

Supplementary Material for:  
Voronoi Boundary Classification: A  
High-Dimensional Geometric Approach via  
Weighted Monte Carlo Integration

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**Lemma 1** (Change of Variables and Monte Carlo). *Let  $P = V(t) \cap V(x_j)$ . If  $P \neq \emptyset$ ,  $P$  lies in some hyperplane  $\Pi = \{x \in \mathbb{R}^d : \langle x, n \rangle = c\}$ , where  $n$  is of unit norm. Denote by  $\mathbb{S}^{d-1}$  the  $d - 1$  dimensional unit sphere centered at the origin and denote by  $f_j$  the map which maps  $m \in \mathbb{S}^{d-1}$  to the intersection between the ray starting at  $t$  in direction  $m$  with  $P$  if this intersection exists. Let  $I_j = \int_{V(t) \cap V(x_j)} w(x) d\text{Vol}$ , then*

$$I_j = \int_{f_j^{-1}(V(t) \cap V(x_j))} w(f_j(m)) \frac{\|f_j(m) - t\|^{d-1}}{|\langle m, n \rangle|} d\text{Vol}_{\mathbb{S}^{d-1}} \quad (1)$$

where  $d\text{Vol}_{\mathbb{S}^{d-1}}$  denotes the standard induced volume form of the sphere in Euclidean space. Secondly, consider a sequence  $\{m_i\}_1^T$  of uniform samples on  $f_j^{-1}(V(t) \cap V(x_j)) \subset \mathbb{S}^{d-1}$ . We have

$$I_j = V_j \lim_{T \rightarrow \infty} \frac{1}{T} \sum_{i=1}^T w(f_j(m_i)) \frac{\|f_j(m_i) - t\|^{d-1}}{|\langle m_i, n \rangle|} \quad (2)$$

where  $V_j$  denotes the volume of the set  $f_j^{-1}(V(t) \cap V(x_j))$  with respect to the standard induced metric on the unit sphere in Euclidean space.

*Proof.* Consider spherical coordinates  $(\phi_1, \dots, \phi_{d-1})$  on  $\mathbb{S}^{d-1}$ . Define  $m = (m_1, \dots, m_d)$  by  $m_1 = \cos \phi_1$ ,  $m_p = \cos \phi_p \prod_{j=1}^{p-1} \sin \phi_j$ , for  $p = 2, \dots, d - 1$  and  $m_d = \prod_{j=1}^{d-1} \sin \phi_j$ . One can verify that

$$B = \left\{ \frac{\frac{\partial m}{\partial \phi_1}}{\left\| \frac{\partial m}{\partial \phi_1} \right\|}, \dots, \frac{\frac{\partial m}{\partial \phi_{d-1}}}{\left\| \frac{\partial m}{\partial \phi_{d-1}} \right\|}, m \right\}$$

forms an orthonormal basis of  $\mathbb{R}^d$  and we note that the induced metric on  $\mathbb{S}^{d-1}$  is given by  $g_{ij} = \langle \frac{\partial m}{\partial \phi_i}, \frac{\partial m}{\partial \phi_j} \rangle$ , which we note is a diagonal matrix in local  $\phi_i$

coordinates. We observe that  $f_j(m) = l(m)m + t$ , where  $l(m) = \frac{c}{\langle m, n \rangle}$ . We observe that the resulting induced metric is

$$\hat{g}_{ij} = \left\langle \frac{\partial f}{\partial \phi_i}, \frac{\partial f}{\partial \phi_j} \right\rangle = l^2 \left( g_{ij} + l^{-2} \frac{\partial l}{\partial \phi_i} \frac{\partial l}{\partial \phi_j} \right)$$

Using Sylvester's formula, we obtain

$$\begin{aligned} \det \hat{g} &= l^{2(d-1)} \det g \det(I + l^{-2} g^{-\frac{1}{2}} (\nabla l)^T \nabla l g^{-\frac{1}{2}}) \\ &= l^{2(d-1)} \det g (1 + l^{-2} \|g^{-\frac{1}{2}} \nabla l\|^2) \\ &= \frac{l^{2(d-1)}}{\langle m, n \rangle^2} \det g, \end{aligned}$$

where we observe in the last step that  $1 + l^{-2} \|g^{-\frac{1}{2}} \nabla l\|^2$  is just  $\frac{1}{\langle m, n \rangle^2}$  times the expression for  $1 = \|n\|^2$  in the orthonormal basis  $B$ . The second part follows from the standard local coordinate Monte-Carlo integration theorems, see e.g. [1].  $\square$

**Lemma 2.** *Let  $t \in \mathbb{R}^d$  and  $m \in \mathbb{S}^{d-1}$  and define*

$$l_m^*(x) = \frac{\|x - t\|^2}{2 \langle m, x - t \rangle}$$

$$\text{face}(m) = \arg \min_{i \in \{1, \dots, n\}} \{l_m^*(x_i) \mid l_m^*(x_i) > 0\}.$$

*If there is no  $i \in \{1, \dots, n\}$  such that  $l_m^*(x_i) > 0$ , then the ray  $R$  starting at  $t$  and in direction  $m$  is fully contained in  $V(t)$  (and  $V(t)$  is unbounded in direction  $m$  starting at  $t$ ). Otherwise  $m$  lies in  $f_j^{-1}(V(t) \cap V(x_{\text{face}(m)}))$ .*

*Proof.* Solving for  $l \geq 0$ , for an equidistant point between  $t$  and  $x$  along the ray  $\{t + lm \mid t \geq 0\}$ , we observe that  $\|t + lm - t\|^2 = \|x - t - lm\|^2$  for  $l = l_m^*(x)$ . The expression for  $\text{face}(m)$  above hence selects the neighboring Voronoi cell to  $t$  along the direction  $m$  and  $l_m^*(x_{\text{face}(m)})$  returns the distance to the Voronoi cell boundary along the ray.  $\square$

**Theorem 1.** *Consider a labeled dataset  $D = \{(x_1, c_1), \dots, (x_n, c_n)\}$  of data points  $x_i \in \mathbb{R}^d$  and corresponding class labels  $c_i \in \{1, 2, \dots, k\}$  and a test point  $t \in \mathbb{R}^d$ , where  $t \neq x_i$  for all  $i \in \{1, \dots, n\}$ . Assume that  $t$  only has a single nearest neighbor among  $\{x_1, \dots, x_n\}$ . Consider a sequence of weight functions  $\{w_n\}_{n=1}^\infty$ ,  $w_n : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  which are each monotonically decreasing and where*

$$\lim_{n \rightarrow \infty} \int_{z_2}^{+\infty} \frac{w_n(z)}{w_n(z_1)} z^{d-2} dz = 0 \quad \text{for all} \quad 0 < z_1 < z_2 \quad (3)$$

*Then, for sufficiently large  $n$ , the class  $VBC(t|D, w_n)$  assigned by the Voronoi Boundary Classifier of  $t$  is equal to the class  $1NN(t|D)$  assigned by the nearest neighbor classifier for  $t$ .*

*Proof.* Let  $\mathbb{B}_r(t)$  denote the ball of radius  $r$  around  $t$  in  $\mathbb{R}^d$  and denote by  $\Pi_i$  the unique hyperplane containing  $V(t) \cap V(x_i)$  whenever this intersection is non-empty and  $d - 1$  dimensional. We observe that, for all  $r > 0$ ,

$$\begin{aligned} \int_{V(t) \cap V(x_i)} w_n(\|x - t\|) d\text{Vol} &\geq \int_{V(t) \cap V(x_i) \cap \mathbb{B}_r(t)} w_n(\|x - t\|) d\text{Vol} \\ &\geq \text{Vol}(V(t) \cap V(x_i) \cap \mathbb{B}_r(t)) w_n(r) \end{aligned}$$

since  $w$  decreases with distance from  $t$ .

Denote  $\text{Vol}(V(t) \cap V(x_i) \cap \mathbb{B}_r(t))$  as  $C_r$ . Let  $x_i$  be the nearest neighbor to  $t$ , and pick  $r_1 = \frac{1}{2}\|x_i - t\| + \delta$  for some  $\delta > 0$  so that  $\text{dist}(\Pi_j, t) > r_1$  for all  $j \neq i$ ; such  $\delta$  exists due to the assumed uniqueness of the nearest neighbor to  $t$ . Therefore, for any  $j \neq i$  such that  $V(t) \cap V(x_j) \neq \emptyset$ ,

$$\begin{aligned} \frac{\int_{V(t) \cap V(x_j)} w_n(\|x - t\|) d\text{Vol}}{\int_{V(t) \cap V(x_i)} w_n(\|x - t\|) d\text{Vol}} &\leq \frac{1}{C_{r_1}} \int_{V(t) \cap V(x_j)} \frac{w_n(\|x - t\|)}{w_n(r_1)} d\text{Vol} \\ &\leq \frac{1}{C_{r_1}} \int_{\Pi_j} \frac{w_n(\|x - t\|)}{w_n(r_1)} d\text{Vol} \end{aligned}$$

Let  $r_2 = \text{dist}(\Pi_j, t)$  so that  $r_2 > r_1$ . Pick polar coordinates on  $\Pi_j = \mathbb{S}^{d-2}(p) \times \mathbb{R}_{\geq 0}$  centered at the closest point  $p \in \Pi_j$  to  $t$ . Then

$$\begin{aligned} \frac{1}{C_{r_1}} \int_{\Pi_j} \frac{w_n(\|x - t\|)}{w_n(r_1)} d\text{Vol} &= \frac{1}{C_{r_1}} \int_0^\infty \int_{\mathbb{S}^{d-2}} \frac{w_n(\sqrt{r_2^2 + r^2})}{w_n(r_1)} r^{d-2} d\text{Vol}_{\mathbb{S}^{d-2}} dr \\ &= \frac{\text{Vol}(\mathbb{S}^{d-2})}{C_{r_1}} \int_0^\infty \frac{w_n(\sqrt{r_2^2 + r^2})}{w_n(r_1)} r^{d-2} dr \\ &\leq \frac{\text{Vol}(\mathbb{S}^{d-2})}{C_{r_1}} \int_0^\infty \frac{w_n(r_2 + r)}{w_n(r_1)} r^{d-2} dr \\ &\leq \frac{\text{Vol}(\mathbb{S}^{d-2})}{C_{r_1}} \int_{r_2}^\infty \frac{w_n(r)}{w_n(r_1)} r^{d-2} dr, \end{aligned}$$

where the last term tends to zero. It follows that

$$\lim_{n \rightarrow \infty} \frac{\int_{V(t) \cap V(x_j)} w_n(\|x - t\|) d\text{Vol}}{\int_{V(t) \cap V(x_i)} w_n(\|x - t\|) d\text{Vol}} = 0.$$

We can replace the numerator with a finite sum over all  $x_k$  of the same class label as  $x_j$ , and the result still tends to zero. Hence, the Voronoi Boundary Rank for class label  $x_i$  dominates the Voronoi Boundary Rank for all other class labels for sufficiently large  $n$  and the result follows.  $\square$

## References

- [1] Philip J Davis and Philip Rabinowitz. *Methods of numerical integration*. Courier Corporation, 2007.