# Convergence of Langevin Monte Carlo in Chi-Squared and Rényi Divergence

Murat A. Erdogdu Department of Computer Science, Department of Statistical Sciences, University of Toronto

#### Abstract

We study sampling from a target distribution  $\nu_* = e^{-f}$  using the unadjusted Langevin Monte Carlo (LMC) algorithm when the potential f satisfies a strong dissipativity condition and it is first-order smooth with a Lipschitz gradient. We prove that, initialized with a Gaussian random vector that has sufficiently small variance, iterating the LMC algorithm for  $\mathcal{O}(\lambda^2 d\epsilon^{-1})$  steps is sufficient to reach  $\epsilon$ -neighborhood of the target in both Chi-squared and Rényi divergence, where  $\lambda$  is the logarithmic Sobolev constant of  $\nu_*$ . Our results do not require warm-start to deal with the exponential dimension dependency in Chi-squared divergence at initialization. In particular, for strongly convex and first-order smooth potentials, we show that the LMC algorithm achieves the rate estimate  $\widetilde{\mathcal{O}}(d\epsilon^{-1})$  which improves the previously known rates in both of these divergences, under the same assumptions. Translating this rate to other metrics, our results also recover the state-of-the-art rates in KL divergence, total variation and 2-Wasserstein distance in the same setup. Finally, as we rely on the log-Sobolev inequality, our framework covers a range of non-convex potentials that are first-order smooth and exhibit strong convexity outside of a compact region.

# Rasa HosseinzadehMatthew S. Zhangcience,Department of Computer Science,Department of Computer Science,university of TorontoUniversity of Toronto

# **1 INTRODUCTION**

We consider sampling from a target distribution  $\nu_* = e^{-f}$  using the Langevin Monte Carlo (LMC)

$$x_{k+1} = x_k - \eta \nabla f(x_k) + \sqrt{2\eta} W_k, \qquad (1.1)$$

where  $f : \mathbb{R}^d \to \mathbb{R}$  is the potential function,  $W_k$  is a *d*-dimensional isotropic Gaussian random vector independent from  $\{x_l\}_{l \leq k}$ , and  $\eta$  is the step size. This algorithm is the Euler discretization of the following stochastic differential equation (SDE)

$$dz_t = -\nabla f(z_t)dt + \sqrt{2}dB_t, \qquad (1.2)$$

where  $B_t$  denotes the *d*-dimensional Brownian motion. The solution of the above SDE is referred to as the first-order Langevin diffusion, and the convergence behavior of the LMC algorithm (1.1) is intimately related to the properties of the diffusion process (1.2). Intuitively, fast mixing of LMC (1.1) is inherited from the Langevin diffusion (1.2) since the Euler discretization scheme with a sufficiently small step size ensures that the Markov chain generated by the LMC iterations tracks its continuous counterpart. Therefore, to ensure that the LMC algorithm converges, one typically starts from conditions that imply the fast convergence of the diffusion process given in (1.2).

Denoting the density of the Langevin diffusion  $z_t$  with  $\pi_t$ , the following Fokker-Planck equation describes the evolution of the dynamics (1.2)(Risken, 1996)

$$\frac{\partial \pi_t(x)}{\partial t} = \nabla \cdot (\nabla f(x)\pi_t(x)) + \Delta \pi_t(x).$$
(1.3)

Convergence to the equilibrium of the above equation has been studied extensively under various assumptions and distance measures. We define the Chisquared, Kullback–Leibler (KL) and Rényi divergences

Proceedings of the 25<sup>th</sup> International Conference on Artificial Intelligence and Statistics (AISTATS) 2022, Valencia, Spain. PMLR: Volume 151. Copyright 2022 by the author(s).

between two probability distributions  $\rho$  and  $\nu$  in  $\mathbb{R}^d$ 

$$\chi^{2}(\rho|\nu) = -1 + \int \left(\frac{\rho(x)}{\nu(x)}\right)^{2} \nu(x) dx \tag{1.4}$$

$$\operatorname{KL}(\rho|\nu) = \int \log\left(\frac{1}{\nu(x)}\right) \rho(x) dx,$$
$$R_{\alpha}(\rho|\nu) = \frac{1}{\alpha - 1} \log \int \left(\frac{\rho(x)}{\nu(x)}\right)^{\alpha} \nu(x) dx \text{ for } \alpha > 1.$$

The logarithmic Sobolev inequality (LSI) is a particularly useful condition on the target  $\nu_*$ , equivalent to the following for  $\nu = e^{-f}$ 

$$\forall 
ho, \quad \mathrm{KL}(
ho|
u) \le \frac{\lambda}{2} \int \left\| \nabla \log \frac{\rho(x)}{\nu(x)} \right\|^2 \rho(x) dx. \quad (\mathrm{LSI})$$

LSI is known to hold for strongly log-concave distributions (Bakry and Émery, 1985) in which case the constant  $\lambda^{-1}$  is equal to the strong convexity constant of the potential. This condition is also robust against finite perturbations (Holley and Stroock, 1987) which allows one to deal with non-convex potentials (to a somewhat limited extent). If the target  $\nu_*$  satisfies LSI, then the distribution  $\pi_t$  convergences to the target  $\nu_*$  in all three divergence measures defined in (1.4) exponentially fast, i.e. for all  $t \geq 0$ 

$$\operatorname{LSI} \implies \begin{cases} \operatorname{KL}(\pi_t | \nu_*) &\leq e^{-2t/\lambda} \operatorname{KL}(\pi_0 | \nu_*), \\ \chi^2(\pi_t | \nu_*) &\leq e^{-2t/\lambda} \chi^2(\pi_0 | \nu_*), \\ R_\alpha(\pi_t | \nu_*) &\leq e^{-2t/\alpha\lambda} R_\alpha(\pi_0 | \nu_*), \end{cases}$$
(1.5)

Exponential convergence in Chi-squared divergence as in (1.5) can be established under the Poincaré inequality (Cao et al., 2019; Chewi et al., 2020), which holds for a wider class of potentials (Bakry et al., 2008) (see Cao et al. (2019); Vempala and Wibisono (2019) for the convergence of  $\pi_t$  in Rényi divergence under various conditions).

Under additional smoothness assumptions on the potential function f, the fast convergence of the Langevin diffusion (1.3) to equilibrium as in (1.5) can be translated to that of the LMC algorithm. In particular, implications of LSI on the convergence of LMC are relatively well-understood in KL divergence (Dalalvan, 2017b; Durmus and Moulines, 2017; Erdogdu and Hosseinzadeh, 2020). In addition to LSI, assuming further that the gradient of the potential is Lipschitz continuous, taking  $\mathcal{O}(d/\epsilon)$  steps is sufficient to reach the  $\epsilon$ neighborhood of a *d*-dimensional target distribution  $\nu_*$  in KL divergence (Vempala and Wibisono, 2019). However, convergence in stronger notions of distance such as Chi-squared and Rényi divergence are not adequately shown in (Vempala and Wibisono, 2019) as their results in Rényi divergence rely on two unverifiable assumptions: a Poincaré (or LSI) inequality on the *limit of the LMC iterates* (rather than the target), a growth condition on the Rényi divergence of this limit from the target. However, such properties have not been shown even in simple cases such as a strongly convex target.

Ganesh and Talwar (2020) is an exception, where authors analyzed the convergence of LMC in  $\alpha$ -Rényi divergence for strongly log-concave targets and obtained the rate  $\tilde{\mathcal{O}}(d/\epsilon^2)$ , which implies the same rate of convergence in Chi-squared divergence when  $\alpha = 2$ . More specifically, their result implies a convergence estimate of  $\tilde{\mathcal{O}}(d/\epsilon^2)$  in Chi-squared divergence for strongly convex potentials that have Lipschitz gradients.

Chi-squared divergence is particularly of interest because it conveniently upper bounds a variety of distance measures. For example, KL divergence (relative entropy), total variation (TV) distance and 2-Wasserstein ( $W_2$ ) metrics can be upper bounded as

$$\operatorname{TV}(\rho,\nu_*) \leq \sqrt{\operatorname{KL}(\rho|\nu_*)/2} \leq \sqrt{\chi^2(\rho|\nu_*)/2}$$
$$\mathcal{W}_2(\rho,\nu_*)^2/(2\lambda) \leq \chi^2(\rho|\nu_*).$$
(1.6)

See Tsybakov (2008, Lem 2.7) together with Csiszár-Kullback-Pinsker inequality (Bolley and Villani, 2005) for the former, and see e.g. Liu (2020, Thm 1.1) for the latter under (LSI). Therefore convergence in Chi-squared divergence implies convergence in these measures of distance as well. Moreover, for any 1-Lipschitz test function  $\phi$  and a target  $\pi$  satisfying LSI, if  $\chi^2(\rho_N|\pi) \lesssim 1$  then  $\mathbb{P}_{\rho_N}(|\phi(x) - \mathbb{E}_{\pi}[\phi(x)]| \geq t) \lesssim$  $\exp(-t^2)$ , which allows us to get sub-Gaussian concentration for the N-th LMC iterate (distributed as  $\rho_N$ ) around the expectation under the target  $\mathbb{E}_{\pi}[\phi(x)]$ .

Rényi-divergence is even stronger than Chi-squared, and has important applications to the field of differential privacy (Dwork et al., 2014; Chaudhuri et al., 2012; Zhang et al., 2016; Dwork and Feldman, 2018). One formalization of this objective involves the  $\alpha$ -Rényi divergence (Mironov, 2017), in which an algorithm guaranteeing  $\epsilon$  accuracy to the target in  $\alpha$ -Rényi can generate a scheme guaranteeing the classical criteria for differential privacy such as ( $\zeta$ ,  $\delta$ )-DP or  $\zeta$ -DP (McSherry and Talwar, 2007; Hardt and Talwar, 2010). We refer to the detailed discussion after Ganesh and Talwar (2020, Theorem 1).

Translating the existing rate estimate  $\widetilde{\mathcal{O}}(d/\epsilon^2)$  obtained in Ganesh and Talwar (2020) using the above inequalities (1.6), one cannot recover the state-of-theart convergence rates in TV, KL, and  $\mathcal{W}_2$  metrics. For example, the rate estimate  $\widetilde{\mathcal{O}}(d/\epsilon^2)$  in Chi-squared (or Rényi) divergence implies the same rate in KL divergence, which is substantially slower than the wellknown estimate  $\widetilde{\mathcal{O}}(d/\epsilon)$  under the same assumptions (see Dalalyan (2017b); Vempala and Wibisono (2019)). Our work bridges the gap in rates, and further extends the analysis to strongly dissipative potentials. Our contributions can be summarized as follows.

• We analyze first-order smooth potential *f* satisfying strong dissipativity in the sense of the following assumption.

**Assumption 1.** The potential function f is firstorder smooth and strongly dissipative, i.e.,  $\forall x, y$ 

$$\begin{aligned} \left\|\nabla f(x) - \nabla f(y)\right\| &\leq L \left\|x - y\right\|, \\ \left\langle x - y, \nabla f(x) - \nabla f(y)\right\rangle &\geq m \left\|x - y\right\|^2 - b, \end{aligned}$$

for some constants L, m > 0 and  $b \ge 0$ , where we also define the condition number as  $\kappa \coloneqq L/m$ .

In this case, we prove that taking  $\widetilde{\mathcal{O}}\left(\frac{\lambda^2 L^4}{m^2} \times \frac{b+d}{\epsilon}\right)$  steps of LMC is sufficient to obtain an  $\epsilon$ -accurate sample from a *d*-dimensional target in both Chi-squared and Rényi divergence, where  $\lambda$  is the LSI constant for  $\nu_* = e^{-f}$ . Our results do not require warm-start to deal with exponential dimension dependency at initialization, and can tolerate non-convexity as long as the tails of the potential is growing quadratically fast.

- When translated to KL divergence, TV and W<sub>2</sub> metrics using the inequalities (1.6), we obtain the rate estimates Õ((λ<sup>2</sup>L<sup>4</sup>/m<sup>2</sup> × b+d)/ϵ), Õ((λ<sup>2</sup>L<sup>4</sup>/m<sup>2</sup> × b+d)/ϵ<sup>2</sup>), and Õ((λ<sup>3</sup>L<sup>4</sup>/m<sup>2</sup> × b+d)/ϵ<sup>2</sup>), respectively.
  For m-strongly convex potentials (b = 0), we have
- For *m*-strongly convex potentials (b = 0), we have  $\lambda^{-1} = m$ ; thus, our rate estimate established in Chi-squared divergence is able to recover the best-known rate estimates<sup>1</sup> for LMC in KL divergence, TV and  $W_2$  metrics, respectively given as  $\widetilde{\mathcal{O}}(d/\epsilon)$ ,  $\widetilde{\mathcal{O}}(d/\epsilon^2)$ , and  $\widetilde{\mathcal{O}}(d/\epsilon^2)$ .
- We further discuss sampling from non-convex potentials that are covered by our assumptions, namely smooth potentials exhibiting strong convexity outside of a compact region. By deriving bounds on their LSI constant  $\lambda$ , we establish rate estimates for LMC under various scenarios.

Our analysis builds on the prominent works by Vempala and Wibisono (2019); Ganesh and Talwar (2020). More specifically, we conduct a two-phase analysis: In the first phase, we extend the analysis provided in Ganesh and Talwar (2020) to potentials that are strongly dissipative (e.g. strongly convex outside of a compact region) and control key quantities that impact the convergence of LMC for the interpolation process. In the second phase, we analyze a differential inequality for the Chi-squared (and Rényi) divergence, which resembles the (single-phase) analysis conducted by Vempala and Wibisono (2019) for the KL divergence, to obtain our final rate estimate. The rest of the paper is organized as follows. We discuss related work and notation in the rest of this section. In Section 2, we motivate the two-phase analysis, and state two key lemmas describing the characteristics of each phase. Section 3 contains the main results on the convergence of LMC. In Section 4, we provide examples and discuss the relative merits of certain non-convexity structures on our rate estimates. Finally in Section 5, we discuss future work. Majority of the proofs and the derivations are deferred to Appendix.

**Related work.** Convergence in  $L_p$  norms for some stochastic processes under a Poincaré inequality was first established in Cattiaux et al. (2010a). Started by the pioneering works by Durmus and Moulines (2016); Dalalyan (2017b); Durmus and Moulines (2017), nonasymptotic analysis of LMC has drawn a lot of interest (Dalalyan, 2017a; Cheng and Bartlett, 2018; Cheng et al., 2018; Durmus and Moulines, 2019; Durmus et al., 2019; Vempala and Wibisono, 2019; Dalalyan and Karagulyan, 2019; Brosse et al., 2019; Li et al., 2019; Erdogdu and Hosseinzadeh, 2020). It is known that  $\widetilde{\mathcal{O}}(d/\epsilon)$  steps of LMC yield an  $\epsilon$ -accurate sample in KL divergence for strongly convex and first-order smooth potentials (Cheng and Bartlett, 2018; Durmus et al., 2019). This is still the best rate obtained in this setup, and recovers the fastest rates in total variation and 2-Wasserstein metrics (Durmus and Moulines. 2017; Dalalyan, 2017b; Durmus and Moulines, 2019). For the same setting, Ganesh and Talwar (2020) showed that  $\widetilde{\mathcal{O}}(d/\epsilon^2)$  steps are enough for  $\epsilon$ -accurate solution in Rénvi divergence. Recently, these global curvature assumptions are relaxed to growth conditions (Cheng et al., 2018; Erdogdu et al., 2018). For example, Vempala and Wibisono (2019) established convergence guarantees for LMC when sampling from targets distributions that satisfy a log-Sobolev inequality, and has a smooth potential. This corresponds to potentials with quadratic tails (Bakry and Émery, 1985; Bobkov and Götze, 1999) up to finite perturbations (Holley and Stroock, 1987); thus, this result is able to deal with non-convex potentials while achieving the same rate of convergence  $\widetilde{\mathcal{O}}(d/\epsilon)$  in KL divergence. Their proof for Rénvi, however, relies on assumptions on the limit of the LMC iterates and thus is inconclusive. Convergence of zigzag samplers is established in Chi-squared divergence under a warm-start condition, in order to deal with the ill behavior at initialization (Lu and Wang, 2020).

<sup>&</sup>lt;sup>1</sup>Additional second order smoothness is known to speed up the convergence in KL divergence and 2-Wasserstein distance Mou et al. (2019); Dalalyan and Karagulyan (2019); however, our focus in this paper is first-order smoothness.

**Notation.** Throughout the paper, log denotes the natural logarithm. For a real number  $x \in \mathbb{R}$ , we denote its absolute value with |x|. We denote the Euclidean norm of a vector  $x \in \mathbb{R}^d$  with ||x||. The gradient, divergence, and Laplacian of f are denoted by  $\nabla f(x)$ ,  $\nabla \cdot f(x)$  and  $\Delta f(x)$ , respectively.

We use  $\mathbb{E}[x]$  to denote the expected value of a random variable or a vector x over all the randomness inside the brackets. For probability densities p,q on  $\mathbb{R}^d$ , we use  $\mathrm{KL}(p|q)$ ,  $\chi^2(p|q)$ , and  $R_\alpha(p|q)$  to denote their KL (or relative entropy), Chi-squared, and Rényi divergence (for  $\alpha > 1$ ), respectively, which are defined in (1.4). To ease the notation, we often use  $\frac{p}{q}(x)$  instead of p(x)/q(x). We denote the Borel  $\sigma$ field of  $\mathbb{R}^d$  with  $\mathcal{B}(\mathbb{R}^d)$ . 2-Wasserstein metric and the total variation (TV) distance are defined respectively as  $\mathcal{W}_2(p,q) = \inf_{\nu} (\int ||x-y||^2 d\nu(p,q))^{1/2}$  and TV  $(p,q) = \sup_{A \in \mathcal{B}(\mathbb{R}^d)} |\int_A (p(x) - q(x)) dx|$ , where in the first formula, infimum runs over the set of probability measures on  $\mathbb{R}^d \times \mathbb{R}^d$  that has marginals with corresponding densities p and q. Multivariate Gaussian distribution with mean  $\mu \in \mathbb{R}^d$  and covariance matrix  $\Sigma \in \mathbb{R}^{d \times d}$  is denoted with  $\mathcal{N}(\mu, \Sigma)$ .

# 2 TWO-PHASE ANALYSIS: MOTIVATION

A representative analysis of LMC starts with the interpolation process (Vempala and Wibisono, 2019),

$$d\widetilde{x}_t = -\nabla f(x_{\lfloor t/\eta \rfloor})dt + \sqrt{2}dB_t$$
 with  $\widetilde{x}_0 = x_0$ . (2.1)

The drift  $\nabla f(x_{\lfloor t/\eta \rfloor})$  of the above process is evaluated at the LMC iterate  $x_{\lfloor t/\eta \rfloor}$ , and is constant within each interval  $t \in [k\eta, (k+1)\eta)$  for an integer k. With the right coupling of the Brownian motion in (2.1) and the additive Gaussian term in the LMC update (1.1), the solution of (2.1) produces the LMC iterates for  $t = \eta k$  (i.e.  $\tilde{x}_{k\eta} = x_k$ ) by interpolating the discrete algorithm to a continuous-time process. We denote by  $\tilde{\rho}_t$  and  $\rho_k$ , the distributions of  $\tilde{x}_t$  and  $x_k$ , and we observe easily that  $\tilde{\rho}_{k\eta} = \rho_k$ . As the interpolation process is continuous in time, we can work with its Fokker-Planck equation. In Lemma 1, we show that the time derivative of  $\chi^2(\tilde{\rho}_t|\nu_*)$  differs from that of the continuous-time process by an additive error term.

To get this differential inequality, it is sufficient if the target satisfies a Poincaré inequality (PI)

$$\forall \rho, \quad \chi^2(\rho|\nu_*) \le \lambda \int \left\|\nabla \frac{\rho(x)}{\nu_*(x)}\right\|^2 \nu_*(x) dx. \quad (\text{PI})$$

We note that the above condition holds under LSI with the same constant  $\lambda$  (Villani, 2021), and emphasize that our final convergence results (in both Chi-squared and Rényi divergence) require the stronger condition LSI even though PI suffices for the following lemma.

**Lemma 1.** If  $\nu_*$  satisfies PI, then the following inequality governs the evolution of the Chi-squared divergence of the interpolated process (2.1) from the target

$$\frac{d}{dt}\chi^{2}(\widetilde{\rho}_{t}|\nu_{*}) \leq -\frac{3}{2\lambda}\chi^{2}(\widetilde{\rho}_{t}|\nu_{*})$$

$$+ 2\mathbb{E}\left[\frac{\widetilde{\rho}_{t}}{\nu_{*}}(\widetilde{x}_{t})^{2}\right]^{1/2} \mathbb{E}\left[\left\|\nabla f(\widetilde{x}_{t}) - \nabla f(x_{\lfloor t/\eta \rfloor})\right\|^{4}\right]^{1/2}.$$
(2.2)

The above differential inequality will be used to establish a single step bound that can be iterated to yield the final convergence result. For this, one needs to control *i*) the additive error term in (2.2), namely  $\mathbb{E}[\|\nabla f(\tilde{x}_t) - \nabla f(x_{\lfloor t/\eta \rfloor})\|^4]$  under a smoothness condition on the potential function, and *ii*) the expected squared ratio of densities  $\mathbb{E}[\frac{\tilde{\rho}_t}{\nu_*}(\tilde{x}_t)^2]$  which is harder to bound. Therefore we conduct our convergence analysis in two phases. In the first phase, we show that after taking N steps of LMC, the expected squared ratio (over the interpolation process) is bounded by an absolute constant at time  $N\eta$ , and moreover it stays uniformly bounded for the time interval  $[N\eta, 2N\eta]$ .

$$\mathbb{E}\left[\frac{\tilde{\rho}_T}{\nu_*}(\tilde{x}_T)^2\right] \le B \quad \text{for} \quad N\eta \le T \le 2N\eta, \quad (2.3)$$

where B is an absolute constant. The above opaque condition would ultimately imply that the LMC iterates also stay warm when the iteration counter belongs to the interval [N, 2N].

**Motivating Example.** In this toy example, the above uniform warmness condition (2.3) is verified for sampling from a Gaussian target  $e^{-f}$  using LMC with step size  $\eta$ . Assume for simplicity that  $f(x) = \frac{1}{2}||x||^2 + C$ , where C is the normalizing constant and  $x_0 \sim \mathcal{N}(0, \sigma_0^2 \mathbf{I})$ . For an integer  $k \geq 0$ ,  $t \in [0, \eta)$ , and  $T = k\eta + t$ , it is easy to compute the distribution of the interpolation process  $\tilde{\rho}_T = \mathcal{N}(0, \sigma_T^2 \mathbf{I})$  where  $\sigma_T^2 \coloneqq (1-t)^2 \sigma_{k\eta}^2 + 2t$  and  $\sigma_{k\eta}^2 \coloneqq (1-\eta)^{2k} \sigma_0^2 + \frac{1-(1-\eta)^{2k}}{1-\eta/2}$ . The expected squared ratio can be calculated as

$$\mathbb{E}\left[\frac{\tilde{\rho}_T}{\nu_*}(\tilde{x}_T)^2\right] = \frac{1}{(3/\sigma_T^2 - 2)^{d/2}\sigma_T^{3d}} \quad \text{whenever} \quad \sigma_T^2 < \frac{3}{2}.$$

For simplicity, let us initialize with  $\sigma_0^2 = 0.5/(1-\eta/2)$ . For a sufficiently small step size  $\eta$ , one can verify that  $\sigma_{k\eta}^2$  is monotonically increasing and converges to  $1/(1-\eta/2) < 1.5$ . Moreover,  $\sigma_0^2 > 1/2$  bounded away from 0. Therefore, at initialization (for k = 0) we have  $\mathbb{E}\left[\frac{\tilde{\rho}_0}{\nu_*}(\tilde{x}_0)^2\right] \approx e^d$ . However, notice that if at any point along the iterations, the condition  $1 - \frac{1}{d} \leq \sigma_{k\eta}^2 \leq 1 + \frac{1}{d}$  is satisfied, then we can show  $\mathbb{E}\left[\frac{\tilde{\rho}_T}{\nu_*}(\tilde{x}_T)^2\right] = \mathcal{O}(1)$  in the subsequent iterations, and accordingly B in (2.3) becomes  $\mathcal{O}(1)$ . Note that the denominator  $\sigma \to (3/\sigma^2 - 2)^{d/2}\sigma^{3d}$  attains its minimum value in the interval  $[1 - \frac{1}{d}, 1 + \frac{1}{d}]$  on its boundary (assuming d > 3). Then the resulting upper bound on its inverse becomes  $\mathcal{O}(1)$ . On the other hand, reaching  $1 - \frac{1}{d} \leq \sigma_T^2 \leq 1 + \frac{1}{d}$  in this setting is exponentially fast, which suggests a two-phase analysis. First, we prove that the distribution  $\tilde{\rho}_T$  gets close to target  $\nu_*$  so that their expected squared ratio reduces to and remains at  $\mathcal{O}(1)$ . Then in the next phase, we proceed the analysis with the differential inequality in Lemma 1 to obtain the final convergence estimate. The above argument is formalized in Assumption 1.

The strong dissipativity condition is equivalent to Cheng et al. (2018, Assumption 3). The target satisfies a LSI under strong dissipativity which can be easily deduced from Bakry and Émery (1985); Cattiaux et al. (2010b) (see Section C, cf. Raginsky et al. (2017, Prop 3.2)). For strongly convex potentials (b = 0), by the Bakry-Emery criterion we have  $\lambda = 1/m$ , i.e., the LSI constant is equal to the inverse of the strong convexity parameter of the potential. By plugging in y = 0, elementary algebra reveals that the strong dissipativity implies the standard 2-disspativity condition  $\langle x, \nabla f(x) \rangle \geq m' \|x\|^2 - b'$ , which is commonly employed in recent analyses in sampling and non-convex optimization (Raginsky et al., 2017; Yu et al., 2020; Erdogdu and Hosseinzadeh, 2020). While the stronger version does not cover all the potentials covered by the standard dissipativity, it still allows for finite perturbations (similar to 2-dissipativity and LSI), which we discuss in detail in Section 4.

First phase. We have the following in the first phase.

**Lemma 2.** For  $\alpha > 1$  and for a potential f satisfying Assumption 1, initialize the LMC algorithm with  $x_0 = \mathcal{N}(0, \sigma^2 I)$  for  $\sigma^2 < (1+L)^{-1}$ . If the step size satisfies  $\eta \leq \frac{2}{\|\nabla f(0)\|^2} \wedge \frac{1 \wedge m}{4(1 \vee L^2)}$  and for some absolute constant c, the following conditions hold

$$c\alpha^{2}\kappa^{2}L^{2}N(b+d+\log N)\eta^{2} \leq 1$$
$$N\eta \geq 2\alpha\lambda\log(4\alpha dC_{\sigma}),$$

where  $C_{\sigma} = 1 + \frac{f(0) + \|\nabla f(0)\|^2}{d} - \log(\sigma^2[(1+L) \wedge 2\pi])$ is dimension free,  $\lambda$  is the LSI constant of f, then

$$\mathbb{E}\left[\frac{\tilde{\rho}_T}{\nu_*}(\tilde{x}_T)^{2\alpha-2}\right] \le 14\alpha^{\frac{1}{4}}, \qquad \forall T \in [N\eta, 2N\eta].$$

This is shown in two parts: first by using the convergence of the continuous time process to the target in Rényi (Cao et al., 2019), and by bounding the Rényi of the interpolation process from the continuous process via a careful limiting argument that builds on Ganesh and Talwar (2020). When the jumps  $\|\tilde{z}_t - z_{kh}\| \leq \delta, \|\tilde{x}_t - x_{kh}\| \leq \delta$  for  $t \in [kh, (k+1)h)$ 

are bounded for an appropriately small  $\delta$ , we can show this Lemma using Girsanov's Theorem. To extend this to the general case, we show a that these jumps are bounded with high probability and then uncondition from the high probability event to complete the argument. The details of this proof are highly technical, and we defer it to Section A. We use the above bound for  $\alpha = 2$  for the Chi-squared divergence, but the case  $\alpha > 2$  will be useful when we extend the results to the Rényi divergence. After taking N iterations of LMC, the expected density ratio  $\mathbb{E}\left[\frac{\tilde{p}_T}{\nu_*}(\tilde{x}_T)^{2\alpha-2}\right]$  is bounded and it stays bounded in the subsequent N iterations, as in (2.3).

Second phase. In the next stage, we use a differential inequality in Chi-squared divergence only for the iterations ranging from step N to 2N. Since for these iterations, we have a uniform bound on the expected squared ratio over the interpolation process (by Lemma 2), we can simply integrate the differential inequality in Lemma 1 to obtain the single step bound.

**Lemma 3.** Instantiate the assumptions of Lemma 2 for  $\alpha = 2$ . If further  $\eta \leq \frac{\lambda}{2}$ , then for any iteration number k such that  $2N \geq k \geq N$ , the following inequality controls the evolution of LMC in  $\chi^2$ 

$$\chi^{2}(\rho_{k+1}|\nu_{*}) \leq (1 - \frac{3\eta}{4\lambda})\chi^{2}(\rho_{k}|\nu_{*}) + c\beta L^{2}(b+d)\eta^{2} \quad (2.4)$$

 $\begin{array}{l} \beta^2 \coloneqq 1 + \frac{\sigma^4(1+2/d) + 6\sigma^2 \|x^*\|^2/d + \|x^*\|^4/d^2}{(1+b/d)^2} + \frac{\sigma^2 + \|x^*\|^2/d}{1+b/d} \ is \ dimension-free \ and \ c \ is \ an \ absolute \ constant. \end{array}$ 

The proof follows by integrating the differential inequality derived in Lemma 1 for  $t \in [0, \eta]$  after using the uniform bound on the expected squared ratio given by Lemma 2, which we defer to Section A. The key innovation of the above result is that the additive error term in (2.4), the second term on the right hand side, has  $\mathcal{O}(d\eta^2)$  dependence for the LMC iterations ranging from N to 2N. This is because the constant  $\beta$  is uniformly bounded in dimension.

## 3 MAIN RESULTS

In this section, we first provide results on the convergence of LMC (1.1) by simply iterating the single step bound in Lemma 3.

**Theorem 4.** Let the potential f satisfy Assumption 1 and suppose we run 2N iterations of LMC (1.1) with step size  $\eta$  to sample from  $\nu_* = e^{-f}$ . If we initialize  $x_0$  with  $\mathcal{N}(0, \sigma^2 \mathbf{I})$  for some  $\sigma^2 < (1 + L)^{-1}$ , in order to get  $\chi^2(\rho_{2N}|\nu_*) \leq \epsilon$ , it is sufficient if the following inequalities hold

$$\eta \leq \frac{2}{\|\nabla f(0)\|^2} \wedge \frac{1 \wedge m}{4(1 \vee L^2)} \wedge \frac{\lambda}{2} \wedge \frac{c_3}{\beta \lambda L^2} \times \frac{\epsilon}{b+d} \quad (3.1)$$
$$N\eta \geq c_2 \lambda \log \left( 144 dC_{\sigma}/\epsilon \right)$$
$$c_1 \geq \kappa^2 L^2 (b+d+\log N) N\eta^2,$$

where  $\lambda$  is the LSI constant of the target,  $c_1, c_2, c_3$  are absolute constants, and  $C_{\sigma}$  and  $\beta$  are dimension free constants defined respectively in Lemmas 2 and 3.

Consequently, if we choose

$$\eta = \frac{c_3}{\beta} \times \frac{m^2}{\lambda L^4 \log(\frac{L^4 \lambda^2}{m^2})} \times \frac{\epsilon}{b+d} \times \frac{1}{\log(144dC_{\sigma}/\epsilon)^2} \qquad (3.2)$$

$$N = \frac{c_2\beta}{c_3} \times \frac{\lambda^2 L^4 \log(\frac{\lambda^2 L^4}{m^2})}{m^2} \times \frac{b+d}{\epsilon} \times \log(144dC_{\sigma}/\epsilon)^3,$$

then 2N iterations of LMC yield  $\chi^2(\rho_{2N}|\nu_*) \leq \epsilon$  for  $N \geq 2$  and for  $\epsilon > 0$  sufficiently small.

The above theorem implies that  $\tilde{\mathcal{O}}(\lambda^2 L^4/m^2 \times d/\epsilon)$ steps of LMC algorithm is sufficient to obtain an  $\epsilon$ accurate sample in Chi-squared divergence. The rate estimate given in (3.2) can be slightly improved to  $\mathcal{O}(d/\epsilon \log(d/\epsilon) \log(d)^2)$  in terms of  $\epsilon$  dependency at the expense of introducing more complicated expressions; yet, we use (3.2) for simplified exposition.

For strongly convex potentials (i.e.  $\lambda = 1/m$  and b = 0), we can recover the condition number dependency of Vempala and Wibisono (2019) in the case  $\kappa^2 \lesssim \epsilon^{-1}$ . This can be seen by choosing  $\eta = c \times \frac{m}{L^2} \times \frac{\epsilon}{d}$  and  $N = C \times \kappa^2 \times \frac{d}{\epsilon}$  and verifying the conditions in (3.1). As  $\epsilon$  is the error tolerance and is typically chosen to be very small, this condition is reasonable in practice. In the case that the condition number satisfies  $\kappa^2 \gg \epsilon^{-1}$ (which we believe is unrealistic), then our rate becomes  $\mathcal{O}(\kappa^4)$  as stated in the theorem, which is worse than the known dependency  $\mathcal{O}(\kappa^2)$ .

The theorem states that if the step size and the number of iterations satisfy the three conditions given in (3.1), the LMC algorithm is guaranteed to produce an  $\epsilon$ accurate sample in exactly 2N iterations. We emphasize that this result may not hold for the subsequent iterates of LMC because of the last condition (3.1), due to the delicate bound we construct using Lemma 2, which will be violated as  $N \to \infty$ . Rate estimates with this restriction are frequent in the literature (Shen and Lee, 2019; Ganesh and Talwar, 2020; Erdogdu and Hosseinzadeh, 2020). This typically occurs when there is a diverging bound on a quantity that appears in the convergence analysis. In our case, the source of this is the expected squared ratio bounded in Lemma 2. We note that LMC is ergodic (Mattingly et al., 2002) and its subsequent iterates after iteration 2N remain  $\epsilon$ accurate in KL divergence and 2-Wasserstein distance from the target under LSI (Vempala and Wibisono,

Table 1: Translation of the rate estimate in Chisquared divergence to various divergences by choosing an appropriate accuracy level  $\epsilon_{\chi^2}$  in Theorem 4.

	$\epsilon_{\chi^2}$	N	$\eta$
$\chi^2$	$\epsilon$	$\widetilde{\mathcal{O}}\left(rac{\lambda^2 L^4}{m^2}  imes rac{b+d}{\epsilon} ight)$	$\widetilde{\mathcal{O}}\left(rac{m^2}{\lambda L^4}  imes rac{\epsilon}{b+d} ight)$
KL	$\epsilon$	$\widetilde{\mathcal{O}}\left(rac{\lambda^2 L^4}{m^2}  imes rac{b+d}{\epsilon} ight)$	$\widetilde{\mathcal{O}}(rac{m^2}{\lambda L^4}  imes rac{\epsilon}{b+d})$
TV	$2\epsilon^2$	$\widetilde{\mathcal{O}}\left(rac{\lambda^2 L^4}{m^2}  imes rac{b+d}{\epsilon^2} ight)$	$\widetilde{\mathcal{O}}\left(\frac{m^2}{\lambda L^4}  imes \frac{\epsilon^2}{b+d}\right)$
$\mathcal{W}_2$	$\epsilon^2/2\lambda$	$\widetilde{\mathcal{O}}\left(\frac{\lambda^3 L^4}{m^2} \times \frac{b+d}{\epsilon^2}\right)$	$\widetilde{\mathcal{O}}\left(\frac{m^2}{\lambda^2 L^4} \times \frac{\epsilon^2}{b+d}\right)$

2019). Therefore we can likely show this for  $N \to \infty$  with a different proof technique.

We can translate our rate estimate in Chi-squared divergence using (1.6), to obtain guarantees in KL divergence, TV, and  $W_2$  metrics.

**Corollary 5.** Instantiate the assumptions and the notation in Theorem 4. Table 1 summarizes the convergence rate estimates in various measures of distance.

For strongly convex potentials (i.e.  $\lambda = 1/m$  and b = 0), the above rate estimates recover the stateof-the-art estimates in all of the above measures of distance in both accuracy  $\epsilon$  and dimension d. In other words, there is no loss in converting the rates using the inequalities (1.6).

#### 3.1 Extending to Rényi Divergence

The results presented in the previous section for the Chi-squared divergence can be extended to the Rényi divergence with minimal effort. The key is to establish a differential inequality in this measure of distance as given below (cf. Lemma 1), which will be solved and iterated to yield a convergence rate in the Rényi divergence. Contrary to Lemma 1 which was established under PI, the following result is established under LSI.

**Lemma 6.** If  $\nu_*$  satisfies LSI and  $\alpha > 1$ , then the following inequality controls the evolution of the  $\alpha$ -Rényi divergence of the interpolated process from the target

$$\frac{d}{dt}R_{\alpha}\left(\widetilde{\rho}_{t}|\nu_{*}\right) \leq -\frac{3}{2\alpha\lambda}R_{\alpha}\left(\widetilde{\rho}_{t}|\nu_{*}\right) \\ + \alpha \mathbb{E}\left[\frac{\widetilde{\rho}_{t}}{\nu_{*}}(\widetilde{x}_{t})^{2\alpha-2}\right]^{\frac{1}{2}}\mathbb{E}\left[\left\|\nabla f(\widetilde{x}_{t}) - \nabla f(x_{\lfloor t/\eta \rfloor})\right\|^{4}\right]^{\frac{1}{2}}.$$

The proof of the above statement is similar to that of Lemma 1, and deferred to Section B. To iterate the bound obtained using Lemma 6, we again conduct a two-phase analysis. In the first phase, we use Lemma 2; N steps of LMC implies that  $\mathbb{E}\left[\frac{\tilde{\rho}_t}{\nu_*}(\tilde{x}_t)^{2\alpha-2}\right]$ is bounded by  $\mathcal{O}(\alpha^{0.25})$ , and stays bounded in the subsequent N iterations. In the second phase, we use the following generalization of the single-step bound in Lemma 3 for the Rényi divergence.

**Lemma 7.** Under the assumptions of Lemma 2, and if we additionally have  $\eta \leq \frac{2\alpha\lambda}{3}$ , then for any iteration k such that  $k \in [N, 2N]$ , LMC satisfies  $R_{\alpha} (\rho_{k+1}|\nu_*) \leq (1 - \frac{3\eta}{4\alpha\lambda})R_{\alpha} (\rho_k|\nu_*) + c\beta L^2 (b+d)\alpha^{9/8}\eta^2$ , where c is an absolute constant and  $\beta$  is defined in Lemma 3.

The immediate consequence of this lemma is a bound on the Rényi divergence, which is stated below.

**Theorem 8.** For  $\alpha > 1$  and for a potential f satisfying Assumption 1, suppose we run 2N iterations of LMC(1.1) with step size  $\eta$  to sample from  $\nu_* = e^{-f}$ . If we initialize  $x_0$  with  $\mathcal{N}(0, \sigma^2 \mathbf{I})$  for some  $\sigma^2 < (1 + L)^{-1}$ , in order to get  $R_{\alpha}(\rho_{2N}|\nu_*) \leq \epsilon$ , it is sufficient if the following inequalities hold

$$\eta \leq \frac{2}{\|\nabla f(0)\|^2} \wedge \frac{1 \wedge m}{4(1 \vee L^2)} \wedge \frac{2\alpha\lambda}{3} \wedge \frac{c_3}{\beta\lambda L^2 \alpha^{17/8}} \times \frac{\epsilon}{(b+d)}$$
$$N\eta \geq c_2 \alpha \lambda \log\left(\frac{6\alpha^2 dC_\sigma}{(\alpha-1)\epsilon}\right)$$
$$c_1 \geq \alpha^2 \kappa^2 L^2 (b+d+\log N) N\eta^2,$$

where  $\lambda$  is the LSI constant of the target,  $c_1, c_2, c_3$  are absolute constants, and  $C_{\sigma}$  and  $\beta$  are dimension free constants defined respectively in Lemmas 2 and 3.

Consequently, if we choose

$$\eta = \frac{c_3}{\beta} \times \frac{m^2}{L^4 \lambda \log\left(\frac{L^4 \lambda^2}{m^2}\right)} \times \frac{1}{\alpha^3} \times \frac{\epsilon}{b+d} \times \frac{1}{\log\left(\frac{6\alpha^2 dC_{\sigma}}{(\alpha-1)\epsilon}\right)^2}$$
$$N = \frac{c_2\beta}{c_3} \times \frac{L^4 \lambda^2 \log\left(\frac{L^4 \lambda^2}{m^2}\right)}{m^2} \times \alpha^4 \times \frac{b+d}{\epsilon} \times \log\left(\frac{6\alpha^2 dC_{\sigma}}{(\alpha-1)\epsilon}\right)^3,$$

then, 2N steps of LMC yield  $R_{\alpha}(\rho_{2N}|\nu_*) \leq \epsilon$  for  $N \geq 2$  and for a sufficiently small  $\epsilon > 0$ .

The above theorem is similar to Theorem 4; therefore the same remarks also apply to this result. One important difference is the  $\alpha$  dependency of the rate  $\mathcal{O}(\alpha^4 \log(\frac{\alpha^2}{\alpha-1})^3)$ , which diverges as  $\alpha \to 1$  and  $\alpha \to \infty$ . If one is interested in  $\alpha \approx 1$ , then using the monotonicity of Rényi divergence, one can obtain better rate estimates, for example by bounding  $R_{\alpha}$  by  $R_2$ .

# 4 EXAMPLES

Assumption 1 implies that the target satisfies a log-Sobolev inequality. This can be deduced from the results of Bakry and Émery (1985); Cattiaux et al. (2010b), and a derivation is provided in Section C (cf. Raginsky et al. (2017, Prop 3.2)). The proof relies on showing the Lyapunov condition found in Bakry et al. (2008) for the functional  $W(x) = \exp(\frac{\gamma}{2} ||x - x_*||^2)$ for some critical point  $x_*$  of f, and yields an LSI constant of order  $\mathcal{O}(d^2 e^{\operatorname{Osc}_R(f)})$ , where  $\operatorname{Osc}_R(f) =$  $\sup_{||x-x_*|| \leq R} f(x) - \inf_{||x-x_*|| \leq R} f(x)$ . However, under more specific curvature conditions on the potential, one can obtain better estimates on the LSI constant, as seen below.

# 4.1 Strongly convex and first-order smooth potentials

Potentials that are in this category satisfy  $LI \succeq \nabla^2 f(x) \succeq mI$ . It is easy to see that Assumption 1 holds for the same parameters L, m, and b = 0. Moreover, due to the Bakry-Émery criterion, the target  $\nu_* = e^{-f}$  satisfies LSI with constant  $\lambda = 1/m$ .

While strongly convex potentials have often been studied in prior work, the known rate in  $\chi^2$  and Rényi divergence is  $\mathcal{O}(d/\epsilon^2)$  (Ganesh and Talwar, 2020). Our analysis instead obtains  $\mathcal{O}(d/\epsilon)$ ; this represents a significant improvement to the known convergence rates. When translated to KL divergence (using (1.4)), our rate recovers the state-of-the-art rates for the same class of potentials (Dalalyan, 2017b; Durmus and Moulines, 2017).

Despite their apparent simplicity, this function class contains numerous practical applications.

**Ex 1: Gaussian mixtures.** In this case, we consider sampling from potentials of the form

$$\nu_*(x) \propto \exp\left(-\frac{1}{2} \|x-a\|^2\right) + \exp\left(-\frac{1}{2} \|x+a\|^2\right)$$

with  $a \in \mathbb{R}^d$  a parameter controlling the modal separation. These potentials have strongly convex densities if  $\|a\|_2 < 1$ , with first, second and third order derivatives all being Lipschitz (Dalalyan, 2017b).

**Ex 2: Bayesian logistic regression**. Consider data samples  $V = \{v_i\}_{i=1}^n \in \mathbb{R}^{n \times d}, y = \{y_i\}_{i=1}^n \in \mathbb{R}^n$ , and a Bernoulli distribution  $\mathbb{P}(y = 1|v) = 1/(1 + \exp(-\langle x, v \rangle))$  with parameter  $x \in \mathbb{R}^d$ . If we use the prior  $x \sim \mathcal{N}(0, \alpha \Sigma_V^{-1})$  where  $\Sigma_V = V^\top V/n$ , then the resulting posterior is proportional to

$$\exp(y^{\top}Vx - \sum_{i=1}^{n} \log(1 + \exp(\langle x, v_i \rangle)) - \frac{\alpha}{2} \|\Sigma_V^{1/2} x\|^2).$$

Again, the potential is strongly convex, with Lipschitz derivatives up to the third order (Dalalyan, 2017b).

**Ex 3: Bounded perturbations.** We also admit potentials  $f = f_{sc} + f_p$  such that  $f_{sc}$  is  $m_0$ strongly convex with  $L_0$ -Lipschitz gradient, and  $f_p$  satisfies  $|f_p| \vee ||\nabla f_p|| \vee ||\nabla^2 f_p|| \leq B$ . Then  $\langle \nabla f(x) - \nabla f(y), x - y \rangle = \langle \nabla f_{sc}(x) - \nabla f_{sc}(y), x - y \rangle +$  $\langle \nabla f_p(x) - \nabla f_p(y), x - y \rangle$ , which is bounded by  $m_0 ||x - y||^2 - 2B ||x - y|| \geq m ||x - y||^2 - b$ , where the last inequality holds for  $m = m_0/2$  and  $b = 2B^2/m$ . We also have  $||\nabla^2 f|| \leq ||\nabla^2 f_{sc}|| + ||\nabla^2 f_p|| \leq L_0 + B \coloneqq$ L. Thus, Assumption 1 holds for such functions. Further, by the Holley-Stroock lemma (Holley and Stroock, 1987), LSI is satisfied for  $\lambda = m_0^{-1}e^{2B}$ .

#### 4.2 Strong convexity outside a ball

For a second class of examples, consider potentials that are strongly convex outside a ball. If we assume that f has continuous and upper bounded Hessian  $\nabla^2 f(x) \preceq M_0 \mathbf{I}$ , this assumption means  $\inf_{\|x\|\geq r} \nabla^2 f(x) \succeq m_0 \mathbf{I}$ ,  $\inf_{\|x\|< r} \nabla^2 f(x) \succeq -k\mathbf{I}$ , where  $m_0 > 0$  is the convexity parameter, and  $r \ge 0$ , k > 0. This condition implies f is first-order smooth with  $L := M_0 \lor k$ . The first condition in (4.2) is enough to verify strong dissipativity; we write  $y = x + s_3 z$  for  $s_3 = \|x - y\|$ ,  $\|z\| = 1$ , and let  $s_1, s_2 \in [0, s_3]$  such that  $\|x + sz\| \le r \iff s \in [s_1, s_2]$ . Then,

$$\begin{split} \langle \nabla f(x) - \nabla f(y), x - y \rangle &= \int_{s \in [0,s_1] \cup [s_2,s_3]} \langle \nabla^2 f(x + sz) z, s_3 z \rangle ds \\ &+ \langle \nabla f(x + s_2 z) - \nabla f(x + s_1 z), s_3 z \rangle, \end{split}$$

which is bounded by  $m_0(s_3 - 2r)s_3 - 2Lrs_3 \geq \frac{m_0}{2} ||x - y||^2 - \frac{2}{m_0} (m_0 r + Lr)^2$ , where outside of the ball we use strong convexity, and inside we use smoothness.

For LSI, we replace f with a strongly convex function  $\tilde{f}(x) = f(x) + 0.5(k+m_0) ||x||^2 \mathbf{1}_{\{||x|| \le r\}}$ , so that  $\nabla^2 \tilde{f} \succeq m_0 \mathbf{I}$  everywhere. Then  $||f - \tilde{f}||_{\infty} \le 0.5(k+m_0)r^2$ , and by the Holley-Stroock perturbation lemma (Holley and Stroock, 1987),  $\lambda \le \lambda_{\tilde{f}} \cdot \exp\left((k+m_0)r^2\right) = m_0^{-1} \exp\left((k+m_0)r^2\right)$ .

**Ex:** Student's t-Regression, Gaussian prior. Consider the function with  $\alpha > 0$ 

$$f(x) = \frac{1}{2}\log(1 + ||x||^2) + \frac{\alpha}{2} ||x||^2 + \text{constant.} (4.1)$$

The gradient is  $\frac{x}{1+||x||^2} + \alpha x$ , which is  $(\alpha+1)$ -Lipschitz, and Hessian is  $\alpha I + \frac{(1+||x||^2)I-2xx^{\top}}{(1+||x||^2)^2}$ . When  $\alpha < 1/8$  is sufficiently small, this function is non-convex. However, if we take the radius to be  $||x|| \ge 1/\sqrt{\alpha}$ ; we find strong convexity outside the ball with  $m_0 = \alpha^2(\alpha+3)/(\alpha+1)^2$ , and k = -1/8. Strong dissipativity is satisfied, and LSI holds with constant  $\frac{(\alpha+1)^2}{\alpha^2(\alpha+3)} \exp\left(\frac{\alpha^2(\alpha+3)}{\alpha(\alpha+1)^2} + \frac{1}{8\alpha}\right)$ .

For instance, when data is heavy tailed, Student's t-distribution is used to model the errors. Under a Gaussian prior on the coefficients  $x \sim \mathcal{N}(0, \alpha I)$ , the posterior distribution has the potential  $f(x) = \sum_{i=1}^{n} \log(1 + (y_i - \langle v_i, x \rangle)^2) + \frac{\alpha}{2} ||x||^2 + \text{constant}$ , where  $\{v_i\}_{i=1}^n, \{y_i\}_{i=1}^n$  are data samples as before. Notice that the potential has the same form as (4.1). Under suitable assumption on data, one can use the same steps above to verify our conditions.

#### 4.3 Non-uniform strong convexity

Finally, we consider functions which are similar to the previous section, but with variable convexity 
$$\begin{split} &\inf_{\|x\|\geq r} \nabla^2 f(x) \succeq m_0(r) \text{I. Then if } \sup_{r\geq 0} m_0(r) > 0, \\ &\text{strong dissipativity holds for the same reason as in the } \\ &\text{prior subsection, since we need only fix some } r > 0, \\ &\text{where } m_0(r) > 0 \text{ to recover the first inequality in (4.2).} \\ &\text{LSI is satisfied as well (Chen and Wang, 1997) with the } \\ &\text{constant } \lambda \text{ bounded by } \lambda \leq \frac{a_0^2}{2} \exp\left(\int_0^{a_0} rm_0(r) dr - 1\right) \\ &\text{where } a_0 \text{ uniquely solves } \int_0^a m_0(r) = 2/a. \end{split}$$

**Ex:** Heavy-tailed regression, corrupted noise. Consider the function

$$f(x) = -\frac{1}{2}\log(\beta + \exp(-\|x\|^2)) + \frac{\alpha}{2}\|x\|^2 + \text{constant},$$

where  $\beta > 0, \alpha > 0$ . The gradient is  $\frac{x}{\beta \exp(\|x\|^2)+1} + \alpha x$ , which is  $\alpha + \frac{1}{1+\beta}$ -Lipschitz, and the Hessian is

$$\frac{\beta \exp(\|x\|^2)(\mathbf{I} - 2xx^{\top}) + \mathbf{I}}{(\beta \exp(\|x\|^2) + 1)^2} + \alpha \mathbf{I}.$$

In this case,

$$m_0(r) = \alpha - \frac{\beta \exp(r^2)(2r^2 - 1) - 1}{(\beta \exp(r^2) + 1)^2} \ge \alpha - \frac{r^2}{\beta \exp(r^2)}$$

Since  $\frac{r^2}{\beta \exp(r^2)} \to 0$ , this quantity eventually becomes positive. By our argumentation, the function is strongly dissipative and we can solve for the LSI constant numerically.

For an instance of this, consider linear regression on data  $\{v_i\}_{i=1}^n, \{y_i\}_{i=1}^n$ , with corrupted Gaussian noise such that with small probability the noise is sampled from uniform distribution (arises in visual reconstruction problems (Blake and Zisserman, 1987)). Assuming a prior  $x \sim \mathcal{N}(0, \alpha I)$ , we obtain the following potential for the posterior f(x) = $-\frac{1}{2}\sum_{i=1}^n \log (\beta + \exp(-(y_i - \langle v_i, x \rangle)^2)) + \frac{\alpha}{2} ||x||^2 +$ constant. Our assumptions can be verified using the same steps, under suitable conditions on the data.

# 5 CONCLUSION

In this paper, we analyzed the convergence of unadjusted LMC algorithm for a class of potentials that are first-order smooth and strongly dissipative. We used the Fokker-Planck equation of the interpolated process alongside the smoothness assumptions to obtain a differential inequality which in turn yielded a single step bound to be iterated to obtain our main convergence results. The obtained rates improve upon the existing rates in Chi-squared and Rényi divergence, and recover the state-of-the-art rates in KL, TV, and  $W_2$ .

We highlight a few important future directions below.

• Although we assumed LSI throughout the paper, Poincaré inequality is sufficient to establish the differential inequality in Lemma 1. The restriction is due to the strong dissipativity assumption, which enforces a quadratic growth on the potential function; thus, LSI must hold. This also enforces at least linear growth on the gradient, which prevents us from considering weakly smooth potentials that satisfy Hölder continuity. Relaxing this assumption may allow one to establish convergence only under the Poincaré inequality, which permits weakly smooth potentials that have at least linear growth. We note that this setting is already considered in Erdogdu and Hosseinzadeh (2020) under the KL divergence.

- The rate estimates presented in this paper do not hold for all iterates as  $N \to \infty$ , similar to Shen and Lee (2019); Ganesh and Talwar (2020); Erdogdu and Hosseinzadeh (2020). This is an artifact of our proof technique, and hopefully can be remedied in the future work.
- In some toy examples such as the Gaussian, the rate is instead  $\tilde{\mathcal{O}}(\sqrt{d/\epsilon})$  iterations to obtain  $\epsilon$  Chi-squared divergence. This is  $\tilde{\mathcal{O}}(\sqrt{d/\epsilon})$  better than the rate estimate we obtained in the current paper, and is due to the additional second-order smoothness of the Gaussian potential. Improving the rate under additional smoothness is an interesting direction left for future work.
- Similar techniques can be utilized to establish convergence rates for other numerical schemes (Li et al., 2019); the ones that satisfy certain optimality criteria are of particular interest (Shen and Lee, 2019; Cao et al., 2020; He et al., 2020).

# 6 ACKNOWLEDGEMENTS

This research is partially funded by NSERC Grant [2019-06167], Connaught New Researcher Award, and CIFAR AI Chairs program at the Vector Institute. RH and MAE thank Andre Wibisono for pointing out an error in a previous version of this paper. To fix this, stronger assumptions were made in the current version. Finally, RH is grateful to Arun Ganesh for the helpful email exchange on formalizing Lemma 12.

#### References

- Bakry, D., Barthe, F., Cattiaux, P., and Guillin, A. (2008). A simple proof of the Poincaré inequality for a large class of probability measures. *Electron. Commun. Probab.*, 13:60–66. (Cited on pages 2, 7, and 23.)
- Bakry, D. and Émery, M. (1985). Diffusions hypercontractives. In Séminaire de Probabilités XIX 1983/84, pages 177–206, Berlin, Heidelberg.

Springer Berlin Heidelberg. (Cited on pages 2, 3, 5, and 7.)

- Bellman, R. (1943). The stability of solutions of linear differential equations. *Duke Math. J.*, 10(4):643– 647. (Cited on page 24.)
- Blake, A. and Zisserman, A. (1987). Visual reconstruction. MIT press. (Cited on page 8.)
- Bobkov, S. G. and Götze, F. (1999). Exponential integrability and transportation cost related to logarithmic Sobolev inequalities. *Journal of Functional Analysis*, 163(1):1–28. (Cited on page 3.)
- Bolley, F. and Villani, C. (2005). Weighted csiszárkullback-pinsker inequalities and applications to transportation inequalities. In Annales de la Faculté des sciences de Toulouse: Mathématiques, volume 14, pages 331–352. (Cited on page 2.)
- Brosse, N., Durmus, A., Moulines, E., and Sabanis, S. (2019). The tamed unadjusted Langevin algorithm. *Stochastic Processes and their Applications*, 129(10):3638 – 3663. (Cited on page 3.)
- Cao, Y., Lu, J., and Lu, Y. (2019). Exponential decay of rényi divergence under fokker-planck equations. *Journal of Statistical Physics*, 176(5):1172– 1184. (Cited on pages 2 and 5.)
- Cao, Y., Lu, J., and Wang, L. (2020). Complexity of randomized algorithms for underdamped langevin dynamics. arXiv preprint arXiv:2003.09906. (Cited on page 9.)
- Cattiaux, P., Guillin, A., and Roberto, C. (2010a). Poincaré inequality and the lp convergence of semigroups. *Electronic Communications in Probability*, 15:270–280. (Cited on page 3.)
- Cattiaux, P., Guillin, A., and Wu, L.-M. (2010b). A note on Talagrand's transportation inequality and logarithmic Sobolev inequality. *Probability theory and related fields*, 148(1-2):285–304. (Cited on pages 5, 7, and 23.)
- Chaudhuri, K., Sarwate, A., and Sinha, K. (2012). Near-optimal differentially private principal components. Advances in Neural Information Processing Systems, 25:989–997. (Cited on page 2.)
- Chen, M.-F. and Wang, F.-Y. (1997). Estimates of logarithmic sobolev constant: An improvement of bakry–emery criterion. *Journal of Functional Anal*ysis, 144(2):287–300. (Cited on page 8.)
- Cheng, X. and Bartlett, P. (2018). Convergence of langevin mcmc in kl-divergence. In *Algorithmic Learning Theory*, pages 186–211. PMLR. (Cited on page 3.)
- Cheng, X., Chatterji, N. S., Abbasi-Yadkori, Y., Bartlett, P. L., and Jordan, M. I. (2018). Sharp con-

vergence rates for Langevin dynamics in the nonconvex setting. *arXiv preprint arXiv:1805.01648.* (Cited on pages 3 and 5.)

- Chewi, S., Gouic, T. L., Lu, C., Maunu, T., Rigollet, P., and Stromme, A. (2020). Exponential ergodicity of mirror-Langevin diffusions. arXiv preprint arXiv:2005.09669. (Cited on page 2.)
- Dalalyan, A. (2017a). Further and stronger analogy between sampling and optimization: Langevin Monte Carlo and gradient descent. In Proceedings of the 2017 Conference on Learning Theory, volume 65 of Proceedings of Machine Learning Research, pages 678–689. PMLR. (Cited on page 3.)
- Dalalyan, A. S. (2017b). Theoretical guarantees for approximate sampling from smooth and log-concave densities. Journal of the Royal Statistical Society: Series B (Statistical Methodology), 79(3):651–676. (Cited on pages 2, 3, and 7.)
- Dalalyan, A. S. and Karagulyan, A. (2019). Userfriendly guarantees for the Langevin Monte Carlo with inaccurate gradient. *Stochastic Processes and their Applications*, 129(12):5278–5311. (Cited on page 3.)
- Durmus, A., Majewski, S., and Miasojedow, B. (2019). Analysis of Langevin Monte Carlo via Convex Optimization. Journal of Machine Learning Research, 20(73):1–46. (Cited on page 3.)
- Durmus, A. and Moulines, E. (2016). Sampling from strongly log-concave distributions with the Unadjusted Langevin Algorithm. *arXiv preprint arXiv:1605.01559*, 5. (Cited on page 3.)
- Durmus, A. and Moulines, E. (2017). Nonasymptotic convergence analysis for the unadjusted langevin algorithm. Annals of Applied Probability, 27(3):1551– 1587. (Cited on pages 2, 3, and 7.)
- Durmus, A. and Moulines, E. (2019). Highdimensional Bayesian inference via the unadjusted Langevin algorithm. *Bernoulli*, 25(4A):2854–2882. (Cited on page 3.)
- Dwork, C. and Feldman, V. (2018). Privacy-preserving prediction. In *Conference On Learning Theory*, pages 1693–1702. PMLR. (Cited on page 2.)
- Dwork, C., Roth, A., et al. (2014). The algorithmic foundations of differential privacy. *Found. Trends Theor. Comput. Sci.*, 9(3-4):211–407. (Cited on page 2.)
- Erdogdu, M. A. and Hosseinzadeh, R. (2020). On the convergence of Langevin Monte Carlo: The interplay between tail growth and smoothness. *arXiv* preprint arXiv:2005.13097. (Cited on pages 2, 3, 5, 6, and 9.)

- Erdogdu, M. A., Mackey, L., and Shamir, O. (2018). Global non-convex optimization with discretized diffusions. In Advances in Neural Information Processing Systems, pages 9671–9680. (Cited on page 3.)
- Ganesh, A. and Talwar, K. (2020). Faster differentially private samplers via Rényi divergence analysis of discretized Langevin MCMC. Advances in Neural Information Processing Systems, 33. (Cited on pages 2, 3, 5, 6, 7, 9, 16, 20, 21, and 23.)
- Hardt, M. and Talwar, K. (2010). On the geometry of differential privacy. In Proceedings of the fortysecond ACM symposium on Theory of computing, pages 705–714. (Cited on page 2.)
- He, Y., Balasubramanian, K., and Erdogdu, M. A. (2020). On the ergodicity, bias and asymptotic normality of randomized midpoint sampling method. Advances in Neural Information Processing Systems, 33. (Cited on page 9.)
- Holley, R. and Stroock, D. (1987). Logarithmic Sobolev inequalities and stochastic Ising models. *Journal of Statistical Physics*, 46(5):1159–1194. (Cited on pages 2, 3, 7, and 8.)
- Ikeda, N. and Watanabe, S. (2014). Stochastic differential equations and diffusion processes. Elsevier. (Cited on page 24.)
- Li, X., Wu, Y., Mackey, L., and Erdogdu, M. A. (2019). stochastic Runge-Kutta accelerates Langevin Monte Carlo and beyond. In Advances in Neural Information Processing Systems 32, pages 7748–7760. Curran Associates, Inc. (Cited on pages 3 and 9.)
- Liu, Y. (2020). The poincaré inequality and quadratic transportation-variance inequalities. *Electron. J. Probab.*, 25:16 pp. (Cited on page 2.)
- Lu, J. and Wang, L. (2020). Complexity of zigzag sampling algorithm for strongly log-concave distributions. arXiv preprint arXiv:2012.11094. (Cited on page 3.)
- Mattingly, J. C., Stuart, A. M., and Higham, D. J. (2002). Ergodicity for SDEs and approximations: locally Lipschitz vector fields and degenerate noise. *Stochastic processes and their applications*, 101(2):185–232. (Cited on page 6.)
- McSherry, F. and Talwar, K. (2007). Mechanism design via differential privacy. In 48th Annual IEEE Symposium on Foundations of Computer Science (FOCS'07), pages 94–103. IEEE. (Cited on page 2.)
- Mironov, I. (2017). Rényi differential privacy. In 2017 IEEE 30th Computer Security Foundations Symposium (CSF), pages 263–275. IEEE. (Cited on pages 2 and 23.)

- Mou, W., Flammarion, N., Wainwright, M. J., and Bartlett, P. L. (2019). Improved bounds for discretization of Langevin diffusions: Nearoptimal rates without convexity. arXiv preprint arXiv:1907.11331. (Cited on page 3.)
- Oksendal, B. (2013). Stochastic differential equations: an introduction with applications. Springer Science & Business Media. (Cited on page 24.)
- Raginsky, M., Rakhlin, A., and Telgarsky, M. (2017). Non-convex learning via stochastic gradient Langevin dynamics: a nonasymptotic analysis. In *Proceedings of the 2017 Conference on Learning Theory*, volume 65, pages 1674–1703. (Cited on pages 5 and 7.)
- Risken, H. (1996). Fokker-planck equation. In The Fokker-Planck Equation, pages 63–95. Springer. (Cited on page 1.)
- Shen, R. and Lee, Y. T. (2019). The randomized midpoint method for log-concave sampling. In Advances in Neural Information Processing Systems, pages 2098–2109. (Cited on pages 6 and 9.)
- Tsybakov, A. B. (2008). Introduction to nonparametric estimation. Springer Science & Business Media. (Cited on page 2.)
- Van Erven, T. and Harremos, P. (2014). Rényi divergence and Kullback-Leibler divergence. *IEEE Transactions on Information Theory*, 60(7):3797– 3820. (Cited on page 23.)
- Vempala, S. and Wibisono, A. (2019). Rapid convergence of the unadjusted Langevin algorithm: Isoperimetry suffices. In Advances in Neural Information Processing Systems, pages 8092–8104. (Cited on pages 2, 3, 4, 6, 12, 14, and 25.)
- Villani, C. (2021). Topics in optimal transportation, volume 58. American Mathematical Soc. (Cited on page 4.)
- Yu, L., Balasubramanian, K., Volgushev, S., and Erdogdu, M. A. (2020). An analysis of constant step size sgd in the non-convex regime: Asymptotic normality and bias. arXiv preprint arXiv:2006.07904. (Cited on page 5.)
- Zhang, Z., Rubinstein, B. I., and Dimitrakakis, C. (2016). On the differential privacy of bayesian inference. In *Thirtieth AAAI Conference on Artificial Intelligence*. (Cited on page 2.)

# A PROOFS OF THE MAIN RESULTS

**Proof of Lemma 1.** The proof follows from similar lines that lead to a differential inequality in KL divergence (see for example Vempala and Wibisono (2019)). Let  $\tilde{\rho}_{t|k}$  denote the distribution of  $\tilde{x}_t$  conditioned on  $x_k$  for  $k = \lfloor t/\eta \rfloor$ , which satisfies

$$\frac{\partial \widetilde{\rho}_{t|k}(x)}{\partial t} = \nabla \cdot \left( \nabla f(x_k) \widetilde{\rho}_{t|k}(x) \right) + \Delta \widetilde{\rho}_{t|k}(x).$$

Taking expectation with respect to  $x_k$  and using Bayes' rule, we get

$$\frac{\partial \widetilde{\rho}_t(x)}{\partial t} = \nabla \cdot \left( \widetilde{\rho}_t(x) \left( \mathbb{E} \left[ \nabla f(x_k) - \nabla f(x) | \widetilde{x}_t = x \right] + \nabla \log \left( \frac{\widetilde{\rho}_t(x)}{\nu_*(x)} \right) \right) \right).$$
(A.1)

Now we consider the time derivative of Chi-squared divergence of  $\tilde{\rho}_t$  from the target  $\nu_*$ 

$$\begin{split} \frac{d}{dt}\chi^{2}\big(\widetilde{\rho}_{t}|\nu_{*}\big) &= 2\int \frac{\widetilde{\rho}_{t}(x)}{\nu_{*}(x)} \times \nabla \cdot \left(\widetilde{\rho}_{t}(x) \left(\mathbb{E}\left[\nabla f(x_{k}) - \nabla f(x)|\widetilde{x}_{t}=x\right] + \nabla \log\left(\frac{\widetilde{\rho}_{t}(x)}{\nu_{*}(x)}\right)\right)\right) dx \\ &= -2\int \widetilde{\rho}_{t}(x) \Big\langle \nabla \frac{\widetilde{\rho}_{t}(x)}{\nu_{*}(x)}, \mathbb{E}\left[\nabla f(x_{k}) - \nabla f(x)|\widetilde{x}_{t}=x\right] + \nabla \log\left(\frac{\widetilde{\rho}_{t}(x)}{\nu_{*}(x)}\right) \Big\rangle dx \\ &= \frac{2}{3}\int \left\|\nabla \frac{\widetilde{\rho}_{t}(x)}{\nu_{*}(x)}\right\|^{2} \nu_{*}(x) dx + 2\int \mathbb{E}\left[\frac{\widetilde{\rho}_{t}(x)}{\nu_{*}(x)} \left\|\nabla f(x) - \nabla f(x_{k})\right\|^{2} |\widetilde{x}_{t}=x\right] \widetilde{\rho}_{t}(x) dx \\ &= \frac{3}{2\lambda}\chi^{2}\big(\widetilde{\rho}_{t}|\nu_{*}\big) + 2\mathbb{E}\left[\frac{\widetilde{\rho}_{t}(\widetilde{x}_{t})}{\nu_{*}(\widetilde{x}_{t})} \left\|\nabla f(\widetilde{x}_{t}) - \nabla f(x_{k})\right\|^{2}\right], \end{split}$$

where step 1 follows from the divergence theorem, step 2 from  $\langle a, b \rangle \leq \frac{1}{4} \|a\|^2 + \|b\|^2$  and in step 3, we used PI with  $\rho$  replaced by  $\tilde{\rho}_t$ . Finally, the result follows from the Cauchy-Schwartz inequality on the second term.  $\Box$ 

Proof of Lemma 2. We use Cauchy-Schwarz inequality to get

$$\mathbb{E}_{\widetilde{\rho}_T}\left[\frac{\widetilde{\rho}_T}{\nu_*}(x)^{2\alpha-2}\right] \le \mathbb{E}_{\nu_*}\left[\frac{\pi_T}{\nu_*}(x)^{4\alpha-3}\right]^{\frac{1}{2}} \mathbb{E}_{\pi_T}\left[\frac{\widetilde{\rho}_T}{\pi_T}(x)^{4\alpha-2}\right]^{\frac{1}{2}}.$$

We apply Lemma 25, and find that

$$\log \mathbb{E}_{\nu_*}\left[\frac{\pi_T}{\nu_*}(x)^{4\alpha-3}\right] \leq \exp\left(-\frac{2T}{(4\alpha-3)\lambda}\right)\log \mathbb{E}_{\nu_*}\left[\frac{\rho_0}{\nu_*}(x)^{4\alpha-3}\right],$$

as  $\pi_0 = \rho_0$ . Choosing  $T \geq N\eta = \frac{(4\alpha-3)\lambda}{2}\log\log(\mathbb{E}_{\nu_*}\left[\frac{\rho_0}{\nu_*}(x)^{4\alpha-3}\right])$  yields 1 on the RHS, implying  $\mathbb{E}_{\nu_*}\left[\frac{\pi_T}{\nu_*}(x)^{4\alpha-3}\right] \leq e$ . With our initialization, we next use Lemma 26 to get  $\mathbb{E}_{\nu_*}\left[\frac{\rho_0}{\nu_*}(x)^{4\alpha-3}\right] \leq e^{d(4\alpha-3)C_{\sigma}}$ , which is substituted into the final bound. We can apply a crude bound of  $\mathbb{E}_{\nu_*}\left[\frac{\rho_0}{\nu_*}(x)^{4\alpha-3}\right] \leq \exp(4\alpha dC_{\sigma})$ , where  $C_{\sigma}$  is as in the remark after Lemma 26.

For the second term, we apply Lemma 14 with  $16\alpha - 10$  and number of iterations 2N, under the condition that

$$c\alpha^2 \kappa^2 L^2 (b+d+\log 2N) N\eta^2 \le 1$$

Then we get  $\mathbb{E}_{\pi_T}\left[\frac{\tilde{\rho}_T}{\pi_T}(x)^{4\alpha-2}\right] \leq 20e\sqrt{\alpha}$ ; combining these two terms yields the final bound.  $\Box$ **Proof of Lemma 3.** Suppose  $x^*$  is the global minimizer of f (therefore  $\nabla f(x^*) = 0$ ). From Lemma 10 and  $\eta \leq m/L^2$  we have

$$||x - \eta \nabla f(x) - x^*||^2 \le (1 - m\eta) ||x - x^*||^2 + 2b\eta.$$

Using the previous inequality with the fact that Gaussian has zero odd moments and Lemma 22 we get

$$\mathbb{E}\left[\|x_k - x^*\|^2\right] \le \mathbb{E}\left[\|x_0 - x^*\|^2\right] + \frac{2(b+d)}{m}.$$

Doing the same for power 4 we get the following

$$\mathbb{E}\left[\|x_{k+1} - x^*\|^4\right] \le (1 - m\eta)\mathbb{E}\left[\|x_k - x^*\|^4\right] + 12\eta(b+d)\mathbb{E}\left[\|x_k - x^*\|^2\right] + 12\eta^2(b+d)^2.$$

Plugging the bound on  $\mathbb{E}\left[\|x_k - x^*\|^2\right]$  back in the previous inequality and using Lemma 22, we get the following

$$\mathbb{E}\left[\|x_k - x^*\|^4\right] \le \left[\frac{\mathbb{E}\left[\|x_0 - x^*\|^4\right]}{(b+d)^2} + \frac{12}{m}\left(\frac{\mathbb{E}\left[\|x_0 - x^*\|^2\right]}{b+d} + \frac{2}{m} + \eta\right)\right](b+d)^2.$$

For  $t \leq \eta$ , we write

$$\mathbb{E}\left[\left\|t\nabla f(x_k) + \sqrt{2}B_t\right\|^4\right] \le 8\eta^4 \mathbb{E}\left[\left\|\nabla f(x_k)\right\|^4\right] + 32\mathbb{E}\left[\left\|B_t\right\|\right]^4$$
$$\le 8\eta^4 L^4 \mathbb{E}\left[\left\|x_k - x^*\right\|^4\right] + 96\eta^2 d^2.$$

By combining the last two inequalities we get the following.

$$\mathbb{E}\left[\left\|t\nabla f(x_k) + \sqrt{2}B_t\right\|^4\right] \\ \leq \left(96 + 8\eta^2 L^4 \left[\frac{\mathbb{E}\left[\|x_0 - x^*\|^4\right]}{(b+d)^2} + \frac{12\mathbb{E}\left[\|x_0 - x^*\|^2\right]}{m(b+d)} + \frac{24}{m^2} + \frac{12\eta}{m}\right]\right)(b+d)^2\eta^2,$$

using the definition of  $\beta$  and moments of Gaussian and the bound on  $\eta$  we get

$$\mathbb{E}\left[\left\|t\nabla f(x_k) + \sqrt{2}B_t\right\|^4\right]^{1/2} \le c\beta(b+d)\eta,\tag{A.2}$$

for some universal constant c. Now if the conditions of Lemma 2 hold, then we have the expected ratio of the densities bounded by an absolute constant for  $N \leq k\eta + t \leq 2N$ . Combining this with the previous bound, we obtain

$$\mathbb{E}\left[\frac{\widetilde{\rho}_{k\eta+t}}{\nu_*}\left(\widetilde{x}_{k\eta+t}\right)^2\right]^{1/2}\mathbb{E}\left[\left\|\nabla f(\widetilde{x}_{k\eta+t})-\nabla f(x_k)\right\|^4\right]^{1/2} \le c\beta L^2(b+d)\eta$$

where c is an absolute constant.

We plug in the derived upper bounds back in (2.2) to get

$$\frac{d}{dt}\chi^2\big(\widetilde{\rho}_{k\eta+t}|\nu_*\big) \le -\frac{3}{2\lambda}\chi^2\big(\widetilde{\rho}_{k\eta+t}|\nu_*\big) + c\beta L^2(b+d)\eta$$

Integrating this differential inequality and using  $t \leq \eta$  results in the following single step bound

$$\chi^2(\rho_{k+1}|\nu_*) \le \left(1 - \frac{3\eta}{4\lambda}\right)\chi^2(\rho_k|\nu_*) + c\beta L^2(b+d)\eta^2,$$

where we used  $\eta \leq \frac{\lambda}{2}$  and that  $e^{-x} \leq 1 - x/2$  for  $x \in [0, 1]$ , and we absorbed universal constants into c. **Proof of Theorem 4.** In the first phase, by Lemma 2, we used the first N steps of LMC to show that the expected squared ratio of densities evaluated at the interpolation process is bounded by an absolute constant and it stays bounded for the subsequent N iterations. This allows us to iterate the single-step bound provided by Lemma 3, for which we need to bound its starting point, the LMC iteration N. We write

$$\chi^{2}(\rho_{N}|\nu_{*}) = \mathbb{E}_{\nu_{*}}\left[\frac{\rho_{N}}{\nu_{*}}(x)^{2}\right] - 1 \leq \mathbb{E}_{\pi_{N\eta}}\left[\frac{\rho_{N}}{\pi_{N\eta}}(x)^{4}\right]^{1/2} \mathbb{E}_{\nu_{*}}\left[\frac{\pi_{N\eta}}{\nu_{*}}(x)^{3}\right]^{1/2} - 1,$$

by Cauchy-Schwartz inequality. We bound the right hand side term by term with an absolute constant. For the first term we use Lemma 14 for  $\alpha = 14$ . In order for it to be bounded by 22*e*, it is sufficient if the following holds that  $c_1 \kappa^2 L^2 N(b+d+\log N)\eta^2 \leq 1$ , where  $c_1$  is some universal constant. The second term can be written as

$$\mathbb{E}_{\nu_*}\left[\frac{\pi_{N\eta}}{\nu_*}\left(x\right)^3\right] = \mathbb{E}_{\nu_*}\left[\frac{\pi_{N\eta}}{\nu_*}\left(x\right)^{4\alpha-3}\right] \text{ for } \alpha = 3/2,$$

for which we already obtained an upper bound in the proof of Lemma 2. That is, whenever  $N\eta \geq \frac{3\lambda}{2}\log(6dC_{\sigma})$ , the right hand side is bounded by e. Thus, we have  $\chi^2(\rho_N|\nu_*) \leq 12$ .

In the second phase of the analysis, we use the differential inequality. Iterating the single step bound in Lemma 3 with the help of Lemma 22, together with the upper bound on the initialization of the second phase, we get

$$\chi^2(\rho_{2N}|\nu_*) \le \exp\left(-\frac{3\eta N}{4\lambda}\right) 12 + c\lambda L^2\beta(b+d)\eta,$$

where we used the bound on Chi-square divergence in step N and absorbed absolute constants into c. To make this less than  $\epsilon$ , it suffices if the following additional inequalities hold

$$N\eta \ge \frac{4}{3}\lambda \log \frac{24}{\epsilon}, \qquad \eta \le \frac{1}{2c\beta\lambda L^2} \times \frac{\epsilon}{b+d}$$

for some absolute constant c. Combining the above conditions with the conditions of used Lemmas, and simplifying the statements, we obtain the inequalities in (3.1).

For the last statement, it suffices to check the inequalities in (3.1) for the given choice of step size and the number of iterations.

#### A.1 Proofs for the Rényi Divergence

**Proof of Lemma 6.** Define the following quantities for  $\alpha \geq 1$  between two densities p, q

$$F_{\alpha}(p|q) = \mathbb{E}_{q}\left[\frac{p}{q}(x)^{\alpha}\right], \qquad G_{\alpha}(p|q) = \mathbb{E}_{q}\left[\frac{p}{q}(x)^{\alpha-2} \left\|\nabla\frac{p}{q}(x)\right\|^{2}\right].$$

Then we have  $(\alpha - 1)R_{\alpha}(p|q) = \log F_{\alpha}(p|q)$ . Note that  $F_{\alpha}(p|q) \ge 1$  for any p, q. We have the following result for the Langevin diffusion.

**Lemma 9.** (Adapted from (Vempala and Wibisono, 2019, Lemma 5)) If q satisfies LSI with constant  $\lambda$ , then

$$\frac{G_{\alpha}\left(p|q\right)}{F_{\alpha}\left(p|q\right)} \geq \frac{2}{\alpha^{2}\lambda}R_{\alpha}\left(p|q\right).$$

The above lemma was used in Vempala and Wibisono (2019) to prove the exponential convergence of the Langevin diffusion. We use it in a similar way, but for the interpolation process.

Consider the dynamics in (A.1) and write to express the time-derivative of  $F_{\alpha}$  as

$$\begin{split} \frac{d}{dt}F_{\alpha}\left(\widetilde{\rho}_{t}|\nu_{*}\right) &= \alpha \int \frac{\widetilde{\rho}_{t}}{\nu_{*}}(x)^{\alpha-1}\frac{\partial\widetilde{\rho}_{t}(x)}{\partial t}dx\\ &= \alpha \int \frac{\widetilde{\rho}_{t}}{\nu_{*}}(x)^{\alpha-1}\nabla \cdot \left(\widetilde{\rho}_{t}(x)\left(\mathbb{E}\left[\nabla f(x_{k}) - \nabla f(x)|\widetilde{x}_{t}=x\right] + \nabla\log\frac{\widetilde{\rho}_{t}}{\nu_{*}}(x)\right)\right)dx\\ &= \alpha(\alpha-1)\int \frac{\widetilde{\rho}_{t}}{\nu_{*}}(x)^{\alpha-2}\left\langle\nabla\frac{\widetilde{\rho}_{t}}{\nu_{*}}(x), \mathbb{E}\left[\nabla f(x) - \nabla f(x_{k})|\widetilde{x}_{t}=x\right] - \nabla\log\frac{\widetilde{\rho}_{t}}{\nu_{*}}(x)\right\rangle\widetilde{\rho}_{t}(x)dx, \end{split}$$

where in 1 we use the divergence theorem. For the first term, we write

$$\begin{split} &\int \frac{\widetilde{\rho}_t}{\nu_*} (x)^{\alpha-2} \left\langle \nabla \frac{\widetilde{\rho}_t}{\nu_*} (x) \sqrt{\frac{\nu_*(x)}{\widetilde{\rho}_t(x)}}, \sqrt{\frac{\widetilde{\rho}_t(x)}{\nu_*(x)}} \mathbb{E} \left[ \nabla f(x) - \nabla f(x_k) | \widetilde{x}_t = x \right] \right\rangle \widetilde{\rho}_t(x) dx \\ & \leq \frac{1}{4} \int \frac{\widetilde{\rho}_t}{\nu_*} (x)^{\alpha-2} \left\| \nabla \frac{\widetilde{\rho}_t}{\nu_*} (x) \right\|^2 \nu_*(x) dx \\ & \quad + \int \mathbb{E} \left[ \frac{\widetilde{\rho}_t}{\nu_*} (x)^{\alpha-1} \left\| \nabla f(x) - \nabla f(x_k) \right\|^2 | \widetilde{x}_t = x \right] \widetilde{\rho}_t(x) dx \\ & = \frac{1}{4} G_\alpha \left( \widetilde{\rho}_t | \nu_* \right) + \mathbb{E} \left[ \frac{\widetilde{\rho}_t}{\nu_*} (\widetilde{x}_t)^{\alpha-1} \left\| \nabla f(\widetilde{x}_t) - \nabla f(x_k) \right\|^2 \right], \end{split}$$

where in 1 we used that  $\langle a, b \rangle \leq \frac{1}{4} \|a\|^2 + \|b\|^2$ . For the second term, we find

$$\int \frac{\widetilde{\rho}_t}{\nu_*} (x)^{\alpha - 2} \left\langle \nabla \frac{\widetilde{\rho}_t}{\nu_*} (x), -\nabla \log \frac{\widetilde{\rho}_t}{\nu_*} (x) \right\rangle \widetilde{\rho}_t (x) dx = -G_\alpha \left( \widetilde{\rho}_t | \nu_* \right)$$

Combining terms, we get

$$\frac{d}{dt}R_{\alpha}\left(\widetilde{\rho}_{t}|\nu_{*}\right) = \frac{1}{(\alpha-1)F_{\alpha}\left(\widetilde{\rho}_{t}|\nu_{*}\right)} \frac{dF_{\alpha}\left(\widetilde{\rho}_{t}|\nu_{*}\right)}{dt} 
\leq -\frac{3\alpha}{4}\frac{G_{\alpha}\left(\widetilde{\rho}_{t}|\nu_{*}\right)}{F_{\alpha}\left(\widetilde{\rho}_{t}|\nu_{*}\right)} + \alpha \frac{\mathbb{E}\left[\frac{\widetilde{\rho}_{t}}{\nu_{*}}(\widetilde{x}_{t})^{\alpha-1}\left\|\nabla f(\widetilde{x}_{t}) - \nabla f(x_{k})\right\|^{2}\right]}{F_{\alpha}\left(\widetilde{\rho}_{t}|\nu_{*}\right)} 
\stackrel{1}{\leq} -\frac{3\alpha}{4}\frac{G_{\alpha}\left(\widetilde{\rho}_{t}|\nu_{*}\right)}{F_{\alpha}\left(\widetilde{\rho}_{t}|\nu_{*}\right)} + \alpha \mathbb{E}\left[\frac{\widetilde{\rho}_{t}}{\nu_{*}}(\widetilde{x}_{t})^{2\alpha-2}\right]^{\frac{1}{2}}\mathbb{E}\left[\left\|\nabla f(\widetilde{x}_{t}) - \nabla f(x_{k})\right\|^{4}\right]^{\frac{1}{2}},$$

where in 1 we use a Cauchy-Schwarz inequality and that  $F_{\alpha}(\tilde{\rho}_t|\nu_*) \geq 1$ . It remains to apply Lemma 9 on the first term.

**Proof of Lemma 7.** The bound on the second term in (7) is obtained directly from (A.2), as

$$\mathbb{E}\left[\left\|\nabla f(\widetilde{x}_{k\eta+t}) - \nabla f(x_k)\right\|^4\right]^{\frac{1}{2}} \le c\beta L^2(b+d)\eta.$$

So combining this with Lemma 2, for any  $k \in [N, 2N]$ , we get

$$\mathbb{E}\left[\frac{\widetilde{\rho}_{k\eta+t}}{\nu_*}(\widetilde{x}_{k\eta+t})^{2\alpha-2}\right]^{\frac{1}{2}}\mathbb{E}\left[\left\|\nabla f(\widetilde{x}_{k\eta+t})-\nabla f(x_k)\right\|^4\right]^{\frac{1}{2}} \le c\beta L^2(b+d)\alpha^{1/8}\eta.$$

Substitution into Lemma 6 yields

$$\frac{d}{dt}R_{\alpha}\left(\widetilde{\rho}_{t}|\nu_{*}\right) \leq -\frac{3}{2\alpha\lambda}R_{\alpha}\left(\widetilde{\rho}_{t}|\nu_{*}\right) + c\beta L^{2}(b+d)\alpha^{9/8}\eta.$$

It remains to integrate this for  $t \leq \eta$ , and apply  $e^{-x} \leq (1 - \frac{x}{2})$  for  $x \in [0, 1]$ , and  $\eta \leq \frac{2\alpha\lambda}{3}$ .

**Proof of Theorem 8.** In the first phase, in accordance with the proof of Theorem 4, we will need to ensure that the density ratio at step N remains bounded. So we again write

$$\mathbb{E}_{\nu_*}\left[\frac{\widetilde{\rho}_{N\eta}}{\nu_*}(x)^{\alpha}\right] \leq \mathbb{E}_{\pi_{N\eta}}\left[\frac{\widetilde{\rho}_{N\eta}}{\pi_{N\eta}}(x)^{2\alpha}\right]^{\frac{1}{2}} \mathbb{E}_{\nu_*}\left[\frac{\pi_{N\eta}}{\nu_*}(x)^{2\alpha-1}\right]^{\frac{1}{2}}.$$

For the first term, we can use Lemma 14 with  $8\alpha - 2$ , so that again we have the condition

$$c\alpha^2 \kappa^2 L^2 (b+d+\log N) N\eta^2 \le 1$$

to guarantee that the first term is bounded by  $7\alpha^{0.25}$ . The second term is bounded via a Hölder inequality

$$\mathbb{E}_{\nu_*}\left[\frac{\pi_{N\eta}}{\nu_*}(x)^{2\alpha-1}\right] \leq \mathbb{E}_{\nu_*}\left[\frac{\pi_{N\eta}}{\nu_*}(x)^{4\alpha-3}\right]^{\frac{2\alpha}{4\alpha-3}},$$

which is simply bounded by  $\exp(\frac{2\alpha-1}{4\alpha-3})$  under the conditions of Lemma 2. Consequently the Rényi divergence at k = N is bounded by

$$R_{\alpha}\left(\rho_{N}|\nu_{*}\right) \leq rac{\log(12\alpha)}{\alpha-1}$$

In the second phase, we simply iterate the differential inequality in Lemma 7 and apply Lemma 21 to get

$$R_{\alpha}\left(\rho_{2N}|\nu_{*}\right) \leq \exp\left(-\frac{3N\eta}{4\alpha\lambda}\right)\frac{\log(12\alpha)}{\alpha-1} + c\beta\lambda L^{2}(b+d)\alpha^{17/8}\eta.$$

Thus we obtain  $\epsilon$  accuracy if the following inequalities hold

$$N\eta \ge \frac{4}{3}\alpha\lambda\log\frac{2\log(12\alpha)}{(\alpha-1)\epsilon}, \qquad \eta \le \frac{1}{2c\beta\lambda L^2\alpha^{17/8}} \times \frac{\epsilon}{b+d}$$

for some absolute constant c. Combining these conditions with the conditions of other lemmas used above and simplifying the expressions using  $\alpha, C_{\sigma} > 1 \ge \epsilon$ , we conclude the proof of the first part for the given choice of  $\eta$  and N, and choosing a sufficiently small  $\epsilon$ .

The second part of the theorem follows from verifying the conditions in the first part, and choosing a suitably small accuracy  $\epsilon$ .

## **B** MAIN TECHNICAL LEMMAS

Let  $X_t$  show the clipped interpolation process, with step size  $\eta$ , which is defined similar to interpolation process with the following exception: if for any  $s \leq t$  we have  $||X_s - X_{\lfloor s/\eta \rfloor \eta}|| > r$  we change  $X_t$  to  $\bot$ . We define  $X_t^j$  similarly, with step size  $\eta/j$  for  $j \in \mathbb{N}$  and define  $X_t'$  similarly for the continuous time process. We use the same r and  $\eta$  for all processes, in other words we change  $X_t^j$  and  $X_t'$  to  $\bot$  when for some  $s \leq t$  we have  $||X_s^j - X_{\lfloor s/\eta \rfloor \eta}^j|| > r$  and  $||X_s' - X_{\lfloor s/\eta \rfloor \eta}'|| > r$ , respectively. We refer to these processes as clipped processes that are started from the same distribution. Let  $P_t(x), P_t^j(x)$  and  $Q_t(x)$  show the density of  $X_t, X_t^j$  and  $X_t'$  at x.

We prove a bound on the probability of jump on both continuous time and discrete time process that will be used to remove the bounded movement assumption. This part is an extension of Lemma 13 in Ganesh and Talwar (2020). First we prove both continuous-time and discrete-time processes satisfy a semi-contraction inequality.

**Lemma 10.** If f satisfies Assumption 1 and  $z_t$  and  $z'_t$  are two instances of Langevin diffusion with synchronously coupled Brownian motion, then we have the following

$$||z_t - z'_t|| \le e^{-mt} ||z_0 - z'_0|| + \sqrt{\frac{b}{m}} (1 - e^{-2mt}).$$

Furthermore, if  $\eta \leq m/L^2$ , then gradient descent satisfies the following

$$||(x - \eta \nabla f(x)) - (y - \eta \nabla f(y))||^2 \le (1 - m\eta) ||x - y||^2 + 2\eta b.$$

**Proof.** For discrete-time, the results follow from elementary calculations. For continuous-time, by coupling the Brownian motions and subtracting we get the following,

$$\frac{d}{dt}(z_t - z'_t) = -\left(\nabla f(z_t) - \nabla f(z'_t)\right),$$

then we differentiate  $\left\| z_t - z_t' \right\|^2$  with respect to time to get

$$\frac{d}{dt} \|z_t - z'_t\|^2 = -2\langle z_t - z'_t, \nabla f(z_t) - \nabla f(z'_t) \rangle \le -2m \|z_t - z'_t\|^2 + 2b,$$

where the last step follows from strong dissipativity. Solving this differential inequality and using the inequality  $\sqrt{x+y} \leq \sqrt{x} + \sqrt{y}$  concludes the proof.

The second statement follows from

$$\begin{aligned} \|x - \eta \nabla f(x) - (y - \eta \nabla f(x))\|^2 &= \|x - y\|^2 - 2\eta \langle x - y, \nabla f(x) - \nabla f(y) \rangle + \eta^2 \|\nabla f(x) - \nabla f(y)\|^2 \\ &\leq (1 - 2\eta m + \eta^2 L^2) \|x - y\|^2 + 2\eta b \\ &\leq (1 - m\eta) \|x - y\|^2 + 2\eta b, \end{aligned}$$

where we used Assumption 1 for the first inequality, and that  $\eta \leq m/L^2$  for the second inequality.

**Lemma 11.** Suppose the potential satisfies Assumption 1 and  $x_0 = z_0 \sim \mathcal{N}(0, \sigma^2 \mathbf{I})$ , for  $\sigma^2 < (L+1)^{-1}$ . If the step size is small enough,  $\eta \leq \frac{1 \wedge m}{4(1 \vee L^2)} \wedge \frac{2}{\|\nabla f(0)\|^2}$ , then each of the following jump conditions, denoted with  $\mathcal{E}^1_{\delta}$  and  $\mathcal{E}^2_{\delta}$ , happens with probability at least  $1 - \delta$ .

$$\begin{aligned} \forall t \le N\eta : \left\| \widetilde{x}_t - \widetilde{x}_{\lfloor t/\eta \rfloor \eta} \right\| \le (2\kappa + 1) \left( 1 + \sqrt{b} + \sqrt{d} + 2\sqrt{\log\left(2(N+1)/\delta\right)} \right) \sqrt{2\eta} \\ \forall t \le N\eta : \left\| z_t - z_{\lfloor t/\eta \rfloor \eta} \right\| \le (5\kappa + 1) \left( 1 + \sqrt{b} + \sqrt{d} + 2\sqrt{\log\left(2(N+1)/\delta\right)} \right) \sqrt{2\eta} \end{aligned}$$

**Remark.** The RHS of both of the bounds can be written as  $c\kappa \left(\sqrt{b} + \sqrt{d} + \sqrt{\log N/\delta}\right)\sqrt{\eta}$ , for a universal constant c (note that  $\kappa > 1$ ).

**Proof.** In order to ease the notation we will use  $B_u^t$  to denote  $B_{t+u} - B_t$ . From Lemma 20 we know that

$$\sqrt{2} \sup_{s \le \eta} \left\| B_s^{k\eta} \right\| \le \sqrt{2\eta} \left( \sqrt{d} + 2\sqrt{\log \frac{2(N+1)}{\delta}} \right),$$

with probability at least  $1 - \frac{\delta}{N+1}$ , for all  $k \leq N$ . We also note that the initial distribution  $x_0 \sim \rho_0$  satisfies the following (see Lemma 19)

$$\mathbb{P}\left[\|x_0\| \le \frac{2\sqrt{2}}{m\sqrt{\eta}} \left(1 + \sqrt{b} + \sqrt{d} + 2\sqrt{\log\frac{2(N+1)}{\delta}}\right)\right] \ge 1 - \frac{\delta}{N+1}.$$

First, we prove the discrete-time case. By plugging y = 0 into Lemma 10 and taking the square root, we get the following

$$||x - \eta \nabla f(x)|| \le (1 - \frac{m\eta}{2}) ||x|| + \sqrt{2b\eta} + \eta ||\nabla f(0)||,$$

thus, we can write

$$\begin{aligned} \|x_{k+1}\| &\leq \|x_k - \eta \nabla f(x_k)\| + \sqrt{2} \left\| B_{\eta}^{k\eta} \right\| \\ &\leq (1 - \frac{m\eta}{2}) \left\| x_k \right\| + \sqrt{2\eta} (1 + \sqrt{b}) + \sqrt{2} \sup_{s \leq \eta} \left\| B_s^{k\eta} \right\|, \end{aligned}$$

where we used  $\eta^2 \|\nabla f(0)\|^2 \leq 2\eta$ . This, combined with the high probability bound on  $x_0$  and supremum of Brownian motion with the aid of union bound implies the following happens for  $k \leq N$ , with probability at least  $1 - \delta$ .

$$\|x_k\| \le \frac{2\sqrt{2}}{m\sqrt{\eta}} \left( 1 + \sqrt{b} + \sqrt{d} + 2\sqrt{\log\frac{2(N+1)}{\delta}} \right)$$

Let  $k = \lfloor t/\eta \rfloor$ , we write

$$\begin{split} \left\| \widetilde{x}_{t} - \widetilde{x}_{\eta \lfloor t/\eta \rfloor} \right\| &\leq \eta \left\| \nabla f(x_{k}) \right\| + \sqrt{2} \sup_{t \leq \eta} \left\| B_{t}^{k\eta} \right\| \\ &\leq \eta L \left\| x_{k} \right\| + \eta \left\| \nabla f(0) \right\| + \sqrt{2} \sup_{t \leq \eta} \left\| B_{t}^{k\eta} \right\| \\ &\leq \eta L \left\| x_{k} \right\| + \sqrt{2\eta} + \sqrt{2} \sup_{t \leq \eta} \left\| B_{t}^{k\eta} \right\|, \end{split}$$

combining this with the high probability bound on the Brownian motion and  $||x_k||$  (note that there is no need for union bound as this event is subset of the high probability event on the norm of the Brownian motion) concludes the proof for the discrete case.

We use a similar structure for proving the continuous-time case. Let  $z'_u$  denote the continuous time Langevin dynamics started at  $z'_0 = 0$ . We write

$$\|z'_u\| \le \int_0^u \|\nabla f(z'_s)\| \, ds + \sqrt{2} \, \|B_u\| \le L \int_0^u \|z'_s\| \, ds + \eta \, \|\nabla f(0)\| + \sup_{s \le \eta} \sqrt{2} \, \|B_s\| \, ,$$

for  $u \leq \eta$ . Using Grönwall inequality (Lemma 21), we get the following (for  $u \leq \eta$ )

$$\|z'_u\| \le e^{Lu} \left( \eta \|\nabla f(0)\| + \sup_{s \le \eta} \sqrt{2} \|B_s\| \right) \le 2 \left( \eta \|\nabla f(0)\| + \sup_{s \le \eta} \sqrt{2} \|B_s\| \right).$$

where the last inequality is because  $u \leq \eta \leq \log 2/L$ . Plug  $z'_0 = 0$  in Lemma 10 and shift  $z_0$  to  $z_t$ , using the semi-group property, to get the following

$$||z_{t+u}|| \le e^{-mu} ||z_t|| + ||z'_u|| + \sqrt{\frac{b}{m} (1 - e^{-2mu})}$$

$$\le (1 - mu/2) ||z_t|| + 2 \left(\sqrt{2\eta} + \sup_{s \le \eta} \sqrt{2} ||B_s^t||\right) + \sqrt{2b\eta},$$
(B.1)

where the last inequality follows from  $4mu \le 4m\eta \le 1$ , and  $\eta^2 \|\nabla f(0)\|^2 \le 2\eta$ . We plug  $u = \eta$  in the previous inequality and use the high probability bound on the Brownian motion and  $z_0 = x_0$  with union bound to get  $\|z_{k\eta}\| \le \frac{4\sqrt{2}}{m\sqrt{\eta}}(1+\sqrt{b}+\sqrt{d}+2\sqrt{\log\frac{2(N+1)}{\delta}})$  with probability at least  $1-\delta$  for all  $k \le N$ .

Next, we modify (B.1) as follows

$$||z_{t+u}|| \le ||z_t|| + 2\left(\sqrt{2\eta} + \sup_{s \le \eta} \sqrt{2} ||B_s||\right) + \sqrt{2b\eta}.$$

Using this inequality with previous high probability bound on  $||z_{k\eta}||$  shows that the following happens with probability at least  $1 - \delta$  for all  $t \leq N\eta$ .

$$||z_t|| \le \frac{5\sqrt{2}}{m\sqrt{\eta}} \left( 1 + \sqrt{b} + \sqrt{d} + 2\sqrt{\log\frac{2(N+1)}{\delta}} \right)$$

where we used  $\eta \leq 1/4m$ . Finally we use the following inequality to connect this tail bound to probability of jump

$$\begin{aligned} \left\| z_t - z_{\lfloor t/\eta \rfloor \eta} \right\| &= \left\| \int_{\lfloor t/\eta \rfloor \eta}^t -\nabla f(z_s) ds + \sqrt{2} dB_s \right\| \\ &\leq \eta L \sup_{s \leq N\eta} \|z_s\| + \eta \|\nabla f(0)\| + \sqrt{2} \sup_{s \leq \eta} \left\| B_s^{\lfloor t/\eta \rfloor \eta} \right\| \end{aligned}$$

Combining previous inequality with high probability bounds on  $||z_t||$  and the Brownian motion and using  $\eta^2 ||\nabla f(0)||^2 \leq 2\eta$  concludes the proof for the continuous-time case (where again, there is no need for union bound as this event is subset of the high probability event on the norm of the Brownian motion).

Finally, we collect all the upper bounds on  $\eta$  in a more compact form

$$\eta \leq \frac{1 \wedge m}{4(1 \vee L^2)} \wedge \frac{2}{\left\|\nabla f(0)\right\|^2} \leq \frac{2}{\left\|\nabla f(0)\right\|^2} \wedge \frac{4}{m\sigma^2} \wedge \frac{m}{L^2} \wedge \frac{1}{4m} \wedge \frac{\log 2}{L}.$$

Now we prove the continuous-time and discrete-time clipped processes stay sufficiently close to each other. In order to prove that we first state a lemma that describes the behavior of discrete chain as step size approaches zero. We will show that the Rényi divergence of the discrete-time process and the continuous-time process converges to zero as the step size approaches zero. The proof relies on the Girsanov theorem and Lemma 11.

**Lemma 12.** Let  $\Gamma_T^{\eta}$ ,  $\Pi_T$  be the distribution of the paths on [0,T] of the interpolated time process with step-size  $\eta$ , and continuous time process respectively. Starting from  $x_0 = z_0 = \mathcal{N}(0, \sigma^2 I)$  for  $\sigma^2 \leq (L+1)^{-1}$ , and under Assumption 1, for any T > 0,  $\alpha \geq 1$ 

$$\lim_{\eta \to 0} R_{\alpha} \left( \Gamma_T^{\eta} | \Pi_T \right) = 0.$$

**Proof.** Denote our underlying probability space by  $(\Omega, \mathcal{F}, P)$ ; let  $\mathcal{Z} = \{f | f : [0, T] \to \mathbb{R}^d\}$  be the space of possible paths. We use the notations  $\tilde{x}_{\cdot}(\omega)$  and  $z_{\cdot}(\omega)$  to denote one realization of discrete and continuous time process. Using Girsanov's Theorem (see Lemma 24), we define the measure Q

$$\frac{dQ}{dP}(\omega) = N(\widetilde{x}_{.})$$

$$\triangleq \exp\left(-\frac{1}{\sqrt{2}}\int_{0}^{T} \left(\nabla f(\widetilde{x}_{s}) - \nabla f(\widetilde{x}_{\lfloor s/\eta \rfloor \eta})\right)^{\top} dB_{s} - \frac{1}{4}\int_{0}^{T} \left\|\nabla f(\widetilde{x}_{s}) - \nabla f(\widetilde{x}_{\lfloor s/\eta \rfloor \eta})\right\|^{2} ds\right),$$

such that the *P*-law of z. equals the *Q*-law of  $\tilde{x}$ . Note that Novikov condition can be checked by using Lemmas 11 and 18 and smoothness of potential. Thus, we can write the following

$$\begin{split} \Pi_T(A) &= P\left(\{\omega|z.(\omega)\in A\}\right) \\ &= Q\left(\{\omega|\widetilde{x}.(\omega)\in A\}\right) \\ &= \int \mathbf{1}_{\{\widetilde{x}.(\omega)\in A\}} N(\widetilde{x}.(\omega)) dP(\omega) \\ &= \int_{\widetilde{x}.\in A} N(\widetilde{x}.) d\Gamma^{\eta}_T(\widetilde{x}.), \end{split}$$

for any measurable  $A \in \mathcal{Z}$ . This implies the following about the Radon–Nikodym derivative

$$\frac{d\Pi_T}{d\Gamma_T^{\eta}}(\widetilde{x}_{\cdot}) = N(\widetilde{x}_{\cdot}).$$

Raising to power  $-(\alpha - 1)$  and using the definition of N and taking expectation we get

$$\mathbb{E}_{\Pi_T} \left[ \left( \frac{d\Gamma_T^{\eta}}{d\Pi_T} \right)^{\alpha} \right] = \mathbb{E}_{\Gamma_T^{\eta}} \left[ \left( \frac{d\Gamma_T^{\eta}}{d\Pi_T} \right)^{\alpha - 1} \right]$$
$$= \mathbb{E} \left[ \exp \left( \frac{\alpha - 1}{\sqrt{2}} \int_0^T \left( \nabla f(\widetilde{x}_s) - \nabla f(\widetilde{x}_{\lfloor s/\eta \rfloor \eta}) \right)^\top dB_s + \frac{\alpha - 1}{4} \int_0^T \left\| \nabla f(\widetilde{x}_s) - \nabla f(\widetilde{x}_{\lfloor s/\eta \rfloor \eta}) \right\|^2 ds \right) \right].$$

If we define  $M_s = \sqrt{2}(\alpha - 1) \left( \nabla f(\widetilde{x}_s) - \nabla f(\widetilde{x}_{\lfloor s/\eta \rfloor \eta}) \right)$ , this expectation is equal to the following

$$\mathbb{E}\left[\exp\left(\frac{1}{2}\int_{0}^{T}M_{s}^{\top}dB_{s}-\frac{1}{4}\int_{0}^{T}\|M_{s}\|^{2}ds+\int_{0}^{T}\left(\frac{1}{4}+\frac{1}{8(\alpha-1)}\right)\|M_{s}\|^{2}ds\right)\right].$$

Subsequently, the following holds by Cauchy-Schwartz

$$\mathbb{E}_{\Pi_{T}}\left[\left(\frac{\Gamma_{T}^{\eta}}{\Pi_{T}}\right)^{\alpha}\right] \leq \mathbb{E}\left[\exp\left(\int_{0}^{T}M_{s}^{\top}dB_{s}-\frac{1}{2}\int_{0}^{T}\|M_{s}\|^{2}ds\right)\right]^{1/2} \\ \times \mathbb{E}\left[\exp\left\{\left((\alpha-1)^{2}+\frac{\alpha-1}{2}\right)\int_{0}^{T}\|\nabla f(\widetilde{x}_{s})-\nabla f(\widetilde{x}_{\lfloor s/\eta \rfloor \eta})\|^{2}ds\right\}\right]^{1/2} \\ \leq \mathbb{E}\left[\exp\left(\alpha^{2}\int_{0}^{T}\|\nabla f(\widetilde{x}_{s})-\nabla f(\widetilde{x}_{\lfloor s/\eta \rfloor \eta})\|^{2}ds\right)\right]^{1/2},$$

where the last inequality step follows from Lemma 23 and again Novikov's condition holds as argued before. We use Assumption 1, and the first event in Lemma 11 to get

$$\int_{0}^{T} \left\| \nabla f(\widetilde{x}_{s}) - \nabla f(\widetilde{x}_{\lfloor s/\eta \rfloor \eta}) \right\|^{2} ds \leq L^{2} \int_{0}^{T} \left\| \widetilde{x}_{s} - \widetilde{x}_{\lfloor s/\eta \rfloor \eta} \right\|^{2} ds$$
$$\leq KTL^{2} \kappa^{2} \left( b + d + \log \frac{T}{\eta \delta} \right) \eta,$$

with probability at least  $1 - \delta$ , if  $\eta$ , is sufficiently small for some universal constant K. Letting the event in which this bound holds be called  $\mathcal{E}_{\delta}$ , by calculating the conditional expectation we get

$$\mathbb{E}\left[\exp\left(c\alpha^{2}\int_{0}^{T}\left\|\nabla f(\widetilde{x}_{s})-\nabla f(\widetilde{x}_{\lfloor s/\eta \rfloor \eta})\right\|^{2}ds\right)|\mathcal{E}_{\delta}\right]$$
  
$$\leq \exp\left(Kc\alpha^{2}TL^{2}\kappa^{2}\left(b+d+\log\frac{T}{\eta\delta}\right)\eta\right)$$
  
$$\leq \delta^{-\gamma_{c}(\eta)}\exp\left(Kc\alpha^{2}TL^{2}\kappa^{2}\left(b+d+\log T-\log \eta\right)\eta\right),$$

where  $\gamma_c(\eta) = Kc\alpha^2 T L^2 \kappa^2 \eta$ , and we absorbed constants into K. For any fixed c, we know  $\lim_{\eta\to 0} \gamma_c(\eta) = 0$ , therefore for small enough  $\eta$ , we have  $\gamma_c(\eta) < 1$ , thus we can apply Lemma 18 with  $\theta = c$  and  $\gamma = \gamma_c(\eta)$  to get

$$\mathbb{E}\left[\exp\left(\alpha^{2} \int_{0}^{T} \left\|\nabla f(\widetilde{x}_{s}) - \nabla f(\widetilde{x}_{\lfloor s/\eta \rfloor \eta})\right\|^{2} ds\right)\right] \leq \frac{2^{\frac{2}{c}} c}{c-1} \exp\left(K\alpha^{2} T L^{2} \kappa^{2} \left(b + d + \log T - \log \eta\right) \eta\right) ds$$

We substitute this into our earlier bound,

$$\mathbb{E}_{\Pi_T}\left[\left(\frac{\Gamma_T^{\eta}}{\Pi_T}\right)^{\alpha}\right] \leq \frac{2^{\frac{2}{c}}c}{c-1} \exp\left(K\alpha^2 T L^2 \kappa^2 \left(b+d+\log T-\log \eta\right)\eta\right).$$

We take the limit as  $\eta \to 0$  to get

$$\lim_{\eta \to 0} \mathbb{E}_{\Pi_T} \left[ \left( \frac{\Gamma_T^{\eta}}{\Pi_T} \right)^{\alpha} \right] \le \frac{2^{\frac{2}{c}} c}{c-1}$$

Finally, we take another limit as  $c \to \infty$  to get

$$\lim_{\eta \to 0} \mathbb{E}_{\Pi_T} \left[ \left( \frac{\Gamma_T^{\eta}}{\Pi_T} \right)^{\alpha} \right] \le 1.$$

Substituting this into the definition of the Rényi divergence and using continuity of log at 1 concludes the proof.  $\hfill \Box$ 

Now using the previous lemma, we extend (Ganesh and Talwar, 2020, Corollary 11) to the interpolation process under strong dissipativity.

**Lemma 13.** If  $P_0 = Q_0 = \mathcal{N}(0, \sigma^2 I)$  for  $\sigma^2 < (L+1)^{-1}$ , then the following holds for  $\alpha \ge 2$ , when Assumption 1 is satisfied.

$$\mathbb{E}_{Q_T}\left[\frac{P_T}{Q_T}\left(x\right)^{\alpha}\right] \le \exp\left(T\alpha(\alpha-1)L^2r^2\right) \tag{B.2}$$

**Proof.** We use the same argument as in (Ganesh and Talwar, 2020, Lemma 10). By sampling both  $X_t$  and  $X'_t$  at multiples of  $\eta/j$  and at the final moment(T), we get the following tuples.

$$X_{0-T} = \{X_{i\eta/j}\}_{0 \le i < jT/\eta} + \{X_T\}, \qquad \qquad X_{0-T}^j = \{X_{i\eta/j}^j\}_{0 \le i < jT/\eta} + \{X_T^j\},$$

where by + we mean appending the element to the end of the tuple. In order to use Lemma 17, we consider functions  $\phi_1$  and  $\phi_2$  that append one new sample to the tuples of sampled clipped processes. For example  $\phi_1$  gets  $\{X_{i\eta/j}\}_{0\leq i< k}$  and applies Langevin update rule along with the clipping criteria for step size  $\eta/j$  using the gradient at the last multiple of  $\eta$  to produce  $\{X_{i\eta/j}\}_{0\leq i\leq k}$ .  $\phi_2$  is defined similarly but uses gradient at last multiple of  $\eta/j$ . Note that we get  $X_{0-T}$  and  $X_{0-T}^j$  by multiple applications of  $\phi_1$  and  $\phi_2$ , except for the final iterate. Assume  $\tilde{X}$  is a deterministic tuple (i.e. point mass) we bound  $R_\alpha\left(\phi_1(\tilde{X})|\phi_2(\tilde{X})\right)$ . If  $\tilde{X}$  contains  $\perp$  then this is zero, therefore we assume  $\tilde{X}$  does not contain jumps larger than r and by data processing inequality (Lemma 16) we can ignore clipping done by  $\phi_1$  and  $\phi_2$ . Since  $\tilde{X}$  was a point mass, both  $\phi_1(\tilde{X})$  and  $\phi_2(\tilde{X})$  are Gaussians with possibly different means, which cannot differ more than  $Lr\eta/j$ , because of smoothness of potential and assumption that jumps are smaller than r. Thus, Lemma 15 implies  $R_\alpha\left(\phi_1(\tilde{X})|\phi_2(\tilde{X})\right) \leq \alpha L^2 r^2 \eta/4j$ . Let  $T = k\eta/j + t'$  such that  $t' < \eta/j$ . We can apply Lemma 17 for k times to get that the Rényi divergence between  $\{X_{i\eta/j}\}_{0\leq i< jT/\eta}$  and  $\{X_{i\eta/j}^j\}_{0\leq i< jT/\eta}$  is bounded by  $\frac{\alpha L^2 r^2 (T-t')}{4}$ . Now modifying  $\phi_1$  and  $\phi_2$  to use time t' instead of  $\eta/j$ , by the same argument as before and using Lemma 17 once more, we can conclude that

$$R_{\alpha}\left(X_{0-T}|X_{0-T}^{j}\right) \leq \frac{\alpha L^2 r^2 T}{4}$$

To go back to  $P_T$  and  $Q_T$  we write

$$R_{\alpha}\left(P_{T}|Q_{T}\right) \leq \frac{\alpha - 0.5}{\alpha - 1} R_{2\alpha}\left(P_{T}|P_{T}^{j}\right) + R_{2\alpha - 1}\left(P_{T}^{j}|Q_{T}\right),$$

where we used Cauchy-Schwartz inequality. Taking the limit as  $j \to \infty$  and using  $\alpha \ge 2$ , we get

$$R_{\alpha}\left(P_{T}|Q_{T}\right) \leq 2\lim_{j \to \infty} R_{2\alpha}\left(P_{T}|P_{T}^{j}\right) + \lim_{j \to \infty} R_{2\alpha-1}\left(P_{T}^{j}|Q_{T}\right)$$

The second term in RHS converges to 0, since by data processing inequality (see Lemma 16) we have

$$\lim_{j \to \infty} R_{2\alpha-1}\left(P_T^j | Q_T\right) \le \lim_{j \to \infty} R_{2\alpha-1}\left(\Gamma_T^{\eta/j} | \Pi_T\right) = 0,$$

where the last step is due to Lemma 12. Therefore, we get the following

$$R_{\alpha}\left(P_{T}|Q_{T}\right) \leq 2\lim_{j \to \infty} R_{2\alpha}\left(P_{T}|P_{T}^{j}\right) \leq 2\lim_{j \to \infty} R_{2\alpha}\left(X_{0-T}|X_{0-T}^{j}\right) \leq T\alpha L^{2}r^{2},$$

where the second inequality follows from data processing inequality (Lemma 16). This in turn implies (B.2).  $\Box$  Finally, we combine the previous results to go back to the unclipped process.

**Lemma 14.** Suppose Assumption 1 holds and  $x_0 = z_0 = \mathcal{N}(0, \sigma^2 \mathbf{I})$  for  $\sigma^2 < (L+1)^{-1}$ . If  $\eta \leq \frac{1 \wedge m}{4(1 \vee L^2)} \wedge \frac{2}{\|\nabla f(0)\|^2}$ , and for some universal constant c we have  $N\eta^2 \leq \frac{1}{c\kappa^2 L^2 \alpha^2}$ , then for any  $T \leq N\eta$  and  $\alpha \geq 2$ , we have the following

$$\mathbb{E}_{\pi_T}\left[\frac{\widetilde{\rho}_T}{\pi_T}(x)^{\frac{\alpha}{4}+\frac{1}{2}}\right] \le \frac{5\alpha+10}{\sqrt{\alpha}} \times \exp\left(cT\kappa^2 L^2 \alpha^2 (b+d+\log{(N)})\eta\right).$$

**Proof.** Considering the events  $\mathcal{E}^1_{\delta_1}, \mathcal{E}^2_{\delta_2}$  from Lemma 11, we plug the following value in (B.2)

$$r = c\kappa(\sqrt{b} + \sqrt{d} + \sqrt{\log(N/\delta_1)} + \sqrt{\log(N/\delta_2)})\sqrt{\eta}$$

where c is a universal constant such that the remark after Lemma 11 holds. This implies  $r^2 \leq c\kappa^2 (b + d + \log (N/\delta_1) + \log (N/\delta_2)) \eta$ , where we absorbed universal constants into c. We write

$$\mathbb{E}_{\pi_T} \left[ \frac{P_T}{\pi_T} \left( x \right)^{\alpha} \middle| \mathcal{E}_{\delta_2}^2 \right] \leq \frac{1}{1 - \delta_2} \mathbb{E}_{Q_T} \left[ \frac{P_T}{Q_T} (x)^{\alpha} \right]$$
$$\leq 2 \exp \left( T \alpha (\alpha - 1) L^2 r^2 \right)$$
$$\leq \frac{2 \exp \left( cT \kappa^2 L^2 \alpha^2 (b + d + \log (N)) \eta \right)}{(\delta_1 \delta_2)^{cT \kappa^2 L^2 \alpha^2 \eta}},$$

where the first step follows from  $\pi_T(x) \ge Q_T(x)$  (for  $x \in \mathbb{R}^d$ ), and the second from Lemma 13. In order to utilize Lemma 18 we set  $\gamma = cT\kappa^2 L^2 \alpha^2 \eta$  and we need  $\gamma < 1$  which combined with  $T \le N\eta$  shows that it is sufficient if we have

$$N\eta^2 \le \frac{1}{c\kappa^2 L^2 \alpha^2}$$

Lemma 18 implies

$$\mathbb{E}_{\pi_T}\left[\frac{P_T}{\pi_T}\left(x\right)^{\frac{\alpha}{2}}\right] \le 4\sqrt{2} \frac{\exp\left(cT\kappa^2 L^2 \alpha^2 (b+d+\log\left(N\right))\eta\right)}{\delta_1^{cT\kappa^2 L^2 \alpha^2 \eta}},$$

where universal constants are again absorbed into c. For replacing  $P_T$  with  $\tilde{\rho}_T$  we write

$$\mathbb{E}_{\pi_T} \left[ \frac{P_T}{\pi_T} (x)^{\frac{\alpha}{2}} \right] = \int_{\mathbb{R}^d} \frac{P_T(x)^{\alpha/2}}{\pi_T(x)^{\alpha/2-1}} dx$$
  

$$= \frac{\alpha}{2} \int_{\mathbb{R}^d} \int_0^{P_T(x)} \frac{y^{\alpha/2-1}}{\pi_T(x)^{\alpha/2-1}} dy dx$$
  

$$= \frac{\alpha}{2} \int_{\mathbb{R}^d} \left( \int_0^{\widetilde{\rho}_T(x)} \frac{y^{\alpha/2-1} \mathbf{1}_{\{y \le P_T(x)\}}}{\pi_T(x)^{\alpha/2-1}} \times \frac{1}{\widetilde{\rho}_T(x)} dy \right) \widetilde{\rho}_T(x) dx$$
  

$$= \frac{\alpha}{2} \mathbb{E}_{x \sim \widetilde{\rho}_T, y \sim \mathrm{U}(0, \widetilde{\rho}_T(x))} \left[ \frac{y^{\alpha/2-1}}{\pi_T(x)^{\alpha/2-1}} \middle| y \le P_T(x) \right]$$
  

$$\times \mathbb{P}_{x \sim \widetilde{\rho}_T, y \sim \mathrm{U}(0, \widetilde{\rho}_T(x))} [y \le P_T(x)].$$

We consider RHS term by term. For the first term we write

$$\mathbb{E}_{x \sim \widetilde{\rho}_T, y \sim \mathrm{U}(0, \widetilde{\rho}_T(x))} \left[ \frac{y^{\alpha/2 - 1}}{\pi_T(x)^{\alpha/2 - 1}} \middle| y \leq P_T(x) \right] = \mathbb{E}_{x \sim \widetilde{\rho}_T, y \sim \mathrm{U}(0, \widetilde{\rho}_T(x))} \left[ \frac{y^{\alpha/2 - 1}}{\pi_T(x)^{\alpha/2 - 1}} \middle| \mathcal{E}_{\delta_1} \right]$$

with the right coupling between y and the path x. For the second term we have

$$\mathbb{P}_{x \sim \widetilde{\rho}_T, y \sim \mathrm{U}(0, \widetilde{\rho}_T(x))} \left[ y \leq P_T(x) \right] = \int_{\mathbb{R}^d} \int_0^{P_T(x)} \frac{dy}{\widetilde{\rho}_T(x)} \widetilde{\rho}_T(x) dx = \int_{\mathbb{R}^d} P_T(x) dx \geq 1 - \delta_1 \geq \frac{1}{2}$$

Putting these together we get

$$\mathbb{E}_{x\sim\tilde{\rho}_{T},y\sim\mathrm{U}(0,\tilde{\rho}_{T}(x))}\left[\frac{y^{\alpha/2-1}}{\pi_{T}(x)^{\alpha/2-1}}\Big|\mathcal{E}_{\delta_{1}}\right] \leq \frac{4}{\alpha}\mathbb{E}_{\pi_{T}}\left[\frac{P_{T}}{\pi_{T}}(x)^{\alpha/2}\right] \leq \frac{16\sqrt{2}}{\alpha}\frac{\exp\left(cT\kappa^{2}L^{2}\alpha^{2}(b+d+\log\left(N\right))\eta\right)}{\delta_{1}^{cT\kappa^{2}L^{2}\alpha^{2}\eta}}.$$

Using Lemma 18 another time, we need to set  $\gamma = cT\kappa^2 L^2 \alpha^2 \eta$ . The condition  $\gamma < 1$  is already satisfied as we used this lemma before (with a different c). Therefore, we get the following (universal constants are absorbed into c again.)

$$\mathbb{E}_{x\sim\tilde{\rho}_T,y\sim\mathrm{U}(0,\tilde{\rho}_T(x))}\left[\frac{y^{\frac{\alpha}{4}-\frac{1}{2}}}{\pi_T(x)^{\frac{\alpha}{4}-\frac{1}{2}}}\right] \leq \frac{2^{17/4}}{\sqrt{\alpha}}\exp\left(cT\kappa^2L^2\alpha^2(b+d+\log{(N)})\eta\right).$$

Finally, we write

$$\mathbb{E}_{\pi_T}\left[\frac{\widetilde{\rho}_T}{\pi_T}(x)^{\frac{\alpha}{4}+\frac{1}{2}}\right] = \left(\frac{\alpha}{4} + \frac{1}{2}\right) \mathbb{E}_{x\sim\widetilde{\rho}_T,y\sim\mathrm{U}(0,\widetilde{\rho}_T(x))}\left[\frac{y^{\frac{\alpha}{4}-\frac{1}{2}}}{\pi_T(x)^{\frac{\alpha}{4}-\frac{1}{2}}}\right]$$
$$\leq \left(\frac{\alpha}{4} + \frac{1}{2}\right) \frac{2^{17/4}}{\sqrt{\alpha}} \exp\left(cT\kappa^2 L^2 \alpha^2 (b+d+\log\left(N\right))\eta\right).$$

#### C LOGARITHMIC SOBOLEV INEQUALITY UNDER ASSUMPTION 1

For some m, b > 0, assume that the following holds

$$\langle \nabla f(x) - \nabla f(y), x - y \rangle \ge m ||x - y||^2 - b$$
 for all  $x, y \in \mathbb{R}^d$ .

Define the Lyapunov function  $W(x) = \exp\{\frac{\gamma}{2} \|x - x_*\|^2\}$  for some  $\gamma$  and a critical point  $x_*$  of f. We have

$$\nabla W(x) = \gamma(x - x_*)W(x)$$
 and  $\Delta W(x) = \gamma(d + \gamma ||x - x_*||^2)W(x)$ 

and consequently

$$\frac{LW(x)}{W(x)} = \gamma \left( d + \gamma \|x - x_*\|^2 - \langle x - x_*, f(x) \rangle \right)$$
$$\leq \gamma \left( d + b + (\gamma - m) \|x - x_*\|^2 \right).$$

Next, choosing  $\gamma = m/2$  and defining  $R^2 = \frac{2}{m}(d+b+1)$ , one can show that the right hand side above is upper bounded by

$$-\frac{m}{2} + \frac{m}{2}(d+b)\mathbf{1}_{\{\|x-x_*\| \le R\}}.$$

Thus, the target  $\nu_* = e^{-f}$  satisfies the Lyapunov condition given in Bakry et al. (2008), and consequently satisfies a Poincaré inequality with a constant upper bounded with

$$\lambda \le \frac{2}{m} \left( 1 + c \frac{m}{2} (d+b) e^{\operatorname{Osc}_R(f)} \right)$$

where  $\operatorname{Osc}_R(f) = \sup_{\|x-x_*\| \leq R} f(x) - \inf_{\|x-x_*\| \leq R} f(x)$  and c is a absolute constant. This bound is of order  $\mathcal{O}(de^{\operatorname{Osc}_R(f)})$ . Further using the results of Cattiaux et al. (2010b), one can show that LSI holds for this class of potentials with a constant bounded by  $\mathcal{O}(d^2 e^{\operatorname{Osc}_R(f)})$ .

#### D USEFUL LEMMAS

**Lemma 15.** (From Van Erven and Harremos (2014)) The Rényi divergence of two Gaussians can be calculated as follows

$$R_{\alpha}\left(\mathcal{N}(0,\sigma^{2}\mathbf{I})|\mathcal{N}(x,\sigma^{2}\mathbf{I})\right) = \frac{\alpha \|x\|^{2}}{2\sigma^{2}}$$

**Lemma 16.** (Data processing inequality, From Van Erven and Harremos (2014)) Suppose  $x_1 \sim \rho_1$  and  $x_2 \sim \rho_2$ . For any function f, let  $f(x_1) \sim \pi_1$  and  $f(x_2) \sim \pi_2$ , then  $R_{\alpha}(\pi_1|\pi_2) \leq R_{\alpha}(\rho_2|\rho_2)$ .

**Lemma 17.** (From Mironov (2017)) Let  $\Delta(S_1)$ ,  $\Delta(S_2)$  be the space of probability measures on  $S_1$ ,  $S_2$  let  $\phi_1, \phi'_1 : \Delta(S_1) \to \Delta(S_2)$  and  $\phi_2, \phi'_2 : \Delta(S_2) \to \mathfrak{P}$  be maps such that for any distributions  $\delta$  that is a point mass (on either  $\Delta(S_1)$  or  $\Delta(S_2)$ ) we have  $R_{\alpha}(\phi_i(\delta)|\phi'_i(\delta)) \leq \epsilon_i$ . Then, for any probability measure  $\rho \in \Delta(S_1)$  we have  $R_{\alpha}(\phi_2(\phi_1(\rho))|\phi'_2(\phi'_1(\rho))) \leq \epsilon_1 + \epsilon_2$ .

**Lemma 18.** (Adapted from (Ganesh and Talwar, 2020, Lemma 14)) Let Y > 0 (a.s), $\gamma < 1$  and  $\theta > 1 + \gamma$ . If for all  $0 < \delta < 1/2$  an event  $\mathcal{E}_{\delta}$  has probability at least  $1 - \delta$ , and  $\mathbb{E}\left[Y^{\theta}|\mathcal{E}_{\delta}\right] \leq \frac{\beta}{\delta^{\gamma}}$ , then  $\mathbb{E}\left[Y\right] \leq 2^{2/\theta}\beta^{1/\theta}\frac{\theta}{\theta-1}$ . In particular, if  $\theta = 2$ , we get:  $\mathbb{E}\left[Y\right] \leq 4\sqrt{\beta}$ .

**Lemma 19.** For  $W \sim \mathcal{N}(0, \mathbf{I})$  we have the following tail bound for  $x \geq 0$ 

$$\mathbb{P}\left[\|W\| \ge \sqrt{d} + x\right] \le \exp\left(-x^2/2\right),$$

**Proof.** Suppose  $W = (w_1, \ldots, w_d)$  and denote  $\sqrt{d} + x$  with a. We write

$$\mathbb{P}\left[\left\|W\right\| \ge a\right] = \mathbb{P}\left[\exp\left(t\left\|W\right\|^{2}\right) \ge \exp\left(ta^{2}\right)\right] \le \frac{\mathbb{E}\left[\exp\left(tw_{1}^{2}\right)\right]^{a}}{\exp\left(ta^{2}\right)} = \exp\left(-ta^{2} - \frac{d}{2}\ln\left(1 - 2t\right)\right),$$

for all t < 1/2, therefore we can plug  $t = \frac{1}{2} \left(1 - \frac{d}{a^2}\right)$ , and put  $a = \sqrt{d} + x$  back to get

$$\mathbb{P}\left[\|W\| \ge \sqrt{d} + x\right] \le \exp\left(-x^2/2\right) \times \exp\left(-d\left(\frac{x}{\sqrt{d}} - \ln\left(1 + \frac{x}{\sqrt{d}}\right)\right)\right) \le \exp\left(-x^2/2\right),$$

where the last inequality holds since  $\frac{x}{\sqrt{d}} - \ln\left(1 + \frac{x}{\sqrt{d}}\right) \ge 0$ .

**Lemma 20.** For d-dimensional Brownian motion  $B_t$  we have  $(x \ge 0)$ 

$$\mathbb{P}\left[\sup_{s \le t} \|B_s\| \ge \sqrt{t}(\sqrt{d} + x)\right] \le 2\exp\left(-x^2/4\right).$$

**Proof.** Let r denote  $\sqrt{t}(\sqrt{d} + x)$  and  $\tau$  denote the first exit time of  $B_t$  out of the ball of radius r around origin. Note that  $\tau < t$  coincides with  $\sup_{s \le t} ||B_s|| > r$ , furthermore  $||B_{\tau}|| = r$ . We write

$$\mathbb{P}\left(\sup_{s\leq t}\|B_s\|\geq r\right)\leq \mathbb{P}\left(\|B_t\|\geq r\right)+\mathbb{P}\left(\tau< t,\|B_t\|< r\right)$$
$$=\mathbb{P}\left(\|B_t\|\geq r\right)+\mathbb{E}\left[\mathbf{1}_{\{\tau< t\}}\mathbb{P}\left(\|B_t-B_{\tau}+B_{\tau}\|< r|\tau,B_{\tau}\right)\right]$$
$$\leq \mathbb{P}\left(\|B_t\|\geq r\right)+\mathbb{E}\left[\mathbf{1}_{\{\tau< t\}}\mathbb{P}\left(\langle B_t-B_{\tau},B_{\tau}\rangle< 0|\tau,B_{\tau}\right)\right]$$
$$=\mathbb{P}\left(\|B_t\|\geq r\right)+\mathbb{P}\left(\sup_{s\leq t}\|B_s\|\geq r\right)/2,$$

where the last step follows from independence of updates and normality. Rearranging and using Lemma 19 concludes the proof.  $\hfill \Box$ 

**Lemma 21.** (Grönwall inequality Bellman (1943)) For a function v satisfying  $v(t) \leq C + A \int_0^t v(s) ds$ , for  $0 \leq t \leq T$  with A > 0. The following holds:  $v(t) \leq Ce^{At}$ .

**Lemma 22.** For a real sequence  $\{\theta_k\}_{k\geq 0}$ , if we have  $\theta_k \leq (1-a)\theta_{k-1} + h$  for some  $a \in (0,1)$ , and  $h \geq 0$ , then  $\theta_k \leq e^{-ak}\theta_0 + h/a$ .

**Proof.** Recursion on  $\theta_k \leq (1-a)\theta_{k-1} + h$  yields

$$\theta_k \le (1-a)^k \theta_0 + h(1+(1-a)+(1-a)^2 + \dots + (1-a)^{k-1}) \le (1-a)^k \theta_0 + \frac{h}{a}.$$

Using the fact that  $1 - a \le e^{-a}$  completes the proof.

**Lemma 23.** (Exponential Martingale Theorem (Ikeda and Watanabe, 2014, Chapter III, Theorem 5.3)) Let  $B_t$  be a Brownian motion and  $\mathcal{F}_t$  its associated filtration. If for an  $\mathcal{F}_t$ -adapted stochastic process  $M_t$  and some  $T \geq 0$ , the following (Novikov's) condition holds

$$\mathbb{E}\left[\exp\left(\frac{1}{2}\int_{0}^{T}\left\|M_{s}\right\|^{2}ds\right)\right]<\infty,$$

then  $\exp\left(\int_0^t M_s^\top dB_s - \frac{1}{2}\int_0^t \|M_s\|^2 ds\right)$  is an exponential Martingale and in particular its expectation is equal to 1 for all  $t \leq T$ .

**Lemma 24.** (Girsanov Theorem, Adapted from (Oksendal, 2013, Theorem 8.6.8)) Let  $x_t, y_t \in \mathbb{R}^d$  be defined as follows

$$dx_t(\omega) = b(x_t(\omega))dt + \sqrt{2}dB_t(\omega),$$
  
$$dy_t(\omega) = \gamma(\omega, t)dt + \sqrt{2}dB_t(\omega),$$

such that  $y_0 = x_0$  and  $\omega$  is an element of underlying probability space  $\Omega$ . Let  $\{\mathcal{F}_t\}$  be the natural filtration for  $B_t$  and P be the measure such that  $B_t$  is Brownian with respect to P and let

$$M_t(\omega) \triangleq \exp\left(-\frac{1}{\sqrt{2}}\int_0^t (\gamma(\omega,s) - b(y_s(\omega)))^\top dB_s(\omega) - \frac{1}{4}\int_0^t \|\gamma(\omega,s) - b(y_s(\omega))\|^2 ds\right).$$

If  $M_t$  is a martingale with respect to  $\mathcal{F}_t$ , in particular if  $\gamma(\omega, s) - b(y_s(\omega))$ , satisfies Novikov's condition, then on  $\mathcal{F}_T$  we have a unique measure Q such that

$$\frac{dQ}{dP}(\omega) = M_T(\omega),$$

with the property that the Q-law of y. is equal to the P-law of x., where  $x_{\cdot}(\omega)$  and  $y_{\cdot}(\omega)$  are one realization of  $x_t$  and  $y_t$  on [0,T].

Finally, we state two helper lemmas. The first lemma shows the convergence of continuous time process when the target satisfies LSI.

**Lemma 25** (Adapted from Theorem 3 in Vempala and Wibisono (2019)). If  $f = -\log \nu_*$  satisfies (LSI), then the following holds

$$\log \mathbb{E}_{\nu_*}\left[\frac{\pi_T}{\nu_*}\left(x\right)^{\alpha}\right] \le e^{-\frac{2T}{\alpha\lambda}} \log \mathbb{E}_{\nu_*}\left[\frac{\pi_0}{\nu_*}\left(x\right)^{\alpha}\right].$$

We briefly remark that the analog of the above lemma in Chi-squared divergence requires only the (PI).

In the second helper lemma, we prove that initializing with a normal distribution with a sufficiently small variance will cause  $\mathbb{E}_{\nu_*}\left[\frac{\rho_0}{\nu_*}(x)^{\alpha}\right]$  to be of order  $\widetilde{\mathcal{O}}(c^{\alpha d})$  for some constant c.

**Lemma 26.** Suppose f is L-smooth and  $\alpha \geq 2$ , then the following holds for  $\nu_* = e^{-f}$  and  $\rho_0 = \mathcal{N}(0, \sigma^2 I)$  when  $\sigma^2 < (L+1)^{-1}$ .

$$\mathbb{E}_{\nu_{*}}\left[\frac{\rho_{0}}{\nu_{*}}\left(x\right)^{\alpha}\right] \leq \frac{\exp\left((\alpha-1)(f(0)+\frac{\|\nabla f(0)\|^{2}}{2})\right)}{(2\pi\sigma^{2})^{\frac{\alpha d}{2}}}\left(\frac{2\pi}{\frac{\alpha}{\sigma^{2}}-(\alpha-1)(L+1)}\right)^{\frac{d}{2}}$$

**Remark.** For the sake of simplicity, we use the following crude bound

$$\mathbb{E}_{\nu_*}\left[\frac{\rho_0}{\nu_*}\left(x\right)^{\alpha}\right] \le e^{\alpha dC_{\sigma}} \quad \text{with} \quad C_{\sigma} = 1 + \frac{f(0) + \|\nabla f(0)\|^2}{d} - \log(\sigma^2[(1+L) \wedge 2\pi])$$

where  $C_{\sigma}$  is a dimension free constant that does not depend on  $\alpha$ .

**Proof.** For any x we have

$$f(x) \le f(0) + \frac{\|\nabla f(0)\|^2}{2} + \left(\frac{L+1}{2}\right) \|x\|^2.$$

Thus, we can write

$$\begin{split} \mathbb{E}_{\nu_{*}}\left[\frac{\rho_{0}}{\nu_{*}}\left(x\right)^{\alpha}\right] &\leq \frac{1}{\left(2\pi\sigma^{2}\right)^{\frac{\alpha d}{2}}} \int_{\mathbb{R}^{d}} \exp\left(-\frac{\alpha \|x\|^{2}}{2\sigma^{2}} + (\alpha - 1)f(x)\right) dx \\ &\leq \frac{\exp\left((\alpha - 1)(f(0) + \frac{\|\nabla f(0)\|^{2}}{2})\right)}{\left(2\pi\sigma^{2}\right)^{\frac{\alpha d}{2}}} \int_{\mathbb{R}^{d}} \exp\left(-\frac{1}{2}\left(\frac{\alpha}{\sigma^{2}} - (\alpha - 1)(L + 1)\right) \|x\|^{2}\right) dx \\ &\leq \frac{\exp\left((\alpha - 1)(f(0) + \frac{\|\nabla f(0)\|^{2}}{2})\right)}{\left(2\pi\sigma^{2}\right)^{\frac{\alpha d}{2}}} \left(\frac{2\pi}{\sigma^{2}} - (\alpha - 1)(L + 1)\right)^{\frac{d}{2}}. \end{split}$$

r		