
Supplementary for Locally Regularized Sparse Graph by Fast Proximal Gradient Descent

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1 PROOFS AND MORE TECHNICAL RESULTS

Proposition 1.1. Define $\mathcal{C}^+ = \{t: 1 \leq t \leq n, c_{ti} > 0\}$, and $\mathcal{C}^- = \{t: 1 \leq t \leq n, c_{ti} < 0\}$. Let \mathbf{z}^* be a critical point of function \tilde{F} in eq.(7) of the main paper. Then for arbitrary small positive number $\varepsilon > 0$, $\tilde{\mathbf{z}}^{*,\varepsilon} \in \mathbb{R}^n$ defined by

$$\tilde{\mathbf{z}}_k^{*,\varepsilon} = \begin{cases} \mathbf{z}_k^* & \text{if } \mathbf{z}_k^* \neq 0 \text{ or } k \in \mathcal{C}^+ \\ \varepsilon & \text{otherwise} \end{cases} \quad (1)$$

Then there exists $\mathbf{u} \in \tilde{\partial}F(\tilde{\mathbf{z}}_k^{*,\varepsilon})$ for F in eq.(6) of the main paper such that $\|\mathbf{u}\|_2 \leq L_f|\mathcal{C}|\varepsilon$ where $L_f := 2\sigma_{\max}(\mathbf{X}^\top \mathbf{X})$.

Proof. Since the only different elements between $\tilde{\mathbf{z}}^{*,\varepsilon}$ and \mathbf{z}^* are those with indices in $\mathcal{A} = \mathcal{C}^{-1} \cap \{k: \mathbf{z}_k^* = 0\}$, we have

$$\|\nabla f(\tilde{\mathbf{z}}^*) - \nabla f(\mathbf{z}^*)\|_2 \leq L_f \|\tilde{\mathbf{z}}^* - \mathbf{z}^*\|_2 \leq L_f |\mathcal{C}^{-1}| \varepsilon,$$

where $L_f = 2\sigma_{\max}(\mathbf{X}^\top \mathbf{X})$. Because \mathbf{z}^* be a critical point of function \tilde{F} , there exists $\mathbf{q} \in \tilde{\partial}h_{\gamma,c}$ such that $\mathbf{p} := \nabla f(\mathbf{z}^*) + \mathbf{q} = \mathbf{0}$. Define $\tilde{h}_{\gamma,c} = \gamma \sum_{k=1}^n c_{ki} \mathbb{1}_{\mathbf{z}_k^i \neq 0}$. With the definition of $\tilde{\mathbf{z}}^{*,\varepsilon}$, we have $\tilde{\mathbf{q}} \in \tilde{\partial}\tilde{h}_{\gamma,c}(\tilde{\mathbf{z}}^{*,\varepsilon})$ such that $\tilde{\mathbf{q}}_k = 0$ for $k \in \mathcal{A}$ and $\tilde{\mathbf{q}}_k = \mathbf{q}_k$ otherwise. Moreover, $\mathbf{q}_k = 0$ for all $k \in \mathcal{A}$.

Therefore, let $\tilde{\mathbf{p}} \triangleq \nabla f(\tilde{\mathbf{z}}^{*,\varepsilon}) + \tilde{\mathbf{q}} \in \partial F(\tilde{\mathbf{z}}^{*,\varepsilon})$, we have

$$\|\tilde{\mathbf{p}}\|_2 = \|\tilde{\mathbf{p}} - \mathbf{p}\|_2 = \|\nabla f(\tilde{\mathbf{z}}^*) - \nabla f(\mathbf{z}^*)\|_2 \leq L_f |\mathcal{C}^{-1}| \varepsilon.$$

The claim of this proposition follows with $\mathbf{u} = \tilde{\mathbf{p}}$. □

We repeat critical equations in the main paper and define more notations before stating the proof of Theorem 3.2.

$$\text{prox}_{sh_{\gamma,c}}(\mathbf{u}) := \arg \min_{\mathbf{v} \in \mathbb{R}^n, \mathbf{v}_i=0} \frac{1}{2s} \|\mathbf{v} - \mathbf{u}\|_2^2 + h_{\gamma,c}(\mathbf{z}) = T_{s,\gamma,c}(\mathbf{u}),$$

where $s > 0$ is the step size, $T_{s,\gamma,c}$ is an element-wise hard thresholding operator. For $1 \leq t \leq n$,

$$[T_{s,\gamma,c}(\mathbf{u})]_t = \begin{cases} 0 & : |\mathbf{u}_t| \leq \sqrt{2s\gamma c_{ti}} \text{ and } c_{ti} > 0, \text{ or } t = i \\ \mathbf{u}_t & : \text{otherwise} \end{cases} \quad (2)$$

1.1 PROOF OF THEOREM 3.2

Proof of Theorem 3.2. First of all, it can be verified that $\text{supp}(\mathbf{z}_c^{(k)}) \subseteq \text{supp}(\mathbf{z}_c^{(k-1)})$ for all $k \geq 1$ when $s < \frac{2\tau}{C^2}$. Therefore, there exists a finite $k' \geq 1$ such that $\{\mathbf{z}_c^{(k)}\}_{k \geq k'}$ have the same support \mathcal{S} . We note that λ can be also be slightly adjusted so that $\text{supp}(\mathbf{v}_c^{(k)}) = \mathcal{S}$ for all $k \geq k_0$. Now we consider any $k > k'$ in the sequel, and let $\mathbf{z} \in \mathbb{R}^n$ be a vector such that $\text{supp}(\mathbf{z}_c) = \mathcal{S}$.

Because f have L_f -Lipschitz continuous gradient, we have

$$f(\mathbf{z}^{(k)}) \leq f(\mathbf{m}^{(k)}) + \langle \nabla f(\mathbf{m}^{(k)}), \mathbf{z}^{(k)} - \mathbf{m}^{(k)} \rangle + \frac{L_f}{2} \|\mathbf{z}^{(k)} - \mathbf{m}^{(k)}\|_2^2. \quad (3)$$

Also,

$$\begin{aligned} & f(\mathbf{m}^{(k)}) - (1 - \alpha_k)f(\mathbf{z}^{(k-1)}) - \alpha_k f(\mathbf{z}) \\ &= (1 - \alpha_k) \left(f(\mathbf{m}^{(k)}) - f(\mathbf{z}^{(k-1)}) \right) + \alpha_k \left(f(\mathbf{m}^{(k)}) - f(\mathbf{z}) \right) \\ &\stackrel{\textcircled{1}}{\leq} (1 - \alpha_k) \langle \nabla f(\mathbf{m}^{(k)}), \mathbf{m}^{(k)} - \mathbf{z}^{(k-1)} \rangle + \alpha_k \langle \nabla f(\mathbf{m}^{(k)}), \mathbf{m}^{(k)} - \mathbf{z} \rangle \\ &\leq \langle \nabla f(\mathbf{m}^{(k)}), (1 - \alpha_k)(\mathbf{m}^{(k)} - \mathbf{z}^{(k-1)}) + \alpha_k(\mathbf{m}^{(k)} - \mathbf{z}) \rangle \\ &= \langle \nabla f(\mathbf{m}^{(k)}), \mathbf{m}^{(k)} - (1 - \alpha_k)\mathbf{z}^{(k-1)} - \alpha_k\mathbf{z} \rangle, \end{aligned} \quad (4)$$

where $\textcircled{1}$ is due to the convexity of f .

We have $\tilde{\mathbf{v}}^{(k)} = \mathbf{v}^{(k-1)} - \lambda_k \nabla f(\mathbf{m}^{(k)})$, and it follows that

$$\begin{aligned} & \frac{1}{2\lambda_k} \left(\|\mathbf{v}^{(k-1)} - \mathbf{z}\|_2^2 - \|\mathbf{v}^{(k)} - \mathbf{z}\|_2^2 - \|\mathbf{v}^{(k)} - \mathbf{v}^{(k-1)}\|_2^2 \right) \\ &= \frac{1}{\lambda_k} \langle \mathbf{z} - \mathbf{v}^{(k)}, \mathbf{v}^{(k)} - \mathbf{v}^{(k-1)} \rangle \\ &\stackrel{\textcircled{1}}{=} \frac{1}{\lambda_k} \langle \mathbf{z} - \mathbf{v}^{(k)}, \tilde{\mathbf{v}}^{(k)} - \mathbf{v}^{(k-1)} \rangle \\ &= \langle \nabla f(\mathbf{m}^{(k)}), \mathbf{v}^{(k)} - \mathbf{z} \rangle, \end{aligned} \quad (5)$$

and $\textcircled{1}$ is due to the fact that $\text{supp}(\mathbf{z}_c - \mathbf{v}_c^{(k)}) \subseteq \mathcal{S}$ because $\text{supp}(\mathbf{z}_c) = \mathcal{S}$, $\text{supp}(\mathbf{v}_c^{(k)}) \subseteq \mathcal{S}$.

Because $\text{supp}(\mathbf{v}_c^{(k)}) \subseteq \text{supp}(\mathbf{z}_c)$, we have

$$h_{\gamma,c}(\mathbf{v}^{(k)}) \leq h_{\gamma,c}(\mathbf{z}). \quad (6)$$

It follows by (5) and (6) that

$$\begin{aligned} & \langle \nabla f(\mathbf{m}^{(k)}), \mathbf{v}^{(k)} - \mathbf{z} \rangle + h_{\gamma,c}(\mathbf{v}^{(k)}) \\ &\leq h_{\gamma,c}(\mathbf{z}) + \frac{1}{2\lambda_k} \left(\|\mathbf{v}^{(k-1)} - \mathbf{z}\|_2^2 - \|\mathbf{v}^{(k)} - \mathbf{z}\|_2^2 - \|\mathbf{v}^{(k)} - \mathbf{v}^{(k-1)}\|_2^2 \right) \end{aligned} \quad (7)$$

Similar to (5), we have

$$\frac{1}{2s} \left(\|\mathbf{m}^{(k)} - \mathbf{z}\|_2^2 - \|\mathbf{z}^{(k)} - \mathbf{z}\|_2^2 - \|\mathbf{z}^{(k)} - \mathbf{m}^{(k)}\|_2^2 \right) = \frac{1}{s} \langle \mathbf{z} - \mathbf{z}^{(k)}, \mathbf{z}^{(k)} - \mathbf{m}^{(k)} \rangle. \quad (8)$$

For any $\mathbf{q} \in \partial h_{\gamma,c}(\mathbf{z}^{(k)})$, due to the fact that $\text{supp}(\mathbf{z}_c) = \text{supp}(\mathbf{z}_c^{(k)})$,

$$\langle \mathbf{z} - \mathbf{z}^{(k)}, \mathbf{q} \rangle + h_{\gamma,c}(\mathbf{z}^{(k)}) = h_{\gamma,c}(\mathbf{z}). \quad (9)$$

By (8) and (9),

$$\begin{aligned} & \langle \mathbf{z} - \mathbf{z}^{(k)}, \frac{1}{s}(\mathbf{z}^{(k)} - \mathbf{m}^{(k)}) + \mathbf{q} \rangle + h_{\gamma,c}(\mathbf{z}^{(k)}) \\ &= h_{\gamma,c}(\mathbf{z}) + \frac{1}{2s} \left(\|\mathbf{m}^{(k)} - \mathbf{z}\|_2^2 - \|\mathbf{z}^{(k)} - \mathbf{z}\|_2^2 - \|\mathbf{z}^{(k)} - \mathbf{m}^{(k)}\|_2^2 \right) \end{aligned} \quad (10)$$

By the optimality condition of the proximal mapping in eq.(10) in Algorithm 1, we can choose $\mathbf{q} \in \partial h_{\gamma,c}(\mathbf{z}^{(k)})$ such that $\mathbf{z}^{(k)} = \mathbf{m}^{(k)} - s(\nabla f(\mathbf{m}^{(k)}) + \mathbf{q})$. Plugging such \mathbf{q} in (10), we have

$$\langle \nabla f(\mathbf{m}^{(k)}), \mathbf{z}^{(k)} - \mathbf{z} \rangle + h_{\gamma,c}(\mathbf{z}^{(k)}) = h_{\gamma,c}(\mathbf{z}) + \frac{1}{2s} \left(\|\mathbf{m}^{(k)} - \mathbf{z}\|_2^2 - \|\mathbf{z}^{(k)} - \mathbf{z}\|_2^2 - \|\mathbf{z}^{(k)} - \mathbf{m}^{(k)}\|_2^2 \right) \quad (11)$$

Setting $\mathbf{z} = (1 - \alpha_k)\mathbf{z}^{(k-1)} + \alpha_k\mathbf{v}^{(k)}$ in (11), we have

$$\begin{aligned} & \langle \nabla f(\mathbf{m}^{(k)}), \mathbf{z}^{(k)} - (1 - \alpha_k)\mathbf{z}^{(k-1)} - \alpha_k\mathbf{v}^{(k)} \rangle + h_{\gamma,c}(\mathbf{z}^{(k)}) \\ & \leq h_{\gamma,c}((1 - \alpha_k)\mathbf{z}^{(k-1)} + \alpha_k\mathbf{v}^{(k)}) + \frac{1}{2s} \left(\|\mathbf{m}^{(k)} - (1 - \alpha_k)\mathbf{z}^{(k-1)} - \alpha_k\mathbf{v}^{(k)}\|_2^2 - \|\mathbf{z}^{(k)} - \mathbf{m}^{(k)}\|_2^2 \right) \\ & \stackrel{\textcircled{1}}{\leq} (1 - \alpha_k)h_{\gamma,c}(\mathbf{z}^{(k-1)}) + \alpha_k h_{\gamma,c}(\mathbf{v}^{(k)}) \\ & \quad + \frac{1}{2s} \left(\|\mathbf{m}^{(k)} - (1 - \alpha_k)\mathbf{z}^{(k-1)} - \alpha_k\mathbf{v}^{(k)}\|_2^2 - \|\mathbf{z}^{(k)} - \mathbf{m}^{(k)}\|_2^2 \right) \\ & \stackrel{\textcircled{2}}{\leq} (1 - \alpha_k)h_{\gamma,c}(\mathbf{z}^{(k-1)}) + \alpha_k h_{\gamma,c}(\mathbf{v}^{(k)}) + \frac{1}{2s} \left(\alpha_k^2 \|\mathbf{v}^{(k)} - \mathbf{v}^{(k-1)}\|_2^2 - \|\mathbf{z}^{(k)} - \mathbf{m}^{(k)}\|_2^2 \right), \end{aligned} \quad (12)$$

where $\textcircled{1}$ is due to the fact that $\text{supp}(\mathbf{v}_c^{(k)}) = \text{supp}(\mathbf{z}_c^{(k-1)})$ and $h_{\gamma,c}$ satisfies $h_{\gamma,c}((1 - \tau)\mathbf{u} + \tau\mathbf{v}) \leq (1 - \tau)h_{\gamma,c}(\mathbf{u}) + \tau h_{\gamma,c}(\mathbf{v})$ for any two vectors \mathbf{u}, \mathbf{v} with $\text{supp}(\mathbf{u}_c) = \text{supp}(\mathbf{v}_c)$ and any $\tau \in (0, 1)$. $\textcircled{2}$ is due to the fact that $\mathbf{m}^{(k)} - (1 - \alpha_k)\mathbf{z}^{(k-1)} - \alpha_k\mathbf{v}^{(k)} = \alpha_k(\mathbf{v}^{(k-1)} - \mathbf{v}^{(k)})$ according to eq.(9) in Algorithm 1.

Computing $\alpha_k \times (7) + (12)$, we have

$$\begin{aligned} & \langle \nabla f(\mathbf{m}^{(k)}), \mathbf{z}^{(k)} - (1 - \alpha_k)\mathbf{z}^{(k-1)} - \alpha_k\mathbf{z} \rangle + h_{\gamma,c}(\mathbf{z}^{(k)}) \\ & \leq (1 - \alpha_k)h_{\gamma,c}(\mathbf{z}^{(k-1)}) + \alpha_k h_{\gamma,c}(\mathbf{z}) \\ & \quad + \frac{\alpha_k}{2\lambda_k} \left(\|\mathbf{v}^{(k-1)} - \mathbf{z}\|_2^2 - \|\mathbf{v}^{(k)} - \mathbf{z}\|_2^2 \right) + \left(\frac{\alpha_k^2}{2s} - \frac{\alpha_k}{2\lambda_k} \right) \|\mathbf{v}^{(k)} - \mathbf{v}^{(k-1)}\|_2^2 - \frac{1}{2s} \|\mathbf{z}^{(k)} - \mathbf{m}^{(k)}\|_2^2 \\ & \stackrel{\textcircled{1}}{\leq} (1 - \alpha_k)h_{\gamma,c}(\mathbf{z}^{(k-1)}) + \alpha_k h_{\gamma,c}(\mathbf{z}) + \frac{\alpha_k}{2\lambda_k} \left(\|\mathbf{v}^{(k-1)} - \mathbf{z}\|_2^2 - \|\mathbf{v}^{(k)} - \mathbf{z}\|_2^2 \right) - \frac{1}{2s} \|\mathbf{z}^{(k)} - \mathbf{m}^{(k)}\|_2^2, \end{aligned} \quad (13)$$

and $\textcircled{1}$ is due to $\lambda_k \alpha_k \leq s$.

Combining (3), (4) and (13), and noting that $\tilde{F}(\mathbf{z}) = f(\mathbf{z}) + h_{\gamma,c}(\mathbf{z})$, we have

$$\begin{aligned} \tilde{F}(\mathbf{z}^{(k)}) & \leq (1 - \alpha_k)\tilde{F}(\mathbf{z}^{(k-1)}) + \alpha_k \tilde{F}(\mathbf{z}) - \left(\frac{1}{2s} - \frac{L_f}{2} \right) \|\mathbf{z}^{(k)} - \mathbf{m}^{(k)}\|_2^2 \\ & \quad + \frac{\alpha_k}{2\lambda_k} \left(\|\mathbf{v}^{(k-1)} - \mathbf{z}\|_2^2 - \|\mathbf{v}^{(k)} - \mathbf{z}\|_2^2 \right). \end{aligned} \quad (14)$$

It follows by (14) that

$$\begin{aligned} \tilde{F}(\mathbf{z}^{(k)}) - \tilde{F}(\mathbf{z}) & \leq (1 - \alpha_k) \left(\tilde{F}(\mathbf{z}^{(k-1)}) - \tilde{F}(\mathbf{z}) \right) \\ & \quad - \left(\frac{1}{2s} - \frac{L_f}{2} \right) \|\mathbf{z}^{(k)} - \mathbf{m}^{(k)}\|_2^2 + \frac{\alpha_k}{2\lambda_k} \left(\|\mathbf{v}^{(k-1)} - \mathbf{z}\|_2^2 - \|\mathbf{v}^{(k)} - \mathbf{z}\|_2^2 \right). \end{aligned} \quad (15)$$

Define a sequence $\{T_k\}_{k=1}^{\infty}$ as $T_1 = 1$, and $T_k = (1 - \alpha_k)T_{k-1}$ for $k \geq 2$. Dividing both sides of (15) by T_k , we have

$$\begin{aligned} \frac{\tilde{F}(\mathbf{z}^{(k)}) - \tilde{F}(\mathbf{z})}{T_k} &\leq \frac{\tilde{F}(\mathbf{z}^{(k-1)}) - \tilde{F}(\mathbf{z})}{T_{k-1}} - \frac{1 - L_f s}{2sT_k} \left\| \mathbf{z}^{(k)} - \mathbf{m}^{(k)} \right\|_2^2 \\ &\quad + \frac{\alpha_k}{2\lambda_k T_k} \left(\left\| \mathbf{v}^{(k-1)} - \mathbf{z} \right\|_2^2 - \left\| \mathbf{v}^{(k)} - \mathbf{z} \right\|_2^2 \right). \end{aligned} \quad (16)$$

Since we choose $\alpha_k = \frac{2}{k+1}$, it follows that $T_k = \frac{2}{k(k+1)}$ for all $k \geq 1$. Plugging the values of α_k and T_k in $\frac{\alpha_k}{2\lambda_k T_k}$ in (16), we have

$$\begin{aligned} \frac{\tilde{F}(\mathbf{z}^{(k)}) - \tilde{F}(\mathbf{z})}{T_k} &\leq \frac{\tilde{F}(\mathbf{z}^{(k-1)}) - \tilde{F}(\mathbf{z})}{T_{k-1}} - \frac{1 - L_f s}{2sT_k} \left\| \mathbf{z}^{(k)} - \mathbf{m}^{(k)} \right\|_2^2 \\ &\quad + \frac{k}{2\lambda_k} \left(\left\| \mathbf{v}^{(k-1)} - \mathbf{z} \right\|_2^2 - \left\| \mathbf{v}^{(k)} - \mathbf{z} \right\|_2^2 \right) \\ &\stackrel{\textcircled{1}}{\leq} \frac{\tilde{F}(\mathbf{z}^{(k-1)}) - \tilde{F}(\mathbf{z})}{T_{k-1}} - \frac{1 - L_f s}{2sT_k} \left\| \mathbf{z}^{(k)} - \mathbf{m}^{(k)} \right\|_2^2 + \frac{k}{2\lambda_k} \left\| \mathbf{v}^{(k-1)} - \mathbf{z} \right\|_2^2 \\ &\quad - \frac{k+1}{2\lambda_{k+1}} \left\| \mathbf{v}^{(k)} - \mathbf{z} \right\|_2^2, \end{aligned} \quad (17)$$

where $\textcircled{1}$ is due to the condition that $\lambda_{k+1} \geq \frac{k+1}{k}\lambda_k$ for $k \geq 1$.

Set $k_0 = k' + 1$. Summing the above inequality for $k = k_0, \dots, m$ with $m \geq k_0$, we have

$$\begin{aligned} \frac{\tilde{F}(\mathbf{z}^{(m)}) - \tilde{F}(\mathbf{z})}{T_m} &\leq \frac{\tilde{F}(\mathbf{z}^{(k_0-1)}) - \tilde{F}(\mathbf{z})}{T_{k_0-1}} + \frac{k_0 \left\| \mathbf{v}^{(k_0-1)} - \mathbf{z} \right\|_2^2}{2\lambda_{k_0}} - \sum_{k=k_0}^m \frac{1 - L_f s}{2sT_k} \left\| \mathbf{z}^{(k)} - \mathbf{m}^{(k)} \right\|_2^2 \\ &\leq \frac{k_0(k_0 - 1) \left(\tilde{F}(\mathbf{z}^{(k_0-1)}) - \tilde{F}(\mathbf{z}) \right)}{2} + \frac{\left\| \mathbf{v}^{(k_0-1)} - \mathbf{z} \right\|_2^2}{2\eta}. \end{aligned} \quad (18)$$

Since $T_m = \frac{2}{m(m+1)}$, it follows by (18) with $z = z^*$ that

$$\tilde{F}(\mathbf{z}^{(m)}) - \tilde{F}(\mathbf{z}^*) \leq \frac{1}{m(m+1)} \cdot \left(k_0(k_0 - 1) \left(\tilde{F}(\mathbf{z}^{(k_0-1)}) - \tilde{F}(\mathbf{z}^*) \right) + \frac{\left\| \mathbf{v}^{(k_0-1)} - \mathbf{z}^* \right\|_2^2}{\eta} \right). \quad (19)$$

Changing m to k in (19) completes the proof. □

2 ADDITIONAL ILLUSTRATION

Figure 1 illustrates the comparison between the weighed adjacency matrix of ℓ^1 -graph and SRSG.

References

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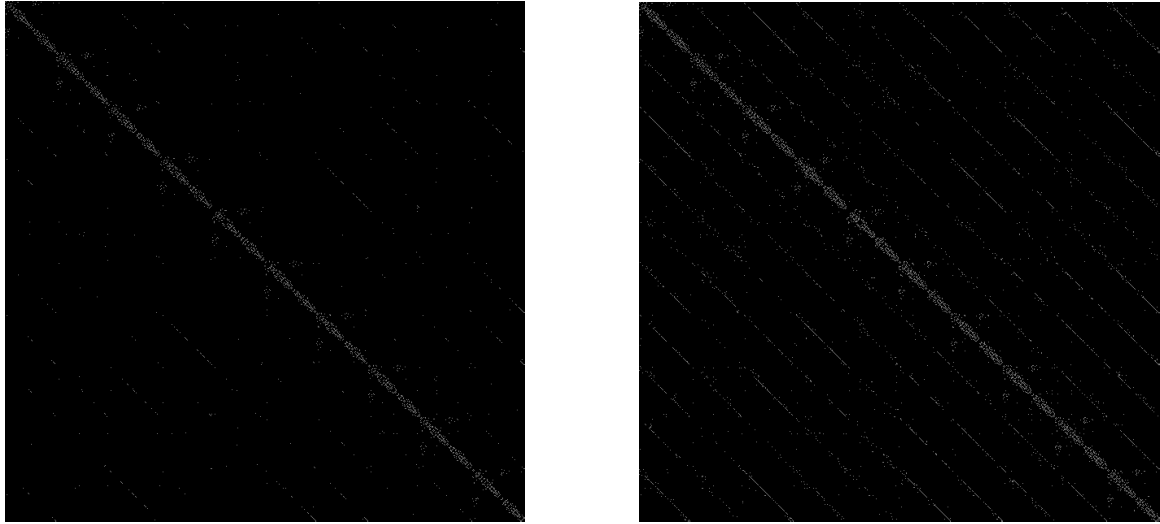


Figure 1: The comparison between the weighed adjacency matrix W of the sparse graph produced by ℓ^1 -graph (right) and SRSG (left) on the Extended Yale Face Database B, where each white dot indicates an edge in the sparse graph.