. and conditionally independent given \( y_n \). As such

\[
\|\hat{\gamma}_M - \gamma(y_n)\|_2^2 = \frac{1}{M} \mathbb{E}\left[\text{Var}\left(\phi(y_n, z_{n,1})\bigg| y_n\right)\right] = O(1/M),
\]

noting that \( \mathbb{E}\left[\text{Var}\left(\phi(y_n, z_{n,1})\bigg| y_n\right)\right] \) is a finite constant by our assumption that \( \phi(y_n, z_{n,m}) \in L^2 \). Consequently,

\[
V \leq \frac{NK}{N} O\left(\frac{1}{\sqrt{M}}\right) = O\left(\frac{1}{\sqrt{M}}\right).
\]

Substituting these bounds for \( U \) and \( V \) in (25) gives

\[
\|I - I_{N,M}\|_2^2 \leq 2\left(O\left(\frac{1}{\sqrt{N}}\right)^2 + O\left(\frac{1}{\sqrt{M}}\right)^2\right) = O\left(\frac{1}{N} + \frac{1}{M}\right)
\]

as desired.

Appendix B  The Inevitable Bias of Nested Estimation

In this section we demonstrate formally that NMC schemes must produce biased estimates of \( I(f) \) for certain functions \( f \). In fact, our result applies more generally: we show that this holds for any MC scheme that makes use of imperfect estimates.
Assume that $E$, where the $\hat{\zeta}_n$ is a result of Jensen’s inequality on the inner expectation. Since $\hat{\zeta}_n \neq \gamma(y_n)$, there exists a measurable $A \subseteq Y$ as $A = \{ y \in Y \mid \text{Var}(\hat{\zeta}_n | y_n = y) > 0 \}$ and assume that $P(y_n \in A) > 0$. Then for any $f$ that is strictly convex in its second argument,

$$\mathbb{E} \left[ \frac{1}{N} \sum_{n=1}^{N} f(y_n, \hat{\zeta}_n) \right] > I(f).$$

Similarly for any $f$ that is strictly concave in its second argument,

$$\mathbb{E} \left[ \frac{1}{N} \sum_{n=1}^{N} f(y_n, \hat{\zeta}_n) \right] < I(f).$$

Proof. We prove our claim for the case that $f$ is strictly convex; our proof for the other concave case is symmetrical. We have

$$\mathbb{E} \left[ \frac{1}{N} \sum_{n=1}^{N} f(y_n, \hat{\zeta}_n) \right] = \mathbb{E} \left[ f(y_1, \hat{\zeta}_1) \right] = \mathbb{E} \left[ \mathbb{E} \left[ f(y_1, \hat{\zeta}_1) | y_1 \right] \right] \geq \mathbb{E} \left[ f \left( y_1, \mathbb{E} \left[ \hat{\zeta}_1 | y_1 \right] \right) \right] = I(f)$$

where the $\geq$ is a result of Jensen’s inequality on the inner expectation. Since $f$ is strictly convex and therefore non-linear, equality holds if and only if $\hat{\zeta}_1$ is almost surely constant given $y_1$. This is violated whenever $y_1 \in A$, which by assumption has a non-zero probability of occurring. Consequently, the inequality must be strict, giving the desired result.

In addition to some special cases discussed in the Section[4], it may still be possible to develop unbiased estimation schemes for certain non-linear $f$ using Russian roulette sampling ([Lyne et al., 2015]) or other debiasing techniques. However, these induce their own complications; for some problems the resultant estimates have infinite variance ([Lyne et al., 2015]) and as shown by ([Jacob et al., 2015]), there are no general purpose “$f$-factories” that produce both non-negative and unbiased estimates for non-constant, positive output functions $f : \mathbb{R} \rightarrow \mathbb{R}^+$, given unbiased estimates for the inputs.

### Appendix C Proof of Theorem 2 - “Almost almost sure” convergence

**Theorem 2.** For $n \in \mathbb{N}$, let

$$(\epsilon_M)_n = |f(y_n, (\hat{\gamma}_M)_n) - f(y_n, \gamma(y_n))|.$$

Assume that $\mathbb{E} \left[ |(\epsilon_M)_1| \right] \rightarrow 0$ as $M \rightarrow \infty$. Let $\Omega$ be the sample space of our underlying probability space, so that $I_{\tau_\delta(M),M}$ forms a mapping from $\Omega$ to $\mathbb{R}$. Then, for every $\delta > 0$, there exists a measurable $A_\delta \subseteq \Omega$ with $P(A_\delta) < \delta$, and a function $\tau_\delta : \mathbb{N} \rightarrow \mathbb{N}$ such that, for all $\omega \notin A_\delta$,

$$I_{\tau_\delta(M),M}(\omega) \overset{a.s.}{\rightarrow} I \quad \text{as} \quad M \rightarrow \infty.$$
Proof. For all \( N, M \), we have by the triangle inequality that
\[
|I_{N,M} - I| \leq V_{N,M} + U_N,
\]
where
\[
V_{N,M} = \frac{1}{N} \sum_{n=1}^{N} f(y_n, \gamma(y_n)) - I_{N,M} \quad \text{and} \quad U_N = \left| I - \frac{1}{N} \sum_{n=1}^{N} f(y_n, \gamma(y_n)) \right|.
\]
A second application of the triangle inequality then allows us to write
\[
V_{N,M} \leq \frac{1}{N} \sum_{n=1}^{N} (\epsilon_M)_n
\]
where we recall that \((\epsilon_M)_n = |f(y_n, \gamma(y_n)) - f(y_n, \gamma_n)|\). Now, for all fixed \( M \), each \((\epsilon_M)_n\) is i.i.d. Furthermore, since \( \mathbb{E}[|\epsilon_M|] \to 0 \) as \( M \to \infty \) by our assumption and \((\epsilon_M)_n\) is nonnegative, there exists some \( L \in \mathbb{N} \) such that \( \mathbb{E}[|\epsilon_M|] < \infty \) for all \( M \geq L \). Consequently, the strong law of large numbers means that as \( N \to \infty \) then for all \( M \geq L \)
\[
\frac{1}{N} \sum_{n=1}^{N} (\epsilon_M)_n \xrightarrow{a.s.} \mathbb{E}[\epsilon_M].
\]
(26)

For any fixed \( \delta > 0 \) then by repeatedly applying Egorov’s theorem to each \( M \geq L \), we can find a sequence of events
\[
B_L, B_{L+1}, B_{L+2}, \ldots
\]
such that for every \( M \geq L \),
\[
\mathbb{P}(B_M) < \frac{\delta}{4} \cdot \frac{1}{2^{M-L}}
\]
and outside of \( B_M \), the sequence \( \frac{1}{N} \sum_{n=1}^{N} (\epsilon_M)_n \) converges uniformly to \( \mathbb{E}[\epsilon_M] \). This uniform convergence (as opposed to just the piecewise convergence implied by (26)) now guarantees that we can define some function \( \tau^1_\delta : \mathbb{N} \to \mathbb{N} \) such that
\[
\left| \frac{1}{M'} \sum_{n=1}^{M'} (\epsilon_M)_n(\omega) - \mathbb{E}[\epsilon_M] \right| < \frac{1}{M}
\]
for all \( M \geq L, M' \geq \tau^1_\delta(M) \), and \( \omega \notin B_M \), remembering that \( \omega \) is a point in our sample space. We further have that (27) holds for all \( M \geq M_0, M' \geq \tau^1_\delta(M) \), and \( \omega \notin B_\delta := \bigcup_{M \geq L} B_M \). Consequently, for all such \( M, M' \) and \( \omega \),
\[
V_{M',M}(\omega) \leq \frac{1}{M'} \sum_{n=1}^{M'} (\epsilon_M)_n(\omega) < \frac{1}{M} + \mathbb{E}[\epsilon_M],
\]
(28)
while we also have
\[
\mathbb{P}(B_\delta) \leq \sum_{M \geq L} \mathbb{P}(B_M) < \sum_{M \geq L} \frac{\delta}{4} \cdot \frac{1}{2^{M-L}} = \frac{\delta}{2}.\]
(29)

To complete the proof, we must remove the dependence of \( U_N \) on \( N \) as well. This is straightforward once we observe that \( U_N \xrightarrow{a.s.} 0 \) as \( N \to \infty \) by the strong law of large numbers. So, by Egorov’s theorem again, there exists an event \( C_\delta \) such that
\[
\mathbb{P}(C_\delta) < \frac{\delta}{2}
\]
(30)
and outside of \( C_\delta \), the sequence \( U_N \) converges uniformly to 0. This uniform convergence, in turn, ensures the existence of a function \( \tau^2_\delta : \mathbb{N} \to \mathbb{N} \) such that
\[
U_{M'}(\omega) < \frac{1}{M}
\]
(31)
for all \( M \in \mathbb{N}, M' \geq \tau^2_\delta(M) \), and \( \omega \notin C_\delta \).

We can now define \( \tau_\delta(M) = \max(\tau^1_\delta(M), \tau^2_\delta(M)) \), and \( A_\delta = B_\delta \cup C_\delta \). By inequalities in (29) and (30),
\[
\mathbb{P}(A_\delta) \leq \mathbb{P}(B_\delta) + \mathbb{P}(C_\delta) < \delta.
\]
Also, by the inequalities in (28) and (31),
\[ |I - I_{\tau(M),M}(\omega)| \leq V_{\tau(M),M}(\omega) + U_{\tau(M)}(\omega) \leq \frac{1}{M} + \frac{1}{M} + \mathbb{E}[(\epsilon_M)_1] \]
for all \( M \geq L \) and \( \omega \notin A_M \). Since \( \mathbb{E}[(\epsilon_M)_1] \to 0 \), we have here that \( I_{\tau(M),M}(\omega) \to I \) as desired.

\[ \square \]

Appendix D - Proof of Theorem 3 - Convergence for Repeated Nesting

**Theorem 3.** If \( f_0, \ldots, f_D \) are all Lipschitz continuous in their second input with Lipschitz constants
\[ K_k := \sup_{y^{(k)}} \left| \frac{\partial f_k(y^{(k)}, \gamma_{k+1}(y^{(k)}))}{\partial \gamma_{k+1}} \right|, \]
for all \( k \in 0, \ldots, D-1 \) and if
\[ \varsigma_k := \mathbb{E} \left[ \left( f_k(y^{(0:k)}, \gamma_{k+1}(y^{(0:k)})) - \gamma_k(y^{(0:k-1)}) \right)^2 \right] \]
then
\[ \mathbb{E} \left[ (I_0 - \gamma_0)^2 \right] \leq \frac{\varsigma_0^2}{N_0} + \sum_{k=1}^{D} \left( \prod_{\ell=0}^{k-1} K_{\ell}^2 \right) \frac{\varsigma_k^2}{N_k} + O(\epsilon) \quad (5) \]
where \( O(\epsilon) \) represents asymptotically dominated terms.

If \( f_0, \ldots, f_D \) are also continuously differentiable with second derivative bounds
\[ C_k := \sup_{y^{(k)}} \left| \frac{\partial^2 f_k(y^{(k)}, \gamma_{k+1}(y^{(k)}))}{\partial \gamma_{k+1}^2} \right| \]
then this mean square error bound can be tightened to
\[ \mathbb{E} \left[ (I_0 - \gamma_0)^2 \right] \leq \frac{\varsigma_0^2}{N_0} + \left( \frac{C_0 \varsigma_1}{2N_1} + \sum_{k=2}^{D} \left( \prod_{d=0}^{k-2} K_d \right) \frac{C_{k+1} \varsigma_{k+2}^2}{2N_{k+2}} \right) \frac{\varsigma_k^2}{N_k} + O(\epsilon). \quad (6) \]

For a single nesting, we can further characterize \( O(\epsilon) \) giving
\[ \mathbb{E} \left[ (I_0 - \gamma_0)^2 \right] \leq \frac{\varsigma_0^2}{N_0} + \frac{4K_0^2 \varsigma_1^2}{N_0 N_1} + \frac{2K_0 \varsigma_1^2}{N_0 \sqrt{N_1}} + \frac{K_0^2 \varsigma_1^2}{N_1} \quad (7) \]
\[ \mathbb{E} \left[ (I_0 - \gamma_0)^2 \right] \leq \frac{\varsigma_0^2}{N_0} + \frac{C_0 \varsigma_1^4}{4N_1^2} \left( 1 + \frac{1}{N_0} \right) \]
\[ + \frac{K_0 \varsigma_1^2}{N_0 N_1} \sqrt{\varsigma_0^2 + \frac{C_0 \varsigma_1^4}{4N_1^2}} + O \left( \frac{1}{N_1^3} \right) \quad (8) \]
for when the continuous differentiability assumption does not hold and holds respectively.

**Proof.** As this is a long and involved proof, we start by defining a number of useful terms that will be used throughout. Unless otherwise stated, these definitions hold for all \( k \in \{0, \ldots, D\} \). Note that most of these terms implicitly depend on the number of samples \( N_0, N_1, \ldots, N_D \). However, \( s_k, \varsigma_{d,k}, \) and \( \varsigma_k \) do not and are thus constants for a particular problem.

\( E_k(y^{(0:k-1)}) \) is the MSE of the estimator at depth \( k \) given \( y^{(0:k-1)} \)
\[ E_k(y^{(0:k-1)}) := \mathbb{E} \left[ \left( I_k(y^{(0:k-1)}) - \gamma_k(y^{(0:k-1)}) \right)^2 \right] \quad (32) \]
On Nesting Monte Carlo Estimators

\( \hat{f}_k \left( y^{(0:k-1)} \right) \) is the expected value of the estimate at depth \( k \), or equivalently the expected function output using the estimate of the layer below

\[
\hat{f}_k \left( y^{(0:k-1)} \right) := E \left[ f_k \left( y^{(0:k-1)} \right) \mid y^{(0:k-1)} \right] \quad \forall k \in \{1, \ldots, D - 1\}
\]

\( \tilde{f}_k \left( y^{(0:k-1)} \right) \) is the expectation of \( \omega \)

\[
\tilde{f}_k \left( y^{(0:k-1)} \right) := E \left[ f_k \left( y^{(0:k-1)} \right) \mid \tilde{y}^{(0:k-1)} \right]
\]

(33)

\( v_k^2 \left( y^{(0:k-1)} \right) \) is the variance of the estimator at depth \( k \)

\[
v_k^2 \left( y^{(0:k-1)} \right) := \text{Var} \left[ I_k \left( y^{(0:k-1)} \right) \mid y^{(0:k-1)} \right]
\]

(34)

\( \beta_k \left( y^{(0:k-1)} \right) \) is the bias of the estimator at depth \( k \)

\[
\beta_k \left( y^{(0:k-1)} \right) := E \left[ f_k \left( y^{(0:k-1)} \right) \mid y^{(0:k-1)} \right] - \gamma_k \left( y^{(0:k-1)} \right) y^{(0:k-1)}
\]

(35)

\( s_k^2 \left( y^{(0:k-1)} \right) \) is the variance at depth \( k \) of the true function output

\[
s_k^2 \left( y^{(0:k-1)} \right) := E \left[ \left( f_k \left( y^{(0:k)} \right) \gamma_{k+1} \left( y^{(0:k)} \right) \right) - \gamma_k \left( y^{(0:k-1)} \right) \right] y^{(0:k-1)}
\]

(36)

\( s_D^2 \left( y^{(0:D-1)} \right) \) is the variance of \( f_d \left( y^{(0:d-1)} \right) \) over \( y^{(0:d-1)} \)

\[
s_D^2 \left( y^{(0:D-1)} \right) := E \left[ f_d \left( y^{(0:d)} \right) - \gamma_d \left( y^{(0:d-1)} \right) \right] y^{(0:d-1)}
\]

(37)

(38)

\( \zeta_{d,k}^2 \left( y^{(0:k-1)} \right) \) is expectation of \( s_d^2 \left( y^{(0:d-1)} \right) \) over \( y^{(0:k-1)} \)

\[
\zeta_{d,k}^2 \left( y^{(0:k-1)} \right) := E \left[ \left( f_k \left( y^{(0:k)} \right) \gamma_{k+1} \left( y^{(0:k)} \right) \right) - \gamma_k \left( y^{(0:k-1)} \right) \right] y^{(0:k-1)}
\]

(39)

(40)

(41)

(42)
\( \lambda_k \left( y^{(0:k-1)} \right) \) is the expectation over \( y^{(k)} \) of the magnitude of the bias for the next layer, we fix \( \lambda_D \left( y^{(0:D-1)} \right) := 0 \) and note that \( \lambda_{D-1} \left( y^{(0:D-2)} \right) := 0 \) also as the innermost layer is an unbiased

\[
\lambda_k \left( y^{(0:k-1)} \right) := \mathbb{E} \left[ \beta_{k+1} \left( y^{(0:k)} \right) \right] y^{(0:k-1)}
\]

\[
= \mathbb{E} \left[ \mathbb{E} \left( I_{k+1} \left( y^{(0:k)} \right) - \gamma_{k+1} \left( y^{(0:k)} \right) \right) \left| y^{(0:k)} \right| y^{(0:k-1)} \right]
\]  

\[\text{(43)}\]

**Lipschitz Continuous Case**

Given these definitions, we start by breaking the error down into a variance and bias term. Using the standard bias-variance decomposition we have

\[
E_k \left( y^{(0:k-1)} \right) = \mathbb{E} \left( I_k \left( y^{(0:k-1)} \right) - \gamma_k \left( y^{(0:k-1)} \right) \right)^2 \left| y^{(0:k-1)} \right|
\]

\[
= \nu_k^2 \left( y^{(0:k-1)} \right) + \left( \beta_k \left( y^{(0:k-1)} \right) \right)^2
\]  

\[\text{(44)}\]

It is immediately clear from its definition in (35) that the bias term \( \left( \beta_k \left( y^{(0:k-1)} \right) \right)^2 \) is independent of \( N_0 \). On the other hand, we will show later that the dominant components of the variance term for large \( N_{0:D} \) depend only on \( N_0 \). We can thus think of increasing \( N_0 \) as reducing the variance of the estimator and increasing \( N_{1:D} \) as reducing the bias.

We first consider the variance term

\[
\nu_k^2 \left( y^{(0:k-1)} \right) = \mathbb{E} \left[ \frac{1}{N_k} \sum_{n=1}^{N_k} f_k \left( y_n^{(0:k)}, I_{k+1} \left( y_n^{(0:k)} \right) \right) - \bar{f}_k \left( y^{(0:k-1)} \right) \right] ^2 \left| y^{(0:k-1)} \right|
\]

\[
= \frac{1}{N_k} \mathbb{E} \left[ \left( f_k \left( y^{(0:k)}, I_{k+1} \left( y^{(0:k)} \right) \right) - \bar{f}_k \left( y^{(0:k-1)} \right) \right) ^2 \left| y^{(0:k-1)} \right| \right]
\]

with the equality following because the \( y_n^{(0:k)} \) being drawn i.i.d. and the expectation of each \( f_k \left( y_n^{(0:k)}, I_{k+1} \left( y_n^{(0:k)} \right) \right) \) equaling \( \bar{f}_k \left( y^{(0:k-1)} \right) \) means that all the cross terms are zero. By the definition of \( \sigma_k^2 \) we now have

\[
\nu_k^2 \left( y^{(0:k-1)} \right) = \frac{\sigma_k^2 \left( y^{(0:k-1)} \right)}{N_k}.
\]  

\[\text{(45)}\]

By using Minkowski’s inequality and the definition of \( A_k \) it also follows that

\[
\sigma_k \left( y^{(0:k-1)} \right) \leq \left( A_k \left( y^{(0:k-1)} \right) \right) ^\frac{1}{2} + \left( \mathbb{E} \left[ \left( f_k \left( y^{(0:k)}, \gamma_{k+1} \left( y^{(0:k)} \right) \right) - \bar{f}_k \left( y^{(0:k-1)} \right) \right) ^2 \left| y^{(0:k-1)} \right| \right] \right) ^\frac{1}{2}.
\]  

\[\text{(46)}\]

Using a bias-variance decomposition on the second term above and noting that \( s_k^2 \left( y^{(0:k-1)} \right) \) and \( f_k \left( y^{(0:k-1)} \right) - \beta_k \left( y^{(0:k-1)} \right) \) are respectively the variance and expectation of \( f_k \left( y^{(0:k)}, \gamma_{k+1} \left( y^{(0:k)} \right) \right) \), we can rearrange the right-hand size of (46) to give

\[
\sigma_k \left( y^{(0:k-1)} \right) \leq \left( A_k \left( y^{(0:k-1)} \right) \right) ^\frac{1}{2} + s_k^2 \left( y^{(0:k-1)} \right) + \left( \beta_k \left( y^{(0:k-1)} \right) \right) ^2 \left( y^{(0:k-1)} \right) ^\frac{1}{2}.
\]  

\[\text{(47)}\]

Here \( s_k^2 \) is independent of the number of samples used at any level of the estimate, while \( A_k \) and \( \beta_k^2 \) are independent of \( N_d \ \forall d \leq k \). Now by Jensen’s inequality, we have that

\[
\left( \beta_k \left( y^{(0:k-1)} \right) \right) ^2 \leq A_k \left( y^{(0:k-1)} \right)
\]  

\[\text{(48)}\]

noting that the only difference in the definition of \( \left( \beta_k \left( y^{(0:k-1)} \right) \right) ^2 \) and \( A_k \left( y^{(0:k-1)} \right) \) is whether the squaring occurs inside or outside the expectation. Therefore, presuming that \( A_k \) does not increase with \( N_d \ \forall d > k \), neither will \( \sigma_k^2 \left( y^{(0:k-1)} \right) \), and so the variance term will converge to zero with rate \( O \left( 1/N_k \right) \). Further, if \( A_k \rightarrow 0 \) as \( N_k \rightarrow \infty \), then for a large number of inner samples \( \sigma_k^2 \rightarrow s_k^2 \) and thus we will have \( \nu_k^2 \left( y^{(0:k-1)} \right) \leq \frac{s_k^2}{N_k} + O \left( \epsilon \right) \) where \( O \left( \epsilon \right) \) represents higher order
We now show that Lipschitz continuity is sufficient for $A_k$ which is the standard error for Monte Carlo convergence. We further have

$$E_k \left( y^{(0:k-1)} \right) = \frac{\sigma_k^2 \left( y^{(0:k-1)} \right)}{N_k} + \beta_k^2 \left( y^{(0:k-1)} \right) = \frac{s_k^2 \left( y^{(0:k-1)} \right)}{N_k} + \beta_k^2 \left( y^{(0:k-1)} \right) + O(\epsilon).$$

(49)

We now show that Lipschitz continuity is sufficient for $A_k \to 0$ and derive a concrete bound on the variance by bounding $A_k$. By definition of Lipschitz continuity, we have that

$$\left( A_k \left( y^{(0:k-1)} \right) \right)^\frac{1}{2} \leq \left( \mathbb{E} \left[ K_k^2 \left( I_{k+1} \left( y^{(0:k)} \right) - \gamma_{k+1} \left( y^{(0:k)} \right) \right)^2 \right] \right)^\frac{1}{2}$$

$$= K_k \left( \omega_k \left( y^{(0:k-1)} \right) \right)^\frac{1}{2}$$

(50)

where we remember that $\omega_k \left( y^{(0:k-1)} \right) = \mathbb{E} \left[ E_{k+1} \left( y^{(0:k)} \right) \right] \mathbb{E} \left[ y^{(0:k-1)} \right]$ is the expected MSE of the next level estimator. Once we also have an expression for the bias, we will thus be able to use this bound on $A_k$ along with (44), (45), and (47) to inductively derive a bound on the error.

For the case where we only assume Lipschitz continuity then we will simply use the bound on the bias given by (48) leading to

$$E_k \left( y^{(0:k-1)} \right) \leq \frac{s_k^2 \left( y^{(0:k-1)} \right)}{N_k} + A_k \left( y^{(0:k-1)} \right).$$

(51)

$$\leq \frac{s_k^2 \left( y^{(0:k-1)} \right) + 2A_k \left( y^{(0:k-1)} \right) + 2 \left( A_k \left( y^{(0:k-1)} \right) \right)^\frac{1}{2} \left( s_k^2 \left( y^{(0:k-1)} \right) \right)^\frac{1}{2} + A_k \left( y^{(0:k-1)} \right)}{N_k}$$

$$= \frac{s_k^2 \left( y^{(0:k-1)} \right) + 2K^2_k \omega_k \left( y^{(0:k-1)} \right) + K^2_k \omega_k \left( y^{(0:k-1)} \right)}{N_k}$$

$$+ \frac{2K_k \left( \omega_k \left( y^{(0:k-1)} \right) \right)^\frac{1}{2} \left( s_k^2 \left( y^{(0:k-1)} \right) \right)^\frac{1}{2} + K^2_k \omega_k \left( y^{(0:k-1)} \right)}{N_k}$$

$$\leq \frac{s_k^2 \left( y^{(0:k-1)} \right) + 4K^2_k \omega_k \left( y^{(0:k-1)} \right) + 2K_k \left( \omega_k \left( y^{(0:k-1)} \right) \right)^\frac{1}{2} \left( s_k \left( y^{(0:k-1)} \right) \right)^\frac{1}{2} + K^2_k \omega_k \left( y^{(0:k-1)} \right)}{N_k}$$

(52)

which fully defines a bound on conditional the variance of one layer given the mean squared error of the layer below. In particular as $\omega_0 \left( y^{(0:D-1)} \right) = 0$ we now have

$$E_D \left( y^{(0:D-1)} \right) \leq \frac{s_D^2 \left( y^{(0:D-1)} \right)}{N_D} = \frac{\mathbb{E} \left[ \left( f_D \left( y^{(0:D)} \right) - \gamma_D \left( y^{(0:D)} \right) \right)^2 \right]}{N_D}$$

which is the standard error for Monte Carlo convergence. We further have

$$\omega_{D-1} \left( y^{(0:D-2)} \right) = \mathbb{E} \left[ E_D \left( y^{(0:D-1)} \right) \right] \left( y^{(0:D-2)} \right) = \frac{\omega_{D-1}^2 \left( y^{(0:D-2)} \right)}{N_D},$$

and thus

$$E_{D-1} \left( y^{(0:D-2)} \right) \leq \frac{s_{D-1}^2 \left( y^{(0:D-2)} \right) + 4K_{D-1}^2 \omega_{D-1}^2 \left( y^{(0:D-2)} \right)}{N_{D-1} N_D}$$

$$+ \frac{2K_{D-1} s_{D-1} \left( y^{(0:D-2)} \right) \omega_{D-1} \left( y^{(0:D-2)} \right)}{N_{D-1} \sqrt{N_D}} + \frac{K_{D-1}^2 \omega_{D-1} \left( y^{(0:D-2)} \right)}{N_D}.$$  

(53)

This leads to the following result for the single nesting case

$$E_0 \leq \frac{s_0^2}{N_0} + \frac{4K_0^2 \omega_0^2}{N_0 N_1} + \frac{2K_0 \omega_0 \gamma_1}{N_0 \sqrt{N_1}} + \frac{K_0^2 \omega_1^2}{N_1}.$$  

(54)

$$\approx \frac{s_0^2}{N_0} + \frac{K_0^2 \omega_0^2}{N_1} = O \left( \frac{1}{N_0} + \frac{1}{N_1} \right)$$

where the approximation becomes exact as $N_0, N_1 \to \infty$. Note that there is no $O \left( \epsilon \right)$ term as this bound is exact in the finite sample case.

Things quickly get messy for double nesting and beyond so we will ignore non-dominant terms in the limit $N_0, \ldots, N_D \to \infty$. 

On Nesting Monte Carlo Estimators
and resort to using $O(\epsilon)$ for these instead. We first note that removing dominated terms from (55) gives
\[
E_k \left( y^{(0:k-1)} \right) \leq \frac{s_k^2}{N_k} + K_k^2 \omega_k \left( y^{(0:k-1)} \right) + O(\epsilon) \tag{55}
\]
as $s_k^2$ does not decrease with increasing $N_{k+1:D}$ whereas the other terms do. We therefore also have
\[
\omega_k \left( y^{(0:k-1)} \right) = \mathbb{E} \left[ E_{k+1} \left( y^{(0:k)} \right) \bigg| y^{(0:k-1)} \right] \\
\leq \mathbb{E} \left[ \frac{s_k^2}{N_k} + K_{k+1}^2 \omega_{k+1} \left( y^{(0:k)} \right) \bigg| y^{(0:k-1)} \right] + O(\epsilon) \tag{56}
\]
and therefore by recursively substituting (56) into itself we have
\[
K_k^2 \omega_k \left( y^{(0:k-1)} \right) \leq \sum_{d=k+1}^{D} \left( \prod_{\ell=k}^{d-1} K_{\ell}^2 \right) \mathbb{E} \left[ \frac{s_d^2}{N_d} \left( y^{(0:d-1)} \right) \bigg| y^{(0:k-1)} \right] + O(\epsilon). \tag{57}
\]
Now noting that $\zeta_{k,d}^2 \left( y^{(0:k-1)} \right) = \mathbb{E} \left[ \frac{s_d^2}{N_d} \left( y^{(0:d-1)} \right) \bigg| y^{(0:k-1)} \right]$, substituting (57) back into (55) gives
\[
E_k \left( y^{(0:k-1)} \right) = \frac{s_k^2}{N_k} + \sum_{d=k+1}^{D} \left( \prod_{\ell=k}^{d-1} K_{\ell}^2 \right) \zeta_{d,k}^2 \left( y^{(0:k-1)} \right) + O(\epsilon). \tag{58}
\]
By definition we have that $\zeta_{0,0}^2 = s_0^2 = s_0^2$ and $\zeta_{d,0}^2 = s_d^2$ and as (58) holds in the case $k = 0$, the mean squared error of the overall estimator is as follows
\[
\mathbb{E} \left[ (I_0 - \gamma_0)^2 \right] = E_0 \leq \frac{s_0^2}{N_0} + \sum_{k=1}^{D} \frac{\left( \prod_{\ell=0}^{k-1} K_{\ell}^2 \right) s_k^2}{N_k} + O(\epsilon) \tag{59}
\]
and we have the desired result for the Lipschitz case.

**Continuously Differentiable Case**

We now revisit the bound for the bias in the continuously differentiable case to show that a tighter overall bound can be found. We first remember that
\[
\beta_k \left( y^{(0:k-1)} \right) = \mathbb{E} \left[ f_k \left( y^{(0:k)} \right), I_{k+1} \left( y^{(0:k)} \right) \right] - f_k \left( y^{(0:k)}, \gamma_{k+1} \left( y^{(0:k)} \right) \right) \left| y^{(0:k-1)} \right].
\]
Taylor’s theorem implies that for any continuously differentiable $f_k$ we can write
\[
f_k \left( y^{(0:k)}, I_{k+1} \left( y^{(0:k)} \right) \right) - f_k \left( y^{(0:k)}, \gamma_{k+1} \left( y^{(0:k)} \right) \right) \\
= \frac{\partial f_k \left( y^{(0:k)}, \gamma_{k+1} \left( y^{(0:k)} \right) \right)}{\partial \gamma_{k+1}} \left( I_{k+1} \left( y^{(0:k)} \right) - \gamma_{k+1} \left( y^{(0:k)} \right) \right) \\
+ \frac{1}{2} \frac{\partial^2 f_k \left( y^{(0:k)}, \gamma_{k+1} \left( y^{(0:k)} \right) \right)}{\partial^2 \gamma_{k+1}} \left( I_{k+1} \left( y^{(0:k)} \right) - \gamma_{k+1} \left( y^{(0:k)} \right) \right)^2 \\
+ h_3 \left( I_{k+1} \left( y^{(0:k)} \right) \right) \left( I_{k+1} \left( y^{(0:k)} \right) - \gamma_{k+1} \left( y^{(0:k)} \right) \right)^3 \tag{60}
\]
where $\lim_{x \to \gamma_{k+1} \left( y^{(0:k)} \right)} h_3(x) = 0$. Consequently, the last term is $O \left( \left( I_{k+1} \left( y^{(0:k)} \right) - \gamma_{k+1} \left( y^{(0:k)} \right) \right)^3 \right)$ and so will diminish in magnitude faster than the first two terms provided that the derivatives are bounded, which is guaranteed by our assumptions. We will thus use $O(\epsilon)$ for this term and note that it is dominated in the limit.

Now defining
\[
\delta_{\ell,k} = \mathbb{E} \left[ \frac{\partial f_k \left( y^{(0:k)}, \gamma_{k+1} \left( y^{(0:k)} \right) \right)}{\partial \gamma_{k+1}} \left( I_{k+1} \left( y^{(0:k)} \right) - \gamma_{k+1} \left( y^{(0:k)} \right) \right)^\ell \left| y^{(0:k-1)} \right].
\]
then we have
\[ \beta_k^2 \left( y^{(0:k-1)} \right) = \delta_{1,k}^2 + \frac{\delta_{2,k}^2}{4} + \delta_{1,k} \delta_{2,k} + O(\epsilon). \]

By using the tower property we further have that
\[
\delta_{\ell,k} = \mathbb{E} \left[ \frac{\partial f_k^\ell (y^{(0:k)}, \gamma_{k+1}(y^{(0:k)}))}{\partial \gamma_{k+1}} \right] \mathbb{E} \left[ \left( I_{k+1} \left( y^{(0:k)} \right) - \gamma_{k+1} \left( y^{(0:k)} \right) \right) \ell \left( y^{(0:k)} \right) \right] \left| y^{(0:k-1)} \right|
\]
\[ = \mathbb{E} \left[ \frac{\partial f_k^\ell (y^{(0:k)}, \gamma_{k+1}(y^{(0:k)}))}{\partial \gamma_{k+1}} \right] \mathbb{E} \left[ \left( I_{k+1} \left( y^{(0:k)} \right) - \gamma_{k+1} \left( y^{(0:k)} \right) \right) \ell \left( y^{(0:k)} \right) \right] \left| y^{(0:k-1)} \right|
\]
\[ \leq \left( \sup_{y^{(0)}} \left| \frac{\partial f_k^\ell (y^{(0:k)}, \gamma_{k+1}(y^{(0:k)}))}{\partial y^{(0:k)}} \right| \right) \mathbb{E} \left[ \left( I_{k+1} \left( y^{(0:k)} \right) - \gamma_{k+1} \left( y^{(0:k)} \right) \right) \ell \left( y^{(0:k)} \right) \right] \left| y^{(0:k-1)} \right|
\]
Now for the particular cases of \( \ell = 1 \) and \( \ell = 2 \) then the derivative terms where defined in the theorem and the expectations correspond respectively to our definitions of \( \lambda_k \) and \( \omega_k \) giving
\[ \delta_{1,k} \leq K_k \lambda_k \left( y^{(0:k-1)} \right) \]
\[ \delta_{2,k} \leq C_k \omega_k \left( y^{(0:k-1)} \right) \]
and therefore
\[ \beta_k^2 \left( y^{(0:k-1)} \right) \leq K_k^2 \lambda_k^2 \left( y^{(0:k-1)} \right) + \frac{C_k^2}{4} \omega_k^2 \left( y^{(0:k-1)} \right) + K_k C_k \lambda_k \left( y^{(0:k-1)} \right) \omega_k \left( y^{(0:k-1)} \right) + O(\epsilon)
\]
\[ = \left( K_k \lambda_k \left( y^{(0:k-1)} \right) + \frac{C_k}{2} \omega_k \left( y^{(0:k-1)} \right) \right)^2 + O(\epsilon). \quad (61) \]

Remembering (49) we can recursively define the error bound in the same manner as the Lipschitz case. We can immediately see that, as \( \beta_D = 0 \) without any nesting, we recover the bound from the Lipschitz case for the innermost estimator as expected. As the innermost estimator is unbiased we also have \( \lambda_{D-1} \left( y^{(0:D-2)} \right) = 0 \) and so
\[ \beta_{D-1}^2 \left( y^{(0:D-2)} \right) \leq \frac{C_{D-1}}{4} \omega_{D-1}^2 \left( y^{(0:D-2)} \right) + O(\epsilon)
\]
\[ \leq \frac{C_{D-1}}{4} \left( \frac{s_D^2 \left( y^{(0:D-1)} \right)}{N_D} \right)^2 + O(\epsilon)
\]
\[ = \frac{C_{D-1}^2 \varsigma_{D,D-1}^4 \left( y^{(0:D-2)} \right)}{4 N_D^2} + O(\epsilon). \]

Going back to our original bound on \( \sigma_{D-1}^2 \left( y^{(0:D-2)} \right) \) given in (47) and substituting for \( \beta_{D-1} \left( y^{(0:D-2)} \right) \) we now have
\[ \sigma_{D-1} \left( y^{(0:D-2)} \right) \leq \left( A_{D-1} \left( y^{(0:D-2)} \right) \right)^{\frac{1}{2}} + \left( s_{D-1}^2 \left( y^{(0:D-2)} \right) + \frac{C_{D-1}^2 \varsigma_{D,D-1}^4 \left( y^{(0:D-2)} \right)}{4 N_D^2} + O(\epsilon) \right)^{\frac{1}{2}}. \quad (62) \]

There does not appear to be tighter bound for \( A_{D-1} \left( y^{(0:D-2)} \right) \) than in the Lipschitz continuous case and so using the same bound of \( A_{D-1} \left( y^{(0:D-2)} \right) \leq K_{D-1}^2 \varsigma_{D,D-1}^2 \left( y^{(0:D-2)} \right) / N_{D-1} \) we have
\[ E_{D-1} \left( y^{(0:D-2)} \right) \leq \frac{\sigma_{D-1}^2 \left( y^{(0:D-2)} \right) N_{D-1}}{N_{D-1}} + \frac{C_{D-1}^2 \varsigma_{D,D-1}^4 \left( y^{(0:D-2)} \right)}{4 N_D^2} + O(\epsilon). \]
when expanding the brackets are zero, we have

$$\omega = \approx \varsigma \quad (61)$$

now noting that the term comes from the Taylor expansion and is equal to $O \left( \frac{1}{N^1} \right)$ because we have $\delta_{1,D-1} = 0$ and therefore

$$O(\epsilon) = O \left( \delta_{2,D-1} \delta_{3,D-1} + \delta_{2,D-1} \delta_{4,D-1} \right)$$

$$= O \left( \delta_{2,D-1} \mathbb{E} \left[ (I_1 (y^{(0)}) - \gamma_1 (y^{(0)}))^2 \right] + O \left( \delta_{2,D-1} \mathbb{E} \left[ (I_1 (y^{(0)}) - \gamma_1 (y^{(0)}))^4 \right] \right)$$

$$= O \left( \frac{1}{N_1^1} \mathbb{E} \left[ \left( \frac{1}{N_1^1} \sum_{n=1}^{N_1^1} f_1 (y_n^{(0,1)}) - \mathbb{E} \left[ f_1 (y^{(0,1)}) \right] \right)^3 \right] \right)$$

$$+ O \left( \frac{1}{N_1^1} \mathbb{E} \left[ \left( \frac{1}{N_1^1} \sum_{n=1}^{N_1^1} f_1 (y_n^{(0,1)}) - \mathbb{E} \left[ f_1 (y^{(0,1)}) \right] \right)^4 \right] \right)$$

now noting that the $y_n^{(0,1)}$ are i.i.d., and that $\mathbb{E} \left[ f_1 (y^{(0,1)}) - \mathbb{E} \left[ f_1 (y^{(0,1)}) \right] \right] = 0$ such many of the cross terms when expanding the brackets are zero, we have

$$= O \left( \frac{1}{N_1^1} \sum_{n=1}^{N_1^1} \mathbb{E} \left[ f_1 (y_n^{(0,1)}) - \mathbb{E} \left[ f_1 (y^{(0,1)}) \right] \right] \right)$$

$$+ O \left( \frac{1}{N_1^1} \sum_{n=1}^{N_1^1} \mathbb{E} \left[ f_1 (y_n^{(0,1)}) - \mathbb{E} \left[ f_1 (y^{(0,1)}) \right] \right] \right)$$

$$+ O \left( \frac{3}{N_1^1} \sum_{n=1}^{N_1^1} \sum_{m=1, m \neq n}^{N_1^1} \mathbb{E} \left[ f_1 (y_n^{(0,1)}) - \mathbb{E} \left[ f_1 (y^{(0,1)}) \right] \right] \right)$$

$$= O \left( \frac{1}{N_1^1} \right) + O \left( \frac{1}{N_1^1} \right) + O \left( \frac{1}{N_1^1} \right) = O \left( \frac{1}{N_1^1} \right)$$

as required.

Returning to calculating the bound for the repeated nesting case then by substituting (61) into (49) we have more generally

$$E_k (y^{(0,k-1)}) \leq \frac{s_{k-1}^2 (y^{(0,k-1)})}{N_k} + \frac{K_k \lambda_k (y^{(0,k-1)})}{N_k} + \frac{C_k}{2} \omega_k (y^{(0,k-1)})^2 + O(\epsilon). \quad (65)$$

Now remembering that $\omega_k (y^{(0,k-1)}) = \mathbb{E} \left[ E_{k+1} (y^{(0,k)}) \right] | y^{(0,k-1)}$ from (49) we have

$$\omega_k (y^{(0,k-1)}) = \mathbb{E} \left[ \frac{s_{k+1}^2 (y^{(0,k)})}{N_{k+1}} + \beta_{k+1}^2 (y^{(0,k)}) \right] + O(\epsilon)$$

$$= \frac{s_{k+1}^2 (y^{(0,k)})}{N_{k+1}} + \mathbb{E} \left[ \beta_{k+1}^2 (y^{(0,k)}) \right] + O(\epsilon). \quad (66)$$
We also have that except at \( k = D - 1 \) and \( k = D \) (for which both \( \lambda_k \) and \( \beta_{k+1} \) are zero), then
\[
\lambda_k \left( y^{(0:k-1)} \right) = \mathbb{E} \left[ \beta_{k+1} \left( y^{(0:k)} \right) \middle| y^{(0:k)} \right] \gg \mathbb{E} \left[ \beta_{k+1}^{2} \left( y^{(0:k)} \right) \middle| y^{(0:k-1)} \right]
\]
for sufficiently large \( N_{k+1}, \ldots, N_D \). This means that when we substitute (66) into (65), the second term in (66) becomes dominated giving
\[
E_k \left( y^{(0:k-1)} \right) = \frac{s_k^2 \left( y^{(0:k-1)} \right)}{N_k} + \left( K_k \lambda_k \left( y^{(0:k-1)} \right) + \frac{C_k \gamma_{k+1,k}}{2N_{k+1}} \right)^2 + O(\epsilon). \tag{67}
\]

Now as \( \beta_{k+1}^2 \left( y^{(0:k)} \right) = E_{k+1} \left( y^{(0:k)} \right) - \frac{s_{k+1}^2 \left( y^{(0:k)} \right)}{N_{k+1}} \) we have
\[
\lambda_k \left( y^{(0:k-1)} \right) = \mathbb{E} \left[ \frac{1}{E_{k+1} \left( y^{(0:k)} \right) - \frac{s_{k+1}^2 \left( y^{(0:k)} \right)}{N_{k+1}}} \right] + O(\epsilon)
\]
and substituting in (67) gives
\[
\lambda_k \left( y^{(0:k-1)} \right) \leq \mathbb{E} \left[ K_{k+1} \lambda_{k+1} \left( y^{(0:k)} \right) + \frac{C_{k+1} \gamma_{k+2,k}}{2N_{k+2}} \right] \left( y^{(0:k-1)} \right) + O(\epsilon)
\]
\[
= \frac{C_{k+1} \gamma_{k+2,k}}{2N_{k+2}} + K_{k+1} \mathbb{E} \left[ \lambda_{k+1} \left( y^{(0:k)} \right) \middle| y^{(0:k-1)} \right] + O(\epsilon)
\]
\[
\leq \frac{C_{k+1} \gamma_{k+2,k}}{2N_{k+2}} + \sum_{d=k+1}^{D-2} \mathbb{E} \left[ \left( \prod_{\ell=k+1}^{d} K_{\ell} \right) \frac{C_{d+1} \gamma_{d+2,k}}{2N_{d+2}} \right] \left( y^{(0:k-1)} \right) + O(\epsilon)
\]
and thus
\[
E_k \left( y^{(0:k-1)} \right) \leq \frac{s_k^2 \left( y^{(0:k-1)} \right)}{N_k} + \frac{1}{4} \left( \frac{C_k \gamma_{k+1,k}}{N_{k+1}} + \sum_{d=k}^{D-2} \left( \prod_{\ell=k}^{d} K_{\ell} \right) \frac{C_{d+1} \gamma_{d+2,k}}{N_{d+2}} \right)^2 + O(\epsilon),
\]
and therefore
\[
\mathbb{E} \left[ (I_0 - \gamma_0)^2 \right] = E_0 \leq \frac{s_0^2}{N_0} + \frac{1}{4} \left( \frac{C_0 \gamma_0^2}{N_1} + \sum_{k=0}^{D-2} \left( \prod_{d=0}^{k} K_{d} \right) \frac{C_{k+1} \gamma_{k+2,k}}{N_{k+2}} \right)^2 + O(\epsilon)
\]
as required and we are done.

\[\square\]

**Appendix E  Proof of Theorem 4 - Convergence Rate for Finite Realisations of y**

**Theorem 4.** If \( f \) is Lipschitz continuous, then the mean squared error of \( I_N = \sum_{c=1}^{C} (\hat{P}_N)_c (\hat{f}_N)_c \) as an estimator for \( I \) as per (11) converges at rate \( O(1/N) \).

**Proof.** Denote \( P_c = P(y = y_c) \) and \( f_c = f(y_c, \gamma(y_c)) \) noting that as the \( y_c \) are fixed values, so are \( P_c \) and \( f_c \). Then, Minkowski’s inequality allows us to bound the mean squared error as
\[
\mathbb{E} \left[ (I_N - I)^2 \right] = \|I_N - I\|_2^2 \leq \sum_{c=1}^{C} W_c \quad \text{where} \quad W_c := \left\| (\hat{P}_N)_c (\hat{f}_N)_c - P_c f_c \right\|_2^2.
\]
Moreover, again by Minkowski, we have \( W_c \leq U_c + V_c \) where
\[
U_c = \left\| (\hat{P}_N)_c (\hat{f}_N)_c - (\hat{P}_N)_c f_c \right\|_2, \quad V_c = \left\| (\hat{P}_N)_c f_c - P_c f_c \right\|_2.
\]
Factoring out \((\hat{P}_N)_c\) in \(U_c\) and noting that each \(y_n\) and \(z_{n,c}\) are sampled independently gives

\[
U_c = \sqrt{\mathbb{E} \left( (\hat{P}_N)_c^2 \right)} = \sqrt{\mathbb{E} \left( (\hat{P}_N)^2 \right) \mathbb{E} \left( (\hat{f}_N)_c - f_c \right)^2}.
\]

Using Minkowski’s inequality, we may write the first right-hand term as

\[
\sqrt{\mathbb{E} \left( (\hat{P}_N)_c^2 \right)} = \left\| (\hat{P}_N)_c - P_c \right\|_2 \leq \frac{1}{N} \sum_{n=1}^{N} \left\| (y_n - y_c) \right\|_2 = \frac{1}{N} \sum_{n=1}^{N} \mathbb{E} \left[ (y_n = y_c) \right] = \frac{1}{N} \sum_{n=1}^{N} P_c = P_c.
\]

For the second term, note that by Lipschitz continuity, we have for some constant \(K > 0\)

\[
\sqrt{\mathbb{E} \left( (\hat{f}_N)_c - f_c \right)^2} \leq K \left\| \frac{1}{N} \sum_{n=1}^{N} \phi(y_c, z_{n,c}) - \gamma(y_c) \right\|_2 = K \cdot O(1/\sqrt{N}) = O(1/\sqrt{N}),
\]

since \(\frac{1}{N} \sum_{n=1}^{N} \phi(y_c, z_{n,c})\) is a Monte Carlo estimator for \(\gamma(y_c)\). Altogether then, we have that

\[
U_c = P_c \cdot O(1/\sqrt{N}) = O(1/\sqrt{N}).
\]

We can also factor out \(f_c\) in \(V_c\) to obtain

\[
V_c = |f_c| \cdot \left\| (\hat{P}_N)_c - P_c \right\|_2 = |f_c| \cdot O(1/\sqrt{N}) = O(1/\sqrt{N}),
\]

since \((\hat{P}_N)_c\) is a Monte Carlo estimator for \(P_c\). Now by noting that \((A + B)^2 \leq 2(A^2 + B^2)\) for any \(A, B \in \mathbb{R}\), an inductive argument shows that

\[
\left( \sum_{t=1}^{L} A_t \right)^2 \leq 2^{\lceil \log_2 L \rceil} \sum_{t=1}^{L} A_t^2
\]

for all \(A_1, \cdots, A_L \in \mathbb{R}\). We can now show that our asymptotic bounds for \(U_c\) and \(V_c\) entail that our overall mean squared error satisfies

\[
\mathbb{E} \left[ (I_N - I)^2 \right] \leq 2^{\lceil \log_2 C \rceil} \sum_{c=1}^{C} W_c^2 \leq 2^{\lceil \log_2 C \rceil} \sum_{c=1}^{C} (U_c + V_c)^2 \leq 2^{\lceil \log_2 C \rceil + 1} \sum_{c=1}^{C} U_c^2 + V_c^2 \leq 2^{\lceil \log_2 C \rceil + 1} O(1/N) + O(1/N) = O(1/N),
\]

as desired.

\[\square\]

**Appendix F Proof for Theorem 5 - Products of Expectations**

**Theorem 5.** Consider the NMC estimator

\[
I_N = \frac{1}{N} \sum_{n=1}^{N} f \left( y_n, \prod_{t=1}^{L} \frac{1}{M_t} \sum_{m=1}^{M_t} \psi_t(y_n, z'_{n,t,m}) \right)
\]

where each \(y_n \in \mathcal{Y}\) and \(z'_{n,t,m} \in Z_t\) are independently drawn from \(y_n \sim p(y)\) and \(z'_{n,t,m} \sim p(z_t|y_n)\), respectively. If \(f\) is linear, the estimator converges almost surely to \(I\), with a convergence rate of \(O(1/N)\) in the mean square error for any fixed choice of \(\{M_t\}_{t=1:L}\).

**Proof.** Consider fixed sizes of nested sample sets, \(\{M_t\}_{t=1:L}\). For each \(y \in \mathcal{Y}\) and

\[
x = \{ z'_{t,m} \}_{m=1:M_t} \in \mathcal{X} = Z_1^{M_1} \otimes \cdots \otimes Z_L^{M_L},
\]

define

\[
\eta(y, x) = f \left( y, \prod_{t=1}^{L} \frac{1}{M_t} \sum_{m=1}^{M_t} \psi_t(y, z'_{t,m}) \right).
\]
Now, \( I_N = \frac{1}{N} \sum_{n=1}^{N} \eta(y_n, x_n) \) is a standard MC estimator on the space \( \mathcal{Y} \otimes \mathcal{X} \). Thus, \( I_N \overset{a.s.}{\to} E[I_N] \) with convergence properties and rate as per standard MC. We finish the proof by showing that \( E[I_N] = I \) when \( f \) is linear:

\[
E[I_N] = \mathbb{E} \left[ \frac{1}{N} \sum_{n=1}^{N} f \left( y_n, \prod_{\ell=1}^{L} \frac{1}{M_\ell} \sum_{m=1}^{M_\ell} \psi_\ell(y_n, z_m^\ell, m) \right) \right] = \mathbb{E} \left[ f \left( y_1, \prod_{\ell=1}^{L} \frac{1}{M_\ell} \sum_{m=1}^{M_\ell} \psi_\ell(y_1, z_m^\ell, \cdot) \right) | y_1 \right],
\]

now using the linearity of \( f \)

\[
= \mathbb{E} \left[ f \left( y_1, \mathbb{E} \left[ \prod_{\ell=1}^{L} \frac{1}{M_\ell} \sum_{m=1}^{M_\ell} \psi_\ell(y_1, z_m^\ell) \big| y_1 \right] \right) \right],
\]

and using the fact that terms for different \( \ell \) are by construction independent

\[
= \mathbb{E} \left[ f \left( y_1, \prod_{\ell=1}^{L} \mathbb{E} \left[ \psi_\ell(y_1, z_1^\ell) \big| y_1 \right] \right) \right] = \mathbb{E} \left[ f \left( y_1, \prod_{\ell=1}^{L} \mathbb{E} \left[ \psi_\ell(y_1, z_1^\ell) \big| y_1 \right] \right) \right] = I,
\]

as required.

\[\square\]

### Appendix G Optimizing the Convergence Rates

We have shown that the mean squared error converges at a rate

\[
O \left( \sum_{k=0}^{D} \frac{1}{N_k} \right) \text{ or } O \left( \frac{1}{N_0} + \left( \sum_{k=1}^{D} \frac{1}{N_k} \right)^2 \right)
\]

depending on the smoothness assumptions that can be made about \( f \). Here we show that given a sample budget for the inner most estimator \( T = \prod_{k=0}^{D} N_k \), then these bounds are optimized by setting \( N_0 \propto N_1 \propto \cdots \propto N_D \) and \( N_0 \propto N_1^2 \propto \cdots \propto N_D^2 \) respectively for the two cases and that this gives bounds of \( O(1/T^{\frac{1}{2}}) \) and \( O(1/T^{\frac{2}{3}}) \) respectively. For the single nested case, this gives bounds of \( O(1/\sqrt{T}) \) and \( O(1/T^{2/3}) \) respectively.

We start by explaining why \( T \) is an appropriate measure of the overall computational cost. First note that for each sample of \( y^{(0:k)} \), the NMC estimator requires \( N_k \) samples of \( y^{(k+1)} \). Thus there are \( N_0 \) samples of the outermost level, \( N_0 \times N_1 \) of the next level, and \( T = \prod_{k=0}^{D-1} N_k \) samples of the innermost level, regardless of the setup. In other words, each individual estimate of the innermost level uses \( N_D \) samples and we generate \( \prod_{k=0}^{D-1} N_k = T/N_D \) of these estimates because we need to generate one estimate for each sample of the layer above. Thus what we can vary for a fixed \( T \) is whether we use more estimates each using fewer samples, or fewer estimates each using more samples.

Now the total cost of generating \( I_0 \) scales with sum the costs of each individual layer, namely

\[
\text{Cost} = \sum_{k=0}^{D} c_k \prod_{\ell=0}^{k} N_\ell
\]

where \( c_k \) is the per sample cost local computations made at the \( k \)th layer (i.e. sampling \( y^{(0:k)} \) and evaluating \( f_k \) for given inputs), which is independent of the \( N_k \). For large \( N_D \), we see that the dominant cost is that of the inner most layer, namely \( c_T \prod_{\ell=0}^{D} N_\ell = c_T T \), and we asymptotically spend 100% of our time dealing with the innermost estimator. To give intuition to this, think about writing the estimator as a hierarchy of nested for loops; as the length of the loops increases we spend an increasing proportion of our time inside the innermost loop. Consequently, in the asymptotic regime, our computational cost is \( O(T) \) and we can use \( T \) is an appropriate measure of the overall computational cost.

To derive the optimal rates, we first consider the single nested case where \( D = 1, N_0 = N, \) and \( N_1 = M \). Consider setting \( N = \tau(M) \) then \( T = \tau(M) \cdot M \) and our bounds become \( O(R) \), where

\[
R = 1/\tau(M) + 1/M \quad \text{and} \quad R = 1/\tau(M) + 1/M^2.
\]

for the two cases respectively.

In this first case supposing \( \tau(M) = O(M) \) easily gives

\[
T = M\tau(M) = O(M^2)
\]
and as such

\[ R = O \left( \frac{1}{M} \right) = O \left( \frac{1}{\sqrt{T}} \right) \]  

(68)
as \( M \to \infty \). In contrast, consider the case that \( \tau(M) \gg M \) as \( M \to \infty \). We then have \( \frac{1}{\sqrt{M}} \gg \frac{1}{\sqrt{\tau(M)}} \) as \( M \to \infty \), so that

\[ R = O \left( \frac{1}{M} \right) \gg \frac{1}{\sqrt{M}} \frac{1}{\sqrt{\tau(M)}} = \frac{1}{\sqrt{T}}. \]

Comparing with (68), we observe that, for the same total budget of samples \( T \), this choice of \( \tau \) provides a strictly weaker convergence guarantee than in the previous case. When \( M \gg \tau(M) \) also then we have \( \frac{1}{\sqrt{\tau(M)}} \gg \frac{1}{\sqrt{M}} \) as \( M \to \infty \) and so

\[ R = O \left( \frac{1}{\tau(M)} \right) \gg \frac{1}{\sqrt{M}} \frac{1}{\sqrt{\tau(M)}} = \frac{1}{\sqrt{T}} \]

which is again a weaker bound. We thus see that the \( O(1/N + 1/M) \) bound is optimized when \( N \propto M \), giving a convergence rate of \( O(1/\sqrt{T}) \).

In the second case suppose that \( \tau(M) = O(M^2) \) as \( M \to \infty \). This now gives

\[ T = M\tau(M) = O(M^3) \]

and therefore

\[ R = O \left( \frac{1}{M^2} \right) = O \left( \frac{1}{T^{2/3}} \right) \]
as \( M \to \infty \). Now considering the cases \( \tau(M) \gg M^2 \) leads to \( \frac{1}{M^{7/3}} \gg \frac{1}{\tau(M)^{7/3}} \) and thus

\[ R = O \left( \frac{1}{M^2} \right) \gg \frac{1}{M^{2/3}} \frac{1}{\tau(M)^{2/3}} = \frac{1}{T^{2/3}}. \]

Similarly, if \( \tau(M) \ll M^2 \) then \( \frac{1}{\tau(M)^{7/3}} \gg \frac{1}{M^{7/3}} \) and thus

\[ R = O \left( \frac{1}{\tau(M)} \right) \gg \frac{1}{M^{2/3}} \frac{1}{\tau(M)^{2/3}} = \frac{1}{T^{2/3}}. \]

Both of these cases lead to weaker bounds and so we see that the \( O(1/N + 1/M^2) \) bound is tightest when \( N \propto M^2 \), giving a convergence rate of \( O(1/T^{2/3}) \).

We now consider the repeated nesting case without continuously differentiability such that our bound is \( O \left( \sum_{k=0}^{D} \frac{1}{N_k} \right) \). Here we can immediately see that \( N_0 \propto N_1 \propto \cdots \propto N_D \) leads to \( N_k \propto T^{\frac{1}{\tau(M)}} \) and thus \( O \left( 1/T^{\frac{1}{\tau(M)}} \right) \) convergence. If we were to set any \( N_k \ll T^{\frac{1}{\tau(M)}} \) then this term would dominate the sum and lead to a worse converge. Thus the result from the single nested case trivially extends to the multiple nested case, giving the required result.

Finally considering repeated nesting for the bound \( O \left( \frac{1}{N_0} + \left( \sum_{k=1}^{D} \frac{1}{N_k} \right)^2 \right) \) then we have from the previous result that \( N_1 \propto N_2 \propto \cdots \propto N_D \) is required for optimality as otherwise one of the terms in the sumiation dominates the other terms. If we now define \( M = \prod_{k=1}^{D} N_k = T/N_0 \) then we get a convergence rate of \( O(1/N_0 + 1/M^2) \) which is identical to the single nesting case for this tighter bound. We, therefore, have that the optimal configuration must be \( N_0 \propto N_1^2 \propto \cdots \propto N_D^2 \) giving a bound of \( O \left( 1/T^{\frac{1}{\tau(M)}} \right) \) as it gives \( N_0 \propto T^{\frac{1}{\tau(M)}} \).

**Appendix H Additional details pertaining to cancer simulator**

In this section, we elucidate some more details about the cancer simulator described in the manuscript, provide more rigorous mathematical definitions for the relevant terms using the same nomenclature, and also include more results figures.
Figure 7. Projected expenditure (proportional to $I_{N,M}$) evaluated at different values of $T_{\text{treat}}$. The budget constraint is shown by the horizontal red line. The optimal value of $T_{\text{treat}}$ is found by the intersection and occurs at $T_{\text{treat}} = 12.5\%$. Evaluated was carried out at 100 $T_{\text{treat}}$. Only the bottom 20% is pictured as this is the operating range for most treatment centers.

H.1 Simulator details

We define $I(T_{\text{treat}})$ to be the expected proportion of patients who receive treatment. A particular patient is represented by $y \in \mathbb{R}^d$. Specifically, $y$ consists of only a single real number ($d = 1$) representing the size of the tumor upon discovery. Initial tumor size is drawn from a scaled Rayleigh distribution. The outcome of the simulator is then $\phi(y, z) \in \{0, 1\}$, and is the binary outcome of whether that particular patient and sample of unobserved parameters yield an expected tumor size below the threshold, $T_{\text{opp}}$, after a fixed time duration, $t_{\text{max}}$. The simulator is a pair of coupled, parameterized differential equations for the action of an anti-tumor treatment such as chemotherapy, as described in Enderling & Chaplain (2014):

\[
\frac{dc}{dt} = -\lambda c \log \left( \frac{c}{K} \right) - \xi c
\]

\[
\frac{dK}{dt} = \phi c - \psi K e^{2/3},
\]

where $c(t, x) \in \mathbb{R}_+$ represents tumor size, with initial size $y_n$. Similarly, $K(t, x) \in \mathbb{R}_+$ represents the notion of a carrying capacity, with the initial carrying capacity, $K(0, z)$, set to a known constant $K_0$. The magnitude of the patient response to an anti-tumor treatment (such as chemotherapy) is represented by $\xi \in [0, 1]$, drawn from a beta distribution. $\{\lambda, \psi, \phi\} \in \mathbb{R}_+^3$ represent the parameters of the simulator. We also define $x_{n,m} = \{\lambda, \psi, \phi, K_0, \xi\}$ and $z_{n,m} = \{x_{n,m}, T_{\text{opp}}, t_{\text{max}}\}$, where all but $\xi$ are set to constant values. Expanding this to condition all values on $y_n$ is trivial given domain knowledge. Alternatively, they could also be drawn at random, but not be conditioned on $y_n$. Such relations are omitted here for simplicity.

We can now fully define $\phi$ as:

\[
\phi(y_n, z_{n,m}) = \mathbb{I}(c(t_{\text{max}}, x_{n,m}) < T_{\text{opp}}).
\]

Taking the expectation of $\phi$ over $M$ different realizations of $z$ yields the estimate $(\hat{\gamma}_M)_n$. This value is the probability that treatment will be successful for a particular patient, marginalizing over possible unobserved dynamics. This is the point at which clinician decides whether initiate the treatment plan. This decision is represented $f(y_n, (\hat{\gamma}_M)_n) \in [0, 1]$ as:

\[
f(y_n, (\hat{\gamma}_M)_n) = \mathbb{I}((\hat{\gamma}_M)_n > T_{\text{treat}})
\]

where $T_{\text{treat}}$ is the minimum probability of success required for that patient to receive the treatment, and again, could be conditioned on $y$ also. Taking the expectation of $f$ over patients yields the expected frequency with which the treatment will be delivered, given a value of $T_{\text{treat}}$. The hospital wishes to estimate the value $T_{\text{treat}}$ that maximizes the number of patients treated, while only treating those patients with the highest probability of success, and (in expectation) staying within the budgetary constraint.

The model is completed by the definition of the following distributions and parameters.

\[
K_0 = 100000000, \quad \phi = 0.001, \quad \psi = 0.05, \quad \lambda = 0.5, \quad \xi \sim \text{Beta}(5, 2),
\]

\[
c_0 \sim 1000 \times \text{Rayleigh}(10), \quad T_{\text{opp}} = 2000, \quad T_{\text{treat}} = 0.35, \quad t_{\text{max}} = 250, \quad t_{\text{step}} = 0.01
\]
H.2 Budget result

In the example outlined above, the treatment center is not actually attempting to evaluate the value of $I$, but to find the optimal value of $T_{\text{treat}}$ subject to a budgetary constraint. A simplistic way of evaluating the optimal value is to perform a dense search over different values of the parameter, each time evaluating the estimated expenditure, and select the best performing value.

Figure 7 shows the variation of predicted expenditure against the threshold probability, as well as the budget constraint. The intersection of these curves is the optimal setting of $T_{\text{opp}}$, here evaluated to be 12.5%. From the blue line, it is clear that the relationship between expenditure and treatment probability is non-linear, especially at the extrema of the distribution, and hence the use of NMC was necessarily for evaluating the optimal value.

Appendix I Bayesian Experimental Design

Bayesian experimental design provides a framework for designing experiments in a manner that is optimal from an information-theoretic viewpoint (Chaloner & Verdinelli [1995], Sebastiani & Wynn [2000]). By minimizing the entropy in the posterior distribution of the parameters of interest, one can maximize the information gathered by the experiment.

Let the parameters of interest be denoted by $\theta \in \Theta$ for which we define a prior distribution $p(\theta)$. Let the probability of achieving outcome $y \in \mathcal{Y}$, given parameters $\theta$ and a design $d \in \mathcal{D}$, be defined by likelihood model $p(y|\theta, d)$. Under our model, the outcome of the experiment given a chosen design $d$ is distributed according to

$$p(y|d) = \int_{\Theta} p(y, \theta|d) d\theta = \int_{\Theta} p(y|\theta, d) p(\theta) d\theta, \quad (73)$$

where we have used the fact that $p(\theta) = p(\theta|d)$ because $\theta$ is independent of the design. Our aim is to choose the optimal design $d$ under some criterion. We, therefore, define a utility function, $U(y, d)$, representing the utility of choosing a design $d$ and getting a response $y$. Typically our aim is to maximize information gathered from the experiment, and so we set $U(y, d)$ to be the gain in Shannon information between the prior and the posterior:

$$U(y, d) = \int_{\Theta} p(\theta|y, d) \log(p(\theta|y, d)) d\theta - \int_{\Theta} p(\theta) \log(p(\theta)) d\theta \quad (74)$$

However, we are still uncertain about the outcome. Thus, we use the expectation of $U(y, d)$ with respect to $p(y|d)$ as our target:

$$\bar{U}(d) = \int_{\mathcal{Y}} U(y, d) p(y|d) dy$$

$$= \int_{\mathcal{Y}} \int_{\Theta} p(y, \theta|d) \log(p(\theta|y, d)) d\theta dy - \int_{\Theta} p(\theta) \log(p(\theta)) d\theta$$

$$= \int_{\mathcal{Y}} \int_{\Theta} p(y, \theta|d) \log \left( \frac{p(\theta|y, d)}{p(\theta)} \right) d\theta dy. \quad (75)$$

noting that this corresponds to the mutual information between the parameters $\theta$ and the observations $y$. The Bayesian-optimal design is then given by

$$d^* = \arg\max_{d \in \mathcal{D}} \bar{U}(d). \quad (76)$$

Finding $d^*$ is challenging because the posterior $p(\theta|y, d)$ is rarely known in closed form. To solve the problem, we proceed by rearranging (75) using Bayes' rule (remembering that $p(\theta) = p(\theta|d)$):

$$\bar{U}(d) = \int_{\mathcal{Y}} \int_{\Theta} p(y, \theta|d) \log \left( \frac{p(\theta|y, d)}{p(\theta)} \right) d\theta dy$$

$$= \int_{\mathcal{Y}} \int_{\Theta} p(y, \theta|d) \log \left( \frac{p(y|\theta, d)}{p(y|d)} \right) d\theta dy$$

$$= \int_{\mathcal{Y}} \int_{\Theta} p(y, \theta|d) \log(p(y|\theta, d)) d\theta dy - \int_{\mathcal{Y}} p(y|d) \log(p(y|d)) dy. \quad (77)$$

The first of these terms can now be evaluated using standard MC approaches as the integrand is analytic. In contrast, the
second term is not directly amenable to standard MC estimation as the marginal $p(y|d)$ represents an expectation and taking its logarithm represents a non-linear functional mapping.

To derive an estimator, we will now consider these terms separately. Starting with the first term,

$$\hat{U}_1(d) = \int \int p(y, \theta|d) \log(p(y|\theta, d)) \, d\theta \, dy = \frac{1}{N} \sum_{n=1}^{N} \log(p(y_n|\theta_n, d))$$  \hspace{1cm} (78)

where $\theta_n \sim p(\theta)$ and $y_n \sim p(y|\theta = \theta_n, d)$. We note that evaluating (78) involves both sampling from $p(y|\theta, d)$ and directly evaluating it point-wise. The latter of these cannot be avoided, but in the scenario where we do not have direct access to a sampler for $p(y|\theta, d)$, we can use the standard importance sampling trick, sampling instead $y_n \sim q(y|\theta = \theta_n, d)$ and weighting the samples in (78) by $w_n = \frac{p(y_n|\theta_n, d)}{q(y_n|\theta_n, d)}$.

Now considering the second term we have

$$\hat{U}_2(d) = \int \int p(y|d) \log(p(y|d)) \, dy = \frac{1}{N} \sum_{n=1}^{N} \log \left( \frac{1}{M} \sum_{m=1}^{M} p(y_n|\theta_{n,m}, d) \right)$$  \hspace{1cm} (79)

where $\theta_{n,m} \sim p(\theta)$ and $y_n \sim p(y|d)$. Here we can sample the latter by first sampling an otherwise unused $\theta_{n,0} \sim p(\theta)$ and then sampling $y_n \sim p(y|\theta_{n,0}, d)$. Again we can use importance sampling if we do not have direct access to a sampler for $p(y|\theta_{n,0}, d)$.

Putting (78) and (79) together (and renaming $\theta_n$ from (78) as $\theta_{n,0}$ for notational consistency with (79)) we now have the following complete estimator given in the main paper and implicitly used by (Myung et al., 2013) amongst others

$$\hat{U}(d) \approx \frac{1}{N} \sum_{n=1}^{N} \left[ \log(p(y_n|\theta_{n,0}, d)) - \log \left( \frac{1}{M} \sum_{m=1}^{M} p(y_n|\theta_{n,m}, d) \right) \right]$$  \hspace{1cm} (80)

where $\theta_{n,m} \sim p(\theta) \forall m \in \{0 : M\}, n \in \{1 : N\}$ and $y_n \sim p(y|\theta = \theta_{n,0}, d) \forall n \in \{1 : N\}$.

We now show that if $y$ can only take on one of $C$ possible values $(y_1, \ldots, y_C)$, we can achieve significant improvements in the convergence rate by using a similar to that introduced in Section 3.2 to convert to single MC estimator:

$$\hat{U}(d) = \int \int p(y, \theta|d) \log(p(y|\theta, d)) \, d\theta \, dy - \int p(y|d) \log(p(y|d)) \, dy$$

$$= \int \left[ \sum_{c=1}^{C} p(\theta)p(y_c|\theta, d) \log(p(y_c|\theta, d)) \right] \, d\theta - \sum_{c=1}^{C} p(y_c|d) \log(p(y_c|d))$$

$$\approx \frac{1}{N} \sum_{n=1}^{N} \sum_{c=1}^{C} p(y_c|\theta_n, d) \log(p(y_c|\theta_n, d)) - \sum_{c=1}^{C} \left[ \frac{1}{N} \sum_{n=1}^{N} p(y_c|\theta_n, d) \right] \log \left( \frac{1}{N} \sum_{n=1}^{N} p(y_c|\theta_n, d) \right)$$  \hspace{1cm} (81)

where $\theta_n \sim p(\theta) \forall n \in \{1, \ldots, N\}$. As $C$ is a fixed constant, the MSE for first term clearly converges at the standard MC error rate of $O(1/N)$. Similarly each $\hat{P}_N(y_c|d) = \frac{1}{N} \sum_{n=1}^{N} p(y_c|\theta_n, d)$ term also converges at a rate $O(1/N)$ to $p(y_c|d)$. Now noting that $\hat{P}_N(y_c|d) \leq 1$ and that $f(x) = x \log x$ is Lipschitz continuous in the range $(0, 1)$, each $\hat{P}_N(y_c|d) \log \left( \hat{P}_N(y_c|d) \right)$ term must also converge at the MC error rate if $p(y_c|d) > 0 \forall c = 1, \ldots, C$. Finally if we assume that when $p(y_c|d) = 0$ then $\hat{P}_N(y_c|d) = 0$ almost surely for sufficiently large $N$, then the second term also converges at the MC error when $p(y_c|d) = 0$. We now have a finite sum of terms which each convergence to $\hat{U}(d)$ with MC MSE rate $O(1/N)$, and so the overall estimator (81) must also converge at this rate. This compares to $O(1/T^{2/3})$ for (80) (assuming we take $N \propto M^2$), noting that generating $T$ samples for (80) has the same cost up to a constant factor as generating $N$ for (81). To the best of our knowledge, this is the first introduction of this superior estimator in the literature.

We finish by showing that the theoretical advantages of this reformulation also leads to empirical gains in the estimation of $\hat{U}(d)$. For this, we consider a model used in psychology experiments for delay discounting introduced by (Vincent, 2016; Vincent & Rainforth, 2017). Our experiment comprises of asking questions of the form “Would you prefer £A now, or £B in D days?” and we wish to choose the question variables $d = \{A, B, D\}$ in the manner that will give the most incise
questions. The target participant is presumed to have parameters \( \theta = \{k, \alpha\} \) and the following response model

\[
y \sim \text{Bernoulli} \left( 0.01 + 0.98 \cdot \Phi \left( \frac{1}{\alpha} \left( \frac{B}{1 + e^kD} - A \right) \right) \right)
\]

where \( y = 1 \) indicates choosing the delayed response and \( \Phi \) represents the cumulative normal distribution. As more questions are asked, the distribution over the parameters \( \theta \) is updated, such that the most optimal question to ask at a particular time depends on the previous questions and responses. For the sake of brevity, when comparing the performance of (80) and (81), we will neglect the problem of how best to optimize the design, and consider only the problem of evaluating \( \bar{U}(d) \). We will further consider the case where \( B = 100 \) and \( D = 50 \) are fixed and we are only choosing the delayed value \( A \). We presume the following distribution on the parameters

\[
k \sim \mathcal{N}(-4.5, 0.5^2)
\]

\[
\alpha \sim \Gamma(2, 2).
\]

We first consider convergence in the estimate of \( \bar{U}(d) \) for the case \( A = 70 \) for our suggested method (81) and the naïve solution (80), the results of which are shown in Figure 2a in the main paper. Here we see that the convergence rates of the two methods are both as expected and that our suggested method offers significant empirical performance improvements.

We next consider setting a total sample budget \( T = 10^4 \) and look at the variation in the estimated values of \( \bar{U}(d) \) for different values of \( A \) for the two methods as shown in Figure 8. This shows that the improvement in MSE leads to clearly visible improvements in the characterization of \( \bar{U}(d) \) that will translate to improvements in seeking the optimum.
On Nesting Monte Carlo Estimators

References


